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GEMINI 10 INERTIAL GUIDANCE SYSTEM EVALUATION AND TRAJECTORY RECONSTRUCTION (U)

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ABSTRACT

This report contains a detailed evaluation of the Gemini 10 inertial guidance system accuracy during the ascent and reentry phases of the mission. An analysis of the external tracking instrumentation accuracy during ascent is also included. The results of the error analyses are used to construct a reference Gemini 10 trajectory for the ascent and reentry portions of the mission.

The reconstructed relative trajectory between the Gemini and Agena 10 vehicles is compared to the Gemini 10 onboard radar measurements and the residuals evaluated. The measurements of the altitudes of various stars by the astronaut, using a hand-held sextant, are compared to calculated values.

This TRW supplemental report, the IBM supplemental report, and the NASA/MSC Gemini 10 Mission final report represent the complete approved inertial guidance system analysis accomplished on this mission.

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1. INTRODUCTION AND SUMMARY

The Gemini 10 flight was launched on 18 July 1966 from Complex 19 at Cape Kennedy, Florida. This report, which has been prepared for the NASA Manned Spacecraft Center by TRW Systems in response to Task MSC/TRW G-14 of the Gemini Mission Trajectory Control Program, presents TRW's best estimate of the inertial guidance system (IGS) accuracy performance during the ascent, orbit and reentry phases of its operation on the Gemini 10 flight. Also presented are analysis results of the rendezvous radar performance and sextant sightings taken during the mission. This report constitutes an addendum to the Gemini 10 NASA/MSC Gemini Program Mission Report, Reference 6.

The basic data reduction and techniques of analysis used to obtain the conclusions in this report are defined in detail in the TRW Analysis Plan and Accuracy Prediction reports, References 1 and 2 respectively. The following is a brief summary of the analysis results.

a) The TRW estimate of total IGS error at SECO + 20 seconds is:

Δx	=	$1380 \pm 200 \text{ ft}$	$\Delta \dot{\mathbf{x}} = -0.3 \pm 1 \text{ ft/sec}$
Δy	Ξ	1810 ± 500	$\Delta \dot{y} = 13.5 \pm 3$
Δz	=	450 ± 300	$\Delta \dot{z} = 3.9 \pm 3$

The uncertainties are engineering judgments and equivalent to one sigma error estimates.

b) A set of IGS and tracking system error source coefficients was derived from analysis of position and velocity comparisons between IGS telemetry and tracking system data. Recovered IGS error sources that contributed significantly to the explanation of the observed differences were:

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Error source	Coefficient	Velocity error con- tribution in IGS coordinates at SECO + 20 sec (ft/sec)
x-axis		
No significant contributor		
<u>y-axis</u>		Δy
X accelerometer bias	46.6±10 ppm g	-1.2
Z accelerometer bias	76.9±10 ppm g	0 . 9
Z accelerometer scale factor	-451 ±66 ppm g	3.1
Y gyro constant drift rate	0.35 ±0.16 °/hr	9.3
Y gyro input axis unbalance	$-0.044 \pm 0.08^{\circ}/hr/g$	-1.2
Platform mis- alignment about Y accelerometer axis	17 ±31 sec	2.0
z-axis		Δz
X gyro input axis unbalance	-0.41 ±0.12 $^{\circ}/hr/g$	5.0
X gyro spin axis unbalance	0.14 ±0.14 $^{\circ}/hr/g$	-1.3
Z gyro constant drift rate	0.20 ± 0.13 °/hr	2.8
Z gyro input axis unbalance	-0.038 ±0.074 ⁰ /hr	/g -1.3
Platform mis- alignment about X accelerometer axis	36 ±13 sec	-3.9
IGS azimuth misalignment	19.8 ±10 sec	2. 4

CONTINUE



c) Significant tracking system bias errors recovered from the analysis were:

MISTRAM I	Coefficient	Velocity error con- tribution in IGS coordinates at SECO + 20 sec (ft/sec)		
P100K ^{bias}	-0.50 ± 0.10 ft	$\Delta \dot{y} = 6.5$		

<u>GE/MOD III</u>

Refraction -4.4 ± 2.2 n units $\Delta \dot{y} = 4.4$

d) The TRW estimate of the IGS error during reentry at guidance termination (76, 000 ft) is:

 0 ± 0.3 n.mi.downrange

 -4.9 ± 0.3 n.mi.crossrange (south)

 -3.3 ± 0.3 n.mi.altitude (low)

Approximately 80 percent of the apparent IGS error is estimated to be due to initial platform misalignment at retrofire.

e) The TRW estimate of the reentry trajectory miss from the intended splashdown point is:

 5.1 ± 0.5 n.mi.downrange (long)

 2.9 ± 0.5 n.mi.crossrange (north)

- f) The following conclusions were reached as a result of the rendezvous radar evaluation:
 - During the radar tracking interval preceding platform alignment (208 to 224 minutes GET) radar/platform angle error trends of up to 3 degrees were evident. The error was most likely in the radar measurement.
 - During platform alignment, the azimuth angle residuals showed excursions of ±3 degrees, indicating possible problems in alignment. [MSC analysis indicated the platform was momentarily torqued out of alignment due to a spacecraft roll error.]

- After platform alignment, there is an indicated platform/ radar system misalignment: yaw/azimuth misalignment = -1.9 ± 0.5°, pitch/elevation misalignment = -0.6 • 0.5°.
- No radar range error is evident to within the accuracy of the trajectory reconstruction, 1000 to 3000 feet.

Sections 2 and 3 contain details of the ascent and reentry IGS analysis and trajectory reconstruction. The trajectory listings are contained in Appendixes A and B. An analysis of the quality of the external tracking data obtained during ascent is contained in Section 4, and includes plots of the residuals of each tracking system compared to the reconstructed trajectory. A discussion of tracking system calibration data is contained in Appendix C. Section 5 discusses the comparison made between telemetered rendezvous radar measurements and TRW calculated values. Sextant sighting measurements are compared to calculated values in Section 6.

2. INERTIAL GUIDANCE SYSTEM PERFORMANCE ANALYSIS AND ASCENT TRAJECTORY RECONSTRUCTION

This section provides an evaluation of the performance of the IGS during the Gemini 10 ascent flight phase. The evaluation was accomplished by making comparisons of telemetered IGS quantities and external tracking data and conducting visual and regression analyses on the residuals of the comparisons.

Cartesian comparisons (sensed, total, and delta-delta) were made for display and visual analyses. These were referenced to the IGS computer coordinate system which is an inertial, orthogonal right-handed system referenced to the center of the earth. The x and z axes lie in a plane parallel to the geodetic tangent plane at the launch site at platform release time, with the x axis defined by the launch azimuth (actually the misaligned azimuth) positive down range. The y axis is positive down along the geodetic vertical, and the z axis is directed so as to complete the righthanded x, y, z set.

Sensed comparisons (Figure 2-1) were generated by scaling and biasing accumulated accelerometer count data and comparing the result with external tracking data adjusted for gravity and transformed to IGS coordinates. The Gemini 10 IGS measured quantities were compensated in flight with preflight measured IMU error sources; therefore, postflight IGS/tracker comparisons were generated with similarily compensated IGS sensed velocities. Section 2. 2. 1 provides a discussion of the compensations and their effects. The differences of the sensed coordinate IGS/tracker comparisons are attributable to residual uncompensated IMU errors, external tracking system errors, and initial alignment errors.

Total inertial comparisons, Figures 2-2 and 2-3, were generated by differencing telemetered total position and velocity outputs from the airborne computer with external tracking data. In addition to IMU, tracking data, and alignmenterrors, these comparisons include airborne computer navigation errors. These are caused by gravity computation errors, which result from numerical approximations and IMU position errors, and by computational errors due to truncation, etc. The navigation errors were



extracted by differencing the sensed and inertial comparison sets to form delta-delta comparisons (Figures 2-4 and 2-5).

Position and velocity comparisons were also made in the external tracking system measurement coordinates. These were made for the purpose of isolating uncompensated IGS and tracking system error source coefficients by performing visual and computer regression analyses of the differences. External tracking data used in the evaluation included Quick-Look MISTRAM I 10K and 100K and GE/MOD III. Tracking data constants and corrections are presented in Appendix C.

External tracking data used for complementary analyses included MISTRAM Final and AFETR Final BET data. The results of analysis of these data sources are presented in Table 4-1 of Section 4.

Support in the estimation of the total IGS error was obtained from a comparison of the IGS position and velocity vector at SECO +20 seconds with a similar vector derived from an orbital BET propagated back to SECO +20. The details of this comparison are given in Section 2.1.1.

All ascent-phase plots enclosed are referenced to liftoff time (22h 20m 26. 648s GMT), which occurred 3. 260 seconds after IGS platform release.

2.1 INERTIAL GUIDANCE SYSTEM ERROR

The estimated IGS errors following the end of the powered ascent phase (SECO+20 seconds, 360 seconds from liftoff) are contained in Table 2-1. The column headed "IMU and Alignment Error" represents the error contributed by the accelerometer, gyro, and initial platform alignment sources; the column titled "Navigation Error" is the contribution of various approximations within the airborne computer as observed from the delta-delta comparisons; and the "Total IGS Error" column is the sum of the two and represents the total IGS error. The column titled "TRW Orbit 1 Reconstruction" is the guidance error estimated from a comparison at SECO +20 seconds between the IGS data and the free flight reconstruction of Revolution 1 propagated back to insertion. Details of the reconstructed trajectory are given in Section 2.2.1. An additional column titled "NASA 30-Day Report" lists the values representing the NASA/MSC estimates of IGS errors. The \pm numbers listed are one-sigma uncertainty





estimates. They are the result of the analysis of the MOD III, MISTRAM and free flight trajectory estimations, and the statistical error regression.

	TRW Ascent Data Analysis			TRW orbit 1 recon-	NASA 30-day	
tion	IMU and alignment error	Naviga- tion error	Total IGS error	struction Total IGS error	Total IGS error	
X ft/sec	0.3±1.0	-0.6±0.1	-0.3±1.0	-0.3±2.0	0±1.0	
Ϋ́ ft/sec	13. 3±4. 0	0.2±0.1	13.5±4.0	16.0±3.0	15.5±3.0	
Ż ft/sec	4. 3±2. 0	-0.4±0.1	3. 9±3. 0	6. 9±3. 0	5.4±2.0	
X ft	1280 ± 200	95±5	1375 ± 200	918±300	545 ± 100	
Y ft	1860 ± 500	- 48 ± 5	1812±500	2020 ± 600	2450 ± 100	
Z ft	460 ± 300	-9±5	451 ● 300	308 € 600	440 ± 50	

Table 2-1. IGS Errors at SECO +20 Seconds

2.1.1 Free-Flight Fix

A comparison between the IGS position/velocity vector at SECO +20 seconds and a position/velocity vector derived from a trajectory reconstruction of the flight interval from insertion to first rendezvous was made to support the total IGS error estimation. This comparison point is indicated by a large \underline{X} on Figures 2-1, 2-2, 2-3 and 2-9 at 360 seconds. (The position and velocity comparisons presented in this report were generated excluding a timing error of 0.0485 second in the IGS data. This timing error causes a position error at SECO +20 seconds of 1200, - 330, 10 feet in IGS coordinates. The "TRW ascent data analysis" in Table 2-1 includes this error but the plotted "TRW orbit 1 reconstruction" comparison does not, so as to make it consistent with the "ascent" comparison plots.) This orbit reconstruction utilized tracking data for spacecraft revolutions 1 through 3 and IGS sensed velocity measurements of maneuvers executed during this flight phase. The trackers, which follow, provided C-band tracking data consisting of range, azimuth, and elevation observations.



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Station	<u>Revolutions</u>
Antigua	1, 2
Ascension	1, 2
Pretoria	1, 3
Carnarvon	1, 2
California	1, 2, 3
Hawaii	1, 2, 3
White Sands	1, 2
Eglin	1
Merritt	1
Grand Bahama	2
Grand Turk	3

The following IGS measured maneuver parameters were considered in the reconstruction.

	Burn	Velocity Increment in IGS coordinates			
Maneuver	initiation time (GET) (hr:min:sec)	∆X (ft/sec)	∆Ý (ft/sec)	∆Ż (ft/sec)	Burn duration (sec)
Separation	00:06:11	1.5	0.6	- 0. 8	19
IVAR	00:06:47	26.2	-0.62	0.5	36
Phase adjust	02:18:08	55.2	-1.2	1.2	77
Plane change	02:30:46	0.4	-0.5	-11.0	12
Coelliptical	03:47:35	47.1	- 5. 9	-0.3	93.9
Terminal phase initiation (TPI)	04:33:42	37.1	- 20. 0	0. 2	60

The TRW reconstructed state vector at SECO +20 seconds (361.5 seconds GET) in IGS coordinates was:

X = 3,974,910 ft	$\dot{X} = 25, 265.64 \text{ ft/sec}$
Y = -21,066,644 ft	$\dot{Y} = 4,763.24 \text{ ft/sec}$
Z = -94,789 ft	Ż = -81.14 ft/sec

The uncertainty associated with the orbit reconstruction vector, in Table 2-1, is an engineering estimate based on an examination of the radar residuals to the TRW BET and the uncertainty associated with integrating the BET from the free-flight phase back through the IVAR and Separation maneuvers. Further details of the orbit reconstruction can be found in Reference 3.



2.1.2 Insertion Conditions

The IGS error magnitudes indicated in Table 2-1 under "TRW ascent data analysis" give the following trajectory referenced errors:

= 1.8 ft/sec (IGS too large)
= -0.024 deg(IGS velocity vector below trajectory)

Out-of-plane velocity error = 3.9 ft/sec (IGS left of trajectory).

Estimates of insertion conditions as determined from real time MISTRAM and GE tracking data are presented in Table 2-2. For comparison, the values derived from the TRW BET are also presented.

	TDW		MIST	ſRAM	GE M	OD III
Observation	BET	IGS	Real time	Final	Real time	Final
Velocity magnitude (ft/sec)	25711.8	25713.6	25716	25712	26693	25707
Flight path angle (deg)	-0.001	-0.025	-0.07	-0.035	+0.14	-0.021

Table 2-2. Insertion Conditions (SECO +20 Seconds)

2.2 INERTIAL MEASUREMENT UNIT ERROR ANALYSIS

2.2.1 Preflight Compensation

The Gemini 10 IMU measured quantities were compensated inflight analytically with preflight measured gyro drift error coefficients. The drift errors used for compensation and their contributions to the total IGS compensation are listed in Table 2-3. Also presented are the total observed error and the error which would have been present without compensation. The gyro preflight calibration history plots, Figures 2-6 through 2-8, suggest that a logical set of gyro drift coefficients was chosen and no logical process for deriving a better preflight compensation set based upon the calibration histories is apparent. Two postflight gyro coefficient calibrations are also plotted in these figures.





Error Source	e Units	Coefficient	Contribution to IGS error compensation at SECO +20 seconds		
				Ý(ft/sec)	Ż(ft/sec)
X gyro constant drift rate	°/hr	0.17	- 0. 02	0.00	-1.63
Y gyro constant drift rate	°/hr	-0.24	-0.21	-6.45	0.00
Z gyro constant drift rate	°/hr	-0.06	0.00	0.00	-0.83
X gyro input axis unbalance	⁰ /hr/g	0.29	-0.04	-0.05	- 3, 58
Y gyro input axis unbalance	⁰ /hr/g	0.10	0.35	2.75	0.00
Z gyro input axis unbalance	⁰ /hr/g	-0.29	0.09	0.00	-10.05
X gyro spin axis unbalance	⁰ /hr/g	-0.55	0.04	-0.11	5.05
Y gyro spin axis unbalance	^o /hr/g	0.06	0.00	0.07	0.00
Z gyro spin axis unbalance	^o /hr/g	-0.29	-0.01	0. 00	2.18
	Total co	mpensation	+0.20	-3.79	- 8. 86
Erı	or with co.	mpensation	+0.3	+13.3	+4.3
Error	without co	mpensation	+0.50	+9.5	- 4. 6

Table 2-3. IMU Error Compensation

Table 2-4 contains the TRW estimate of IMU error on Gemini flights 6 through 10, and provides an indication of the effect preflight gyro drift error compensation would have had on these flights if it had been utilized. Gemini 10 was the first flight to incorporate the ability to compensate inflight for preflight estimated gyro drift errors. The summary indicates no significant reduction of errors would have been achieved by compensation with the NASA/Honeywell preflight estimated coefficients. However, the preflight coefficients estimated for flights 6 through 9 were based primarily on single platform calibrations prior to flight, whereas the





Table 2-4.	TRW Estimates of Gemini IMU Errors at SECO
	+20 Seconds With and Without Gyro Drift Error
	Compensation

	Flight No.	TRW Estimates of IMU Error at SECO +20 Seconds					
•		X (ft/sec)	Ϋ́ (ft/sec)	Ż (ft/sec)	Ż' (ft/sec)**		
6	As flown	-1.81	9.7	-1.92	-0.22		
	Honeywell Preflight value	- 0. 87	-6.6	+0, 54	+0.54		
	With compensation	- 0. 94*	16.3	-2.46	-0.76		
7	As flown	+5.6	+9.9	+0.2	-2.4		
	Honeywell Preflight value	+0.7	+4.1	-6.2	-6.2		
	With compensation	+4.9*	+5.8*	+6.8	+3.8		
8	As flown	+5.18	- 4. 86	+11.35	+4. 34		
	Honeywell Preflight value	+0.03	-0.55	+7.65	+7.65		
	With compensation	+5.15*	-4.31*	+3.70*	- 3. 31*		
9	As flown***	+8.60	-1.63	8. 31	2. 54		
	Preflight value	+0.39	+3.43	-1.29	-1.29		
With compensation	+8.21*	- 5. 06	9.60	3.83			
10	Without compensation	+0.50	+9.5	- 4. 6	-7.0		
	Compensation	0.20	- 3. 79	- 8, 86	- 8. 86		
	With compensation (as flown)	+0.3*	+13.3	+4. 3*	+1.9*		

*Error improved or unaffected by compensation

Z' = Crossrange error with the effects of IGS/Burroughs azimuth alignment update error removed *Gemini 9 error listed assumes IGS/Burroughs inflight azimuth update

***Gemini 9 error listed assumes IGS/Burroughs inflight azimuth update was successfully completed. Actual error was 166 f.p.s. in Z.

actual compensations used for Gemini 10 were based upon the complete history of Gemini 10 platform calibrations.

It is observed that the crossrange (\dot{Z}') error, adjusted for the Burroughs azimuth update error, is generally smaller than the vertical (\dot{Y}) error. There is no apparent reason for this difference based on the gyro drift error propagations. It could be explained by assuming that initial platform misalignment was the major system error source, since the

azimuth update procedure nulls out the crossrange component of this error source but not the downrange component. Accelerometer scale factor error also is a contributor to the vertical error but not the crossrange error.

Table 2-5 provides a comparison of the TRW proposed Gemini 10 total IMU errors (compensation + residuals) with error magnitudes derived from both preflight and postflight calibration data. As noted from Table 2-4, there has not been consistent agreement between preflight IMU calibration data and TRW postflight error estimation based on the apparent flight performance. Generally, there has not been a postflight IMU calibration to check on instrument stability.

Table 2-6 shows the velocity error propagation of the differences between the September 23 postflight calibration and the preflight estimated (and flown) coefficients. The shift in the Y gyro constant drift rate(YGCDR)term is 0.22 deg/hr, equivalent to 6 ft/sec y velocity error at SECO. This shift is in remarkably good agreement with the 0.35 deg/hr shift indicated by the TRW regression as the cause of the observed flight error in the vertical direction (see Table 2-8).

This correlation does not show up so obviously for the other large gyro coefficient shift called for by the postflight regression: X gyro input axis unbalance equal to -0.41 deg/hr/g. There are, however, sizeable shifts evident in the postflight X gyro calibrations for the constant drift (-0.2 deg/hr) and spin axis unbalance drift (0.1 deg/hr/g).

If sizeable and unpredictable coefficient shifts are measured across the flight test, it would seem conceivable that different and even larger shifts might be apparent during the very dynamic flight test. This is not to contend that the postflight statistical regression on the IGS/tracker residuals gives absolutely reliable results. In fact, the error separation is very seriously limited by the nigh correlation among the velocity error propagations of the possible error sources. However, the regression does select a statistically "best" fit when given the available data, error model, and related statistics. The most that can be hoped for from the flight profile of Gemini 10 is a reasonable indication of the likely error sources.





					Prefligh	it Platform C	alibrations				Flight Co	mpensation	Postflight calibr	platform ations
Error sources (TRW symbols)	Unite	24 Feb	14 June	15 June	16 June	17 June	20 June	29 June	15 July	Preflight average	NASA / Honeywell preflight estimated	TRW postflight estimated	23 Sept	26 Sept
XGCDR	./hr	0.135	0.185	0.163	0.19	0.14	0.207	0.15	0, 111	0,160	0.17	0.157±0.19	-0.025	-0. 023
XGIAU	•/hr/g	0.23	0.253					0.287	0. 293	0.265	0.29	-0.126±0.12	0. 341	0, 348
XGSAU	°/hr/g	-6.24	-0.485	-0.52	-0, 592	-0.508	-0.567	-0.55	-0.561	-0.502	-0.55	-0.412 ± 0.14	-0.449	-0.452
YGCDR	./hr	-0, 135	-0.222					-0.244	-0.251	-0.213	-0.24	0.107 ± 0.16	-0.02	-0.01
YGLAU	•/hr/g	-0.07	-0.025					0.136	0.102	0. 036	0.10	0.056±0.08	0.122	0.042
YGSAU	8/Jrr/8	0.14	-0, 003					0.114	-0.009	0.06	0.06	0.071 ± 0.20	-0.125	-0.184
ZGCDR	•/hr	-0.014	-0.0611					-0.048	-0.041	-0.041	-0.06	0.14 ± 0.13	-0.008	0.004
ZGIAU	8/14/.	0.06	-0.273					-0.3	-0.251	-0.191	-0.29	-0.33 ± 0.07	-0.278	-0.278
ZGSAU Deviation loaded val	from ue	-0,06	-0.286					-0, 308	-0.176	- 0. 208	-0.29	-0.36±0.09	-0.221	-0. 223
XSF	шdd	- 31	0					-23	-103	- 39	(1)	-46 ± 114		
YSF	mqq	-30	0					130	-117	-4.3	Ξ	0		
ZSF	udd	-240	0					78	18	-36	(1)	-451 ± 65	<u> </u>	
ВХ	8 mdd	38	ø							19	Ξ	4 6 ± 20		
вҮ	g mqq	57	- 3							28	(1)	0 ± 20		
ΒZ	g mqq	-30	12							6-	(1)	<u>77</u> ± 20		
(1) _{No} change mä	ade from pr	eviously load	ed values.											

Table 2-5. IMU Error Coefficients

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CONTIDUNITIE

		Postflight	Error a	t SECO + 20	seconds
source	Units	preflight	∆×(ft/sec) ∆ý (ft/sec)	∆ż(ft/sec)
XGCDR	o/hr	-0.195	0.02		1.88
XGIAU	o/hr/g	0.051	-0.008	-0.008	- 0.642
XGSAU	o/hr/g	0.101	- 0. 007	0.02	-0.93
YGC DR	o/hr	0.22	0.19	5.9	
YGIAU	o/hr/g	0.022	0.08	0.6	
YGSAU	o/hr/g	-0.185	-0.16	- 0.2	
ZGCDR	o/hr	0.052	-0.007		0.73
ZGIAU	o/hr/g	0.012	-0.004		0.42
ZGSAU	o/hr/g	0.069			-0.52
		То	tal 0.11	6.3	0.94

Table 2-6. Expected IGS Error From Postflight Calibrations

Table 2-7. TRW Estimates of Gemini Timing Errors

Flight No.	T	ime correlation (sec)	IGS clock drift (ppm)
3		-0.005	0
4		-0.002	30
5		0.014	-60.5
6		0.015	-63
7		0	- 32. 2
8		0.025	- 90
9		0.017	-63
10		0.006*	-85
	Mean	+0.009	-45.0

*

*0.0485 second known TRS bias removed.

2.2.2 Residual IMU Error After Compensation

Recovery of the IMU error source coefficients, which existed after compensation, was accomplished by visual analysis and by performing computer statistical regressions on IGS/tracker residuals. Figure 2-1 presents sensed velocity comparisons compensated for preflight estimated IMU errors, and a 0.0485 second TRS bias error. The IMU error source coefficients recovered as a result of the analysis are presented in Table 2-8.

2.2.2.1 Timing Error

The first set of velocity comparisons generated showed -5.3 and -5.6 ft/sec jumps in the x velocity residual at booster engine cutoff (BECO) and sustainer engine cutoff (SECO). This error trend indicated large IGS timing errors. Conversations with NASA MSC personnel revealed that 0.0485 second of the observed time correlation error was explained by a known time reference system (TRS) bias. The majority of the time correlation error was therefore identified; however, the remaining trend, obvious in Figure 2-1 from the small jumps at BECO and SECO. called for an additional 0.006 m sec time correlation error and an 85 part per million (ppm) clock drift error. Although the timing error results in zero sensed velocity error after SECO, where the thrust acceleration goes to zero, a relatively large x total position error of 1000 feet does remain after burnout. The Gemini 10 time correlation and clock drift error are compared with timing errors recovered from previous Gemini flights in Table 2-7. The summary indicates that the Gemini 10 timing errors are consistent with timing errors observed on previous flights. The clock drift is large however.

2.2.2.2 Accelerometer Bias Error

Accelerometer bias errors were determined from plots of IGS sensed velocities during free flight intervals of Revolution 4 and later during the free flight period after retrofire. The following bias errors were determined:



	Revolution 4	Post Retrofire
X accelerometer bias	46.6 ± 10 ppm g	6.2 ± 10 ppm g
Y accelerometer bias	0 ± 10 ppm g	43.6 ± 10 ppm g
Z accelerometer bias	76.9 ± 10 ppm g	46.9 ± 10 ppm g

The values calculated from Revolution 4 were used for the ascent phase analysis and those recovered from the post retrofire data were used for the reentry analysis.

2.2.3 Error Coefficient Recovery

The IMU error source coefficients presented in Table 2-8 were recovered by first determining accelerometer bias errors, compensating the IGS/tracker comparisons for these, and then performing statistical regression analysis on the residuals of the comparisons. The regression domain chosen was the following:

10K MISTRAM Þ, Q, R_{SUM}

100K MISTRAM P, Q

GE MOD III (GE processed) R, A, E, R, P, Q

The error model presented in Table 2-9 was selected to recover coefficients for most of the IMU error sources estimated by platform ground calibration tests. The terms preceded by an asterisk were recovered visually and were consequently not solved in the regression solution. However, the estimated uncertainty in their determination was statistically accounted for in the output coefficient uncertainties.

