

E-1142 (REV. 17) (UNCLASSIFIED TITLE)

SYSTEM STATUS REPORT

February 15, 1964



# INSTRUMENTATION LABORATORY

CAMBRIDGE 39, MASSACHUSETTS

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#### ABSTRACT

The System Status Report is distributed monthly on the 15th. This month's revision (E-1142, Rev. 17) contains, in general, the following information for the Block I and II Command Module and LEM equipment configurations: weights, centers of gravity, moments of inertia, power requirements, status of computer programs, and reliability figures.

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#### Section 1

#### INTRODUCTION

#### 1-1 INTRODUCTION

The definition of what constitutes Block I and Block II Command Module and LEM hardware is contained in the Glossary, section 5 of this report.

The following information is included in this month's report:

- (1) Command Module, Block I weights, centers of gravity, moments of inertia, and power requirements.
- (2) Command Module, Block II weights, power requirements, status of computer programs, and reliability figures.
- (3) LEM weights, power requirements, and reliability figures.

Weights in this report for both the Block I and Block II Command Module are based upon current Block I design releases. The Lunar Excursion Module weights are based on the best estimate of those expected for the LEM design release which will occur early this year.

#### 1-2 ACCURACY

The accuracy of numerical values reported in this revision should not be considered to be within the tolerances implied by the significant figures quoted. The reported values, although based upon the most current information, are subject to normal changes as design and development phases approach completion.

#### Section 2

#### BLOCK I COMMAND MODULE DATA

#### 2-1 WEIGHTS

Table 2-I presents the weights of all Block I equipment, grouped according to specific location within the Command Module. Weights are reported to the component level and to the nearest tenth of a pound.

Given component weights are identified as estimated, calculated, and measured in the order of increasing accuracy. These terms are defined by North American Aviation as follows.

Estimated weights (E) are based on rough calculations. Calculated weights (C) are based on detailed calculations made from final production drawings that will be used to build flyable equipment. Measured weights (M) are the actual weights of equipment built to the production drawings.

Since most weight values now reported can be classified as only estimated weights, MIT herein affixes a prime to the (E) symbol, i.e., (E'), to denote values which MIT, for various reasons, feels to be more accurate than estimated values, yet which cannot be defined as either calculated or measured weights.

North American Aviation will provide and be responsible for coldplate weights which are not integral with guidance and navigation equipment.

2-1.1 WEIGHTS STATUS REPORTING. Table 2-I also offers a comparison of present component weight values with those listed in System Status Report, E-1142 (Rev. 16), January 15, 1964. All weight changes are explained in paragraph 2-2.

2-1.2 SPEC. WEIGHT. The "Spec. Weight" column in table 2-I contains "proposed MSC weights," that is, goals set forth by MSC in a memo to MIT dated December 5, 1962.

2-1.3 DESIGN LOAD WEIGHT. The "Design Load Weight" column contains worstestimate design weights assigned to G&N subassemblies attached to the spacecraft structure. These values are included in this report as the result of an S&ID request, at NASA Coordination Meeting No. 8, that one total weight figure for supported G&N load be assigned for structural design use. MIT herein assigns a total G&N design load weight, in table 2-I, which does not include items termed "loose stored items."