Several variations or combinations of error terms were considered in initial regression attempts which considered accelerometer and platform misalignments as being dominant error sources rather than gyro drift errors. None of these provided satisfactory fits to the IGS/tracker residuals, however. Satisfactory explanations of the residuals were achieved only when pitch-drift type error sources were included in the total error model.



Table 2-8. IGS Error Source Summary

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				TRW	ualysis					2	0-0C VCV	ay report			
			Confficient	l sigma	Ve CCC SEC	ilocity errent intribution	or at conds	Coefficient	Vel con SECC	ocity erro tribution) +20 seco	r at nds	Coefficient	Velo SEC(city error 0 +20 seco	at nds
	LMU error source	OTHE	Coefficient	uncertainty	∆X (ft/sec)	∆Ý (ft/sec)	∆Ž (ft/sec)	(Fit 1)	∆X (ft/sec)	∆Ý (ft/aec)	ΔŽ (ft/sec)	(Fit 2)	∆X (ft/sec)	∆Ý (ft/sec)	∆Ż (ft/sec)
-	Accelerometer														-
	X accelerometer bias	bpm g	46.6	10	0. 22	-1.15		50	0. 2	-1.3		z			
	Y accelerometer bias	ppm g	0	10			-	z				z			
	Z accelerometer bias	ppm g	76.9	10		0.89		80		0.9		80		0.9	
	X accelerometer scale factor	bpm	-46	114	-1.15			-50	-1.2			z			
	Z accelerometer scale factor	шdd	-451	66		3.06		00#-		2.7		-300		2.0	
	X accelerometer misalignment toward Z	(ja	- 14	33	0.46			z							
	Z accelerometer misalignment toward X	(je	+2.5	39		0. 30		-17.5		-2.1		06		10.8	
Ħ	Pitch Drift			0.1											
	Y gyro constant drift rate	°/hr	+0.35	0.16	0.31	9. 32		z				N			
	Y gyro input axis unbalance	°/hr/g	-0.044	0.08	-0.15	-1.21		+0.56	1.9	15.3		N			
	Y gyro spin axis unbalance	°/hr/g	+0.011	0. 20		0.01		z				z	-		
Ħ	Roll and Azimuth Drift														
	X gyro constant drift rate	°/hr	-0.013	0.19			0. 13	z				z			
	X gyro input axis unbalance	°/hr/g	-0.41	0.12	0. 06	0.06	5.04	z				z			
	X gyro spin axis unbalance	°/hr/g	+0.14	0.14	-0.01	0. 03	-1.28	z				z			
	Z gyro constant drift rate	°/hr	+0.20	0.13	-0.03		2.78	z				z			
	Z gyro input axis unbalance	°/hr/g	-0.038	0.074	0. 01		-1.34	+0.10			3.40	0.10			3, 4
	Z gyro spin axis unbalance	°/hr/g	-0.066	0.093			0.50	z				z			
Ν	System														
	Platform misalignment about X accelercmeter axis	(je	36	13	-0.05	-0.04	-3.90	z				z			
	Platform misalignment about Y accelerometer axis	(ju ju ju ju ju ju ju ju ju ju ju ju ju j	17	31	0. 56	2. 04		z				z			
	Platform azimuth misalignment	(eg	19.8	10	0. 06		2. 37	+20			2.4	+20			2.4
	IGS time correlation	sec	0.0546	10			-	+0.0556	•	•	•	0. 0556	•	0	•
	IGS time scale factor	bpm	-84.9	65				- 92	•	0	•	-92	•	0	•
	TOTAL			_	0. 29	13. 31	4.30		0.6	15.3	5.8		0	13. 7	5.8
										1					

*N represents negligible coefficient.

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Symbol	Error source	Units	lo a priori uncertainty
* VOZ	Z accelerometer initialization	ft/sec	0.2
DT	Time correlation	sec	0.01
TSF	Time scale factor	ppm	20
*BX	X accelerometer bias	ppm g	10
* BY	Y accelerometer bias	ppm g	10
* BZ	Z accelerometer bias	ppm g	10
XSF	X accelerometer scale factor	ppm	160
ZSF	Z accelerometer scale factor	ppm	160
POX	Position bias - X computer axis	ft	50
POY	Position bias - Y computer axis	ft	50
POZ	Position bias - Z computer axis	ft	50
XZMSL	X accelerometer misaligned toward Z	arc sec	50
ZXMSL	Z accelerometer misaligned toward X	arc sec	50
XGCDR	X gyro constant drift rate	⁰ /hr	0.2
YGCDR	Y gyro constant drift rate	°/hr	0.2
ZGCDR	Z gyro constant drift rate	⁰ /hr	0.2
XGSAU	X gyro spin axis unbalance	⁰ /hr/g	0.2
YGSAU	Y gyro spin axis unbalance	⁰ /hr/g	0.2
ZGSAU	Z gyro spin axis unbalance	⁰ /hr/g	0.2
XGIAU	X gyro input axis unbalance	⁰ /hr/g	0.2
YGIAU	Y gyro input axis unbalance	⁰ /hr/g	0.2
ZGIAU	Z gyro input axis unbalance	⁰ /hr/g	0.2
PHIX	Platform alignment about X accelerometer axis	arc sec	50
PHIY	Platform alignment about Y accelerometer axis	arc sec	50
PHIZ	IGS azimuth alignment	arc sec	10
A4(1)	MISTRAM I refraction - central site	n-units	2.0
CO(3)	GE MOD III range bias	ft	10

Table 2-9. TRW Proposed Error Model

*Not solved for in regression. (See Subsection 2.2.3.)

Symbol	Error source	Units	lσ a priori uncertainty
C2(3)	GE MOD III timing	sec	0.001
C4(3)	GE MOD III refraction	n-units	2.0
C 5(3)	GE MOD III survey (east)	ft	3.0
C6(3)	GE MOD III survey (north)	ft	3.0
C7(3)	GE MOD III survey (up)	ft	1.0
DO(3)	GE MOD III azimuth bias	millirad	0.2
FO(3)	GE MOD III elevation bias	millirad	0.2

Table 2-9. TRW Proposed Error Model (Concluded)

The results of the final regression solution have been presented in part in Table 2-8. Also recovered were the following tracking system and IGS position bias errors along with their one sigma uncertainties.

MISTRAM I refraction	=	$-0.48 \pm 2.0 \text{ n} - \text{units}$
GE MOD III range bias	=	-23 ± 3.8 ft
GE MOD III timing bias	=	-0.61 ± 0.22 millisec
GE MOD III refraction	=	-4.44 ± 2.22 n – units
GE MOD III azimuth bias	=	$-2.7 \pm 15 \mu rad$
GE MOD III elevation bias	=	+44 ± 11 µrad
X computer axis position bias	=	-3.9 ± 4.0 ft
Y computer axis position bias	=	+20.2 ± 5.2 ft
Z computer axis position bias	=	-19.6 • 7.8 ft

IGS data position bias errors are considered to result from postflight data reduction errors rather than the IMU. The effect of tracking data errors on IGS/tracking data comparisons is discussed in Section 4.

The ability of the regression to fit the residuals is graphically displayed by heavy lines drawn upon the tracker coordinate position and velocity residuals in Figures 2-10 through 2-13. These lines represent the total error contribution of the recovered coefficients. It can be seen that the residuals between the lines and the respective data points are for





the most part unbiased and the indicated line closely approximates the apparent position and velocity errors.

The degree to which the recovered IMU error sources explain the IGS/tracker residuals in guidance coordinates is indicated in Figure 2-9 by a heavy line. The x-axis residuals are explained by the IMU functions to within the data noise; however, unexplained residuals remain in the y and z axes. These residual differences are attributed to a MISTRAM P_{100K} bias of -0.5 ft and a GE MOD III refraction error of -4.4 n-units. On the other hand, the IMU functions accounted for nearly all of the IGS/MISTRAM 10K residuals suggesting that the MISTRAM 10K bias errors were smaller than those of the 100K data (see Figures 4-3 and 4-4 of Section 4).

Recovery of the MISTRAM I position bias errors was accomplished by compensating the IMU/tracker position domain residuals with the errors recovered in the regression analysis and estimating the bias levels from the remaining position errors (Section 4).

2.3 IGS AZIMUTH UPDATE

The IGS azimuth alignment update corrections were successfully accomplished on this flight. The initial alignment correction was obtained, during the first pass through the navigation equations, by comparing the actual platform roll gimbal angle after platform release with the desired value. Additional azimuth corrections were made at 100 and 140 seconds after liftoff. These were calculated by comparing the crossrange (z direction) velocity as measured by GE/Burroughs with that derived from the airborne system and attributing the residual to a platform misalignment about the vertical axis.

Table 2-10 compares the initial IGS alignment correction, total inflight update obtained, and residual alignment error on Gemini 10 with those obtained on previous Gemini missions. This summary shows that the Gemini 10 corrections are consistent with those obtained on previous flights. The residual azimuth misalignment on this flight was considerably smaller than rendezvous flights 6, 8, and 9.



Flight No.	Initial alignment correction (deg)	Inflight update (deg)	Total Alignment Correction (deg)	Residual azimuth error (arc sec)
2	-0.07	-0.22	-0.29	0
3	+0.01	-0.53	-0.52	0
4	+0.03	-0.15	-0.12	0
5	+0.05	-0.32	-0.27	0
6	+0.06	- 0. 59	-0.53	-40
7	-0.01	-0.47	-0.48	0
8	+0.11	-0.21	-0.10	+57
9	+0.17	- 0. 40*	-0.23*	+48
10	-0.09	- 0. 13	-0.22	+20
Mea	n +0.03	-0.34	-0.31	
		NASA/Honeywell Specification	l 1 0.75	

Table 2-10. History of Azimuth Alignment Correction

* Simulated

2.4 CONCLUSIONS

- a) The IGS vertical (y) velocity error of over 13 ft/sec was larger than expected. Error in the x and z coordinates was nominal.
- b) The net effect of the inflight gyro compensation was to increase the IGS y coordinate error by 4 ft/sec and leave the z coordinate error magnitude unchanged. However, the compensation would have significantly reduced (5 ft/sec) the z coordinate error magnitude if the Burroughs' azimuth update correction had been accurate. Available preflight gyro calibration data indicate that a logical set of preflight compensation coefficients was selected.
- c) A very large IGS time correlation error of 0.055 seconds was observed; however, the major portion, 0.049 seconds, is attributable to a known TRS bias. The clock drift of 85 parts per million was also large, but is consistent with that observed on previous flights.





- d) Inflight updating of the IGS azimuth alignment was successfully accomplished, though a residual azimuth error equivalent to 20 sec remained after updating. The residual error is one-half or less than that observed on any other rendezvous flight.
- e) Accelerometer bias errors recovered on this flight were nominal though apparent shifts occurred between ascent and reentry.

2.5 ASCENT TRAJECTORY RECONSTRUCTION

The ascent trajectory reconstruction consists of IGS data corrected for the alignment errors and IMU error sources presented in Table 2-8. A listing of this reference trajectory is provided in Appendix A.

The trajectory is given in an earth-centered inertial coordinate system. The z axis is aligned with the earth's rotational axis, positive north, and the x-y plane is the equatorial plane with the x-z plane containing the Greenwich meridian at platform release time. The time is referenced to liftoff, 3.260 seconds after platform release. Trajectory parameters such as velocity magnitude, altitude, flight path angle, heading, latitude and longitude are also printed.



Figure 2-1. Sensed Velocity Comparison in Computer Coordinates





Figure 2-2. Total Inertial Position Comparison in Computer Coordinates



Figure 2-3. Total Inertial Velocity Comparison in Computer Coordinates





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Figure 2-5. Navigation Velocity Error







Figure 2-7. Gyro Spin Axis Unbalance Drift History

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MUSRA Y (YGSAU) d.

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-0.4

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III E



Figure 2-9. Sensed Velocity Comparison in Computer Coordinates with IGS Error Fit





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Figure 2-10. IGS/Mod III Comparisons (RAE)





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3. REENTRY IGS PERFORMANCE EVALUATION AND TRAJECTORY RECONSTRUCTION

3.1 INTRODUCTION AND SUMMARY

This section presents an evaluation of the IGS performance during the reentry flight phase. The evaluation was accomplished by comparing telemetered IGS quantities with external tracking data and with nominal terminal phase conditions, and estimating the most likely error sources from the residual trends.

The following C-band radar and telemetry were available for the analysis:

Data Source	Interval (sec from retrofire)
19:18, Merritt Isl.	1550 to 1747
0:18, Patrick AFB	1550 to 1750
3:18, Grand Bahama Isl.	1558 to 1757
7:18, Grand Turk Isl.	1721 to 1815
PCM Telemetry	0 to 2062

Table 3-1 provides various estimates of the spacecraft location at the times of significant events during the latter part of reentry. This same information is graphically displayed in Figure 3-1 along with the ground trace of the spacecraft as given by a TRW reconstruction of the spacecraft trajectory, uncorrected IGS data, and the last part of Grand Turk radar tracking. Table 3-2 summarizes the TRW estimate of guidance and control error on this flight. It is noted that very little of the indicated downrange miss can be attributed to IGS measurement error. The crossrange miss may be partially explained by the indicated IGS error. If the IGS is in error to the south, it would be expected that the spacecraft would be steered to the north of the intended target.

3.2 REENTRY ERROR SOURCES

Table 3-3 presents a summary of recovered error sources which provide an explanation for the apparent IGS error at guidance termination. To extract error sources from the available data the telemetered IGS trajectory was reconstructed using the RTCC retrofire position/velocity



Source of Data	Altitude (1000 ft)	Latitude (deg N)	Longitude (deg W)	Difference from target (n mi)					
				North	East				
Guidance	Terminat	ion (t* =	1815)						
IGS (uncorrected)	56	26.682	71.992	-2.0	0.43				
TRW BET	76	26.764	71.986	2.9	0.75				
Drogue Deployment (t* = 1870)									
TRW BET	37	26.768	71.902	3.2	5.2				
IGS**	2	26.633	71.915	-4.9	4.6				
Main Chute Deployment (t* = 1951)									
TRW BET	7	26.764	71.894	2.9	5.7				
IGS**	- 50	26.558	71.940	-9.4	2.3				
Splashdown									
Target	0	• 26,715	72.00	0	0				
Ship measurement	0	26.745	71.95	1.8	2.7				
TRW BET (final telemetry point, t* = 2062)	2	26.756	71.888	2.5	6.0				
IGS (final telemetry point)**	-90	26.456	71.991	-16.0	0.5				

Table 3	3-1.	Gemini	10	Reentry	Tra	jectory	y Summary	
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* **Time from retrofire in seconds. Differences between the IGS and true trajectories at times after "guidance termination"do not affect trajectory accuracy, but are use-ful for identification of error sources.

Direction of error*	Value of IGS error at guidance ter- mination (76,000 ft) (n mi)	Spacecraft miss distance from intended target at impact (n mi)
Downrange	0 ± 0, 3	5.1 ± 0.5 (long)
Crossrange	-4.9 ± 0.3 (south)	2.9 ± 0.5 (north)
Vertical	-3.3 ± 0.3 (low)	

*Downrange/crossrange error estimates are based on an approach azimuth of 94° from North.

Table	3-3. Effecti	s of Error at Guic	lance Termi	nation (7	5,000 Feet)	in IGS Coc	ordinates	
Error source	Unit	Coefficient	X (ft)	Y (ft)	Z (ft)	(ft∕sec)	Ý (ft∕sec)	Ż (ft/sec)
X accelerome- ter bias	81	6.23 ± 10	317			0.2		
Y accelerome- ter bias	84	43.58 ± 10			-2,221			-1.7
Z accelerome- ter bias	7 29	46.69 ± 10		2,469			2.7	
Platform roll alignment	arc sec	-2 , 337 ± 150		56	-21,683		-1.0	-226.5
Platform pitch alignment	arc sec	-2,000 ± 300	-18,556	-5,902		- 199	-117	
Platform yaw alignment	arc sec	-1,565 ± 150	-37		-4,618	0.7		-91.7
Y gyro input axis unbalance	°/hr/g	-0.7 15 ± 0.4	- 1, 422	- 855		-21.5	-14.9	
Timing scale factor	bpm	-86 ± 65	-1,832	2,952	- 14	-9.4	6.6	0.2
X accelerome- ter scale factor	mqq	-46 ± 113	33			-0.64		
Z accelerome- ter scale factor	uudd	-451 ± 64		876			9.2	
Initial condi- tions	ft, ft/sec	(See table 3-4)	-280	1,200	290	-0.9	-0.8	1.3
Unexplained position	ft		1,500	2,000	2,000			
		Total	-20,300	2,800	26,200	-230.0	-115.0	-318.0

(state) vector, the telemetered time from retrofire, and properly scaled and biased accelerometer count data. The reconstructed IGS trajectory was then compared to the radar-determined trajectory (see Figure 3-2). A visual analysis was made in which probable error sources were combined to provide an explanation for the observed IGS/radar residuals.

In addition to providing an explanation (or fit) of the IGS radar residuals, the recovered error sources were constrained to provide explanations for differences between the IGS and nominal estimates of spacecraft main chute deployment altitude, descent rate, and available wind velocity data. The altitude rate was fit to approximately 30 feet per second during main chute descent. However, analysis showed that the drogue chute altitude could not be fit to an assumed 50,000-foot nominal value. After removal of the drogue altitude constraint, the analysis showed an estimate for the actual drogue chute deployment to be 37,000 feet (which was later substantiated by NASA's determination of a 38,000-foot drogue altitude).

The following sections provide discussions of the recovered reentry error sources listed in Table 3-3.

3.2.1 Initial Conditions

Reentry initial conditions input into the IGS were computed by the real time computer complex (RTCC), using the Carnarvon, Revolution 42 update, approximately one orbit prior to retrofire. The RTCC initial position/velocity vector is presented in Table 3-4 and compared with TRW estimates of the retrofire position/velocity vector. The TRW vector was derived from the postflight orbit reconstruction program (ESPOD) by fitting pre-retrofire and post-retrofire free flight tracking data while including a solution for the retrofire maneuver.

The agreement between the RTCC and TRW (ESPOD) vectors is well within 1000 feet and 1 foot/second, and is considerably smaller than has been noted on previous flights.

It is interesting to investigate the ESPOD solution for the retrofire maneuver. Table 3-5 gives the indicated IGS retrofire maneuver and small additional impulse apparently resulting from the retrosection





Table 3-4. Gemini 10 Reentry Retrofire Vector Summary (21 July 20^h30^m51.0^s GMT)

[Coordinates are those used in the MSC RTCC - ECI, X through Greenwich at 0 hours day of launch (18 July).]

Vector	IGS (RTCC)	TRW (ESPOD)	RTCC - TRW
X (ft)	-13,815,300	- 13, 814, 853	- 447
Y (ft)	17,301,300	17,302,284	-984
Z (ft)	-746,400	-747,096	+696
X (ft/sec)	-17,381.1	-17,380.9	-0.2
Ý (ft/sec)	-13,556.7	-13,555.9	-0.8
Ż (ft/sec)	12,137.7	12,137.7	0

Table 3-5. Retrofire Maneuver Summary

Impulse source	∆x (ft/sec)	∆ý (ft/sec)	∆ż (ft/sec)
IGS indicated retrofire	-303.0	118.7	-5.0
Retro jettison	-0.3	0.3	0
Total indicated impulse	-303.3	119.0	-5.0
IGS misalignment error	1.1	2.9	3.6
Corrected retrofire impulse	-304.4	116.1	-8.6
ESPOD (free flight reconstruction)	-304.5	117.4	-9.7

jettison (retrofire plus 55 seconds) as obtained from telemetered IGS data (see sensed velocity plots Figure 3-4). Subtracted from the indicated maneuver is the net error in the IGS measurement resulting from the estimated platform misalignment. The ESPOD reconstruction value can then be compared with this adjusted IGS value. The agreement is very good and within the uncertainty generally associated with the trajectory reconstruction. The IGS platform misalignment errors were deduced from atmospheric IGS/tracking comparisons and terminal position/velocity criteria as described in paragraph 3.2.2. Large changes





would be required in the IGS misalignment error estimates during atmospheric reentry to significantly change the indicated IGS retrofire measurement error shown in Table 3-5. This comparison, therefore, supports the validity of the ESPOD maneuver solution.

3.2.2 Alignment Errors

The primary assumption in attempting to extract IGS error sources during reentry was that platform alignment errors were most likely the dominant sources. Using this guideline, a set of alignment errors were determined which removed the error trend indicated in the IGS/tracker position comparisons of Figure 3-2. (Analysis could not be conducted in the velocity domain because of the very high noise on the differentiated radar position measurements.) Some tradeoff with gyro-drift type errors was required to satisfy both the radar tracking data and expected terminal phase conditions.

The platform alignment error coefficients recovered are consistent with those recovered on previous flights and provide an explanation for the major portion of the IGS trajectory error. This is evident in Table 3-3 which shows that the contributions of the misalignment errors are within 17 and 20 percent of total IGS trajectory x and z position errors respectively. The y axis contribution, although also large, had an approximate magnitude equal to the combination of all other contributors, but was in the opposite direction such that the total y error was quite small.

3.2.3 IGS Error Sources

The accelerometer bias errors listed in Table 3-3 were obtained from post retrofire IGS accelerometer output during free-flight. The X and Z accelerometer and timing scale factor errors were recovered during the ascent IGS analysis, as described in Section 2. These were included in the corrections to the IGS indicated reentry trajectory; however, the accelerometer scale factor errors do not contribute significantly to the fit.

The pitch gyro drift error was recovered after initial attempts to explain IGS/tracker differences with only platform alignment errors successfully nulled the IGS/radar differences, but a trajectory was produced which went down to a 20,000-foot altitude and then began

climbing again. A more satisfactory trajectory resulted when the Y gyro input axis unbalance term (YGIAU) was substituted for part of the misalignment error used in the original fit. The position error propagations during reentry of a Y gyro input axis unbalance error (YGIAU) and a pitch misalignment (PHIY) are shown in Figure 3-5. It is noted that though their propagation is similar during the interval of radar tracking (1550 to 1820 seconds), the gyro drift error grows much faster than the misalignment error during the terminal phase of flight (1870 seconds and

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The difference is undoubtedly due to a combination of error sources which were not identified in the analysis. Among these are:

- a) Small error in the assumed (ESPOD) initial conditions. This source is particularly sensitive since it propagates for 1500 seconds before being "observed" in the reentry radar comparison data.
- b) Incorrect selection of IGS error sources which, though they explain the very large error trends (over 25,000 feet and 200 feet/second), do not generate a completely consistent trajectory from retrofire to splashdown.
- c) Inadequate error modeling to account for the error in the calculation of gravity resulting from the IGS errors.
- d) Undiscovered systematic biases in the radar measurements.

Since the main goal of the analysis was to generate the most accurate trajectory reconstruction possible during atmospheric reentry, the apparent position bias was removed in the trajectory published here by arbitrarily altering ESPOD initial conditions as indicated below (ESPOD-BET).

 $\Delta x = 705 \text{ ft}$ $\Delta y = 600 \text{ ft}$ $\Delta z = 2104 \text{ ft}$ $\Delta \dot{x} = -0.8 \text{ ft/sec}$ $\Delta \dot{y} = 0.2 \text{ ft/sec}$ $\Delta \dot{z} = 3.7 \text{ ft/sec}$

3.3 REENTRY SIMULATION

A six-degree of freedom simulation of the Gemini 10 reentry was conducted by McDonnell Aircraft. The simulation was initialized with the RTCC retrofire position/velocity vector which initialized the IGS, assumed preflight aerodynamic characteristics, and the best postflight estimate of the spacecraft center of gravity. Comparisons of the simulation results with the TRW BET (Figure 3-6) show residuals of -6300, 9083, and -9446 in the IGS x, y, and z axes, respectively, at 1400 seconds. Similar differences were noted between the simulation and a reconstruction of the post retrofire free-flight interval prior to atmospheric reentry derived from the orbit reconstruction program (ESPOD).

The available data were not sufficient for determination of the apparent simulation error which caused a large residual even before atmospheric reentry. However, the error could not have been due only to the initial vector, since the ESPOD and RTCC vectors were relatively close (see Table 3-4), but may be associated with the incorporation of the incorrect retrofire maneuver in the simulation.

During atmospheric reentry the error became an order of magnitude worse, since the computations probably used erroneous drag acceleration derived from simulation computed spacecraft altitude. The (simulation-BET) residuals steadily increased from the values at 1400 seconds to approximately 119,000, -222,000 and 29,000 feet in x, y and z at the last telemetry data point (t = 2062).

No comparison was made between the TRW reconstruction and the reentry trajectory presented in the MSC Final Report (Reference 6).

- 3.4 CONCLUSIONS
 - a) The IGS computed trajectory was approximately 3.9 n. mi. south and 0.36 n. mi. west of the actual trajectory at guidance termination. The actual trajectory was approximately 2.5 n. mi. north and 6.0 n. mi. east of the intended target at splashdown.
 - b) Approximately 80 percent of the apparent IGS error is attributable to platform alignment error of approximately 0.6 degree at retrofire.
 - c) MSC real-time (RTCC) and TRW postflight (ESPOD) estimates of the retrofire position/velocity vector were within expected tolerances. However, the final TRW BET indicates the possibility of cross-range (z) differences of approximately 3000 feet and 3.7 feet per second.
 - d) Large differences exist between a McDonnell simulated reentry trajectory and both the TRW reconstructions during the post-retrofire free-flight interval and the atmospheric reentry BET. The major source of the difference is in the simulation.

3.5 REENTRY TRAJECTORY RECONSTRUCTION

The reentry trajectory reconstruction consists of the IGS data corrected for initial conditions, initial platform misalignment, and IMU error sources as presented in Table 3-3. A listing of the BET is provided in Appendix B.



The data are provided in an earth-centered inertial coordinate system. The z axis is aligned with the earth's rotational axis, positive north, and the x-y plane is the equatorial plane with the x-z plane containing the Greenwich meridian at retrofire time. Trajectory parameters such as velocity magnitude, altitude, flight path angle, heading, latitude and longitude are also printed. Time is referenced to retrofire.

Figure 3-7 is a plot of reentry relative velocity, flight path angle, and altitude versus time from retrofire. The uncorrected sensed acceleration and velocity are plotted in Figure 3-8.



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Figure 3-3. Corrected IGS - Radars in IGS Coordinates







Figure 3-4. Post Retro IGS Indicated Sensed Velocity





Figure 3-5. Reentry Error Functions







Figure 3-6. TRW BET - McDonnell Simulation Differences (IGS Coordinates)







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Figure 3-8. IGS Measured Sensed Velocities and Accelerations



4. TRACKING SYSTEM PERFORMANCE

This section provides an evaluation of the ascent phase tracking data which included the following:

- a) GE MOD III Burroughs (TRW reduction)
- b) GE MOD III Burroughs (GE reduction)
- c) MISTRAM I quick-look 10K and 100K
- d) AFETR MISTRAM only BET (Glad reduction)
- e) Air Force Eastern Test Range (AFETR) BET

Each of the above sets was used for position and velocity comparisons as described in Section 2. The TRW reduced GE MOD III Burroughs data were used for quick-look analysis, and the MISTRAM I and GE reduced MOD III Burroughs data were used for detailed analysis. The two AFETR BET's were also used to help substantiate the analysis.

Tracker error sources recovered from the ensemble IMU/tracking system analysis discussed in Section 2 are presented in Table 4-1. MISTRAM bias errors recovered from the AFETR BET programs are also presented for comparison purposes. The table shows that MISTRAM and GE errors were small on this flight and that there is good agreement among the error sources obtained from the separate analyses.

Figures 4-1 through 4-6 are comparisons of tracking data with inertial guidance data which had been corrected for IGS error sources derived from the IGS analysis (see Section 2). These are provided to give a clear indication of tracking data quality.

4.1 GE MOD III

4. 1. 1 GE MOD III Burroughs (TRW Reduction)

The GE/MOD III data, which consisted of raw counts recorded at a 2-per-second rate on punched paper tape, were transferred to magnetic tape at TRW and processed in the data reduction programs.

Figures 4-1 and 4-2 show comparisons of this data with compensated IGS data in IGS coordinates. The comparisons indicate that there

Coefficients	
Error	
Tracking	
Recovered	
Table 4-1.	

3ET	lo rtainty	6	006	8	55	76							
inal I	unce	1.51	0. 0(0. 0(0.0	0.0							
AFETR F	Estimated bias	2.82	-0.14	-0.08	-0.57	-0.45		N/N	N/U	N/N	*	*	
AISTRAM – BET	lσ uncertainty	1.85	0. 0075	0.011	0.077	0.10							
AFETR N Only	Estimated bias	-11.0	- 0.16	- 0.098	- 0.75	- 0. 62		N/U	N/U	N/N	*	*	
alysis	lσ uncertainty	1.0	0. 02	0.17	0.10	_	2. 0	3.8	0.016	0.011	2. 22	0. 00022	
TRW an	Estimated bias	- 5.0	- 0.12	- 0.19	- 0.50	* *	- 0.48	-23	- 0.0027	+ 0.044	- 4, 44	- 0. 00061	
	Units	ft	ft	ft	ft	ft	n-unit	ft	mrad	mrad	n-unit	sec	
	System error	R SUM	P 10K	Q 10K	P 100K	Q 100K	Refraction	Я	A	ы	Refraction	Timing	

*Not included in error model

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Note: AFETR bias estimates were obtained from References 4 and 5.

**Could not be reliably extracted

N/U-GE MOD III position data not included in AFETR BET

is negligible tracking data position bias error, and the random and low frequency noise amplitude is large late in flight.

4. 1. 2 GE MOD III Burroughs (GE Processed)

The General Electric Company processes essentially the same 2-per-second MOD III Burroughs data; however more filtering and a refraction correction incorporating actual atmospheric conditions are applied. The GE processed data were available smoothed in both tracker natural measurement coordinates (R, A, E, R, P, Q) and in ECI cartesian coordinates. The natural measurement coordinate data were used in the computer regression analysis and for plots included in this report.

Figures 4-1 and 4-2 also show the GE processed MOD III/compensated IGS differences. Comparisons with the TRW reduced MOD III clearly show the noise reduction resulting from the increased filtering incorporated in the GE data reduction. However, there are residual trends in the comparisons. The residuals of the GE processed data are for the most part attributed to errors in the tracking data which are partially explained by the GE MOD III errors presented in Table 4-1. From the error sources recovered, only the 4.4 n. unit refraction error contributes significantly to the observed IGS/tracker differences (0.08, +4.8 and +0.02 ft/sec in \pm , \pm , \pm respectively). The TRW processed data also show a refraction type error, but of opposite sign to the GE processed data.

4.2 MISTRAM

The MISTRAM I data received at TRW were fully scaled and corrected but unsmoothed Range Sum, P, and Q measurements. The data were processed in the usual manner to obtain IGS/MISTRAM I position and velocity comparisons.

Figures 4-3 and 4-4 show the MISTRAM I 10K and 100K/compensated IGS comparisons. The MISTRAM I 10K/IGS comparisons show no significant trends; however the MISTRAM 100K/IGS comparisons show trends resulting in approximately 0, +6. 5, and +1 ft/sec \dot{x} , \dot{y} and \dot{z} errors respectively at SECO +20 seconds (t = 360). The TRW recovered MISTRAM I error sources presented in Table 4-1 contribute to the



explanation of these apparent velocity errors. The 6.5 ft/sec \dot{y} residual is attributable to the -0.5 ft P_{100K} bias error which was the most significant error on this flight, but was much less than those observed on previous Gemini flights.

4.3 AFETR BEST ESTIMATE OF TRAJECTORY

The MISTRAM-only BET is computed by means of the AFETR GLAD program using MISTRAM I (10K and 100K) and MISTRAM II measurements. The solution is obtained from a least-squares adjustment of measurement biases and trajectory values. No refraction errors are solved.

The AFETR Final BET is a weighted least squares adjustment of measurements obtained from MISTRAM I and II, GE MOD III (\dot{P} , \dot{Q} , \dot{R}), and available FPQ-6 radar data.

Figures 4-5 through 4-6 show the AFETR MISTRAM only and Final BET's compared with compensated IGS data which is in fact the TRW BET (see Section 2). The comparisons show only small differences between the respective AFETR BETS. This is consistent with the essentially equivalent recovered MISTRAM error sources listed in Table 4-1. The AFETR MISTRAM-only and final BET's generally have agreed on Gemini flights. This is most likely because of relatively heavy weighting of MISTRAM I data in both BET solutions.

4.4 CONCLUSIONS

The tracking system performance was satisfactory, and MISTRAM I bias errors were small relative to previous flights. The GE MOD III data was of expected quality; however, there was an apparent 4 n. unit refraction error in the GE processed MOD III data.





Figure 4-1. Sensed Position Comparison in Computer Coordinates (GE/Compensated IGS)





Figure 4-2. Sensed Velocity Comparison in Computer Coordinates (Mod III/Compensated IGS)





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Figure 4-3. Sensed Position Comparison in Computer Coordinates (MISTRAM/Compensated IGS)





Figure 4-4. Sensed Velocity Comparison in Computer Coordinates (MISTRAM/Compensated IGS)







Figure 4-5. Sensed Position Comparison in Computer Coordinates Coordinates (BET and MF/Compensated IGS)







Figure 4-6. Sensed Velocity Comparison in Computer Coordinates (BET and MF/Compensated IGS)



5. RENDEZVOUS RADAR EVALUATION

5.1 INTRODUCTION

This section presents the results of the analysis of the Gemini 10 rendezvous radar. The radar evaluation was made by comparing the telemetered onboard radar measurements (range, azimuth, elevation) to values obtained by reconstructing the relative trajectories of the Gemini 10 spacecraft and the Agena 10 target vehicle (ATV). The comparisons were made over the interval of time from radar acquisition through the terminal phase maneuvers preceding the first rendezvous. Refer to Figure 5-1 for help in interpreting the directional sense of the radar angular measurements and the IGS platform gimbal angles. It should be remembered that the radar is hard-mounted to the Gemini spacecraft. Details of the orbit reconstruction of both the Agena and Gemini BET can be found in the TRW Gemini 10 Orbit Report (Reference 3).

5.2 TELEMETRY DATA

The telemetered radar parameters are plotted in Figures 5-2, 5-3, and 5-4. A cursory explanation of the data follows. Before 220 minutes GET, the spacecraft appears to be drifting within $\pm 10^{\circ}$ of the local horizontal. After this time but prior to platform alignment (238 minutes GET), the angular radar measurements were relatively constant at -7° in elevation and $\pm 1^{\circ}$ in azimuth; the relative range was between 120 and 100 n mi for this latter period. During alignment (238 to 253 minutes GET), the spacecraft must be held in the local horizontal; thus the elevation angle is offset by the angle between the Agena and the local horizontal and has a trend equal to the relative line-of-sight rate of the Agena. The azimuth measurements during alignment show a sinusoidal trend between plus and minus 3 degrees.

From the end of alignment to terminal phase finalization (TPF), the Agena was maintained near the spacecraft's boresight; i.e., the azimuth and elevation angles were near zero, as they should be for optimal radar accuracy.



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5.3 TRAJECTORY RECONSTRUCTION

5.3.1 Agena 10 Trajectory

The Agena 10 trajectory was reconstructed using the TRW orbit determination program (ESPOD) to fit all ground tracking data from Agena insertion to rendezvous. Since there were no Agena maneuvers, the reconstructed trajectory was estimated to be accurate to within 1000 feet.

5.3.2 Gemini 10 Trajectory Reconstruction

For the Gemini 10 spacecraft, two trajectories were generated.

a) Gemini BET. This trajectory was made by fitting all ground tracking data over the interval of time from just after GT-10 insertion to TPF. IGS telemetric data were used to reconstruct the coelliptical (NSR) and the terminal phase maneuvers.

Prior to the end of platform alignment there was heavy ground radar coverage of the spacecraft. After platform alignment, there was very little ground tracking data - HAW 03 (E_{MAX} = 15.6°) and CAL 03 (E_{MAX} = 5.4°) - occurring just prior to and immediately following TPI, respectively. Coupled with the fact that there were four maneuvers to be reconstructed, the lack of ground radar coverage decreases the accuracy of the GEMINI trajectory reconstruction as the terminal phase progresses. The following are estimates of the accuracy of the BET:

Prior to the end of alignment	1000 feet
Prior to TPI	1500 feet
After TPF	3000 feet

b) <u>HAW 03 short arc fit</u>. The ESPOD program was used to make a single station curve fit on the HAW 03 radar data which were collected just prior to TPI. This fit was made to check the accuracy of the BET during the interval of time that the spacecraft passed over Hawaii. The short arc fit agreed with the BET to within 1500 feet and this discrepancy was most likely caused by an apparent -0. 03 degree elevation bias in this station.

5.4 ANALYSIS OF RENDEZVOUS RADAR OUTPUT

The Tracking Radar Analysis Program (TRAP) was used to compare the onboard radar data with the TRW calculated trajectories. The





comparison was made in radar coordinates using telemetered gimbal angles to transform from IGS to body coordinates. The results are plotted in Figures 5-5, 5-6, and 5-7. Also annotated on these plots are the maneuver initiation times, the period of platform alignment, and the relative range of the Agena with respect to the spacecraft. The analysis was divided into four segments:

- Prior to platform alignment
- During alignment
- End of alignment to TPI
- TPI through TPF.

Table 5-1 gives the average residual magnitudes in range, azimuth, elevation, and total position, as well as an estimate of the uncertainty of the TRW relative trajectory for each of the above time intervals.

Prior to the platform alignment, it was estimated that the TRW reconstructed relative trajectory was accurate to approximately 1500 feet.

The elevation angle residuals (Figure 5-7) show a relatively constant offset of 2.5 degrees from 208 to 219 minutes GET, and then a shift to a much smaller difference of approximately 0.3 degree, which is then maintained nearly constant until alignment. During approximately the same period the azimuth residual (Figure 5-6) grows from a small value to a peak at 3 degrees and back to 0.5 degree, which is then nearly the same until alignment. Since the relative range was greater than 100 miles, these radar angle excursions represent total position differences of greater than 4 n.mi. Therefore, the error is clearly in the radar/ platform measurements. An error of this shape is difficult to imagine in the platform alignment and, therefore, it was concluded to be a radar angle error. As seen in Figure 5-4, the target vehicle was considerably off the spacecraft's boresight, and it may be partially due to this fact that the radar angular measurements were relatively inaccurate.
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During the period of platform alignment, the azimuth residuals show the same ±3 degree variations as noted in the total azimuth measurement (see Figures 5-3 and 5-6). These relatively abrupt changes must be due to onboard measurement error, since any bias error in the TRWcalculated azimuth is smooth. [MSC analyses of the horizon scanner/platform servo loop outputs indicate that the platform was momentarily torqued out of alignment. Approximately 80 percent of the misalignment was due to a spacecraft roll error which resulted in the platform misalignment. MSC also noted that some period of valid alignment mode remained even after the perturbation. This being the case, it would be expected that the major alignment error would be in the yaw direction. This error must be corrected by relatively slow gyrocompassing. The horizontal (pitch and roll) error would be more rapidly corrected by the horizon scanner.]

In any case, between the end of platform alignment and TPI, the azimuth residuals average -1.8° and the elevation residuals -0.5° , representing a total position residual of greater than 2 miles. The TRW calculated trajectory is, with good probability, accurate to within 2000 feet. It is therefore most likely that there was an error in either the platform alignment or the radar, or both. Since there is no evidence of this size radar azimuth bias prior to alignment and the error is closely correlated with alignment, it appears that a platform misalignment of $-1.9 \pm 0.5^{\circ}$ in the yaw direction (platform oriented left of the true down-range direction) was the cause of the large total position error. Similarly, the estimated post alignment error in the pitch (elevation) alignment, Figure 5-7, is $-0.6 \pm 0.5^{\circ}$ (the platform is pitched down from true horizontal).

Assuming the platform was misaligned in yaw, the error will appear in azimuth in the comparison, but decreasing in magnitude as the initial yaw direction is transformed to roll due to the orbit rate. If an initial yaw misalignment were the only error in the compared quantities, the azimuth error (Figure 5-6) should change as $\cos (\omega \Delta t)$, $\omega \Delta t$ being the angular travel of the spacecraft after "alignment." The curve, $\Delta A = 1.9^{\circ}$ $\cos (\omega \Delta t)$, is shown in Figure 5-6. There is some indication that the observed error curve is decreasing as postulated before TPI. There is





no agreement with the curve after TPI, which could be due to one or a combination of the following causes:

- a) The unknown initial roll misalignment is coupling into the azimuth comparison as initial roll becomes yaw with orbital travel
- b) The onboard radar has an azimuth bias error (though this is not completely consistent with the prealignment ΔA which shows a "bias" in the opposite direction)
- c) The trajectory reconstruction error is distorting the comparison.

The last cause is very likely, since the relative range at 280 minutes GET has decreased to 150,000 feet and the assumed trajectory uncertainty of 3,000 feet during this period represents a 1 degree angle uncertainty.

The range comparison, Figure 5-5, shows a sinusoidal trend suggestive of a trajectory reconstruction error. However, it is noted that over the entire comparison range, from 150 miles to a few thousand feet, the difference is within 1,000 feet. This comparison adds considerable confidence both to the accuracy of the reconstruction and the radar range measurement.

5.5 CONCLUSIONS

- a) During the radar tracking interval preceding platform alignment (208 to 224 minutes GET) radar/platform angle error trends of up to 3 degrees were evident. The error was most likely in the radar measurement.
- b) During platform alignment, the azimuth angle residuals showed excursions of ±3 degrees, indicating possible problems in alignment. [MSC analysis indicated the platform was momentarily torqued out of alignment due to a spacecraft roll error.]
- c) After platform alignment, there is an indicated radar platform system misalignment: yaw/azimuth misalignment = $-1.9 \pm 0.5^{\circ}$, pitch/elevation misalignment = $0.6 \pm 0.5^{\circ}$.
- d) No radar range error is evident to within the accuracy of the trajectory reconstruction, 1000 to 3000 feet.

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Table 5-1. Average Magnitude of Residuals (Radar-Calculated)

Time	∆R (ft)	△A (deg)	∆E (deg)	△ Posi- tion (n. mi.)	Estimated Accuracy of Calculated Trajectory
Prior to alignment	497	0.8	1.3	4.0	0.25
During alignment	476	1.4	0.7	2.4	0.25
Alignment - TPI	277	1.8	0.6	2.3	0.33
TPI - TPF	721	0.7	0.4	0.2	0.50





Figure 5-1. Rendezvous Geometry



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Radar Telemetered Parameters (On Board Radar Range) Figure 5-2.





Figure 5-3. Radar Telemetered Parameters (On Board Azimuth)

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5-7. Figure !

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6. ANALYSIS OF SEXTANT SIGHTINGS ON GEMINI 10

6.1 INTRODUCTION

During the flight interval between $0^h 7^m 25^s$ and 2^h GET, the celestial altitudes of six stars were measured by the astronaut with a hand-held sextant. This section presents comparisons of these sextant sightings with calculated values derived from a TRW-reconstructed Gemini 10 trajectory. The TRW reconstruction (TRW BET) was obtained by fitting a best orbit in a minimum variance sense to the ground radar tracking data on the first two Gemini orbits. The estimated accuracy of this trajectory is ±1500 feet.

6.2 HORIZON BLAS

Table 6-1 shows results of six calibration measurements made on the star Schedar to establish the difference between the earth's hard crust horizon and a horizon determinable by visual means. Calculated altitudes using the TRW BET are shown for comparison. Onboard computations using this data resulted in a value of 27,500 yards for the horizon bias, and this value was used in the onboard computer to correct the other measured star altitudes. MSC postflight analysis of the bias computation indicated that 32,000 yards was a better estimate of the bias. The 4500-yard altitude difference results in a star angle bias of approximately 0.14 degrees in all onboard measurements. The TRW estimate of 31,500 yards was obtained by eliminating the first and last observation as wild points and averaging the four remaining differences.

6.3 SEXTANT MEASUREMENTS

The results of four-star altitude measurements made for trajectory updating are presented in Table 6-2 and compared with the TRW BET calculated values. The comparison was made assuming that a horizon bias of 32,000 yards was included in the measurement. Therefore, the last column in the table represents unexplained measurement error.

Ground elapsed time (sec)	Measured Schedar altitude (deg)	TRW BET calculated Schedar altitude (deg)	Difference (measured minus TRW) (deg)
1509.500	4.446	6.56	-2.11
1626.875	8.749	7.60	1,15
1685.875	9.087	8.16	0.93
1760.000	9.849	8.90	0.95
1822.625	10.399	9.51	0.89
189 2. 375	10.842	10.24	0.60
<u></u>	Onboard bias	27,500 yards	
	MSC bias	32,000 yards	
	TRW bias	31,500 yards	

Table 6-1. Horizon Bias

 Table 6-2.
 Star Altitude Measurement Comparison

	Ground	Star altitude (deg)					
Star	elapsed time (sec)	Measured	TRW BET calculated*	Difference (measured - TRW)			
Hamel	2424	32.67	32.63	0. 04			
Vega	2654.5	8.44	7.58	0.86			
Fomalhaut	6451.875	9.09	8.83	0.26			
Arcturus	7112.125	18.02	17.71	0.31			

* Bias = 32,000 yards

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6.4 ONBOARD COMPUTATIONS

These sextant sightings were used to update an onboard reference trajectory. This reference trajectory was propagated from the state vector stored in the IGS at insertion, which resulted from the IGS navigation throughout ascent. The error in this insertion vector was determined as part of the ascent IGS error analysis summarized in Table 2-8 of Section 2.

A comparison between the onboard reference trajectory and the TRW postflight reconstructed trajectory resulted in the following average differences in classical orbital elements.

Right ascension of ascending node	= 0.0225 degrees
Inclination	= 0.00308 degrees
Argument of perigee	= 3.6 degrees
Semimajor axis	= -280 feet
Eccentricity	= 0.0001
Period	= -0.0018 minutes

The relatively large error in the argument of perigee reflects the 13 feet per second IGS error in the vertical direction (\dot{y}) at insertion. This IGS ascent phase navigation error causes the onboard reference orbit to be rotated inplane from the true trajectory. The Cartesian coordinate differences, therefore, vary considerably as the calculated and true trajectory come into agreement periodically. The range of error over the period of interest is

 $\overrightarrow{\Delta P}$ = 5000 - 50,000 feet $\overrightarrow{\Delta V}$ = 19 - 50 feet per second

The residual between the observed, bias corrected altitude and the onboard calculated altitude is also a telemetry quantity. Table 6-3 shows this telemetry quantity along with the TRW simulation of the residual.

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	Altitud	e (deg)	Residuals (deg)			
	Measured	TRW- simulated IGS value*	Measured minus TRW simulated	Measured minus IGS (telemetered)	۵۵	
Hamel	32.67	32.69	- 0, 02	- 0. 02	0. 00	
Vega	8.44	7.54	0. 90	-	-	
Fomalhaut	9.09	9.04	0. 05	-0.15	-0.20	
Arcturus	18.02	17.67	0.35	0.35	0. 00	

Fable	6-3.	Star	Altitude	Residual	Comparison
--------------	------	------	----------	----------	------------

*Bias = 27,500

The "TRW-simulated IGS value" was derived by propagating the onboard, IGS initial state vector by means of the integration of the TRW orbit determination program ESPOD. This TRW/IGS trajectory was used to calculate the respective star altitudes and the results differenced with the telemetered star altitude measurements. For comparative purposes the altitude bias was assumed to be 27,500 yards for the TRW-simulated values. The TRW calculated residuals, therefore, are a simulation of the onboard computations, but using a different trajectory propagation model. The TRW simulation also used the oblate earth radius at the horizon point, where the onboard computations assume a constant earth radius in the calculation of the star altitudes. There are perhaps other minor differences in the simulation, but collectively the onboard calculations are expected to have an accuracy of better than 0.01 degree. The last column of Table 6-3 is a comparison of the TRW-simulation and onboard results and indicates internal consistency to better than 0.01 degree for Hamel and Arcturus. The large difference for Fomalhaut may indicate that an incorrect time was associated with this telemetered angle reading as the result of a data reduction error.

If it is assumed that the onboard computer computations are accurate, which is the case for Hamel and Arcturus, and that the residual difference for Fomalhaut reflects a systematic error in the



TRW-simulation due perhaps to a time mismatch, then the sign sense of the residual difference is such that the TRW-simulated altitude will read larger by 0.20 degrees. The TRW calculated altitude for Fomalhaut in Table 6-2 should then also be increased by 0.20 degree. This adjustment would reduce the unexplained error in the astronaut measurement of Fomalhaut to 0.06 degree.

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APPENDIX A

ASCENT TRAJECTORY

The ascent trajectory is provided in three separate forms: a) guidance coordinates as sensed by the accelerometers (these data are uncorrected for errors determined during flight); b) an earth-centered inertial coordinate set; and c) various special earth-referenced parameters. The latter two have been corrected for apparent IGS errors and therefore represent the TRW best estimate of the ascent trajectory.

The earth-centered inertial coordinate system has the z axis aligned with the earth's rotational axis, positive north, and the x-y plane is in the equatorial plane with the x-z plane containing the Greenwich meridian at <u>platform release</u> time (18 July $22^{h}20^{m}$ 26.648 GMT). Time is referenced to <u>liftoff</u>, which occurred 3.260 seconds after platform release.