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COMMAND MODULE

BLOCK

Table 2-1. Current	t weight stat	ULS OF PLOCK			s ar T Bi	Design	
	Spec. Wt.		Status		Status	Load Wt.	
Item	12/62		1/64		2/64	2./64	
	(a)	(b-a)	(q)	(c-b)	(c)	(q)	
LOWER EQUIPMENT BAY							
CDU & Frame Assv	6.0	+ 8,5	14.5(M)	0.0	14.5(M)	17.2	
Optical Subsystem							
SXT	12.0	+ 2,6	14.6(C)	0,0	14.6(C)-		
SCT	9°0	+ 4.8	13.8(C)	0°0	13, 8(C)		
Optical Base & Gearing	14.0	+ 2,7	16.7(E)	0 : 0	16 7(E)		
Optical Eyepieces							
SXT	° T	ی _ +	1 3(E)	0°0	1.3(E)	154.2	
SCT	, , ,	) 4	2.3(E)	0 ° 0	2, 3(E)		
DMI	40 0	+ 20.5	60.2(M)	0,0	60.2 M		
NVB & Sheek Mounts	16.0	+ 11.2	27, 2(E)	-2.2	25.0(E)		
Bellows Assy	0°%	+ 5.5	13 5(M)	0.0	13.5(M)-		
G&N Interconnection Assy	30.0	+ ]3 9	35_2(E)	0,0	35.2(E)	42, 8	
G&N to S/C Interface Assy	2 2 2	1 0 1	8 0(E.	0,0	×. 0(E)	1	
D&C Nav Station							_
IMI Control Panel			-2 4(M	0°0	2 4(M)	2°2	
D&C Electronics		- 1012 121	2.9(M)	0°0	2 9(M)-	1	
Control Electronics	<b>∳</b> 30,3		2 9(E )	0.0	2 9(E	<b></b>	
Optical Shroud			5, 2(M)	0.0	5 2 M	4 2	
G&N Ind Cont Panel			-9.5(M)	0.0	9, 5 (M	13.2	
D&C/AGC	15.0	+ 4.6	19. 6(C)	+1 0	20, 6(M)	19.4	
MDV (including 1 film)	5,0	+ 2.7	7.7(C)	0.0	7, 7 (C	10.0	
AGC no spares:	80.0	- 10, 0	70, 0(E)	0,0	70 0/E	126.4	
PSA	25.0	+ 34, 4	59.4(C)	0°0	59,4(C)	65 ° 0	
Coolant Hoses	0 0	+ <b>1</b> , 0	1 0(E')	0.0	1.0(E)		
		- 14					
	-	(cont)		-			
		•					

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2-1. Current Weight Status of Block I Command Module (lbs at 1 g) (cont)	n Spec. Wt. Status Status Design $12/62$ (a) (b-a) (b) (c-b) (c) (d) (d)	AREA5.0 $+ 14.5$ $19.5(C)$ $+1.0$ $20.5(M)$ $17.2$ $8.0$ $- 8.0$ $- 8.0$ $$ $$ $$ $$ $8.0$ $- 8.0$ $$ $$ $$ $$ $8.0$ $- 8.0$ $$ $$ $$ $$ $8.0$ $- 8.0$ $$ $$ $$ $$ $8.0$ $- 8.0$ $$ $$ $$ $$ $1.5(E)$ $0.0$ $1.5(E)$ $0.0$ $1.5(E)$ $eces$ $$ $+ 2.4$ $2.4(E)$ $0.0$ $2.4(E)$ $eter$ $$ $+ 3.6$ $3.6(E)$ $0.0$ $3.6(E)$	305.3         +109.6         414.9         -0.2         414.7         *484.1	Spares for     *Does not       Spares for $*$ Does not       Spares for $*$ Does not       c Tray $*$ Does not       c Tray $0.0$ c Tray $0.0$ $25.0(E)$ $0.0$ $25.0(E)$ $0.0$ $25.0(E)$ $0.0$ $25.0(E)$ $0.0$ $27.0(E)$ $0.0$ $27.0(E)$ $0.0$ $16.7(E)$ $0.0$ $0.3(E)$ $0.3(E)$
Table 2-I. Current Weight	Item [3] [3] [3] [3] [3]	MAIN PANEL AREA       5.         0&C/AGC       8.         0&C/NAV       8.         0.00SE STORED ITEMS       8.         100SE STORED ITEMS       9.         100SE STORED ITEMS       9.	TOTAL 305.	List of Possible Spares for Block I AGC Spare Logic Tray AGC Spare Memory Tray SA Spare (Unique) Modules SDU Spare pare Relay & Diode Module

ł

The breakdown of this total weight into the individual items of column "d" is typical only.

#### 2-2 REPORTED WEIGHT CHANGES

The Block I weight status summerized in table 2-I separates the weight of possible spares from the main body of the table. This was done in recognition of the Development Test Plan activities now under way at S&ID which are defining Block I G&N usage. Since any spacecraft flights involving Block I G&N hardware will be unmarned or of only limited duration, the need for carried spares is doubtful. (Block II G&N will carry no spares in any event.) Because Block I was originally designed to use spares for inflight repair, the weight of possible spares is listed separately for information in table 2-I.