Figure

Page

A-1 Sensed Acceleration in Computer Coordinates-Ascent ... A-2

Tables

A-1	Sensed Traject	ory for	the Ascent H	Flight Phase	• • • •	A-3
A-2	Reconstructed	Ascent	Trajectory,	ECI Coordinates	••••	A-5
A-3a,b	Reconstructed	Ascent	Trajectory,	Special Paramete	ers	A-7







Table A-1. Sensed Trajectory for the Ascent Flight Phase

GOMINE CLIT PROGRAM

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COMPUTED PUSITION VEROCITY AND ACCOUNTING IN GUIDANCE THREST COUNTINATES

11#C (SECS)	¥ (FT)	, Y (F1)	2 (FT)	XEOT (FT/SSC)	¥95* (57/5-61	7001 (E1/5FC)	XOGUT LETZS: C#21	YDDCT (FT/SECAL)	2000T
.484	-	-727	-	Cć	-126.75	10	.02	-41.56	10
3.120		-106	-1	-06	-335.00	41	01	-42.12	18
7.831	-	-2288	-5	12		-1-59	00	-42.24	23
5.947	-1	-3307	- 5	.03	-527.05	-2.29	• 0 ?	-43.17	30
12-567	-	-462+	-16	-06	-840.60	-3.15	-03	-43.70	29
17.307	-	-2367	- 34	.11	-650.03	-4.34	02	-44.72	30
19.524	-	-10745	-47	24	-961.72	-5.3-	03	-45.35	33
24.56		-14502		60	-1064-56	-6.00	. 22	-45.51	39
26.550		-16211		2.41	-1?"	-0.11	2.08	-47.11	53
25.245	16	-21776	-11.	10.16	-1412.31	-5.63	3.17	-47.70	63
33.930	114	-1106	-142	24.27	-1029.00	-11.34	5.55	-49.44	75
36.565	235	-333e7	-204	15.70	-1755.35	-15.52	8.72	-45.47	-1.11
32.511	96) AC6	-17631	-234	14.77	-1653.55	-18.08	10.13	-49.67	-1.24
43.922	425	*18	-312	136.15	-21	-25.25	13.55	-50.41	-1.31
45.951	1237	-52041	-407	169.95	-7231.32	-27.73	15.42	-51.35	-1.09
50.632	2203	-stitt -sitt2	-464	212.17	-2356.67	-30.20	17.32	-51.65	97
53.290	2 30	-65113	-635	301.29	-2513.76	-34.57	20.73	-52.65	-1.07
55.543	2.12	-124 IC	-737	258.57	-2752.67	-37.56	22.76	-52.41	-1.16
60.626	57 33		19	473.69	-3002.15	-43.20	25.0	-53.05	-1.27
62.653	6765	-54602	-1010	\$27.35	-3113.44	-46.62	27.40	-53.20	-1.74
65.311		-105060	-1143	601.68	-3252.61	-52.63	25.45	-53.29	-1.98
65.550	11-23	-120563	-1404	150.53	-3501.01	-57.53	34.56	-53.04	-1.78
72.644	13543	-1-2052	-1575	646.47	-3540.3"	-64.72	37.71	-52.52	29
74.674	17547	-137828	-1708	525.55	-3746.74	-62.41	35.13	-52.47	01
	•••••	141.10	•••••	1010.10		-80.00	42.00	-72.02	JV
19.5EE	26846	-138471	-2035	1152.30	-4328.15	-03.74	43.02	-52.58	-1.74
82.015	2:272	-166758	-2169	1245.19	-4134.02	-69.76	46.56	-53.23	-2.49
86.696	25635	-126457	-2527	1476.22	-4394.07	-82.05	52.24	-53.31	-2.49
69.357	32755	-196547	-2756	1615.58	525.31		55.20	-53.32	-2.06
94.042	41973	-220332	-2737	1734+35	-4233.80		61.65	-53-41	-2.02
96.696	47212	-212203	- 34 5 8	2056.67	-4712.20	-102.65	e3.74	-53.67	-2.48
\$8.725	51516	-243254	- 3674	216e-23	-5027.59	-109.29	06.16	-53.67	-2.71
103.446	62607	-2:7625	-4220	2514.59	-5250.44	-122.37	72.15	-53.44	-3.18
106-124	65664	-23155e	-4501	2712.63	-5+23.1+	-131.69	15.67	-53.28	-3.51
102.201	75463	-2:33356	-4942	2612.00	-1534.13	-130.45	75.50	-52.67	-3.63
113.515	91668	-323486	-5637	1210.08	-5612.70	-155.16	86.48	-51.64	-3.81
115.545	587C -	-335354	- 5768	3468.68	-5916-93	-157.13	65.66	-50.99	-3.84
120.232	1150298	-351290	-5428	3576.17	-5051.55	-177.05	- 1+17 56.86	-50.48	-3.93
122.528	127013	-396451	-7309	4152.07	-5268.44	-176.17	100.70	-51.26	-4.42
125.584	1 38 5 1 0	-397937	-7645	4565.01	-6426.54	-208.57	104.51	-52.44	~4.90
127.cle	160622	-4105GE	-363	4971.46		-233.72	112.20	-54.17	-5.35
132.305	176554	-44 7 3 5	- 4365	5202.63	-31-1.5	-244.62	115.45	-54.7t	-5.42
134.564	165205	-455580	-100*9	5517.82	-6934.71	-258.61	121.15	-55.54	-5.62
139.654	212446	-4-3115	-11316	6106.09	-1148.47	-286.53	121.29	-57.11	-5.04
142.348	220366	-512715	-12110	£469.26	-7353.73	-303.05	137.71	-58.07	-6.22
144.377	242803	-527762	-12730	6754.28	-7472.30	-315.60	143.02	-52.86	-6.38
149.125	276604	-523586	-14313	465.60	-7755.70	-347.12	156.67	-60.73	-7.04
151.754	25762-3	-544825	+15262	7852.71	-75185	-366.41	104.56	-61.91	-7.47
152.362	361526	-539336	-15471	7586.63	-7555.67	-370.68	100.24	-62.15	-7.57
133.021			-10013						-2.07
156.466	3347e1	-622742	-17014	£134.34	-+012.80	- 378 .47	35.40	-14.74	-2.15
159.143	120225	-640750	-1:827	3325.76	-432.53	-389.09	41.12	-14.67	-2.28
163.670	315168	-691827	-1 26 6-9	8440.47	-9121.32	-395.15	41.97	-14.66	-2.35
166.335	417350	-732327	-20072	4547.13	-6158.15	-401-03	42.61	-14.75	-2.37
100.6892	452770	-7.1173 -7365 CA	-22537	1724.42	-2219-91	-410.71	43.07	-14.71	-2.26
173.123	475501	-757668	-23624	824C .77	-6259.54	-417.54	44.91	-12.65	-1-61
175.769	459447	-775508	-24733	8560.83	- 1255.02	-420.72	46.13	-12.01	67
180.324	54(775	-11426	-25652	\$176.66	-8335.76	-412.04	48.13	-R.48	.58
143.010	566131	-E4C33C	-2779A	\$367.55	-3302.29	-416.82	48.97		.66
184.919	562435	-6**F12	-24469	5401.10	-2357.55	-413.82	50.40	-7.18	.00
150.332	635057	-5012e7	-30608	\$673.51	-8416.25	-412.00	51.17	-6.66	.70
192.183	653044	-916853	-315es	\$765.31	-2422.43	-410.64	51.80	-6.40	.71
195.736	669065	-55314	-33432	103CF.37	-8455.36	-401.40	53.24	-5.20	.68
195.447	725404	-511241	-34534	10152.55	- 416. 9	-405.45	54.04	-5.35	. 66
202.152	753481	-1001515	-35645	10303.02	-9495.12	-403.84	54.56 55 K3	-4.55	. 66
204.041	301004	-1017209	-37478	10556.65	- 1506.53	-407.86	56.34	-4.42	4
209.455	624773	-10e32e3	-3:560	10710.40	- 5517.95	-364.56	57.27	-4.04	.64
211.304	34567e	-107-016	-3-257	10616.94	- 45 25 . 25	-397.84	51.55	-3.62	.62
214.014	875203	-1124274	-+1442	11132.77	-6544.25	-394.56	55.81	-3.03	.64
218.570	¢26819	-1141051	-+2171	11247.10		-343.30	5C.56	-2.52	.64
221.216	560934	-1164540	-41240	11414.01	-1557.37	-341.50	61.57	-2.00	50.
225.613	1013404	-12035/6	-45077	11555.41		-368.52	53.35	-2.04	.59
228.575	1045457	-127:15	-46077	11672.56	- 4573.20	-327.22	24 • 4 2	-1.61	.57
230.428	100300	-1242610	-46757	12171.03	-6516.25	-384.63	66.47	-1.25	.54
		and see a					-		



Table A-1. Sensed Trajectory for the Ascent Flight Phase (Continued)

CEPTINE LETT FROGFAM TIME IN SECONDS FROM LEFTOFF

COMPUTED POSITION VELOCITY AND ACCLUERATION IN GUIDANCE THRUST COURDINATES

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11×C (SECS)	х (FT)	¥ (+1)	2 (FT)	¥E0T {FT/SLC}	YDCT (=T/3.C)	7007 (F1/510)	XUDOT (FT/S:C+2)	¥98CT (F1/S+C+2)	20667 (FT/S(C#2)
235.849	1122526	-1259122	-40876	12352.76	-6563.33	-393.23	A 60		.55
237.101	1156537	-1305025	-4-537	12476.83	-8564.93	-392.26	68.55	64	.56
240.415	1190455	-1326325	-56622	1266.48	-8556.17	-380.66	55.86	14	-60
243.183	1250165	-1352688	-51674	12161.04		-377.04	72.14	.40	.70
247.752	1266031	-1391656	-53413	1 165 15	- 3 7 - 3 4 4	-375.76	73.62	1.47	.78
245.660	1310911	-140"654	-54114	12333.67	-fi7e.42	-374.26	14.70	1.86	. P Z
252.401	1347631	~14211F2	-55137	13540.56	- 6572.43	-371.54	16.20	2.45	.69
255.133	1384 115	-1454557	-55140	1 17 50.68	-1564.52	-363.34	77.00	3.55	.92
255.740	144510c	-1494021		14115.23	-6545.13	-355.04	80.75		.95
261.647	14761:0	-1510204	-38535	14270.03	-6535.16	-363.07	22.02	4.90	.95
264.384	1515530	-152366-	-51526	14496.33	-6524.65	-360.53	-2.10	5.74	•96
267.118	1555484	-15%6551	-60508	14727.49	- 2507.77	- 357.54	25.31	6.48	.57
271.775	3474243	-1576668	-47147	14126.65	-6474,64	- 353.36	26.16	7.75	1.02
273.510	1652617	-lelleec	-029.04	15255.77	45.5.5	-351.30	0.01	8.26	1.03
276.325	1544842	-1624-52	-03752	15546.07	- 84 76 . 4	-343.64	12.02	8.42	1.05
279.043	1737100	-1658027	-04712	15302.27	-2411.46	-345.70	54.72	S.47	1.07
280.579	1766012	-1674052	-65333	15524.28	- 45 4.11	-343.51	50.11	10.04	1.09
285.573	1542659	-1712676	-66975	16435-67	-6361.37	-333.60	101.30	11.50	1.12
208.313	1559053	-17 35388	- 7 TEE 2	16720.25	-5310.00	-335.40	103.00	12.05	1.16
251.046	1524149	-1754652	-63775	17064.35	-4172.75	-352.30	10:.36	14.42	1.24
292.AL 4	1565337	-1773112	-61371	17264.45	-3246.30	-329.95	107.21	15.22	1.27
295.476	2010554	-175-552	-76234	17452-47	-3235.16	- 20.52	112.34	16.52	1.32
300.453	2103155	-1313873	-71914	13092-55		-717.61	116.58	17.63	1.42
302.503	2136714	-1851578	-72495	13311.34	- 307 1 - 52	-31e.65	121.13	10.et	1.43
305.111	2154453	-1:72771	-7531c	19632.06	-9024.00	-312.54	125.74	20.44	1.47
307.715	2233433	-1197556	-74126	15564.55	-7:22.15	-309.23	133.01	22.74	1.50
310.319	22.3257	+191426E	-74926	19307.49	-1538.75	- 305.24	133.55	23.80	1.58
512.102	2517.01	-1928338	-/3466	1954. •32	-1003014	-302.50	12.07	4	1.04
314.709	2369345	-1045752	-76251	15912.20	-77, 45	-247.13	142.35	27.62	1.81
317.314	2421697	-1969462	-7702C	20250.41	-77216	-253.00	147.13	25.51	1.93
315.917	2+75030	-10:3463		20451.99	-7441.52	-267.84	152.°u	31.40	2.10
221.738	2112335	-2002119	-72217	20565.32	-75,1.54	-233.43	156.56	34+11	2.28
324.345	2967144	-2022485	-75025	21812.86	-13:1.16	-211.52	171.76	35.47	2.49
325.552	2601793	-20-045	-30440	27240.23	-72 -7 17	-2+4.74	177.10	41.38	2.51
331.336	2721034	-2073186	-80965	22566.03	-7211.72	-259.94	166.17	43.53	2.49
333.942	2731373	-2092521	-31577	23101.87	-7053.15	-253.56	116.70	46.65	2.52
336.544	2342173	-2110223	-92225	23624.18	-6370.12	-247.11	206.45	45.51	2.60
340.432	2302213	-21367185	- 12942	24124452	+47/3.37	-236-51	271.35	53.30	2.0/
341.56	2762396	-2145346		24536.45	-6747.47	-235.51	2.70	.33	.10
343.715	301617C	-2155685	-93743	24545.64	-6745.42	-235.28	2.57	•30	.10
345.575	3061335	-2172237	-0+3+0	24551.85	-6744.32	-234.97	2.40	-44	.10
348.105	2125912	-218-124	-94553	241 56 . 59	-6743.34	-234.73	1.32	-25	.06
352.674	3243523	-2720127	-43362	24558.35		-234.72		-14	- 02
355.331	3301-13	-7238023	-=+610	24556.72	->742.52	-234.76	.10	.04	01
257.EE2	1355142	-22:117	-37222	24558.77	-6742.73	-234.90	.27	01	00
340.030	341-622	-2263764	- 97774	24556.91	-e743.05	-234.76	.07	+04	01
363.004	3435812	-2285 60		24355.23	-6742.73	-234.67	53	.83	0Z
367.407	3537354	-2315451	-49504	24355419		-236.57	-06	- 05	04
370.142	3065145	-2337864	014a	24555.46	-6742.48	-235.10	.03	.17	07
372.765	3725667	-2355600	-90767	24561.02	-6742.UE	-235.60	.15	.13	07
374.530	3772576	-1367472	-91112	245c0.79	-0742.20	-235.56	0?	.05	03
377.121	3636564	-2364546	-91752	24560.83	-5742.00	-235.60	20	.00	00
382.327	3544434	-2420643		24000.00	-6761.70	-235.67	06	.02	02
384.051	4001111	-2431494	-13434	74560.75	-17-2-05	-235.54	2	. 07	02
386.685	4671455	-24454 C	-7+0+6	24560.63	-6741.65	-235.86	.24	.00	02
369.273	4135015	-246828	-94656	245eC.5T	-6741.36	-235.71	03	.00	.01
391.85-	415 6401	-2464263	-15265	24560.61	-6741-07	-235.75	.05	02	.03
396.144	4304/57	-2513466		24560.67	-01-2.21	-235.52	.16	14	00
346.767	43-6199	-253017	-96343	24560.75	-6742.02	-235.70	- 28	05	00
461.360	***?0**	-2548464	750 -	24540.70	-0742.13	-235.04	-10	-02	00
403-543	5-55117	-2165-13	-71113	24560.74	-0142.14	-235.4	.04	.0.	.03
405.407	4575421	-7537405	-73*1e	245-0.00	-4741.47	-235.6+		.03	01
410.047	4641315	#261242#	135	24761.60	-0/41.77	-235.45	• 5	-10	01
412.442	4121671	-26 25 + 13	-130351	24565.30	-0741.16	-235.57	-02	•17	~.00



Table A-2. Reconstructed Ascent Trajectory, ECI Coordinates

GEMINE 10 ASCENT NET

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11 ME	₽X	PY	P2	VX	**	٧Z	AX	A¥	A 2
48 36	3024913.8	-18152374.7	9927932.1	1324.215	216.820	1.945	1.4128	-0.4822	4.6026
5, 2324	3031218.2	-10151430.7	9927991.9	1330.446	176.680	23.333	1.4246	-8.8312	4.6468
7.8313	3034683.7	-18151009.5	9928668.2	1334.351	153.263	35.566	1.4752	-9.2697 -9.6296	4.8225
12.5666	2041017.3	-18150391.7	9929292.1	1341.910	107.294	59.292	1.6405	-10.0827	5.2589
17.3069	3044532.3 3047397.0	-18150146.2	9928634.6	1346.250	80.296 57,474	73.489 85.564	1.6845	-10.9570	5.7441
19.9240	3050935.7	-18149887.5	9928878.1	1354.225	27.961	100.729	1.8036	-11.5418	6.0259
24. 56 86	3657244.8	-16149885.7	9929413.4	1363.308	-28.092	130.164	3.0386	-12.5633	6.4214
26. 5901	3063665.7	-18149968.7	9929689.4	1349.756	-54.188	143.066	4.1322	-12.9287	6.5100
31.9016	3667356.3	-18150443.5	99 3054 2.1	1400.882	-125.103	170.145	7.7435	-13.7909	6.6448
35.5642	3070214.8	-16151184.7	9931450.5	1418.138	-191.767	209.443	11.0053	-14,4998	6.5460
38.6105	3076953.5	-18151602.7	9931897.7	1468.082	-221.191	222.324	12.4606	-14.7494	6.5034
43.9221	3084955.1	-18152990.5	4433160.7	1544.624	-301.636	257.036	16.4127	-15.2516	6.7150
45.9514 48.6076	3088124.7 3092385.4	-10153634.0	9933695.9 9934439.6	1579.612	-332.623	270.580	17.8957	-15.5003	6.8789 7.0547
50.6720	3095725.5	-14155361.0	9935040.4	1670.946	-405.362	304.093	21.3118	-15.6805	7.1132
55. 9426	3104918.0	-18157736.5	9936755.1	1794.384	-489,968	341.613	25.3560	-15.9182	6.9218
57.9707 60.6262	3108610.6	-18158764.0	9937462.1 9938430.1	1847.373	-522.790	355.511 373.470	26.7975 28.5778	-15.9705	6.7855
62. 6526	3117567.2	-18161383.7	9939200.4	1980.343	-597.374	386.455	29.9745	-16.0113	6.1860
67.9631	2128520.6	-18164785.7	9941334.4	2149.238	-682.434	417.304	34.7148	-15.2752	5.6159
59.9904 75.6277	3132950.4	-18166201.0	9942191.1	2221.641	-713-523	427.892	36.9806	-14.5034	5.8509
74.6743	3143780.2	-18169697.0	9944258.6	2407.475	-776.730	457.556	42.2556	-13.0599	6.2267
77.3313 79.9856	2150331.0	-18174000.0	9945498.5 9946778.1	2524.027	-845.623	474.980	44.9026	-13.0739	4.5144
82.0149	31 626 59. 5	-18175745.0	9947778.1	2743.636	-874.497	496.514	47.2457	-14,1293	3.8094
74. 67 CL	51/0120+1	-19[/0114.2	4947108.8	2011.470		364.324	22.11.40	-13.9002	3.3047
86.6965 89.3567	3176059.5	-18179999.0	9950136.4	2965.038	-941.576	511.655	54.4709	-13.6122	3.3979
91.3011	2190662.1	-18184553.7	9952570.9	3253.225	-1002.719	528.424	59.8703	-12.8582	3.3851
94.0422	2190534.9	-18187267.0 -18190063.2	9953989.1	3586.665-	-1036.540	537.321 544.888	62.8054	-12.7671	3.0825
· 8. 72 58	3216242.5	-18192267.7	9956536.4	3722.424-	1096.711	549.660	68.2621	-12.4771	2.1763
101.4201	3234596.5	-1 197574.7	9959153.0	4058.042-	-1124.823	557.857	71.5904	-12-1107	1.6035
106.1242	3245733.0	-18200708.7	9960650.1	4261.017-	-1165.324	560.087	77.5331	-11.4698	.4765
110.8606	3265504.6	-18206452.0	9963 304.1	4042.473	1238.469	559.692	94.0622	-10.0818	7330
115.5451	3289499.5	-18209773.0	9965914.4	4870.034-	-1280.987	553.294	87.9518 90.9827	-8.9830	-1.5091
118.2014	3303243.8	-18215787.0	9957375.E	5298.653	-1301.449	546.586	94.9613	-7.2251	-2.7934
122. 9279	3329375.7	-1822 2010-2	9969923.2	5764.131	-1 332. 372	531.197	101.8870	-7.3725	-3.4435
125.5842	3345050.2	2 -19225576.7 -18228345.7	9971322.5	6257.134	-1353.561 -1371.553	522.064	105.7986	-8,2013	-3.6229
130.2736	3374559.5	-18232022.5	9973728.6	6552.053	-1395.784	504.209	113.6107	-9.0661	-3.8578
134. 5641	3406571.1	-18238670.0	9976051.1	7104.815	-1439.015	486.000	122.6204	-9.3828	-3.9565
135.9914	3421229.1	-18241606.7	9977027.4	7356.969	-1458.209	477.063	126.9872	-9.5936	-4.4116
142.3479	3462509.1	8249559.0	9979516.5	8067.385	-1511.326	451.999	139.2778	-10. C124	-4.9512
147.1047	3502504-1	-18256862.7	9981609.6	8758.696	-1559.860	427.422	152.2932	-10.4090	-5.6629
149.1353	3520604.0	-18260051.2	9982465.9	9073.411-	-1501.330	415.955	158.3425	-10.6333	-6.0091
152.3620	3550724	-18265210.5	9983776.1	9599.540	-1616.400	395.659	167.9559	-10.9906	-6.6541
153.8274	3564822+3	9 -13267557.2 9 -18271717.7	9984341.6 9985295.9	9848.734	-1568.929	341.531	34.7577 35.6998	14.0076	-13.1420
159.1428	3616609.0	-18275750.5 -18278802.7	9986157.1	9838.466	-1493.725	306.367	36.6412	18.0587	-13.4192
163.8703	3663536.2	-18282609.2	9987453.1	10015.517	-1407.728	241.950	38.1375	18.1839	-13.6668
164.3889 168.6915	3712272.0	5 -18286096.7 C -18289184.7	9988019.1	10112.420	-1361.753	175.936	38.7576 39.4091	18.1587	-13.6881
170.4895	3730678.0	5 -18291529.5 3 -18294861.2	9988755.0	10273.871	-1288.237 -1241.107	151.603	40.0840	18.1980	-13.6189
175.7688	37854 80.0	-18298077.0	9989364.2	10488.954	-1187.976	79.673	41.7550	21.6854	-13.7658
187.3264	3833725.	7 -14303245.7	9999584.5	10683.271	-1077.674	16.269	43.2612	25.1010	-14.2686
183.0695	2863195.2	2 -18306105.2	9989574.9	10862.912	-1037.369	-23.446	43.9397	25.9073	-14.6478
187.6281	3512901.	-18310424.5	9989313.7	11005.807	-886.864	-91.600	45.1522	26.9016	-15.2075
190.3322 192.1929	3542828.	7 -18312723.7 9 -18314182.0	9989010.0	11128.996	-813.427	-133.137	45.7963	27.4331 27.7133	-15.4844
194.8918	3994052 .	-18216145.0	9988241.1	11340.054	-686.708	-204.523	47.0635	28.1346	-15.9074
199. 4475	4046213.	3 -18318979.7	9987142.7	11558.015	-557.194	-278.020	48.3206	28.7942	-16.3409
202.1926	4078121.	2 -18320400.5 9 -18321233.5	9986317.7	11691.627	-477.699	-323.165	49.0329 49.6408	29.1855	-16.5725
206.7492	4131909.	8 -18322272.0	9984671.7	11918.296	- 34 3. 366	-399.559	50.4013	29.8113	-16.9598
211.3039	4186721.	0 -19323524.5	9992675.0	12150.784	-206.260	-477.529	51.8263	30.4607	-17.3907
214.0139 216.7190	4219840.	2 -18323971.0 3 -18324191.2	9981316.2 9979831.1	12292.225	~123.189 -39.466	-525.159	52.6280	30.8236	-17.8813
218.5695	4276390.	6 -10324210.7	9978740.1	12535-206	18.619	-606.095	54.1224	31.4834	-17.9901
223.1623	4334535.	4 -18323791.0	9975765.6	12787.246	164.602	-689.664	55.7696	32.0816	-18.4127
225.8733 228.5793	4369409.	5 -18323226.7 4 -18322425-5	9973827.9 9971757.1	12939.485	252.005	-739.963	50.6602 57.6664	32.4553	-18.6509
230. 4279	4428938.	6 -18321740.2	9970263.4	13201.341	401.141	-825.629	58.4995	33.0650	-19.0655
235.8488	4501370.	9 -18319078.0	9965505.4	13523.892	582.097	-930.184	67.5027	33.8212	-19.5383
237.7014	4525528.	7 -18317941.5 1 -18316065-0	9963748.6 9961052.7	13636.718	644.910 738.247	-966.547	61.4J56 62.5456	34,1939	-19.7580
243.1828	4602211.	0 -18313888.2	9958151.0	13979.601	835.141	-1076.531	63.6832	35.3945	-20.3771
247.7922	4667332.	-1-312202.5 2 -18309658.2	9952971.0	14278.069	1001.138	-1171.702	65.8903	36.6360	-20.9745
249.6604	4694121. 4733830.	6 -18307723.7 2 -18304651-7	9950745.4 9947346-7	14402.056	1769.941	-1211.0?5	66.9277 68.2106	37.1297 37.8238	-21.2260
255.1330	4773953.	2 -19301306.0	9943797.2	14775.161	1276.716	-1328.803	69.5292	38.5791	-21.9699

CONFIDENTIAL

Table A-2.Reconstructed Ascent Trajectory,
ECI Coordinates (Continued)

GEMINE LO ASCENT BET

TIME	٩X	PY	PZ	VX	٧¥	٧Z	AX	AY	AZ
257.0051	4801736.0	-19298848.0	9941270.7	14906.480	1349.428-13	70.260	70.6349	39.0974	-22.2517
259. 7434	4842776.1	-18295010.5	9937439.1	15101.494	1457.066-14	31.553	72.3713	39.5121	-22.5296
261. 6467	4 8716 95.0	-18292159.7	9934668.9	15240.040	1533.912-14	75.161	73.4383	40.5589	-23-1289
264. 3840	4913687.7	-19287808.2	9930543.6	15442.593	1645.928-15	39.176	74.8262	41.4493	-23.6532
267.11 94	45561 95.6	-18283151.7	9926245.7	15049.409	1760.484-16	04.601	76.3562	42.2780	-24.1365
268.9875	4 \$85580.5	-18?79786.7	9923204.2	15793.280	1840.130-16	50.002	77.7526	42.9998	-24.5262
271.7748	5029105.1	-18274587.7	9918595.0	16008.557	1959.072-17	17.854	79.5828	43.8081	-25.0010
273. 5900	5059103.9	-19270856.7	9915347.2	15158.179	2041.448-17	64.699	81.1998	44.4093	-25.3655
276.3293	5103655.4	-18265099.7	9910419.4	16382.503	2163.657-18	34.694	83.0451	45.1193	-25.7786
279.0527	5149764.1	-18259014.5	9905306.1	16012.325	2287.780-19	05.567	84.9737	45.9161	-26.2493
280,9699	5180503.4	-18254567.2	9901623.9	16775.189	2375.953-19	55.871	86.8112	46.6339	-26.6692
283.7092	5226886.0	-18247882.7	9896165.5	17017.058	2505.002-20	29.749	89.1107	47.7165	-27.3009
285.5734	5258766.1	-18243129.7	9892333.9	17184.744	2 59 4. 472-20	8C.976	91.0712	48.6749	-27.8683
28*. 3127	5306182.7	-18235839.7	9186529.0	17436.617	2728.998-21	57.847	93.3520	49.9110	-28.5623
291.0461	53541.95+9	-18228191.7	9880522.6	17695.435	2867.474-22	37.191	95.498£	51.5474	-29.4296
297.8693	5385619.6	-18222877.7	9876394.7	17872.089	2961.899-22	91.075	98.1515	52.5716	-30.0229
295.4758	5433537.1	-182:4978.2	9870320.7	18130.448	3100.500-23	70.058	170.9981	54.0630	-30.8665
299.0913	54611 20.7	-18206714.7	9864040.4	18390.626	3243.120-24	51.360	103.5299	55,3647	-31.5682
307.6328	5529334.1	-18198089.0	9957554.6	18670.027	3 389.01 3-25	34.869	106.7127	56.7987	-32.4135
302.5031	5561498.1	-18191824.7	9852886.5	18656.946	3493.746-25	94.229	109.7566	57.8811	-33.0697
30 5. 11 36	5613067.2	-18182517.0	9846009.1	19156.396	3646.375-26	81.446	113.4161	59.4997	-34.0101
307.7150	5663347.4	-19172816.7	98 38 908.9	19455.053	3803.052-27	71.152	117.2659	61.4986	-35.1805
310, 31 85	5714401.1	-19162707.2	9831575.2	19765.201	3963.957-28	63.142	120.5520	62.8418	-35.9223
312.1019	5749840.4	-19155538.0	9826412.0	19983.531	40/7. 125-29	28.041	124.5599	64.9355	-37.0532
314. 7092	5902371.6	-10144084.5	9818651.0	20312-124	4249.904-30	/2.2/1	129.1791	67.3228	-38.3503
31 1 21 31	2022/12.4	-18133587.7	9810639.9	20632.924	4426.980-31	20.913	132.9739	09.4798	-34.5008
319.9172	5909943.2	-18121623.0	9802362.9	21006-819	4011.923-32	51.904	1 38.2 624	12.2760	-40.9422
321.73.4		-18113106.7	9796411.1	21203.110	4745.733-33		143.0110	74. 9371	
324.3444	5004747.9	1000474.5	9/8/241.1	21642.989	4 744 . 032- 74	19.940	149.3401	11.1199	-43.9300
320.6630	4110133 0	-10032450 0	9770304.0	22039.330	5150+207-37	5. 007	143 8347	93 4474	-47.4022
324.3320	6169469 T	-180/3030.0	910922347	22929.322	5 51 4 1 2 7 - 37	43 817	102.0341	84 3773	-40 1207
333 9614	4710204 4	-18040274 0	7762623.1	22750.022	5744 104-38	72 744	1 70 04 79	00. 7747	- 51 4447
336 6442	4780798 1	-18034012 7	6767666 6	23200.301	5982 278-40	70 243	1 17.0427	03 9440	-51 4042
313 0578	4346416 7	-18019673 3	9732108 1	250101200	A771 400-41	46.366	107 (.732	07 3400	-55.4797
341.5320	A 374748.7	-18009390.7	97 260 26.1	24464 612	6368 573-42	20.108	202.2024	99.3910	-56.8935
5454 5520		-1000 / / / / /	772032 4 81	44344346	0,000,013-42		20.02014	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
341.5991	6402153.6	-18002621.2	9721532.9	24506-375	6419-260-42	57.209	-6-4444	26.3766	-14.2507
343.7150	6454242.4	-17588912.7	9712448.9	24495.659	5476-857-42	88.400	-6.7285	26. 3831	-14.2483
345.5754	£4998 03.C	-17576417.2	9704446-0	24484.475	6526.477-43	15.083	-6-9771	26. 3904	-14.2461
348.1848	+ 563667.4	-17559697.5	9693138-0	24464.678	6594.920-43	51.997	-9.1004	26-0554	-14.0758
350.6115	6 52 30 11 . 1	-17543617.5	96 92 53 5 . 7	24442.984	6657.482-43	85.837	-8.8547	25.837A	-13.9834
352. 9738	6680727.1	-17527818.5	9672135.1	24421.125	6718.221-44	18.776	-9.3320	25.6973	-13.9307
355.3313	6738271.8	-17911909.7	9661680.0	24398.845	6778.658-44	51.537	-9.5348	25.6248	-13.8830
357.6818	6795596.6	-17895905.0	9651178-4	24376.130	6838.876-44	84.273	-9.4368	25.5853	-13.8484
361.0305	6852820.5	-17879773.0	9640608.7	24353.427	6898.687-45	16.463	-9.7236	25.5770	-13.8482



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Table A-3a. Reconstructed Ascent Trajectory, Special Parameters

	GEN	INT 10 THW ASCE	NT BET				1
TIME FEOM LIFTOFE (SECONDS)	INFPTTAL VEL+ Magnitude (FT/SEC)	FFLATIVE VFL. MAGNITUDE (FT/SFC)	INERTIAL FLT. PATH ANGLF (DEGREFS)	INFRTIAL HEADING ANGLF (DEGREES)	ALTITUDE (FEET)	GEPDETIC LAT. (DEGREES)	GEODETIC LONG (DEGREES)
.484	1341.8	4.3	.182	90.004	4.0	28.507	-80.555
3.120	1342.2	20.5	1.261	90.015	48.5	28.507	-87.555
5.233	1342.5	77.5	2.107	90.060	298.7	28.5^7	-80.555
9.047	1345.2	100.7	4.294	90.088	487.2	28.507	-80.555
12.567	1347.5	130.2	5.544	on 122	789.2	28.507	-80.555
15.192	1350.6	161.2	0.000	90.148	1540.0	28.507	-80.555
10.524	1359.2	221.2	9.377	90.207	2074.2	28.517	-80.555
22.(46	1362.6	240.8	10.562	90.232	2573.7	28.507	-80.555
24.569	1369.8	285.5	12.028	90.264	3248.2	28.597	-80.555
20.540	1395.1	356.5	14.798	90.415	4748.2	28.507	-80.555
31.002	1417.7	309.2	16.329	PC.531	5748.5	28.507	-80.555
33.033	1439.3	433.9	17.492	92.641	6591.5 780C 2	28.577	-80.554
36.585	14/2+2	518.5	20.000	90.990	8804.2	28.506	-80.554
41.267	1544.9	570.9	21.329	91.228	10232.0	28.506	-50.553
43.022	1594.6	626.2	22.550	91.472	11789.2	28.506	-80.552
45.051	1636.R	670.7	23.407	91.673	15069.0	28.500	-80-550
45.0 8	1745.1	781.8	25.193	92.010	16328.0	28.505	-80.549
53.290	1816.1	850.1	26.054	92.227	18375.5	28.505	-80.546
55.043	1891.2	922.5	26.825	92.452	20564.5	28.504	-80.544
57.971	1952.5	980.7	27.337	02.635	22339.0	28.503	-80.538
67.676	2037+3	1122.4	21.100	93.044	26767.7	28.503	-80.535
65.311	2106.7	1208.1	28.690	•3.340	29492.5	28.502	-80.530
67.063	2293.3	1297.4	28.990	93.576	32363.0	28.501	-80.525
69.990	2372.3	1369.3	20.116	93.774	34659.2	28.500	-80.521
72.643	2492.0	1467.9	Z9.178	93,954	37799.5	28.499	-80.515
77.331	2692.9	1656.2	29.036	94.023	43691.5	28.497	-80.501
79.986	2920.6	1772.3	28.916	94.189	47234.7	28.496	-80.493
A2.015	2922.1	1965.3	28.805	94.370	50046.0	28.495	-80.485
84.670	3960.8	1993.2	28.630	94.645	53860.7	28.493	-89.475
39.357	3324.1	2236.7	29.179	94.988	60972.7	28.490	-80.454
91.391	3445.0	2349.3	27.956	95.096	64195.0	28.489	-80.444
94.042	3610.4	2504.0	27.635	95.243	68569.7	28.497	-80.429
98.726	3919.3	2795.4	27.042	97.390 05.522	75092.2	28.483	-80.400
101.420	4108.3	2974.5	26.666	°5.674	81541.0	28.450	-80.392
1^3.446	4255.7	3114.8	26.373	95.793	85321.7	28.478	-80.367
106.124	4458.1	3308.0	25.960	95.946	90462.2	28.475	-80.346
110.861	4837.3	3671.0	25.211	96.219	99959.0	28.470	-87.304
113.515	5062.6	3846.3	24.744	96.349	105502.5	29.466	-80.279
115.545	5241.1	4060.3	24.373	96.449	109846.2	28.463	-80.258
118.201	2473.4 5675 5	4294.3	23.672	96.558	112002.7	28.454	-80.229
122.029	5939.9	4736.6	22.971	96.767	126374.0	28.451	-80.173
125.584	6211.3	5021.3	22.529	96.885	132607.7	28.446	-80.138
127.616	6426.3	5211-6	22.214	96.953	137490.0	28.442	-87.110
132.305	69 49.7	5725.3	21.538	97.186	149153.7	29.433	-80.072
114 044	70/6 5						
1 29 . 404	7515.2	6292.2	21.180	97.289	156029.5	28.427	-79.998
137.654	7857.2	6619.6	20.582	97.473	168644.7	28.415	-79.916
142.348	P223.2	6978.3	20.261	97.572	176192.2	28.475	-79.865
144.377	8505.6	7260.7	20.027	97.642	182030.0	28.472	-79.825
149.135	0219.6	7967.0	19.723	97.805	190092.2	28.394	-79.768
151.794	9648.4	8393.3	19.224	97.897	274569.0	28.379	-79.663
152.362	9742.7	8486.9	19.171	97.917	206377.2	28.377	-79.649
153.827	C785.5	8528-0	18.967	97.944	211044.2	20.372	-79.614
159.143	7707.4 CQ65.0	8690.9	18.011	97.948	219448.2	20.352	-79.550
161.212	10025.2	8757.4	17.986	98.098	234191.5	29.345	-79.434
163.P7C	17116.9	8845.7	17.639	98.154	242370.2	28.335	-79.367
166.389	10205.8	5931.6	17.315	98.208	250046.0	29.326	-79.304
170.489	10355-5	9076-5	16-809	98.296	262396.7	28.317	-79.245
173.123	1-454.5	9172.6	16.493	98.354	270239.0	28.300	-79.129
175.769	11556.4	9271.3	16.156	98.392	278041.7	28.289	-79-060
1//.610	1029.C	9341.6 9444.4	15.897	98.409 98.414	283437.5	28.282	-79.010
183.070	10849.8	9555.4	15.098	98.428	299061.2	28.260	-78.862
184.019	10 927.0	9630.3	14.826	98.437	304252.7	28.252	-78.811
187.628	11041.9	9741.8	14-428	98.450	311755.0	28.240	-78.735
122183	1119945	9936-1	13.764	\$8.474	324092-0	28,229	-78.658 -78_608
194.892	11363.3	10054-8	13.373	98.489	331262.7	28.209	-78.526
196.735	11449.3	1^137.8	13.119	98.500	336078.7	29.201	-78.472



Table A-3a.Reconstructed Ascent Trajectory,
Special Parameters (Continued)

GEMINE 10 THW ASCENT BET

₹1₩₽ ₽₽-]₩-[1₽₽70₽₽ {\$50000\$}	INCOTTAL VEL. MAGNITURE (FT/SEC)	RELATIVE VEL. MAGNITUDE (FT/SEC)	INERTIAL FLT. PATH ANGLE (DEGREES)	INFPTIAL HEADING ANGLE (DEGREES)	ALTITUDE (FEFT)	GEDDETIC LAT. (DEGREES)	GEDDETIC LONG. (DEGREFS)
190.447	11574.B	10261.4	12,727	98.517	343037.7	28.189	-78.392
252.193	11705.9	10389.7	12.344	PR.536	349050.5	29.176	-78.309
2-4.41	117°5.8	1-477.8	12.055	98.548	324247+2	25+107	-78.169
209 455	12066.8	10743.7	11.356	98.589	36764(.5	28.142	-78.084
211.314	12162.0	10937.3	11.111	98.604	371994.0	28.133	-78.026
214.14	12304.1	10077.1	10.755	98.627	378267.5	28.120	-77.939
216.719	12449.1	11110.0	10.409	98.650	384471.7	28.1J7	-77.851
218.570	12557.6	11219.3	10.174	98.600	388524.7	28.077	-77.699
221.510	12017.6	11472.9	9.673	98.709	398498.0	28.074	-77.637
225.973	12963.1	11627.1	9.276	98.737	404211.7	28.061	-77.545
229.579	13122.6	11784.8	8.956	38.764	409788.7	28.046	-77.451
230.428	13233.3	11994.3	R.741	94.784 08 814	413525.7	28.035	-77.387
233.137	13569.4	12226.2	8.137	98.845	424147.7	23.006	-77.194
237.71	13696.2	12342.9	7.929	98.867	427663.0	27.996	-77.126
240.415	13862.1	12517.4	7.636	98.899	432708.2	27.990	-77.027
243.103	14045.5	12699.8	7.342	98.953	43//25.0	27.953	-76.924
247.742	14361.1	13012.7	6.862	08.089	445788.7	27.937	-76.748
749.66	14492.5	13143.3	6.671	09.011	449953.2	27.926	-76.676
252.411	14689.2	13338.7	6.395	99.045	453494.5	27.909	-76.568
255.133	14880.7	13539.1 13477 B	6.126	99.079	457873.5	27.880	-76.384
250.744	15239.1	13885.7	5.691	99.139	464979.7	27.862	-76.272
261.647	15388.C	14033.0	5,499	99.163	467010.7	27.850	-76.194
264.394	156^6.3	14251+1	5.242	99.272	471767.5	27.832	-76.079
343	16073 0	14473 8	4 000	00 240	A76575 7	27.013	.78 042
268.539	12829+8	14475.8	4.959	99.240	478104.2	27.901	-75.892
271.725	16219.4	14861.9	4.573	99.307	481693.2	27.782	-75.762
273.590	16392.1	15024+0	4.479	99.335	484060.Z	27.76R	-75.680
276.328	16626.4	15267.6	4.175	99.378	497422.0	27.749	-75.557
279.063	16677.2	15517+6	3.957	99.471	490040+2	27.714	-75.344
293.779	17319.9	15959.3	3.579	99.456	495P23.2	27.694	-75.215
285.573	17513.8	16142.7	3.434	99.527	497794.2	27.679	-75.127
29P.313	17780.4	16418.R	3.225	99.574	500579.2	27.659	-74.994
211.40	18065.5	16897.7	3.015	99.654	504912.7	27.621	-74.770
295.476	1545.8	17192.9	2.697	99.700	507222.0	27.599	-74.638
208.091	19840.6	17477.1	2.502	00.748	509403.7	27.577	-74.505
31.693	12143.8	17770.0	2.315	07.707	511456.0	27.555	-74.369
372.573	19362.5	19310 4	2.189	90.851	512416.7	27.515	-74.132
3-7.715	21016.P	18651.8	1.844	99.934	516374.2	27.491	-73.990
310.319	2.361.3	18996.7	1.643	99.986	517965.5	27.467	-73.845
312.1-2	21674.6	19239.1	1.570	107.024	518984.2	27.450	-73.745
314.700	2/ 971.4 21262 6	19096 4	1.409	100.077	521619 2	27.399	-73.443
319.017	21749.9	21392.6	1.292	120.188	522739.2	27.372	-73.298
321.733	22036.2	20669.8	.984	100.227	523441.2	27.353	-73.177
324.345	22462.8	21096.1	.837	109.283	524330.7	27.326	-73.017
326.040	22908.1	21541+2	•692	170.341	525081.5	27.241	-12.873
331.336	237:6.9	22339.7	.444	100.442	526034.0	27.248	-72.569
333-042	24213-7	27846.3	- 308	102.504	526411-0	27,217	-77.394
336.544	24747.8	23340.4	.186	102.572	526653.5	27.196	-72.219
339.054	25291.5	23923.0	. 72	100.637	526764.0	27.155	-72.044
347.537	25671.9	24254.3		100.675	526770.7	27.136	-71.940
343.715	25698.2	24330.5	007	100.704	526720-7	27.095	-71.712
345.575	25704.5	24336.9	007	100.844	526690.7	27.071	-71.579
348.185	25719.4	24341.7	206	100.933	52664°.5	27.037	-71.393
35~.612	25715.6	24343.7	075	101.016	526612.0	27.006	-71.219
355.331	25711.6	24344.1	003	101.177	526541.2	26.943	-70-882
357.642	25711.7	24344.2	^?3	101.258	526506.7	26.911	-70.715
361.130	25711.P	24344.3	791	121.337	526473.5	26.880	-70.547
303.54	25712.7	24344.7		101.435	526432.5	26.839	-70.335
367.417	25712.2	24344.7	.0.2	101.588	526374.5	20.013	-70-022
371 .142	25712.4	24345.7	. 253	121.680	526340.0	26.740	-69.828
372.769	25714.1	24346.9	.113	101.770	526307.2	26.704	-69.641
374.530	25713.5	24346.6	.204	101.029	526285.5	26.679	-69.516
779,713	25713.	24346.6		102.003	526224-0	20.092	-69.148
387.327	25714.1	24346.8	- 06	1-2.000	526193.7	26.567	-68.963
384.001	25714.C	24346.8	- 178	122.149	526174.5	26.542	-68.838
180.085	25713.0	24346.8	•083	102.258	526190.2	26.504	-68.654
351.854	25713.5	24346.6	-157	102.451	526441.5	26,427	-68.289
303.617	25713.4	24346.4	.162	172.509	526542.7	26.401	-68.165
354.188	25713.4	24346.5	+162	102.594	526692.7	26.363	-67.983
							

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Table A-3a.Reconstructed Ascent Trajectory,
Special Parameters (Continued)

GEMINE 10 TPW ASCENT BET

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TINF FROM LIFTOFF (SFOORTS)	INFPTIAL VEL. Magnitude (FT/SEC)	RELATIVE VFL. MAGNITUDE (FT/SFC)	IHERTIAL FLT. PATH ANGLE (DEGPEES)	IMFRIIAL MCADING ANGLE (DEGREES)	ALTITUDE (FEET)	GFDDFTIC LAT. (Degrees)	GEDDETIC LONG. (DEGREFS)
300.767	25713.1	24346.2	.163	102.680	526843.7	26.324	-67.801
411.366	25712.*	24345.0	.165	102.765	526096.7	26.294	-67.618
473,943	25712.6	24345.8	.165	177.849	527140.7	26.245	-67.435
415.697	75712.6	24345.7	.165	102.907	527254.5	26.218	-67.312
418.281	25713.2	24346.3	.167	102.991	527409.2	26.178	-67-131
410.863	25715.0	24348.1	.168	103.076	527564.7	26.138	-66.949
413.442	25716.5	24349.7	.170	103.160	527722.C	26.097	-66.768

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Table A-3b. Reconstructed Ascent Trajectory, Special Parameters

	GEMIN	I 10 TRW ASCENT BET			
TIPF (SFC)	PFLATIVE FLT. Path Angle (CEGPEES)	RELATIVE HEADING ANGLE (DEGREES)	INERTIAL LONG. (DEGREES)	GENCENTRIC LAT. (DEGREES)	RADIUS TO Earth Center (FEET)
3.744	98.024	-131-101	-81.539	28.346	20979869.5
6.380	59.209	-168.861	-80.528	28.346	20939914.0
8.493	89.011	-158.141	-87.519	28.346	20910164.2
13.207	86.782	-165.773	-80.500	28.346	20910352.7
15.827	88.692	-165.745	-80.489	27.346	20910654.7
18.442	PR.713	-164.984	-80.478	28.346	20911035.5
23.184	88.645	-160.180	-8C.45P	28.346	20911940.0
25.306	88.616	-156.707	-80.449	28.346	20912439.5
27.829	88.667	-160.507	-87.430	28.346	20913114.C
32.500	£8.109	148.601	-80.419	28.346	20914614.2
35.162	86.E30	127.170	-80.408	28.346	20915614.5
37.190	85.515 83.508	118.716	-80.390	28.346 28.346	20916457.5
41.971	91,969	110.806	-80.379	28.345	20918670.5
44.527	79.809	108.620	-80.367	28.345	20920098.5
47.192	77.557	106.982	-80.355	28.345	20921056.0
51.868	73.607	104.561	-80.333	28.344	20924732.5
53.872	71.936	103.696	-80.323	28.344	20926195.7
56.550	69.764	102.274	-80,310	28,344	20928243.5
61.231	65.101	101.932	-80.286	28.343	20932208.0
63.886	64.043	101.458	-80.271	28.342	20934662.7
65.913	62.604	101.291	-80.260	29.342	20936637.7
04.211	0(./60	1.1.249	-5.4244	20.341	2
71.223	58,914	101.028	-80.228	28.340	20942235.0
73.250	57.460	100.920	-80.215	28.339	20944531.7
77.934	54.035	100.066	-80.184	28.337	20947073.2
86.591	52.106	99.549	-80.165	28.336	20953567.2
83.246	50.314	99.362	-80,145	28.335	20957111.7
87.930	49.012	99.448	-80.120	28.334	20950924.0
89.956	46.157	99.426	-80.092	28.331	20966757.7
92.617	44.570	99.356	-81.067	28.325	20970855.5
97.302	41.573	99.203	-80.023	28.328	20974079.2
90.956	40.604	09.123	-79.996	28.324	20952980.7
101.986	39.602	99.105	-79.074	28.322	20936549.5
106.706	37.362	99.064	-79.921	20.317	20991939.0
109.384	36.153	99.059	-79.889	28,314	21090360.5
111.461	35.262	99.071	-79.863	28.312	21004464.0
116.775	33.022	99.173	-79.791	28.305	21009663.0
118.805	32,186	99.C78	-79.762	28.302	21019756.7
121.461	31.115	90.(78	-79.722	24.298	21025577.5
126.198	29.302	99.064	-79.646	28.290	21030125.0
128.844	28.414	99.081	-79.600	28.285	21042535.5
130.976	27.787	99.109	-79.563	28.242	21047421.7
135.565	26.464	99.157	-79.474	28.272	21059095.5
130.224	25.778	99.175	-79.420	28.266	21065977.5
147.251	25.280	99.196	-79.378	28.261	21071357.5
145.678	24.075	99.249	-79.257	28.247	21076604.5
147.637	23.652	99.264	-79.208	28.241	21092003.0
150.365	23.110	99.289	-79.140	28.233	21100073.5
155.054	22.746	99.308	-79.087	28.227	21106249.0
155.622	22.147	90.344	-78.990	29.216	21116376.0
157.087	21.899	99.366	-78.958	28.211	21121048.2
162.403	21.404	99.412	-78.882	28.202	21129461.7
164.472	20.701	99.407	-78.746	28.185	21144222.2
167.130	20.277	99.544	-78.669	28.175	21152411.0
171.952	19.533	99.633	-78,595	28.100	21100090.5
173.749	19.265	99.665	-78.472	28.150	21172463.0
176.393	18.879	99.714	-78.393	28.140	21180316.0
180.876	18,471	99.742	-78.255	28.129	21100129.2 21193532.7
193.596	17.685	99.737	-78.170	28.111	21201366.7
186.330	17.203	99.732	-78.084	28.099	21209179.2
108.1/4	16.578	99,727	+78.025	28.092	21214378.5 21221#92.4
193.592	15.534	99.725	-77.849	28.069	21229271.0
195.443	15.616	99.724	-77.789	28.061	21234249.5
198.998	15,153	99+725	-77.699 -77.637	28+049 28-041	21241432.2 21246256.5
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Table A-3b.Reconstructed Ascent Trajectory,
Special Parameters (Continued)

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	GEMINI	1.10 TRW ASCENT BET			
(STC)	RELATIVE FLT. PATH ANGLE (DEGPEES)	PELATIVE HEADING Angle (Degrees)	INERTIAL LONG. (DEGREES)	GEOCENTRIC LAT. (DEGREES)	PADIUS TO Eapth Center (feet)
2-2.707	14.389	99.726	-77.545	28.029	21253227.7
205.453	13.937	99.729	-77.451	28.016	21260162.2
21(+()9	13.203	99.737	-77.292	25.008	21209/58.7
212.715	12.776	99.743	-77.196	27.982	21277877.7
214.564	12.490	99.749	-77.129	27.973	21292240.2
21 5.979	12.075	99.768	-76.031	27.960	21288527.2
221.430	11.345	99.775	-76.864	27.938	21296807.2
224.576	10.957	99,787	-76.761	27.924	21304828.7
229.133	10.353	99.811	-76.588	27.919	21306604.2
231.839	9.583	99.825	-76.483	27.896	21320123.7
233.688	0.734	99.837	-76.410	27.876	21323870.7
239.109	9.030	99.873	-76.195	27.847	21329200.2
245.961	R.757	99.887	-76.12	27.836	21338048.5
243.675	8.462	99.907	-76.009	27.821	21343109.2
249.315	7.901	99.943	-75.815	27.794	21351472.5
251.052	7.577	99.965	-75.699	27.778	21356233.5
252.920	7.360	99.980	-75.619	27.767	21359409.2
258.393	6.740	100.025	-75.380	27.733	21368363.7
261.265	6.533	100.041	-75.297	27.721	21371307.7
263.000	6.237	100.087	-75.174	27.704	21375499.5
267.644	5.742	107.109	-74.961	27.673	21382313.0
276.378	5.45.8	100.137	-74 833	37 4EE	71786144 7
272.248	5.267	100.157	-74.744	27.642	21389686.2
274.995	4.992	100.196	-74.613	27.623	21392294.2
276.350	4.808	100.238	-74.523	27.610	21394674.7
282.323	4.296	100.271	-74.252	27.570	21401300.5
284.230	4.125	100.294	-74.156	27.556	21403485.7
286.969	3.844	100.328	-74.016	27.536	21406512.7
291.573	3,493	100.389	-73.776	27.500	21411304.5
294.306	3.264	100.426	-73.631	27.478	21413971.0
296.129	3.115	100.488	-73.532	27+463	21415675.0
301.341	2.695	100.526	-73.246	27.420	21420209.7
313.943	2.403	100.565	-73.099	27.397	21422284.5
328.371	2.163	100.633	-72.944	27.358	21425526.7
310.975	1.979	100.675	-72.691	27.334	21427265.7
313.579	1.871	100.715	-72.535	27.310	21420881.2
317.969	1.507	100.792	-72.266	27.268	21431325.5
321.574	1.335	100.837	-72.103	27.242	21432603.2
323.177	1.165	100.882	-71.937	27.215	21433748.7
327.605	.883	100.960	-71.648	27.169	21435387.5
331.239	.726	101.007	-71.473	27.141	21436166.5
332.912 334.596	• 572 • 471	101.056 111.090	-71.296 -71.172	27.112 27.091	21436807.7 21437168.9
337.202	. 326	101.143	-70.987	27.061	21437575.2
330.874	.197	171.199	-70.799	27.030	21437848.7
343.792	.010	101.285	-70.503	26.980	21438015.2
344.849	007	101.319	-70.423	25.967	21438012.2
346.975	-+008	101.395	-79.262	26.940	Z1438005.5
351.445	007	101.556	-69.924	26.832	21437991.5
353. 972	015	101.643	-69.741	26.857	21437985.5
356.234		101.729	-69.562	26.819 26.788	21437980.5 21437974.4
361.942	+.03	101.899	-69.207	26.756	21437973.0
363.290	01	11.983	-69.029	26.725	21437971.0
366.264	000	102.090	-68.805 -68.473	26.654 26.440	21437969.7
370.667	.0C 2	102.248	-64.473	26.624	21437971.2
373.402	.003	102.346	-69.268	26.586	21437974.0
376.370	.003	102.441	-67.937	20.549	21437977.Z
3#6.381	.005	1 2.596	-67.743	26.488	21437985.2
3#2.973	- 205	102.609	-67.54#	26.451	21437990.5
385.587	.007	102.781	-67,372	20+414 26.388	2143797.0
389.945	.028	102.958	-67.025	26.350	21438055.2
307.533	.16A	103-072	-66.831	26.313	21438196.0
395.114	. 169	103-163	-00.635	26.274	21438380.7 21438507 E
396.448	.171	103.314	-66.314	26.210	21438695.0





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Table A-3b.Reconstructed Ascent Trajectory,
Special Parameters (Continued)

	GEMIN	I 10 TRW ASCENT BET				14
T1N" (SEC)	PILATIVE FLT. PATH ANGLE (DEGREES)	PELATIVE HEADING Angle (Degrees)	INFRTIAL LONG. (DEGREES)	GEOCENTPIC LAT. (DEGREES)	RADIUS TO Eapth center (feet)	
412.027	.173	103.405	-66.121	26.171	21438883.5	
4"4.626	.174	103.495	-65.927	26.132	21439074.7	
407.203	.175	103.584	-65.735	26.092	214 39266.0	
418.757	.175	103.646	-65-604	26.066	21439396.7	
411.541	.177	103.735	-65.411	26.026	21439590.0	
414.123	.178	103.825	-65.219	25.986	21439784.2	
416.792	.180	103.914	-65.027	25.946	21439980.5	

Page

APPENDIX B

REENTRY TRAJECTORY

The reentry trajectory is provided in two sets, the earth-centered inertial coordinates and the special earth-referenced coordinates. The inertial set has the z axis aligned with the earth's rotational axis, positive north, and the x-y plane is in the equatorial plane with the x-z plane containing the Greenwich meridian at the time of retrofire $(21 \text{ July } 20^{\text{h}} 30^{\text{m}} 51.0^{\text{s}})$.