Other changes since last month's report, E-1142 (Rev. 16). January 15, 1964, shown in table 2-I are explained below.

2-2.1 NVB & SHOCK MOUNTS. The 2.2-pound weight decrease is due to (1) a change from a steel to an aluminum shock mount housing and (2) use of a solid instead of a brazed NVB structure.

2-2.2 D&C/AGC (LEB AND MAIN PANEL) The weight increases are due to the weighing of AGE 4B D&C/AGC's. The urethane foam potting, estimated at 0.5 lbs, was not weighed but is included in the total D&C/AGC weight value.

#### 2-3 CENTERS OF GRAVITY

Table 2-II presents the centers of gravity of each weight component or packaged assembly, determined with respect to the basic X, Y, Z, axes of the Command Module. Center of gravity values are given to the nearest tenth of an inch.

#### 2-4 MOMENTS OF INERTIA

Table 2-II also presents the moments of the inertia of each weight component or packaged assembly, determined about each of the component axes which (1) run through the center of gravity of the component and (2) are parallel to the basic X, Y, and Z axes of the Command Module.

#### 2-5 COMMAND MODULE POWER REQUIREMENTS

The power requirements of the Command Module G&N equipment on the primary +28 VDC power supply are shown in figure 2-1, which presents the magnitude and location of dissipated power values on a subassembly level. This chart assumes a

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14-day lunar orbit mission as defined by S&ID for power profile computation (Ref: S&ID letter 63 MA 7332).

Table 2-III shows the magnitude and location of power dissipation for the established G&N activities, each of which consists of various power levels of operation.

Table 2-IV shows the energy requirements for each G&N activity on a power level basis. The table is based upon MIT letter AG 679-6, "G&N power Profile Status," dated August 14, 1963. The vertical column to the left indicates the various G&N activities (phases of operation) for the model 14-day mission submitted by S&ID in S&ID letter 63 MA 7332. This column also indicates the power consumption and operating time for each specific activity. The top row indicates the various power levels along with the power consumption and operating time of each power level.

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COMMAND MODULE

Table 2-II. Block I C	Command M	lodule Cen	tter of Gra	vity and M	loments of	Inertia	
	Weight	Cente	rrs of Grav (inches)	ity	Mome	nts of Iner (Ih_in <sup>2</sup> )	tia
Item	(lbs)						
	-	×	>	2	Ixx	Ivv	Izz
				ſ		60	
LOWER EQUIPMENT BAY							
CDU & Frame Assy	14.5	63.5	- 14.4	35.8	45	410	410
Optical Subsystem							
SXT	14.6	70.5	- 3.5	34.7			
SCT	13.8	70.5	5.5	34.7			
Opt. Base & Gearing	16.7	67.9	0.0	30.7			
<b>Optical Eyepieces</b>							
SXT	1.3	65.1	- 3.5	26.2	ວ	10	വ
SCT	2.3	65.1	4.5	26.2	10	10	10
IMU	60.2	56.6	0.0	41,7	1186	1450	1438
NVB & Shock Mounts	25.0*	<b>b</b> 64.3	- 0.1	41.3	3270	4050	5210
Bellows Assy	13.5 —		;	)   	, , ,	- 	
G&N Interconnection Assy	35.2						
G&N to S/C Signal Assy	8.0						
D&C/NAV Station							
IMU Cont Panel	2,4	74.0	- 15.4	30.9	15	22	24
D&C Electronics	2,9	49,5	- 9.6	39,6	20	22	6
Control Electronics Assy	2,9	63.1	10,7	34.9	6	15	œ
Optical Shroud	5.2	66, 8	0,0	28.9	387	108	413
G&N Ind. Control Panel	9 <sup>.</sup> 5	54, 1	0,1	33, 9	460	120	580
D&C/AGC	20 6*			-			
MDV (Includes 1 film)	7.7	73 . 5	- 4.5	31.0		197.97	
AGC (no spares)	70,0	37. 8	1-3	46.1	4980	3990	1710
Spare Tray (logic)	25.0	3×.2	- 7.7	45.3	1290	1360	140
	7						
			-				
		00)	nt)				

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BLOCK I

1	<u></u>		······					
it.)	rtia	Izz	2620		a。)		1964 .	
nertia (con	ents <sub>2</sub> of Ine 1-in )	Iyy	1460		: 2-1/4" d	inches)	anuary 15,	
ments of h	Mom( (It	İXX	3940		, SXT 3" , x 6 inches	6 x 5 1/2	), dated J	
ty and Mo	ity	2	41.5		-1/2" dia. 1-1/2 x 3	0 x 1-13/1	2 (Rev. 16	
er of Gravi	rs of Grav (inches)	Y	- 1.1		t-5/8" x 2- årtridge,	imately 6. 2 inches)	3 inches) ¢t, E-114	
dule Cente	Cente	×	45.0		(SCT, 4 (Each c	(approx (3 x 3 x	(6 x 6 x e last repc	
mmand Mo	Weight (Ibs)		59.4 1.0	20.5*	1.5 2.4 6	2.5 0.3 0.3	3.6 16.7 s since the	
Table 2-II. Block I Cor	Item		PSA Coolant Hoses	<u>MAIN PANEL AREA</u> D&C/AGC	LOOSE STORED ITEMS Eye Relief Eyepieces (2) Film Cartridges (4)	CDU Spare Gearbox Spare Relay & Diode Mod.	Horizon Photometer PSA Loose Spares *These values represent change	

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Figure 2-1. Electrical load on primary + 28 VDC power supply

\*.

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	Table 2–1	III. No	minal	Power D	issipati	ion (wa	atts) v	s G&N Activity	V	
X O		[N	BA		PS	ŚA		Thermal	D&C	
Ащ	G&N Activity (power levels)	IMU	OBA	CDUJB	IMU	OBA	AGC	Load On S/C Coolant	and S&C	Electrical Load
A	IMU & AGC Operate (1,4)	74.5	0	22.1	233.5	0	110	440.1	10.7	450.8
В	IMU Alignment (1, 2, 4, 6)	74.5	39	44	233.5	63.6	110	564.6	42.7	607.3
υ	Low-Orbit Navigation (1,3,4,6)	74.5	33.8	44	233.5	59.8	110	555.6	42.7	598.3
Q	Standby & Computing (1,5)	25.5	0	0	41.2	0	110	176.7	10	186.7
E	Midcourse Navigation (1, 2, 5, 6)	25.5	39	21.9	41.2	63.6	110	301.2	42	343.2
Ъ	IMU & AGC Standby (5,7)	25.5	0	0	41.2	0	10	76.7	0	76.7
Ū	IMU Operate & AGC Standby (4,7)	74.5	0	22.1	233.5	0	10	340.1	0.7	340.8
J		6 5 4 % 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Hick, Structures, Structures, Structures, Structures, U Open U Open U Stan	SXT on SXT off rate dby nd Contr	<u>ة</u>	120 111. 102. 330. 66.	watt watt 1 watt 1 watt 8 watt 7 watt 4 watt	ស់ សំ សំ សំ សំ សំ សំ		
			IC DIAL	luby		٦T	Wäu	S		

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4.979 1.04525.564 2.2893.543 18.743 2.50458.667 Total (7) AGC Standby 10.0 watts 251.74 hrs 2.5162.4430.073 ł ł ł ł ł (6) Display& Controls45.4 watts22.36 hrs 0.3721.013 0.173 0.468ł ł ł ł 66.7 watts 260.32 hrs Energy Consumption (kwh) (5) IMU Standby 0.689 0.37316.30017.362 ł ł ł ł 330.8 watts 76.09 hrs (4) IMU Operate 18.759 2.7121.2662.43125.168ł ł ł 102.1 watts 3 (3) Optics SXT off 0.3910.391ł ł ł ł ł 1 111.1 watts 18.53 hrs (2) Optics SXT on 2.0580.911 1.147ł ł ł ł ł (1) AGC Operate 120 watts 84.67 hrs 6.805 0.984 0.4591.23910.159 0.6721 ł IMU & AGC Operate 450.8 watts, 56.71 hrs 76.7 watts, 244.39 hrs Midcourse Navigation 343.2 watts, 10.33 hrs IMU Alignment 607.3 watts, 8.20 hrs Standby 340.8 watts, 7.35 hrs Low-Orbit Navigation 598.3 watts, 3.83 hrs Standby & Computing 186.7 watts, 5.60 hrs IMU Operate & AGC G&N Activity IMU & AGC Standby TOTAL c Ω Э щ Гч σ хоры 4