		¥
B-l	Reconstructed Reentry Trajectory, ECI Coordinates	B-2
B-2a, b	Reconstructed Reentry Trajectory, Special Parameters	в-6

Tables

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Table B-1. Reconstructed Reentry Trajectory, ECI Coordinates

GEMINI LE ENTRY TRW BET V FARTH CENTERED INFFTIAL GREENNICH COUPDINATE SYSTEM

TIME (SEC)	Х (FT)	4 (FT)	2 (FT)	(FT/SEC)	(FT/SEC)	(FT/SEC)
1323.3620	-2338678.66	-18586279.00	10225045.00	25785.19	-1461.56	936.14
1325.7900	-1976(63.95	-18589748.25	1(227759.5)	25792.44	-1396.14	893.99
1328.1860	-1914257.27	-18593015.75	10229358.62	25799-21	-1331.21	872.38
1332.9780	-1790596.00	-18599084.50	1(233299.37	25812.09	-1201.52	786.45
1335.3730	-1728769.11	-18601884.50	10235146.12	25818.11	-1136.75	750.77
1337.7690	-1666501.81	-19604530.50	10236896.12	25824+12	-1076.80	/14.96
1340.1040	-1492768.59	-18611140.00	10250505.57	25839.65	-889.16	614.03
1347.3660	-1418961.69	-18613568.75	10243058.12	25845.53	-811.63	571.41
1349.3060	-1368817.33	-18615392.25	10244148.62	25849.62	-758.98	542.48
1352.1630	-1294957.45	-1861715C+C/	10245637+00	25858.73	~681.33	47(.36
1356.9600	-1170909.95	-18620106.50	10247863.50	25863.56	-551.15	427.54
1358.9000	-1127731.47	-18621124.50	10248661.87	25866.77	-498.42	398.56
1361.7600	-1646746.44	-18622439.00	10249740.00	25871.28	- 420.00	375.40
1366.5560	-922651.17	-18624143.75	10251272.37	25878.04	-290.34	283.55
1368.4940	-872497.43	-18624655.50	10251793.62	25880.55	-237.76	254.28
1371.3540	-793474.42	-18625224.00	15252459.50	25684.03	-159.88	211.44
1375.1600	-144203.10	-18625483.00	1(2533312.12	25888.96	-29.05	139.32
1378.10 70	-623655.38	-18625582.75	1(253544.75	25890.78	24.06	109.93
1380.9690	-549552.49	-19625502.50	1(253797.62	25893.22	101.89	66.73
1382.9140	-499189.56	-18625252.75	1(253899.00	25894.48	233.01	37.59
1387.7220	-374681.05	-18624192.75	1(253905.62	25897.62	285.94	-34.85
1390.5880	-300456.82	-18623261.00	16253743.87	25898.82	364,29	-77.95
1392.5340	-250056.80	-18622500.50	1(253563.75	25899.38	417.30	-107.27
1394.474	-199811.36	-18621639.50	10253327.37	25899.97	470.22	-136.36
1399.2860	-125426.50	-18619061.75	10252497.00	25900.69	601.25	-2(8.81
146.2.1610	-714.94	-18617220.25	10251834.37	25900.64	679.87	-252.17
1404.1010	49532.07	-18615850.00	10251316.75	25900.33	732.76	-281.44
1406.9720	123891.15	-18613033.75	10248769.02	25898-68	942.32	-397.32
1416.6020	373280.94	-18604558.75	10246620.37	25895.23	1073.67	-469.86
1418.5420	423522.59	-18602424.25	10245680.50	25894.04	1126.64	-499.08
1421.4179	497964.59 548165 95	-185990/2.25	10244183.25	25891.10	1205-39	-571.70
1426.2300	622570.73	-18592955.25	1(241397.37	25887.14	1336.58	-615.28
1428.1610	672556.57	-18590323.50	1024-181.25	25884.77	1389.29	-644.27
1431.6340	746919.18	-18586219.50	10238267.75	25481.44	1467.59	-687.77
1435.8490	17120.05	-18578837.00	10234780.87	25874.85	1599.00	-760.67
1437.7900	921742.45	-18575682.00	1-233276.25	25872.02	1651.91	-789.76
1440.6640	996191.59	-18570821.75	10230944.00	25867.31	1730.21	-833.18
1442.0080	1120673-17	-18562172.00	1(229292.1)	25858.17	1861.14	-906.03
1447.4250	1170937.42	-18558502.50	16224965.00	25854.02	1914-07	-935.53
1450.3600	1245258.55	-18552887.00	1(222213.25	25847.63	1992.31	-978.79
1452-2430	1295475.92	-18548964.75	10220283.00	25843+10	2045+05	-1007.99
1457.0600	1419933.55	-18538798.25	10215252.87	25930.88	2176.06	-1080.37
1459.9330	1494133.36	~18532434.25	10212086.75	25822.92	2254.10	-1123.73
1461.8750	1544276.89	-18528005.50	10209876.00	25817.25	2306.82	~1152.91
1464./480	1018430+73	-18516578.50	1(204148.50	25801.99	2437.59	-1225.03
140010720						
1469.5650	1742716.44	-18509463.25	10200567.12	25792.24	2515.66	-1268.10
1474.5940	1872380.23	-18496471.00	10194000.37	25773.59	2651.22	-1343.53
1476.7600	1928196.5)	-18490665.25	10191054.87	25765.33	2709.55	-1376.25
1478.9720	2030484 46	-18484744.25	10188044.00	25756.30	2767.76	-1408.99
1483.2420	2:95117.37	-18472537.00	1(181815.50	25737.08	2883.70	-1474.66
1486.4400	2177400.19	-18463179.00	1(177(21.12	25721.87	2969.24	-1521.70
1488+6060	2233101.59	-18456684.iC	10173685.37	25710.34	3027.02	-1556.41
1492.9260	2344118.62	-18443358.00	10166820.62	25686.05	3162.39	-1587.15
1496.1220	2426180.12	-18433179.75	1(161561.50	25666.84	3227.07	-1669.57
1498.2857	2481682.52	-19426138.25	10157914.87	25653.22	3283.86	-1702.25
1502.6086	2592519.41	-18418980.75	10154231-25	25638.99	3346.33	-1734.74
1504.7660	2647800.22	-19464305.25	16146565.75	25608.66	3453.83	-1800.25
1507.9680	2729759.87	-18393111.50	10140723.62	25584.20	3537.90	-1848.77
1512_2890	2840232.47	-18385401.75	10136691.62	25565.74	3594.12	-1881.09
1514.4500	2895422.12	-19369636.25	1(128428.75	25529.34	3754.58	-1944.23
1517.6483	2977617.53	-18357659.50	1(122136.62	25499.72	3785.62	-1993.81
1521.948140	3:32226.52	-18349406.00	10117790.50	25477.84	3840.70	-2022-24
1524.1240	3141937.69	-18332611.25	10108942.62	25431.97	3845.41 3949.5A	-2093-15
1527.3140	3223004.19	-18319886.50	1(1)2226.#	25396.51	4028.31	-2127.35
1529.4680	3277685.47	-18311152.50	1(097612.5)	25370.90	4681.52	-2157-09
1533.7770	3386888 03	-18293335.50	1092927.02	25343.28	4135.07	-2186.80
1536.9490	3467115.87	-18279932.00	10081092.62	2527:.76	4263.31	-2259.04

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Table B-1. Reconstructed Reentry Trajectory, ECI Coordinates (Continued)

		GEMINE 10 ENT	RY TRW BET	v		
		[AR]	H CENTERED INERTIA	AL GREENWICH Stem		
TIME (SEC)	X (FT)	¥ (FT)	(FT)	XDOT (FT/SEC)	YDOT (FT/SEC)	ZDOT (FT/SEC)
1539.0990	3521414.72	-18270710.75	16676235-25	25239.24	4314.60	-2287.22
1541.2460	3575566.31	-18261392.00	10071264-62	25205.36	4366.11	-2315.20
1546.5650	3709398.84	-18237841.25	10058767.00	25116.67	4488.39	-2383.37
1548.7130	3753307.91	-18228147.00	10053619.00	25077.67	4537.94	-2409.92
1553.0040	367(741.16	-18218396.15	10048413+12	25036.93	4634.10	-2463.62
1556.1770	3949951.28	-18193652.75	100 35285.87	24932.42	4703.35	-2500.76
1558.3270	4003507.84	-18183490.75	10029879.75	24887.68 24839.81	4749.56	-2520.10
1562.6220	4110194.00	-18162896.00	10018912.75	24792.14	4840.34	-2577.61
1564.7640	4163245.59	-18152480.50	10013364+75	24742.55	4884.76	-2602.66
1570.0880	4294628.50	-18126184.50	9999350.25	24610.98	4992.21	-2661.13
1572.2360	4347283.19	-18115446.50	9993625.12	24553.05	5033.82 5075.28	~2684.52
1577.5450	4477374.19	-18088427.25	9979217.25	24397.08	5131.16	-2737.30
1579.6960	4529776.50	-18077349.00	9973308.50	24326.59	5169.39	-2756.73
1583.9840	4633781.19	-18055033.50	9961402.62	24181.03	5239.43	-2795.23
1587.1590	4710373.06	-18038319.75	9952484.87	24065.53	5288.83	-2822.26
1591.4480	4813235.81	-18015500.25	9940309.75	23899.19	5351.74	-2855.50
1593.5940	4864432.12	-18003984.25	9934165-87	23814.17	5380.90	-2870.40
1598.9200	4990680.25	-17975136.50	9918776.50	23593.51	5450.47	-2907.85
1601.0630	5041141.19	-17963426.50	9912529.50	23500.11	5478.05	-2922.28
1606.3730	5165362.94	-17934171.25	9896931.37	23262.83	5540.86	-2953.23
1608.5196	5215119.37	-17922257.CC	9690580.25	23164.53	5562.79	-2965.83
1610.6576	5264534.75	-1791(338.00	9884229.50	23061.29	5586.95	-2974.95
1615.9690	5386334.50	-17880527.25	9868360.75	22794.69	5636.74	-2999.19
1618.1167	5435156.37 54836CC.75	-17868406.00	9861913.62 9855466.75	22684.38	5654.64	-3006.57
1622.4010	5531967.25	-17844103.00	9848995.00	22455.25	5687.82	-3021.47
1625.575	5650549.56	-17826013.00	9832874.87	22280.67	5724.45	-3032.00
1629.8640	5697910.81	-17801460.00	9826358.75	22039.48	5738.86	-3043.29
1635.1810	5814262.44	-17770867.75	9810148.87	21732.37	5768.59	-3053.10
1637. 3270	5860781.56	-17758476.25	9803594.37	21603.35	5779.95	-3055.51
1641.6150	5952862.06	-17733650.75	9796489.62	21343.07	5799.57	-3056.70
1644.7100	6018623.25	-17715678.75	9781034.75	21152.03	5813.99	-3053.03
1649.6490	6122320.94	-17686867.75	9765989.87	20837.31	5858.47	-3036.94
1651.6450	6163780.25	-17675141.25	9759936.00	20705.01	5891.46	-3029.09
1656.5860	6265240.94	-17645810.00	9744966.12	26362.51	5984.76	-3035.51
1658.5790	6375679.56	-17633847.50	9738897.6Z 9722878.87	20218.54	6020.02	-3048.33
1665.9370	6452454.94	-17589153.25	9716133.87	19676.40	6116.05	-3142.58
1668.0950	6494743.12	-17575966.50	9709316.87	19515.81	6123.68	-3175.42
1673.4443	6598042.56	-17543236.50	9692171.87	19107.34	6103.91	-3231.70
1675.6010	6639976.12	-17530080.25	9685188.25 9667853.25	18939.81 18519.11	6089.41 6043.95	-3243.68
1683.2220	6781117.56	-17483922.25	9660490.00	18328.40	6022.41	-3227.54
1685,4240	6821262.44 6859862169	-17476683.50 -17457858.75	9653407.12 9646577.87	16133.83	6001.84 5983-94	-3205.57
1689.71 30	6898019.87	-17445085.75	9639815.50	17737.07	5959.08	-3146.08
1692.8670	6953649.56 6490888.00	-17426299.00	9629936.00	17427.07	5916.30	-3098.90
1697.1590	7.27525.50	-17401041.25	9616776.87	16995.75	5854.42	-3030.66
1702.4670	7116266.50	-1737(119.75	9623958+25	16441.06	5796.54	-2929.66
1769.5700	7230203.19	-17328929.75	9580560.12	15634.24	5808.62	-2820.43
1711.5630	7201122.56	-17317348.25	9574949.87 9566670.00	15393.52	5813.38	-2869.50
1716.5320	73366.77.94	-17288499.75	956(963.56	14768.80	5788.08	-2825.36
1721.6750	7300526.59	-17276494.25	9555(65.12 9546334.75	14499.69 14099-05	5750.L0 5660.57	-2843.38
1723.747	74 19237.31	-17247381.00	9540415.50	13821.72	5578.33	-2854.55
1728.0450	7497366.12	-1723325.50	9528275.62	13928.25	5482.55 5378.10	-2830.09
1731.2250	7538676.50	-17206951.25	9519592.87	12760.18	5235.37	-2677.21
1735.5150	7597 149.12	-17184687.25	9508466.00	12122.36	5147.57	-2591.51 -2514.66
1737.0030	7617703.44	-17174190.25	9503156.12	11797.86	4931.80	-2436.32
1742.9720	7678215.75	-17148675.25	9490778.12	10982.96	4//8.00	-2309.43
1745.1120	77:1367.00	-17138785.00	9486107.37	10653.60	4569.08	-2140.58
1750.4170	7755716.50	-17115244.50	9475300.37	9836.40	4304.57	-1935.12
1752.5610	1776447.44	-17106133.25	9471237.12	9502.35	4194.75	-1855.28

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				0045 30	3070 33	-1704 41
1 /50.04 50	1815140.50	-1/086027.75	9403014.0/	0047.70	3717.32	- 110 - 101
1760.0140	7843019.75	-17076262.00	9458383.12	8373.87	3824.94	-1597.20
1762 1616	7860645.69	-17068141.25	9655031.37	8048.25	3739.77	-1524.97
1747 1700	7000164 31	17640933 66	0447774 37	7307-56	3574.31	-1372.58
1101-1160	1899104.31	-11047023.00	7991119.31			
1769.1630	7913373.44	-17642756.75	9445086.62	1011.60	3310.74	-1329.02
1772.10.80	7933386.06	-17032522.25	9441260.25	6575.36	3433.73	-1274.00
1774 1.50	7.14 4 3 1 0 4 4	-17036737 76	0438730 50	6783-24	3371.15	-1250.52
1114+10 50	1740217.44	- 1102 /12101/	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	5000 05	3301 74	-1234 41
1776.0962	7958446.44	-17019085.CC	9436265.75	5999.05	3301.76	-1239.91
1779-6460	7975545.67	-17009519.50	9432652.75	5593.55	3183.19	-1215.10
1761 0440	7094459 25	-17003251 60	9630339 (5	5330-08	3091.27	-1202.01
1101-1440	7900430.23	-1700 3231.90	9430238.00	4052 03	2017 42	-1133 44
1784.0740	8002037-00	-16994117.75	9426639.25	9972.92	2431.02	-1113.40
1786.2240	8012410.56	-16987925.5C	9424153.87	4696.82	2822.38	-1138.41
1788 3400	80 22221 12	-16081993 50	9621760.12	4449.67	2708.83	-1093.59
1100+3040	0.22223++2	-107017773.70		(210 72	2402.47	1041 40
1790.5140	8031566.37	-169/6296.75	9419470.37	4210.75	2002.01	-1041.40
1795.8290	8052400.94	-16963051.25	9414308.37	3651.01	2381.58	-901.03
1707 0500	9:50054 50	-14958052 75	9412443-00	3441.52	2311.71	-850-42
		1.053100 35	0410430 00	3745 40	2241 86	-004 38
1900-0410	8001(87.94	-10422148*12	9410619.00	3243.00	2241.03	-004.30
18C3.318C	8077114.06	-16946133.50	9408183.12	2971.36	2136.99	-/42.48
18:5-5250	8083481.37	-1694149(.5/	9406588.25	2798.78	2070.42	-702.80
1407 4730	1-00325 04	-14037100 35	0405119 00	2643 12	2008 95	-666.76
1961-0130	0.09323.74	-10431104.23	94.9110.00	2045.12	2000.75	-000124
1869.8020	8094799.12	-16932894.75	9403737.CC	2498.47	1956.35	-630.99
1812.9490	8102354.37	-16926885.50	9401831.50	2303.07	1868.64	-579.99
1016 (703	8107130 47	-14022950 07	8400433 25	21.01.47	1818.17	-547.03
1912-0147	8191139-92	-10922939.0	9400031.23	2101.07		
1819.2580	8115804.69	-16915551.00	9398471.50	1404+20	1121.23	-980.37
1822.3350	8121658.56	-16910332.00	9397040.25	1835.38	1664.91	-443.73
1414 4160	0136303 63	-14904939 00	0304144 17	1754 .97	1626 54	-417.86
1024+41 30	0123372033	-107007070	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			- 202 05
1826.4940	8128963.69	-16903364.00	9393301.37	1080.30	1271.44	-372.77
1829.5710	8133484.97	-16898740.50	9394148.12	1583.19	1543.67	-356.63
1021 46 20	4137217 10	-14405541 25	0303477 25	1521.82	1510.39	-335.79
1031-0330	0137211019	-10073301.123	1373421023	1721101		
1836.8570	8144874.31	-16887906.75	9391807.50	1394.04	1431.42	-286.75
1838.9410	8147666.67	-16884952.25	9391224-37	1352-92	1403.98	-272.84
1841.0970	815 1670 64	-16881043 57	0300440 43	1316 31	1201 11	
1041.0070	8133329.39	-10001903.50	9390649.02	1313.21	1301.32	-262.14
1843.2450	8153329.75	-16879006.00	9390092.75	1279.98	1359.73	-253.35
1846.3560	8157745-19	-16874826.50	9389321.25	1237.20	1327.11	*242.67
1040 4310	A150785 44	14973004 50	0300036 (3		1304 33	
1940-4213	0139703.44	-10012040.5	9388823.02	1211+18	1304.31	-234.99
1850.5070	8162285.12	-16869413.25	9388345.62	1192.23	1280.70	-227.51
1853.5780	4165898.94	-16865536.50	9387654.12	1166.52	1263.98	-222.82
1956 4640	41433/1 6-	-14842076 50	0307104 13	1147.04	1222	
1033.0300	8100301.30	-10002973.30	738/190.12	114/-74	1221.11	-217.95
1860.7940	8174111.75	-16856824.00	9386107.37	1113.73	1173.35	-205-89
1862.8690	8176412.06	-16854405.75	9385686.37	1103.38	1157-44	-199.83
1946 0110	8167C45 60	-14949540 75	0304475 35	1007 7.	11.70	
1000.0110	0102043.30	-10848349.13	9384013.23	1081-10	1120.32	-192.48
1870.0900	8184303.97	-16546237.50	9384274.37	1084.81	1103.96	-192.13
1872.1620	8186552.31	-16843976.25	9383876.37	1085.48	1078.81	-192-04
1876 2320	8180887 N4	-14840726 00	0783788 47	1097 03	1030 37	-100 44
101342320	3133337128	-10/12 3.00	7383200.02	1087.02	1037.21	-140.00
1077.3110	8192147.12	-16838585.50	9382887.75	1087.16	1018.86	-194.73
1879.3840	8194402.69	-16836489.50	9362483.87	1088.99	1003.29	-195-01
1882 4510	8107720 12	-14833443 66	0301005 03	1094 40	087 47	-106 47
1002.4310	9177737+12	-10033443.20	7381883.00	1000.09	703.42	-173.41
1884.5290	8200001.37	-16831408.25	9381477.75	1090-62	975.01	-196.47
1866.6(20	8202263.69	-16829394.25	9381072.37	1092.06	967.96	-194.64
1889.6710	8705614.69	-16826452 00	9380470 47	1091.05	949 47	-197.50
100710710	020 301 3.04	-10820432.00	7380410.02	1091.003	747.47	-191.90
1941-1290	8757892.19	-16824481.00	9380064.12	1094.61	941.21	-192.46
1893.8390	8210164.37	-16822535.00	9379656.87	1087.00	927.24	-198.53
1896.9140	8213516.69	-16819698.75	9379644 .00	1093.40	917 40	-200.09
1 -0 - 00 - 0	9315953 13	14017700 25	2370441 00	1077.40	017 07	-200107
1040.9403	8213862.12	-1081(188.25	A319941*00	1102.00	917.97	-187.04
1901.0720	8218083.25	-16815900,25	9378243.75	1095.62	900.91	-195.68
1904-1450	8221461.00	-16813142.50	9377649.50	1102-69	893.03	-191-06
1004 2334	9333763 6.	-14811377 00	0377047190	1105 11		-171100
1906.2000	0223102.30	-100112//.01	4311201-01	1102-11	872.47	-1/5.07
1908.3070	8226(72.25	-16809426.50	9376897.00	1118.94	886.48	-182.02
1910.3830	8228391.41	-16807589.00	9376525-62	1114.4#	883 49	
1011 44 20	0211034 54		7378323402	1113.00	003.00	-113-17
1010 1020		-10004014.43	7213789.12	1120+01	816.40	+172.72
1712-2260	8234163.31	-16803074.50	9375621.87	1125.01	863.98	-181.44
1917.6160	8236503.56	-16801279.50	9375250-12	1125-21	862-07	-175.99
1920.6910	8219972.75	-16798636 (C	9374707 60	1121 1		-174 84
1022 7244	07/7314	1430405-05	037/3/0 00	1121+10	070.70	-110.40
17661110C	0242310.31	-10/90555.25	931434Z.00	1123.37	852.51	-174.59
1924.8480	8244647.94	-16795083.50	9373987.25	1122.62	852.72	-166.90
1927.921	8248119. 4	-16792468.25	9373467.50	1133.75	848 33	-171.14
1930 (030	025.1477 1-	-14700304 75	0373114 75		070.33	
1930.0030	0230472+12	-10190100.15	4313110.13	1128.78	845.37	-166.09
1932.6810	8252816.87	-16788948.75	9372778.62	1127.98	846.75	-159.35
1935.1560	8256361.12	-16786351.00	9372277.87	1138.22	842.79	-166.33
1937.235	825 8646	-16784400 36	0371030 35	1135 44	84	_ 100.13
1030 3155	0230003+35	-1010-000.27	7311719.27	1132-83	0-1.43	-137.43
1434 3120	8261030+81	-16782347.25	9371613.12	1138.95	844.22	-154.18
1942.3876	8254523.69	-16786266.00	9371136.00	1135.06	836.23	-156.38
1944,4670	8266891 75	-16778527 00	9370813 37	1141 01	436 07	_163 64
1040 4365	0200071.17	-10110321.00	7310013.31	1141.91	835.97	-100+62
1242.05(0	8272787.31	-16//4236.12	9370039.25	1146.31	829.41	-146.61
1951.7.00	8775172.12	-16772507.00	9369739.50	1146.80	833.24	-141.47
1951, 7744	4777581 10	-1677: 461 60	9344474 13	1174 30	74 3 74	
			7307719.12	1110+27	103.10	-114.22
1930.8460	8291227.75	-10/08586.(?)	4369168.62	1197.85	710.93	-84.64
1958.927ú	3283721.37	-16767121.00	9369005.25	1198.69	696.97	-72.42
1961-(0.20	H784 773.54	-16765684.75	9368863.50	1211 40	444 77	- 44 14
1044	0400 44 3 . 30	-1010/004.12	5300003.30	1211-04	000.11	-04.14
1 704 .0750	8239961.52	-10/03628.37	¥368689.25	1221.75	652.00	-49.28
1966.1550	8292498.87	-16762302.00	9368592.00	1217.69	623.37	-44,28
1968,2320	8245 24.42	-16761211.25	9368500-75	1210	A10 55	
1071	027/22707C	-147601/3 43	0340373 43	1617.02	949.37	
1711.3.	0240113+04	-10137101.02	7300312.02	1221.72	6Z1.38	- 39 . 96
1973.3840	8301327.37	-16757794.50	9368299.00	1229.05	638.88	-30.68
1975.4540	8353275-24	-16756470.75	9368235.47	1232.34	660 01	-10 64
1078 5364	4317457 61	-14754513 43	0348173 74	1233.34	040.01	- 30 - 33
1710-7250	000100100)	-10124213-02	7300132.13	1229-41	634.59	-36.45
	a 3 1 - 2 2 -) . \^	-16734196.00	9368056.25	1177 41	434 40	- 34 03

TIME X (SEC) (FT)

i

Table B-1.Reconstructed Reentry Trajectory,
ECI Coordinates (Continued)

(FT)

UNCLASSIFIED

GENINI 10 ENTRY TRW BET V

2 (FT)

EAPTH CENTERED INERTIAL GREENWICH COORDINATE SYSTEM

> XDOT (FT/SEC)

YDOT (FT/SEC) ZDOT (FT/SEC)

Table B-1. Reconstructed Reentry Trajectory, ECI Coordinates (Continued)