# Table 2-IV. Block I Command Module Power Profile for 14-Day Lunar Orbit Mission

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#### MODULE COMMAND



#### Section 3

#### BLOCK II COMMAND MODULE DATA

#### 3-1 RELIABILITY

The following numbers do not assume the use of inflight spares or repair. The estimated Command Module G&N reliability is based on the 138-hour mission as defined in the Lunar Landing Mission Design Plan.

Subsystem	Operating Time (hrs) Full Power	Probability of Mission Success
IMU AGC (2) DSKY PSA CDU (5) Optičs	31 19* 19 31* 31 18	0.99575 0.999913 0.999954 0.994 0.9942 0.9985
Total G&N	l System	0.9824

Table 3-1	I. Relia	bility (	(as of	2/	15/6	54)
-----------	----------	----------	--------	----	------	-----

\*Certain assemblies function continuously.

#### 3-2 WEIGHTS

Table 3-II presents the weights of all Block II equipment. Refer to section 2-1 for a general explanation of weight reporting.

#### **3-3 REPORTED WEIGHT CHANGES**

Weight changes shown in column (c - b) of table 3-II are explained below.

3-3.1 D&C/AGC (LEB AND MAIN PANEL). The weight increases are a reflection of Block I weight changes (see 2-2.2).

3-3.2 PSA COVER. This is a new item which is required to protect the Malco connectors against moisture.

3-3.3 SXT AND HORIZON PHOTOMETER. The horizon photometer is incorporated into the SXT in Block II and will henceforth be included in the weight of the SXT.

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CONTRACTOR

Table 3-II. Cur	rent Weight	: Status of E	<b>Block II Com</b>	mand Modu	le (lbs)	
						Design
	Spec. Wt.		Status		Status	Load Wt.
ITEM	12/62		1/64		2/64	2/64
	(a)	(b-a)	(q)	(c-b)	(c)	(d)
LOWER FOUTPMENT BAY						
CDU & Frame Assy	6.0	+ 9.0	15.0(E)	0.0	15.0(E)	17.2
Optical Subsystem				-		
SXT	12.0	+ 2.6	14.6(C)	+ 30%-69	18-8 (C)-	C
SCT	9.0	+ 4.8	13.8(C)	0.0	13.8(C)	
Optical Base & Gearing	14.0	+ 2.7	16.7(E)	0.0	16.7(E)	
<b>Optical Eyepieces</b>	·······					
TXS	2.0	+ 1.6	1, 3(E)	0°0	1.3(E)	<b>F154</b> .2
SCT	)		$2 \cdot 3(E)$	0°0	2.3(E)	
IMU	40.0	+ 2.0	42.0(E)	() () () () () () () () () () () () () (	42.0(E)	_
NVB & Shock Mounts	16.0	+ 6.0	22.0(E)	0.0	22.0(E)	
Bellows Assy	8, 0	+ 5.5	13 · 5(M)	0.0	13.5(M)	
G&N Interconnection Assy		ر ۱۰ ۲۰ ۲	-35.2(E)	0.0	35.2(E) -	42.8
G&N to S/C Interface Assy	<b>1</b> 20° 0	+ 13.4	<u> </u>	0.0	8.0(E) –	7
D&C Nav Station						
D&C Electronics	<i>C</i>		1, 5(E)	0 . 0	$1 \cdot 5(E) -$	7.7
<b>Control Electronics</b>	<b>5</b> 30 3	- 9.6	2.9(E)	0.0	2.9(E)	- - -
Optical Shroud		)	5,2(M)	0.0	5.2(M)	4.2
G&N Ind Cont Panel			11.1(E)	0.0	11.1(E)	13,2
D&C/AGC	15.0	+ 4 6	19.6(E)	+ 1°0	20, 6(E	19,4
M&DV (including 1 film)	2 0	က က +	8.3(E)	0,0	8.3(E)	10.0
AGC (2 complete computers)	000	10 5 4	-×4 0 E	0,0	84 0 E -	126.4
AGC Covers (2)		- 77 - 77	×, 5(E)	0,0	×, 5 (E) −	
				0 0	41 6(E)	
PDA DEA Conce	<b>7</b> 25, 0	+ 16, 6		ນ. ເມີຍ -	3.5(E)	65.0
For Uover	0.0	+ 1.0	$1.0(E^{-1})$	0.0	1.0(E)	

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(cont)

BLOCK II COMMAND MODULE

1

	Design Load Wt.	2/64 (d)	17.2		*477.3	*Minus loose stored items
bs) (cont)	Status	2/64 (c)	20.5(E) 	1.5(E) 1.8(E) 0.0	400.0	
nd Module (1		(c-b)	+ 1.0	0.0 0.0 3.6	+ 5.5	
: II Comman	Status	1/64 (b)	19.5(E) 	1.5(E) 1.8(E) 3.6(E)	394.5	
tus of Block		(b-a)	+ 14.5 - 8.0	+ + + 3.6 8	+ 89.2	
t Weight Sta	Spec. Wt.	12/62 (a)	5.0 8.0		305.3	
Table 3-II. Curren		Item	<u>MAIN PANEL AREA</u> D&C/AGC D&C/NAV	LOOSE STORED ITEMS Eye Relief Eyepieces Film Cartridges (3) Horizon Photometer	TOTAL	

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#### 3-4 STATUS OF COMMAND MODULE AGC PROGRAMS

Table 3-III lists current Command Module memory estimates and the status of AGC programs. The status of LEM AGC programs is not reported at this time.

A high and low word estimate is given with each program. Each status is defined as follows:

- (1) Planning stage
- (2) Programming stage
- (3) Checkout on AGC simulation
- (4) Checkout on G&N simulation
- (5) Checkout on AGC

of Command Module AGC Programs				
Program	Status	Memory (wor	Memory Estimate (words)	
		High	Low	
List Processing Interpreter AGC Executive	(5) (5)	1600 250	$\begin{array}{c} 1600\\ 250 \end{array}$	
AGC Waitlister	(5)	150	150	
AGC System Exerciser, Checkout, and Error Handler	(3)	1000	750	
G&N System Exerciser & Checkout	(2)	1000	750	
Display, Keyboard, and Telemetry	(5)	1500	1500	
Input/Output Control	(4)	850	350	
Midcourse and Orbital Navigation	(4)	2000	1500	
Midcourse and Orbital Guidance	(3)*	500	500	
Prelaunch Platform Alignment	(5)	400	400	
In-Flight Platform Alignment	(2)	980	900	
Re-entry Control	(2)	1290	1024	
Injection and De-Boost	(3)*	1000	400	
Totals		12520	10074	

# Table 3-III. Current Memory Estimates and the Status

\*These items have changed since the last report, E-1142 (Rev. 16), dated January 15, 1964.

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#### BLOCK II

# COMMAND MODULE

#### **3-5 POWER REQUIREMENTS**

The power requirements of the Block II Command Module G&N equipment on the primary +28 VDC power supply are shown in figure 3-1, which presents the magnitude and location of dissipated power values on a subassembly level. This chart assumes a 14-day lunar orbit mission as defined by S&ID for power profile computation (Ref: S&ID letter 63 MA 7332).

Major changes to Block II power requirements, as compared to Block I requirements, are due to the use of two computers and electronic CDU's in the Block II system.



Figure 3-1. Electrical load on primary +28 VDC power supply

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#### Section 4

#### LUNAR EXCURSION MODULE DATA

#### 4-1 POWER REQUIREMENTS

The estimate for LEM power and energy consumption is updated this month based upon recent command module G&N Block II data and a submission by GAEC of preliminary ICD LIS-390-2 which contains new changes in the LEM Electrical Load Analysis Form.

The values shown in Table 4-I are center value estimates and do not include any safety factor for bad estimating. Transient power peaks, occurring at higher power levels during turn-on and slewing operations, are considered to consume negligible energy. When they become available, data on these peaks will be included.