TRW BET

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GEMINI 1C ENTRY

1

EARTH CENTERED INERTIAL GREENWICH COOPUINATE SYSTEM TIME (SEC) XDOT (FT/SEC) YDOT (FT/SEC) 200T (F1/SEC) (ÊT) (FT) (FT) (SEC) (FT) 1985.7400 831537.12 1985.7400 831537.12 1987.8320 8319081.44 1987.8320 8319081.44 1987.8320 8319081.44 1987.8320 8321604.37 1991.9860 8324132.70 1997.125 8330467.44 1997.125 8330467.44 1997.2040 8336184.37 2002.2480 8336186.31 2002.4380 8339352.050 2014.6300 8345637.44 2015.6501 8345637.44 2014.620 8345637.44 2013.6607 834561.30 2014.8200 8354501.50 2014.8201 8356872.87 2031.1990 8372149.37 2033.2790 8374685.75 2033.2790 8374685.75 2033.2790 8374685.75 2033.2790 8374685.75 20452.650 8380973.75 20452.650 8380973.75 20452.650 83980473.75 2047.55 83928846.32</t $\begin{array}{c} -16751870.62\\ -16749923.37\\ -16746995.\\ -16744995.\\ -1674690.60\\ -1674435.87\\ -1674276.25\\ -1674405.02\\ -16738120.02\\ -16738120.02\\ -16738120.02\\ -1673865.87\\ -1673850.25\\ -15734865.87\\ -16738540.87\\ -16738540.87\\ -16738540.87\\ -16738540.87\\ -16724365.87\\ -16724365.87\\ -16724365.87\\ -16724365.87\\ -16724365.87\\ -16724365.87\\ -16724365.87\\ -16724365.87\\ -16713837.25\\ -16713837.25\\ -16713837.25\\ -16713837.25\\ -16710544.25\\ -1670924.02\\ -1670924.02\\ -1670924.02\\ -1670924.02\\ -1670224.02\\ -1070224.02\\ -10$ 9367980.25 936771.37 936771.37 9367683.87 9367683.87 9367683.87 9367322.25 9367382.25 9367382.25 9367382.25 9367142.25 936738.47 9360893.50 9360893.50 9360893.50 9366363.12 9366363.55 936655.50 9366675.12 9366262.55 9365968.25 9365978.37 1231.44 1277.62 1215.34 1212.89 1222.21 1237.34 1237.34 1237.34 1237.35 1225.04 1227.42 1230.55 1226.40 1227.04 1227.04 1227.04 1227.04 1227.04 1227.04 1227.04 1227.04 1227.04 1227.04 1227.04 1227.04 1220.51 1219.10 1221.01 1221.0 637.85 633.16 628.42 625.43 633.46 640.02 635.01 636.30 639.37 639. $\begin{array}{c} -36.36\\ -41.95\\ -43.48\\ -40.75\\ -39.66\\ -43.84\\ -43.13\\ -38.92\\ -31.32\\ -40.55\\ -43.86\\ -42.65\\ -39.45\\ -43.86\\ -43.86\\ -41.93\\ -41.93\\ -42.22\\ -45.84\\ -39.21\end{array}$ 9365778.37 9365662.50 9365577.75 9365481.50 9365338.87 9365245.75 1222.92 1224.76 1228.63 1225.38 1231.66 -39.21 -36.23 -45.16 -47.60 -45.18 -44.53 -50.47 -52.30 9365147.12 9364988.75 1230.01 1222.11 632.54 2054.9820 84(1273.50 2057.0630 8403817.37 2060.1450 8407592.00 2062.2260 8410136.00 -16705945.50 -16704622.75 -16702660.75 -16701335.75 9364883.37 9364783.62 9364635.50 9364534.62 1220.56 1224.39 1225.08 1219.80 634.65 636.62 636.52 636.98 -48.64 -47.18 -49.00 -47.86

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Table B-2a.Reconstructed Reentry Trajectory,Special Parameters

	GEN	MINE 10 ENTRY	TRW BET	v			51
TIME FROM RETROFIRE (SECONDS)	INERTIAL VEL. MAGNITUDE (FT/SEC)	RELATIVE VEL. Magnitude (FT/SEC)	INERTIAL FLT. PATH ANGLE IDEGPEESI	INERTIAL HEADING ANGLE (DEGREES)	ALTITUDE (FEET)	GEDDETIC LAT. (DEGREES)	GEODETIC LONG. (DEGREES)
1347.366	25864.6	24505.1	-1.635	87.658	383719.0	28.917	-99.989
1349.306	25866.4	24507.1	-1.633	87.731	382293.5	28.922	-99.843
1354.105	25870.6	24511.5	-1.632	87.915	378772.2	28.935	-99.482
1356.96(25873.0	24513.9	-1,627	88.325	376680.5	28.942	-99.268
1358.900	25874.6	24515.7	-1.626	88.399	375260.5	28.946	-99.122
1363.699	25878.0	24519.9	-1.622	88.283	371752.5	28.957	-98.761
1366.556	25861.2	24522.6	-1.619	88.393	369667.2	28.963	-98.546
1371.354	25885.4	24527.0	-1.615	88.577	366171.5	28.972	-98.184
1373.296	25887.1	24528.7	-1.614	88.652	364758.7	28.975	-98.038
1378.107	25891.	24532.9	-1.6(9	88.830	361263.7	28.982	-97.676
1386.969	25893.5	24535.5	-1.607	88.947	359188.5	28.986	-97.460
1385.778	25897.4	24537.6	-1.603	89.132	355706.5	28.992	-97.097
1387.722	25899.2	24541.5	-1.601	89.20?	354301.2	28.994	-96.951
1390.568	25901.5	24544.0	-1.599	89.31?	352231.5	28.996 28.998	-96.734
1394.474	25904.6	24547.2	-1.595	89.466	349429.2	28.999	-96.441
1397.346	25906.9	24549.6	-1.592	89.577	347362.0	29.001	-96.224
1402.161	25910.8	24553.8	-1.588	89.762	343902.5	29.003	-95.861
1404.101	25912.2	24555.3	-1.586	89.637	342510.7	29.003	-95.714
1411.785	25918.3	24561.7	-1.579	90.133	337011.5	29.004	-95.133
1416.602	25921.7	24565.4	-1.574	90.319	333575.5	29.002	-94.769
	GEI	MINI 1C ENTRY	TRW BET	v			52
TIME FROM RETROFIRE (SECONDS)	INFRITIAL VEL. Magniture (FT/Sec)	RELATIVE VEL. MAGNITUDE (FT/SEC)	INERTIAL FLT. PATH ANGLE (DEGREES)	INERTIAL Heading Angle (Degrees)	ALTITUDE (FEET)	GEODETIC LAT. (DEGREES)	GEDDETIC LONG. {Degrees}
1418.542	25923.3	24567.0	-1.572	96.394	332194.2	29.001	-94.623
1421.417	25925.4	24569.3	-1.573	90.505	330149.7	29.000	-94.405
1426.230	25928.9	24573.0	-1.565	90.691	326733.7	28.998	-94.258
1428.151	25930.0	24574.2	-1.563	90.765	325365.7	28.994	-93.895
1432.974	25933.4	24577.8	-1.558	90.952	323312.7	28.992	-93.678
1435.849	25935.4	24579.9	-1.555	91.063	319933.2	28.986	-93.313
1440.664	25938.5	24583.2	-1-553	91.137	318565.5	28.983	-93.166
1442.608	25939.5	24584.3	-1.547	91.324	315177.2	28.976	-92.802
1447.425	25941.6	24585.8	-1.544	91.435	313161.7	28.971	-92.584
1450.300	25942.8	24587.9	-1.539	91.622	309789.7	28.962	-92.220
1452.243	25943.5	24588.7	-1.536	91.697	308433.2	28.958	-92.072
1457.060	25944.9	24590.3	-1.530	91.883	305078.0	28.948	-91.708
1459.933	25945.7	24591.0	-1.527	91.994	303007.5	28.941	-91.490
1464.748	25945.8	24591.6	-1.521	92.179	299747.0	28.928	-91.126
1469.565	25945.8	24591.7	-1.519	92.254	298403.5	28.923	-90.979
1471.510	25945.4	24591.5	-1.512	92.439	295082.5	28.909	-90.614
1474.594	25944.4	24590.6	-1.508	92.559	292964.0	28.900	-90.381
1478.922	25942.9	24589.3	-1.502	92.727	290000.2	28.886	~90.053
1481.081	25941.6	24588.1	-1.500	92.812	288525.7	28.878	-89.890
		24300.7	-1,	72.070	201032.02	20.071	- 67. 726
	GEI	MINE 10 ENTRY	TRW BET	v			53
TIME FROM RETROFIRE (SECONDS)	INCRTIAL VEL. MAGNITUDE (FT/SEC)	RELATIVE VEL. MAGNITUDE (FT/SEC)	INEPTIAL FLT. PATH ANGLE (DEGREES)	INERTIAL HEADING ANGLE (DEGREES)	ALTITUDE (FFET)	GEODETIC LAT. {DEGREES}	GEODETIC LONG. (DEGREES)
1486.446	25937.5	24584.3	-1-493	93.022	284876.2	28.859	-89.485
1490.765	25931.7	24578.7	-1.487	93.192	281943.0	28.843	-89.158
1492.926	25928.3	24575.4	-1.484	93.275	280481.0	28.834	-68.994
1498.285	25918.5	24565.8	-1.475	93.485	276870.5	28.812	-88.589
150C.446	25913.8	24561.2	-1.471	93.571	275421.5	28.803	-88.426
1504.766	25903.1	24550.8	-1.465	93.741	272534.5	28.793	-88.100
1507.968	25893.7	24541.5	-1.461	93.867	270402.5	29.768	-67.859
1512.289	25878.5	24526.5	-1.452	94.036	268966.2	28.758 28.747	-87.696
1514.450	25869.9	24518.0	-1.446	94.121	266112.0	28.737	-87.370
1519.014	25844.9	24493.3	-1.433	94.330	262600.0	28.709	-86.967
1521.969	25833.2	24481.6	-1.428	94.413	261198.5	28.697	-86.805
1527.314	258(1.9	24450.5	-1.410	94.617	257750.7	28.686 28.668	-86.643 -86.403
1529.468	25787.5	24436.2	-1.403	94.699	256374.5	28.656	-86.242
1533.777	25753.9	244 2.8	-1.391	94.862	253641.7	28.630	-86.080
1536.949	25727.2	24376.3	-1.378	94.983	251650.0	28.611	-85.682
1541.246	25707+3	24334.5	-1.363	95.143	250311.0	28.598	-85.52L -85.341
1543.391	25661.7	24311.0	-1-355	95.224	247662.5	28.571	-85.201
1548.713	25598.6	24248.7	-1.330	77.343 95.422	245728.7 244433.5	28.551 28.537	-84,965 -84,805
1550.861	2557-1	24214.7	-1.323	95.502	243146.2	28.523	-84.646

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Table B-2a, Reconstructed Reentry Trajectory, Special Parameters (Continued)

	GFM	INT IC ENTRY	TR# BET	v			54
TIME FROM RETROFIRE (SECONDS)	INCETTAL VEL. MAGNITUDE (FT/SEC)	RELATIVE VCL. MAGNITUDE (FT/SEC)	INERTIAL FLT. PATH ANGLE (Degreës)	INERTIAL Méading anglé (degreés)	ALTITUDE (FEET)	GEODETIC LAT. (DEGREES)	GEODETIC LONG. (Dégrees)
1553.004	25540.6	24190.4	-1.312	95.582	241872.5	28.568	-84.487
1558.327	25462.1	24112.0	-1.286	95.780	238760.2	28.472	~84.233
1562.622	25427.0	24677.6	-1.276	95.861	237522.7	28.457	-83.936
1564.764	25354.1	24004.2	-1.253	96.017	235089.5	28.426	-63.620
1570.088	25252.2	23943.4	-1.238	96.132	233315.0	28.403	-83.387
1572.230	25207-1	23 857.6	-1.213	96.288	236970.0	28.371	-83.074
1577.545	25080.7	238(9.1	-1.201	96.362	229817.2	28.355	-82.918
1579.696	25022.1	23672.8	-1.164	96.552	227020.7	28.314	-82.533
1583.984	24962.8	23613.0	-1.147	96.631	225924.0	28.297	-82.378
1587.159	24800.9	23451.9	-1.108	96.817	223276.2	28.255	-81.996
1591.448	24657.0	23380.9 23308.0	-1.090	96.893	222239.2	28.236	-81.843
1593.594	24582.7	23233.8	-1.053	97.038	220224.5	28.203	-81.539
1598.920	24388.9	23119+3	-1.029	97.147	218782.2	28.177	-81.314
16(1.063	243.6.5	22957.8	994	97.293	216901.2	28.141	-81.013
1606.373	24095.3	22874.9	973	97.362	215992.7	28.123	-60.864
1608.519	24007.0	22658.5	929	97.541	213815.2	28.078	-80.496
1612.796	23918.9	22505.1	915	97.604	212972.5	28.059	-80.349
1615.969	23672.1	22323.8	872	97.775	210958.0	28.013	-79.987
1010.110	23571.1	22222.8	851	97.840	210177.0	27.995	-79.842
	GEM	INE LO ENTRY	TRW BET	v			55
FPOM RETROFIRE	MAGNITUDE (FT/SEC)	MAGNITUDE (FT/SEC)	(DEGREES)	INERTIAL HEADING ANGLE (DEGREES)	(FEET)	(DEGREES)	(DEGREES)
1620.257	23466.2	22119.0	837	97.910	209416.0	27.976	-79.698
1625.575	23199.9	21651.8	795	98.071	207605.0	27.929	-79.343
1627.721	23649.5	21741.4	775	98.137	206964.2	27.910	-79.202
1632.007	22863.1	21515.1	750	98.264	205551.0	27.872	-78.921
1635.181	27691.3	21343.3	730	98.353	2(4589.2	27.843	-78.715
1639.471	22451.5	211(2.6	704	98.467	2(3336.2	27.805	-78.439
1641.615	22327.2	2.979.3	695	98.521	202730.7	27.785	-78.303
1646.753	22:31.4	2: 683.3	679	98.624	261336.2	27.739	-77.962
1049.649	21857.2	20509.0	708	98.643	203527.2	27.695	-77.676
1653.638	21617.9	2:269.5	827	98.655	199337.5	27.677	-77.553
1056.550	21439.8	19966.3	-1.064	98.718	197549.7	27.634	-17.253
1663.786	20984+6	19636.6	-1.357	98.906	195185.3	27.588	-76.942
1668.395	2:699.1	19351.4	-1.536	99.146	192872.5	27.550	-76.689
1671.284	2 .473.7	19127.1	-1.618	99.331	191639.2	27.521	-76.504
1675.601	20157.4	10011.4	-1.673	99.562	188480.2	27.482	-76.258
1680.946	19748.5	18463.1	-1.692	99.764	185302.7	27.433	-75.959
1685.424	17368.4	18023.0	-1.698	99.844	182673.5	27.392	-75.714
1687.564	19177.5	17832.1	-1.706	99.849 99.856	181429.7	27.373	-75.599
1007.7(3	1371440	1102044					
TIME	GEN THEOTIAL HEL	RELATIVE VEL	TRW BET	V			56
FROM RETROFIRE	MAGNITUDE (FT/SEC)	MAGNITUDE (FT/SEC)	PATH ANGLE (DEGREES)	HEADING ANGLE (DEGREES)	(FEET)	(DEGREES)	IDEGREESI
1692.867	18663.0	17317.3	-1.712 -1.715	99.868 99.879	178391.2	27.326	-75.319 -75.208
1697.159	18229.5	10883.6	-1.726	99.872	175982.2	27.289	-75.099
1702.467	17677.4	16330.9	-1.817 -1.929	99.789 99.724	172997.6	27.245	-74.835
1709.570	16915.2	15568.0	-2.353	99.577	168531.2	27.188	-74.495
1711.563	14692.8	15365.7	-2.928	99.567	167077.2	27.173	-74.403
1716.532	16112.2	14766.4	-3.163	99.726	162962.5	27.136	-74.179
1721.675	17425.3	14710.3	-3.610	100.125	1581049.5	27.121	- 74.088 - 73.957
1723.747	15175.8	13833.4	-3.698	100.287	156068.7	27.083	-73.870
1728.045	14308.8	132.0.7	-3.749	100.478	151879.2	27.051	-73.697
1731.225	14:49.9	12708.2	-3.755	100.418	148863.2	27.)29	-73-574
1735.515	13367.6	12075.4	-3.774	160.248	144985.2	27.000	-73.416
1737.660	13-17-2	11674.6	-3.761	100-030	143112.5	26.986	-73.340
1742.972	12141.7	1:798.0	-3.800	99.914	138681.0	26.954	-73.162
1745.112	11788.0	10443.8 10090-3	-3.829	99.793 99.441	136966.2	26.942	-73.094
1750.417	1 91	9564.8	-3.926	99.468	132872.5	26.915	-72.936
1752.561	1255154	92(5.0 8849-3	-3.986 -4.0A1	99.338	131275.5	26.905	-72.876
1756.845	9847.9	851.7	-4.151	99.577	128161.5	26.886	-72.763
1762-014	9340.9 9604.8	7994.3	-4.311 -4.537	98.861 98.641	125907.5	26.873 26.865	-72.684 -72.634

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Table B-2a.Reconstructed Reentry Trajectory,
Special Parameters (Continued)

	GEM	INI LU FNTKY	TRW BET	v			5/
TIME FROM RETROFIRE (SECUNDS)	INURTIAL VEL. MAGNITUDE (FT/SEC)	RELATIVE VEL. Magnitude (FT/SEC)	INCETIAL FLT. Path Angle (degrees)	INERTIAL HEADING ANGLE (DEGREES)	ALTITUDE (FEET)	GEDDETIC LAT. (DEGREES)	GEODETIC LONG. (DEGREES)
1767.170	8249.9	6902.8	-5.353	98.044	120654.5	26.947	-72,525
1769.163	7955.2	6668.8	-5.819	97.823	119078.2	26.841	-72.485
1774-165	7239.3	5897.1	-7.273	97.514	114806.7	26.828	-72.393
1776.096	6958.C	5618.6	-7.897	97.514	112937.7	26.823	-72.359
1779.046	6549.6	5214.9	-8.771	97.619	110648.0	26.816	-72.312
1784.274	5876.9	455(.9	-9.954	97.975	104949.5	26.804	-72.240
1786.224	5596.6	4273.5	-10.367	98.052	102776.2	26.800	-72.212
1788.369	5322.9	4((2.4	-10.618	98.C37	100646.5	26.795	-72.186
1795.829	5451.3	3146.6	-12.027	97.164	93536.5	26.782	-72.109
1797.959	4232.2	2925.2	-12.651	96.768	91558.2	26.779	-72.091
1800.091	4025.8	2723.8	-13.261	96.402	87583.2	26.776	-72.074
1805.525	3551.6	2265.3	-14.812	95.534	84601.7	26.771	-72.036
1807.673	3386.1	2167.2	-15.427	95.165	82657.5	26.769	-72.023
1809-832	3231.8	1960.8	-16.030	94.776	80747.0 77960 /	26,767	-72.011
1815.079	2892.2	1644.0	-17.472	93.675	76099.2	26.764	-71.986
1019.258	2664.5	1438.0	-18.570	92.704	72510.5	26.762	-71.970
1822.335	2517.4	1307.8	-19.254	91.940	69926.7	26.762	-71.960
1826.494	2347.6	1162.9	-20.169	90.915	\$6522.7	26.761	-71.948
1829.571	2239.8	1074.2	-20.636	96.394	64066.0	26.761	-71.941
1831.653	2176.2	1019.6	-20.969	89.619 80 479	62435.7	26.761	-71.936
1838.941	1968.9	863.2	-21.672	88.151	56962.5	26.762	-71.924
	GEM	INT TO ENTRY	TRW BET	v			58
TIME FROM RETROFIRE (SECUNDS)	INERTIAL VIL. MAGNITUDE (FT/SEC)	RFLATIVE VEL. MAGNITUDE (FT/SEC)	INERTIAL FLT. PATH ANGLE (DEGREES)	INERTIAL HEADING ANGLE (DEGREES)	ALTITUDE (FEET)	GEIDETIC LAT. (DEGREES)	GEDDETIC LONG. (DEGREES)
1841.087	1925.3	833.9	-21.916	87.879	55411.7	26.762	-71.921
1843.745	1834.5	RC 7.5	-22.146	87.619	53870.C	26.762	-71.919
1848.431	1795.4	747.4	-22.381	87.251	50253.5	26.763	-71.913
1850.507	1764.5	723.3	-22.259	87.179	48850.5	26.764	-71.911
1853.578	1718.5	688.8	- 22.121	87.300	45831.2	26.765	-71.909
1855.050	1636.6	623.7	-21.987	87.309	42331.5	26.765	-71.905
1862.869	1611.5	608.8	-21.475	87.245	41395.7	26.766	-71.904
1868.011	1573.5	575.8	-20.960	87.441	38132.7	26.767	-71.902
1876.390	1559.6	538.0	-20.650	87.017	35858.2	26.768	-71.902
1875.232	1516.0	501.7	-19.100	88.597	34284.7	26.768	-71.901
1877.311	1502.6	485.1	-18.674	89.363	33269.2	26.769	-71.900
1879.384	1493.5	471-1	-18.254	89.342	30874.7	26.769	-71.899
1884.529	1476.0	446.6	-17.531	89.876	29942.2	26.769	-71.899
1886-602	1472.2	439.2	-17.282	89.941	29028.0	26.769	-71.899
1891.755	1454.0	414.7	-16.491	90.333	26833.2	26.769	-71.898
1893.839	1442.5	4.8.5	-16.418	96.736	25978.0	26.769	-71.898
1896.914	1441.2	399.0	-16.018	91.014	24739.5	26.769	-71.898
1901.072	1431.9	382.5	-15.441	91.156	23121.5	26.768	-71.898
1904.145	1432.3	372.0	-14.991	91.162	21966.0	26.768	-71.897
1906.230	1433.1	364.3	-14.691	90.567	21201.0	26.768	-71.897
1908.307	1434.1	352.9	-14.227	92.583	19725.7	26.768	-71.897
							60
	68.4	INT 10 ENTRY		•			
TIME FROM RETROFIRE (SECONDS)	INERTIAL VEL. MAGNITURE (FT/SEC)	RELATIVE VLL. Magnitude (FT/Sec)	INSETIAL FLT. PATH ANGLE (DEGREES)	INERTIAL HEADING ANGLE (DEGREES)	ALTITUDE IFEET)	GEDDETIC LAT. (DEGREES)	GEODETIC LONG. (DEGREES)
1913.462	1433.1	342.1	-13.737	90.934	18663.2	26.767	-71.897
1915.536	1430-6	335.3	-13.437	91.338	17278.7	26.767	-71.896
1920.691	1431.1	326.4	-13.346	91.483	14277.5	26.767	-71.896
1922.770	1+21.0	322.5	-13.015	91.446	15608.5	26.767	-71.896
1924.848	1419.6	318.7	-12.897	91.157	13981.7	20.700	-71.896
1930.003	1420.0	313.1	-12.514	91.307	13338.7	26.766	-71.896
1932. 81	1419.4	307.7	-12.445	91.033	12701.2	26.766	-71.895
1935.156	1426-0	304.9	-12.207	71.435	11143.5	26.765	-71.895
1939.315	1426.1	299.1	-12.062	90.981	10525.0	26.765	-71.895
1942.367	1418.5	294.7	-11.895	91.174	9620.2	26.765	-71.895
1944.467	1423.5	291.0	-11-246	91.027	7558.5	26.764	-71.894
1951.76	1424.6	280.5	-11.248	90.789	6981.2	26.764	-71.894
1953.774	1407.1	202.1	-8.089	91.175	6487.7	26.764	-71,893
1956.846	1395.5	138.7	-5.979	90.939	5717.7	26.764	-71.093
1961.003	1304.4	105+1	-4.076	90.910	5493.7	24.764	-71.893
1964.375	1385.7	08.4	-2.498	91.029	5248.7	26.764	-71.073
1966.155	1368.9	47.3 46.1	-1.362	91.350	5075.7	26.763	-71.893
1971.300	1371.2	43.1	-1.297	91.218	4978.0	26.763	-71.893
1973. 384							
	1385.5	46.0	-1.564	90.636	4906.2	26.763	-71,892
1975.454	1385.5	46.0 47.5 47.1	-1.564 -1.516 -1.505	90.636 90.650 90.935	4904.2 4828.7 4716.5	26.763 26.763 26.763	-71.892 -71.892 -71.892

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Table B-2a.Reconstructed Reentry Trajectory,
Special Parameters (Continued)