	Power (watts)	Time* (hrs)	Energy (kwh)
IMU Standby IMU Operate AGC Standby AGC Operate Radar CDU Optics Display & Controls	58.5 281.7 10.0 95.0 24.0 negligible 12.2	123     12     36     12     12     3.0	7.2 3.4 0.4 1.1 0.3 0.04
Radar (not included)			
Totals	413 (peak)		12.4

Table 4-I. LEM Power Requirements (Updated 2/15/64)

\*Based upon preliminary ICD LIS-390-2 Electrical Load Analysis Form.

Separate power turn-on switches are assumed for "IMU operate." "computer standby," "computer operate," and "radar CDU." The LEM G&N uses only the spacecraft +28 VDC power supply except for operation of condition lights. The condition lights operate from the spacecraft 400-cps power supply.



#### 4-2 RELIABILITY

The numbers in Table 4-II do not assume the use of inflight spares or repair. LEM reliability calculations were based on the guidance and navigation mission profile as directed by MSC for reliability planning.

Subsystem	Operating Time (hrs)	Probability of Mission Success
IMU	7	0.999
AGC	7	0.99769
PSA	7	0.99896
CDU (5)	7	0. 998965
OMU	1	0.999957
Total G&N System	L	0.9946

Table 4-II. Reliability (as of 2/15/64)

#### 4-3 WEIGHTS FOR LEM

Lunar Excursion Module weights are presented in table 4-III. In general the data conform to the information contained in paragraphs 2-1 and 2-1.1.

Column (a), Target Weight, was taken from GAEC LMD 490-39, Enclosure 1, submitted to MIT at a weights review meeting on September 10, 1963. GAEC reported that G&N weights associated with D&C will be reported by them as part of the total spacecraft D&C. Therefore, target weights were not given by GAEC to supply the five items denoted by asterisks in column (a).

The row labeled Bare Guidance System is inserted to provide for comparisons with similarly specified systems.

#### 4-4 REPORTED WEIGHTS CHANGES

Weight changes shown in column (c - b) of table 4-III are explained below.

4-4.1 PSA. The PSA weight decrease is due to a preliminary layout recently completed on a header/cold plate installation. The toe cap (0.5 lb.) is no longer required, but the plane area of the header increased from 50% to 60% of the Block II Command Module header. See Appendix A for a modular weight list of the LEM PSA.

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	Design Load Wt. (d)	* *		
at 1g)	Status 2/64 (c)	15.0 (E) 24.5 (E)  2.0 (E) 5.0 (E) 42.0 (E) 19.5 (E) 19.5 (E) 19.5 (E) 41.5 (E) 41.5 (E) 2.4 (E) 2.4 (E) 2.4 (E) 	208.0	105.3
ponents (lbs	(c-b)	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	+ 4.5	27 71 1
M G&N Com	Status 1/64 (b)	15.0 (E) 24.5 (E)  2.0 (E) 5.0 (E) 42.0 (E) 19.5 (E) 19.5 (E) 19.5 (E) 19.5 (E) 2.0 (E) 41.5 (E)  27.0 (E) 	203.5	110.5
eights of LE	(b-a)			
stimated We	Target Wt. 8/63 (a)	ى * 30 € * * 50 50 * * 50 × 80 50 * * 50 * 1 50 * 1 50 * 50 * 50 * 50	191 Plus * Items not yet given	
Table 4-III. F	Item	CDU's Telescope and All Eyepieces Navigation Base Eye Register for Reticule Two-Digit Readout for Reticule IMU AGC/PSA Interconnection AGC/PSA Interconnection AGC Display and Controls Other Display and Controls Book of Procedures, etc. AGC AGC Cover PSA Cover PSA Cover Cold Plate	TOTAL	Bare Guidance System (IMU, PSA, and computer): ** No design load weight has been assigned

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4-4.2 PSA COVER. This is a protective cover added to protect PSA module connections from moisture during flight.

4-4.3 AGC COVER. This is a protective cover added to seal the Malco connections against moisture.