	GENINS 17 ENTRY		TRN BET V				60.	
TINE FROM RETROFIRE	TACHTIAL VEL.	RFLATIVE VEL. MAGNITUDE	INEPTIAL FLT. PATH ANGLE	INERTIAL HEADING ANGLE	ALTITUDE (FFET)	GEUDETIC LAT.	GEODETIC LUNG.	
ESECONDEL	(FT/SEC)	(FT/SEC)	(DEGPEFS)	(DEGREES)				
1982.685	1387.3	49.2	-1.558	90.899	4562.0	26.167	-71.892	
1985.749	1381.9	50.1	-1.564	91.163	4446.2	26.762	-71.892	
1987.832	1368.9	49.0	-1.645	91.212	4365.7	26.762	-71.892	
1989.910	1365.3	45.6	-1.531	91.146	4287.0	26.762	-71.892	
1991.986	1377.2	47.7	-1.6(3	91.:43	4209.0	26.762	-71.892	
1995.055	1343.8	57.1	-1.617	91.207	4089.2	26.761	-71.891	
1997.125	1391.4	53.7	-1.435	91.268	4012.2	26.761	-71.89L	
1999.204	1385.7	49.1	-1.498	91.050	3938.2	26.761	-71,691	
2002,284	1382.2	44.6	-1.552	90.675	3824.5	26.761	-71.091	
2004,358	1377.6	48.3	-1.604	91.084	3745.5	26.761	-71.891	
2006.439	1369.3	48.8	-1.607	91.249	3665.5	26.761	-71.891	
2009.510	1378.2	49.7	-1.591	91.187	3547.5	26.760	-71.891	
2011.591	1383.8	52.6	-1.657	93.997	3465.7	26.760	-71.890	
2013.666	1381.5	54.6	-1.581	91.466	3385.0	26.760	-71.890	
2016.742	1301.4	55.1	~1.551	91.528	3268.0	26.766	-71.890	
2018.820	1397.9	52.6	-1.566	91.149	3190.0	26.760	-71.890	
2020.699	1382.7	48.6	-1.561	91.021	3111.0	26.759	-71.890	
2023.967	1375.2	48.2	-1.574	91.166	2995.2	26.759	-71.890	
2026+048	1367.0	47.2	-1.593	91.171	2916.2	26.759	-71.890	
2031-199	1373.1	48.6	-1.628	91.155	2717.2	26.759	-71.890	
2033.275	1377.2	51.4	~1.581	91.342	2637.2	26.758	~71.890	
2035.356	1377.6	48.7	-1.683	96.981	2555.5	26.758	-71.890	
2038.429	1382.2	48.5	-1.666	90.846	2431.2	26.758	-71.889	
2040.510	1380.9	51.9	-1,568	91.311	2350.2	26.758	-71.889	
2042.585	1385.2	55.4	-1.595	91.404	2270.5	26.758	-71.889	
2045.659	1382.4	52.8	-1.603	91.292	2151.7	26.757	-71.889	
2047.735	1388.5	54.0	-1.517	91.296	2073.0	26.757	-71.889	
2049,812	1385.9	57.2	-1.547	91.560	1996.0	26.757	-71.889	
	GEI	INI 15 ENTRY	TRW BET	۷			61	
TIME	INERTIAL VEL.	RELATIVE VEL.	INERTIAL FLT.	INERTIAL	ALTITUDE	GEODETIC LAT.	GEODETIC LONG.	
FROM RETROFIRE	MAGNITUDE	MAGNITUDE	PATH ANGLE	HEAUING ANGLE	(FEET)	(DEGREES)	(DEGREES)	
(SECUNDS)	(FT/SEC)	(FT/SEC)	(DEGREES)	(DEGREES)				
2052.893	1377.1	56.2	-1.579	91.644	1879.5	26.757	-71.889	
2054.982	1376.6	53.4	-1.600	91.464	1799.5	26.757	-71.888	
2057.063	1380.8	53.2	-1.561	91.408	1720.2	26.756	-71.888	
2060.145	1381.4	54.8	-1.568	91.488	1603.7	26.756	-71.888	
2062,221	1376.9	53.4	-1.648	91.403	1523.0	26.756	-71.888	

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Table B-2b. Reconstructed Reentry Trajectory,Special Parameters

	GEMINI	IC ENTRY THE	IET V			82
TIML (SEC)	RELATIVE FLT. PATH ANGLE (DEGREES)	PELATIVE HEADING ANGLE (DEGREES)	INERTIAL LONG. (DEGREES)	GEOCENTRIC LAT. Idegreesi	RADIUS TO Earth Center (Feet)	
1347.366	-1.726	87.523	-94.359	28.754	21293164.0	
1349.306	-1.724	87.671	-94.206	28.759	21291733.0	
1354.175	-1.720	87.795	-93.825	28.772	21288198.5	
1356.960	-1.718	87.910	-93.598	28.779	21286099.5	
1358.93	-1.716	87.989	-93.444	28.784	21284674.7	
1363.699	-1.712	88.183	-93.063	28.794	21281155.7	
1366. 256	-1.7,9	88.299	-92.836	28.870	21279364.7	
1365.494	-1.707	88.378	-92.682	28.8/4	21277648.0	
1373.296	-1.703	88.572	-92.300	28.012	21274143.5	
1376.16.	-1.700	88.698	-92.073	28.817	21272657.5	
1378.107	-1.099	88.767	-91.918	28.619	21270641.3	
1382.914	-1.694	88.962	-91.535	28.826	21267150.0	
1345.778	-1.691	89.079	-91.307	28.829	21265074.0	
1390.583	-1.687	69.274	-90.924	28.834	21203000.3	
1392.534	-1.685	89.353	-90.769	28.935	21260188.5	
1394.474	-1.683	89.432	-96.615	28.836	21258788.7	
1399.286	-1.676	89.627	-90.231	28.839	21255324.0	
1402.161	-1.676	89.744	-90.002	28.840	21253258.2	
1404.101	-1.674	89.823	-89.848	28.840	21251866.0	
1411.765	-1.666	90.136	-89.235	28.841	21246366.7	
1416.602	-1.661	92.332	-88.851	28.539	21242932.2	
	GUMINI	1C ENTRY TRW E	NET V			83
T1*F {SEC}	PRIMATIVE FET. MATH ANGLE (OFGREES)	RELATIVE HEADING ANGLE (DEGREES)	INFRTIAL LONG. (DEGREES)	GEOCENTRIC LAT. (DEGREES)	RADIUS TI) Earth Center (Feet)	
1418 642	-1 659	92 411	-88.696	28.938	21241551.7	
1421.417	~1.054	90.578	-88.466	28.837	21239509.0	
1423.355	-1.604	93.617	-88.312	28.936	21238132.7	
1426.233	-1.651	95.813	-83.052	28.832	21234730.2	
1431.034	-1.046	96.920	-87.699	28.829	21232700.2	
1432.974	-1.644	92.999	-87.544	28.827	21231332.0	
1435.849	-1.641	91.117	-87.159	28.620	21227941.7	
1446.664	-1.635	91.313	-86.930	28.816	21225923.5	
1442.668	-1.633	91.393	-86.774	28.013	21224561.0	
1447.425	-1.629	91.590	-86.390	28.805	21221192.5	
1450.301	-1.623	91.707	-86.160	28.799	21219187.7	
1452.243	-1.621	91.785	-86.005	28.795	21217835.2	
1457.26)	-1.615	91.982	-85.620	28.745	21214491.0	
1459.933	-1.611	92.099	-85.391	28.778	21212502.5	
1461.875	~1.609	92.178	-85.236	28.766	21209179.7	
1466.692	-1.602	92.374	-84.851	28.761	21207841.7	
1469.565	-1.599	92.490	-84.621	28.752	21205868.2	
1471.510	-1.590	92.695	-84.220	28.737	21202426.2	
1476.763	-1.588	92.784	-84.047	28.730	21200949.0	
1478.922	-1.585	92.873	-83.874	28.723	21199477.0	
1481.381	-1.579	93.052	-83.529	28.768	21196544.5	
	LEMINI	12 ENTRY TRW	BET V	,		84
TIME (SEC)	FELATIVE FLT. PATH ANGLE {DEGREES}	RELATIVE HEADING ANGLE (DEGREES)	INERTIAL LONG. (DEGREES)	GEOCENTRIC LAT. (Degpees)	RADIUS TU Earth Center (Feet)	
1456.440	-1.575	93.185	-83.274	28.697	21194380.5	
1488.606	-1.572	93.274	-83.1C1 -82.929	28.680	21191464.7	
1492.926	-1.566	93.451	-82.757	28.672	21190011.2	
1496.122	-1.561	93.583	-82.502	28.059	21187869.0	
1498.285	-1.550	93.763	-82.157	28.640	21184984.0	
1502.608	-1.549	93.853	-81.985	28.631	21183547.5	
1504.766	-1.545	93.943	-81.913	28.521	21152117.0	
1507.968	-1.538	94.166	-81.386	28.596	21178574.7	
1512.289	-1.532	94.255	-81.215	28.585	21177156.2	
1514.450	-1.526	94.344	-81.043	28.575	21173661.5	
1519.814	-1.12	94.565	-80.617	28.547	21172259.0	
1521.969	-1.527	94.65	-80.446	28.536	21170869.2	
1524.124	-1.50C -1.489	94.739	-80.022	28.506	21107403.1	
1529.468	-1.480	94.955	-79.852	28.494	21166088.2	
1531.625	-1.474	95.041	-79.681	28.401	21164729.7	
1536.949	-1.468	95.256	-79.260	28.450	21161409.0	
1539.099	-1.445	95.341	-79.091	28.437	21160083.5	
1541.246	-1.438	95.426	-78.922	28.424	21158768.2	
1543.391	-1.430	95.638	-78.503	28.390	21155549.5	
1548.713	-1.404	95.721	-78.335	28.376	21154268.5	
1550.861	-1.397	95.806	-18.166	24.362	21152996.0	

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IME (SFC)	RCLATIVE FLT. PATH ANGLE (DEGREES)	RELATIVE MEADING Angle (Degrees)	IMERTIAL LONG. (Degrees)	GENCENTRIC LAT. (DEGREES)	RADIUS TO Earth Center (Feet)
1553.004	-1.385	95.891	-77.999	28.347	21151737.0
1000.177	~1.267	96.013	-77.751	28.326	21149895.2
1560.475	-1.348	96.187	-77 414	28.311	21148661.7
1562.622	-1.334	96.268	-77.249	28.281	21146231.0
1564.764	-1.323	96.353	-77.083	28.265	21145037.7
1567.945	-1.308	96.476	-76.836	28.242	21143287.0
1572.23	-1.295	96.642	-76.671	28.227	21142123.7
1574.373	-1.269	96.721	-76.341	28.194	21196979.5
1577.545	-1.245	96.845	-76.097	28.170	21138184.7
1579.696	-1.231	96.924	-75.933	28.154	21137083.2
1583.984	-1.196	97.089	-75.789	28.137	21136003.5
1587.154	-1.171	97.238	-75.365	28.295	21133398.5
1589.306	-1.153	97.287	-75.203	28.078	21132379.0
1591.448	-1.136	97.367	-75.042	28.061	21131380.5
1596.771	-1.13	97.544	-74.585	28.043	21130399.7
1598.92	-1.(67	97.643	-74.483	27.999	21128951.0
16(1.063	-1.052	97.721	-74.324	27.981	21127139.5
1603.201	-1.030	97.796	-74.100	27.963	21126249.2
1608.519	985	97.990	-73.933	27.937	21124963.7
1610.657	969	98.059	-73.620	27.910	21129117.7
1612.795	949	98.135	-73.465	27.882	21122487.0
1615.969	924	98.245	-73.236	27.854	21121325.5
1010.115	913	98.317	-73.381	27.835	21120563.2
	GEMINI	I LL ENTRY TAW BI	ET V		
TIME	PREATIVE FLT.	RELATIVE HEADING	INERTIAL LONG.	GEOCENTRIC LAT.	RADIUS TO
(SEC)	PATH ANGLE	ANGLE	(DEGREES)	(DEGREES)	LAKTH CENTER
	(DEGREES)	(DEGREES)			(FEET)
14.20 267		64 303	-73 039		
1622.401	867	98.463	-72.770	27.798	21119097.0
1625.575	845	98.571	-72.552	27.770	21118057.7
1627.721	827	98.643	-72.401	27.751	21117376.2
1637.007	814	98.712 98.784	-72.251	27.132	21116711.0
1635.181	776	98.883	-71.983	27.685	21115128.2
1637.327	765	98.948	-71.736	27.665	21114513.7
1639.471	749	99.011	-71.589	27.646	21113914.2
1041.017	/46	99.372	-71.444	27.627	21113328.0
1646.763	723	99.189	-71.102	27.581	21111979.7
1649.649	755	99.214	-70.907	27.555	21111197.2
1651.645	809	99.216	-70.775	27.537	21110640.5
1033.038	~. 6 82	99.234	-70.699	27.519	21110043.0
1658.579	-1.135	99.309	-70.323	27.476	21108299.0
1663.789	-1.450	99.519	-69.991	27.430	21105983.2
1665.937	-1.553	99.644	-69.855	27.411	21104874.7
1671.284	-1.045	99.990	-69.521	27.342	21103706.0
1473.444	-1.766	139.128	~69.389	27.344	21100646.7
1675.601	-1.793	100.249	-69.257	27.324	21099381.7
168C.946	-1.016	100.482	~68.936	27.276	21096252.7
1685-424	-1.825	100.583	-68.672	27.235	21099932.0
1687.564	-1.835	100.596	-68.548	27.216	21392439.5
1689.703	-1.839	100.613	-68.425	27.197	21091224.0
	GEWINI		et v		
TIME	RELATIVE FLT.	RELATIVE HEADING	INERTIAL LONG.	CENCENTRIC LAT.	RADIUS TO
13667	(DEGPEES)	(DEGREES)			(FEET)
1697.867	-1.845	100.639	-68.246	27.169	21089447.5
1095.217	-1.850	172.664	-68.008	27.133	21387075.2
1702.467	-1.966	163.601	-67.722	27.088	21084134.0
1704.561	-2.(90	100.541	-67.611	27.071	21082932.2
1769.572	-2.557	166.419	-67.352	27.032	21079724.2
1714-508	-2.8.0	167.495	-67.106	26.995	21075952.0
1716.532	-3.452	100.616	-67.007	26.980	21074267.2
1716.613	-3.694	100.795	-66.907	26.965	21072369.5
1721.675	-3,954	101.094	-66.763	26.942	21069388.7
1725.747	-4.038	101.292	-00.000	20.927	21065276.0
1728.045	-4.131	101.551	-66.477	26.896	21063207.7
1731.225	-4.152	101.527	-66.341	26.873	21060234.0
1733.360	-4.193	121.429	-66.252	26.859	21056279.5
1737.565	-9.196	101.373	-66.080	20.831	21054565.0
1740.829	-4.231	101.247	-65.959	26.812	21051848.7
1742.972	-4.274	101.158	-65.880	26.799	21050105.0
1745.112	-4.322	101.064	-65.803	26.787	21048402.0
1750.417	-9.379	100.411	-65.422	29.170	21044335-0
1752.561	-4.570	100.714	-65.553	26.750	21042748.2
1754.714	-4.68C	100.622	-65.487	26.740	21041189.0
1756.845	-4.P10	107.526	-65.422	26.731	21039653.0
1762.161	-7.630	100.300	-07.331	20.710	21 135893.2

Table B-2b.Reconstructed Reentry Trajectory,
Special Parameters (Continued)

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Table B-2b. Reconstructed Reentry Trajectory,Special Parameters (Continued)

	GEMINI	10 ENTRY TRW BE	et V			88
T1™C (SFC)	FELATIVE FLT. PATH ANGLS (DEGREFS)	PELATIVE HEADING ANGLE (DEGREES)	INERTIAL LONG. Loegrefsi	GEDCENTRIC LAT. (DEGREES)	RADIUS TO Earth Center (Feet)	
1767.172	-6.4-1	99.628	-65.142	26.693	21032183.5	
1769.163	-7.(?9	99.433	-65.093	26.687	21028141.2	
1774.105	-3.941	99.252	-64.981	24.673	21726355.0	
1776.096	-9.796	99.342	-64.938	26.668	21024491.0	
1781.046	-11.837	99.937	-54.840	26.656	21019597.0	
1784.)74	-12.899	100.396	-64.786	26.650	21016521.0	
1786.224	-13.551	100.562	-64.714	26.641	21012226.7	
179(.514	-14.876	103.857	-64.681	26.637	21010145.0	
1795.829	-17.181	100.380	-64.606	26.628	21003154.2	
1800.041	-19.018	99.762	-64.553	26.622	21001182.0	
18(3.318	-21.975	99.404	-64.516	26.618	20998217.0	
1807.673	-25.307	99.801	-64.476	26.514	20994263.5	
18.9.802	-27.073	98.440	-64.450	26.613	20992354.7	
1815.079	-31.892	97.192	-64.403	26.61	20987710.C	
1819.258	-36.164	95.746	-64.369	26.608	20984122.7	
1822.335	-39.4-4	93.445	-04.331	26.607	20979826.0	
1826.494	-43.953	92.261	-54.317	26.627	20978136.5	
1829.571	-47.300	90.104	-64.297	26.606	20975680.0	
1836.857	-55.278	84,220	-64.253	26.607	20970104.2	
1838.941	-57.383	82.470	-64.241	26.607	20968575.7	
	GEMINI	L 1 CENTRY TRW B	5 7 V			89
TIME	FOLATIVE FLT.	RELATIVE HEADING	INERTIAL LONG.	GEOCFNTRIC LAT.	RADIUS TO	
(SEC)	PATH ANGLE (DEGREES)	ANGLE (DEGREES)	(DEGREES)	IDEGREESI	(FEET)	
1841.087	-59.509	80.753	-64.229	26.608	20967024.5	
1843.245	-51.6008	76.343	-64.201	26.6.9	20963295.5	
1848.431	-60.148	74.388	-64.190	26.639	20961865.0	
1851.567	-67.534	72.738	-64.165	26.610	20958441.5	
1855.456	-71.465	69.375	-64.155	26.611	20957112.0	
1860.794	-74.736	63.804	-64.131	26.612	20953940.5	
1868.011	-77.836	56.669	-64.098	26.513	20949740.2	
1870.090	-78.633	56.070	-64.088	26.613	20948583.2	
1075.232	-91.381	61.293	-64.066	26.614	20945891.2	
1877.311	-82.616	66.992	-64.057	26.614	20944875.5	
1882.451	- 13.263	77.456	-64.034	26.614	20942480.5	
1884.529	-84.563	84.273	-64.025	26.614	20941548.2	
1885.602	- 54 . 7 0 1 - 85 . 573	10.298	-64.003	26.614	20939312.5	
1891.756	-85.515	102.580	-63.994	26.514	20938439.5	
1893.839	-86.397	131.968	-63.972	26.614	20936346.0	
1898.996	-85.241	115.352	-63.964	26.614	20935527.2	
1901.072	-85.250	153.643	-63.955	26.614	20933573.0	
1906.230	-85.989	120.648	-63.933	26.614	20932868.0	
1908.307	-43.552	130.235	-63.924	26.613	20932063.5	
1912.393	-84-DUD GEMIN	I 1C ENTRY TRM B	-03.915 ET N	20.015	20731333.0	90
TIME (SEC)	DELATIVE FLT. Path Angle Idegrfes)	RELATIVE HEADING ANGLE (DEGREES)	INSETIAL LONG. LDEGREES)	GEOCENTRIC LAT. IDEGREESI	" RADIUS TO EARTH GENTER (FEET)	
1913.462	-84.040	128.531	-63.902	26.613	20930270.7	
1915.536	-82.338	141.267	-63.893	26.613	20929573.2	
1920.691	-81.817	140.25*	-63.871	26.612	20927885.5	
1927.77	-82.857	149.996	-63.863	26.612	20927216.7	
1927.923	-81.742	141.981	-63.841	26.612	20925590.5	
1930 - 203	-82.899	144.459	-63.832	26.612	20924947.7	
1935.156	-81.407	139.475	-63.810	26.611	20923376.2	
1937.245	- 82.489	136.734	-63.801	26.611	20922753.0	
1942.387	-82.537	139.342	-63.779	20.011 26.611	20921236.0	
1944.467	-81.954	132.082	-63.770	26.610	20920626.2	
1949.62	-81.820 -87.125	127.972	-63.748 -63.739	26.61C 26.61C	20919169.0	
1953.774	-78.395	134.053	-63.730	26.610	20918098.2	
1956.846	-74.373	137.545	-63.717	26.61C	20917588.7	
1961.073	-7: .613	128.951	-63.700	26.609	20917105.0	
1964.075	-61.944	143.376	-63.687	26.609	20916860.0	
1968.232	-44_924	173.593	-63.669	26.639	20910759.2	
1971.30	-45.538	106.715	-63.656	26.679	20916590.0	
1973.384	-55.292	125.758	-03.048	26.508	20916518.2	
1978.525	-554	138.837	-63.626	26.608	20916328.7	
1984.011	-52.077	141.759	-63.617	26.638	20916252.2	

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Table B-2b.Reconstructed Reentry Trajectory,
Special Parameters (Continued)

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	GEMINI	L LC ENTRY TRW	827 1	7		91
TIPE	ROLATIVE FLT.	TELATIVE HEADING	INSTIAL LONG.	GEOCHNTRIC LAT.	8101US TO	
(SEC)	PATH ANGLE	ANGLE	(DEGREES)	(DEGREES)	EARTH CENTER	
	(DEGPF+S)	I DEGREE SI			(FEET)	
1982.645	-50.037	133.342	-63.608	26.638	20916174.5	
1985.749	-48.8-77	149.040	-53.595	26.608	20916059.0	
1987.432	-53,324	171.475	-63.586	26.698	20915978.7	
1989.91:	-53,167	174.300	-63.578	26.607	20915900.0	
1991.986	-53.876	152.972	-63.569	26.677	20915822.2	
1995.055	-43,531	135.612	-63.556	26.607	20915762.7	
1997.125	-40.419	139.727	-63.547	26.607	20915626.6	
1999.204	-47.533	139.911	-63.538	26.607	20915552.0	
2002.284	-57.101	132-034	-63.525	26.636	20915438.5	
26C4.35d	-52.950	153.176	-+3.516	26.636	20915359.7	
2006.439	-51.815	170.944	-63.508	26.606	20915279.7	
2009.513	-50.392	154.213	-63.495	26.606	20915162.9	
2011.591	-52.322	141.068	-63.486	26.606	20915080.5	
2013.666	-44.242	154.467	-63.477	26.656	20914999.7	
2016.742	-42.749	155.454	-63.464	26.605	20914883.2	
2018.82)	-46.176	139.746	-63.455	26.605	23914805.2	
2620.899	-53.843	143.243	-63.446	26.675	20914726.5	
2023.967	-51.584	158.092	-63.434	26.605	20914610.7	
2C2E.048	-53.584	174.802	-63.425	26.635	20914532.0	
2031-199	-53.371	162.514	-63.403	26.674	20914333.5	
2033.279	-47.656	158.467	-03.394	26.674	20914253.5	
2035.356	-50.247	150.600	-63.386	26.604	20414172.C	
2038.429	-56.(18	138.665	-43.373	26.604	20914C48.C	
2045.511	-46.705	152.452	-63.364	26.604	20913967.0	
2042.565	-44.139	148.553	-63.355	26.603	20913887.5	
2045.659	-47.1GC	150.074	-63.342	26.673	20913769.0	
2147.735	-42.875	142.391	-43.333	26.633	20913690.5	
2049.812	-40.834	152.535	-63.324	26.623	20915613.7	
	GENIN	E 1C ENTRY TRU	BET	V		92
T1#F	ATLATIVE FLT.	RELATIVE HEADING	INERTIAL LONG.	GEOCENTRIC LAT.	RADIUS TO	
(SEC)	PATH ANGLE	ANGLE	(DEGREES)	(DEGPEES)	FARTH CENTER	
	(DEGREFS)	(PEGRFE S)			(FEET)	
2652.833	-42.514	162.501	-63.311	26.602	20913497.5	
21 54 . 982	-45.979	161.124	-63.303	26.602	20913417.7	
2057.263	-44,992	154.265	-63.294	26.602	20913338.5	
2060.145	-43.638	154.736	-63.281	26.602	20913222.5	
2062.226	-47.798	159.771	-63.272	26.601	20913141.7	

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APPENDIX C

TRACKER CALIBRATION DATA

1. GE MOD III

The following calibration data were used in the processing of the GE/MOD III tracking data. The values listed below are the parameters which vary from flight to flight; approximately 40 other scaling and calibration biases associated with the MOD III data reduction remain the same for each flight. A complete description of the use of each parameter in the data reduction is included in Section 4.4.2.2 of the TRW Gemini Analysis Plan, Reference 1.

Zero-Set Calibration		
=	-1793.343 ft	
=	-130.72247 ⁰	
=	-15.05196 ⁰	
) =	0.01511 ⁰	
	<u>Cali</u> = = = =	

Refraction

Ground Index of Refraction $(J_2) = 1.000380$

The calibration values used by TRW and GE are, as far as known, identical. The General Electric Co. postflight report on the calibration procedures and flight constants used on this mission may be found in Reference 7. However, the refraction correction calculated by GE is based on the measured atmosphere while the TRW correction relies on an analytical model which is a function of the ground-measured index of refraction. This model is defined in Reference 1. Curves of the TRW refraction correction for a typical Gemini flight are shown in Figures C-1 and C-2.

2. MISTRAM

Responsibility for reduction of the MISTRAM data lies with RCA/ PAA at the Eastern Test Range. Their analysis results are reported in the Gemini 10 "Red Book" of trajectory data, References 4 and 5. The following calibration data were extracted from these documents:



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	R (ft)	P1 (ft)	Q1 (ft)	P2 (ft)	Q2 (ft)
Calibrations	211.6487	-79.4601	-38, 2355	-77.0259	-45.1216
Accumulated transfers	0	-10140.3628	-7.6259	-3.2479	-1.4389
Transponder delay	-8.3700				
BIAS**	-0.0540	-3.8897	1.8573	-2.8815	0.9605
Total	203.2247	-10223.7126	-44, 0041	-83.1553	-45.6000

Index of Refraction

Central Receiver = 1.000387 P_2 Site = 1.000387 Q_2 Site = 1.000387

Having corrected the raw measurements as well as possible, all the available MISTRAM as well as "C" band radar data were used by the ETR to form a minimum variance estimate of the spacecraft trajectory. Additional MISTRAM bias errors are solved for in this regression and are recorded in Table 4-1 of this report for comparison with TRW results. The "fully corrected" but unsmoothed measurement data were used by TRW in their simultaneous IGS/tracker error regression program.

Figure	·S	Page
C-1	GE MOD III Refraction Corrections (Range and Elevation)	C-3
C-2	GE MOD III Refraction Corrections (Range Rate, P, and Q)	C - 4

**Data prior to 153. 55 sec were biased to agree with data after 153. 55 sec. The bias was calculated by extrapolating from 153. 55 sec backwards and agreement of the comparison between 10K and 100K base lines.



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Figure C-1. GE MOD III Refraction Corrections (Range and Elevation)





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REFERENCES

- 1. F. B. Lavenhar, "Preliminary Gemini G and C Data Reduction and Analysis Plan, " Technical Report 4160-6009-TU-000, TRW Systems, 30 October 1964.
- R. Sansom, "Gemini Inertia Measurement Unit Accuracy Prediction Study (U), " Technical Report 4160-6016-TW000, TRW Systems, 8 February 1965 (Confidential).
- "Gemini 10 Orbit and Reentry Trajectory Reconstruction," Technical Report 05952-6061-R000, TRW Systems, 14 November 1966.
- 4. "Final Flight Test Data MISTRAM Coordinate Systems No. 1 and 3, AFETR Test No. 3287," Gemini Missile No. GT-11, OD Item 9.2.1.3-20, AFETR Data Reduction, no date.

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- 5. "Final Flight Test Data Best Estimate of Trajectory Coordinate Systems No. 1 and 3, AFETR Test No. 3287," Gemini Missile No. GT-11, OD Item No. 9.2.1.3-26.
- 6. "NASA Gemini Mission Program Report, Gemini 11 (U) MSC-G-R-66-8, November 1966 (Confidential).
- 7. "Flight Test Report MOD III Guidance System With Gemini Launch Vehicle 10" Range Test No. 6833 Gemini Titan 10 (U), dated 18 July 1966, General Electric Company.

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