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#### Section 5

#### GLOSSARY AND SYSTEM DEFINITION

#### Apollo Guidance Computer (AGC)

<u>CM BLOCK I</u> A single complete flight computer containing all logic, memory, associated power supplies, and all interface circuits except those identified with the CDU's. Does not contain the associated displays and controls.

Consists of two trays containing replaceable electronic modules, the AGC end connector, and toe plate. Does not include the necessary cold plate or the G&N to CM interface assembly which is located in the adjacent area. Space exists for carrying an extra spare pair of AGC trays. These would not function in this spares location but could interchange with faulty trays in the active position. The spare trays are not included in this accounting.

<u>CM BLOCK II</u> Two complete and active computers each having the same functions as the Block I AGC.

Consists of two wiring matrix headers mounted on each side of the cold plate. This cold plate is not included in this accounting and must be moved up from the Block I configuration location. The modules of the "X" computer mount on one of these headers, the "Y" computer on the other.

Block I and Block II AGC's are not interchangeable.

<u>LEM</u> A single complete flight computer having the same functions as one of the Block II computers. Unless installation constraints yet to be determined prevent it, the LEM computer will be physically identical with one of the Block II computers.

#### AGC Covers

CM BLOCK I Not required.

<u>CM BLOCK II</u> Two covers, one for each computer, may be required if it becomes necessary to seal the Malco connectors against moisture.

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LEM Same as Block II except that there is only one cover.

#### AGC Spares

<u>CM BLOCK I</u> Spare AGC modules or trays as indicated.

CM BLOCK II No spares for AGC in Block II.

LEM No spares for AGC in LEM.

#### Alignment Optical Telescope (AOT)

CM BLOCK I AND BLOCK II Not in CM, see Optical Subsystem.

<u>LEM</u> A 3-position periscope with single-degree-of-freedom manually read reticule for alignment of the IMU.

#### Bellows Assembly

<u>CM BLOCK I and CM BLOCK II</u> Flexible pressure seal between CM structure and optical subsystem on NAV BASE for penetration of pressure hull with optics.

LEM Not identified separately in LEM. Is included in LEM as part of the AOT.

#### Book of Procedures

CM Not in CM; see MDV.

<u>LEM</u> Book or other form of maps, charts, procedures, instructions, etc., needed for lunar operations.

#### CDU and Frame Assembly

The CDU provides the necessary signal interfaces among the IMU gimbal angles, optics gimbal angles, radar gimbal angles, angle registers in the AGC, the space-craft autopilot attitude error signals, and the tracking radar command error signals.

<u>CM BLOCK I</u> Five interchangeable gear boxes each with necessary motor, tach, resolver synchros, and encoder with mounting framework. Does not include associated electronics which are located in the PSA.

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<u>CM BLOCK II</u> Functionally identical to Block I except the instrumentation is all electronic. Includes all support electronics including special power supply and is located in same volume as Block I CDU's.

Changes in resolver synchro characteristics and mode controls make Block I and II CDU's noninterchangeable.

LEM Interchangeable with CM Block II CDU's.

#### Cold Plate

<u>CM BLOCK I and BLOCK II</u> Cold plates for the IMU are built into the IMU. Necessary cold plates for electronics are part of the equipment supplied by the spacecraft manufacturer.

#### Control Electronics Assembly

<u>CM BLOCK I</u> Consists of one power transformer, one relay and diode module, and a bracket end connector. Used to support display and control functions.

CM BLOCK II May be relocated with other similar functions.

LEM Not defined in LEM.

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#### Coolant Hoses

<u>CM BLOCK I and CM BLOCK II</u> Consists of (1) three aluminum flex coolant hoses between IMU and spacecraft, optics and spacecraft, and optics and IMU, (2) bracket assembly screws and clamp, and (3) entrapped coolant.

LEM Not identified as part of LEM.

#### Display and Control/Apollo Guidance Computer (D&C/AGC)

<u>CM BLOCK I and BLOCK II</u> Number displays and keyboard control associated with the operation of the AGC. Two functionally identical and parallel operation units: one in lower equipment bay and one on main panel between left and center couches.

LEM Identical to CM except only a single unit is required.

#### D&C Electronics Assembly

CM BLOCK I Consists of a chassis, a relay and diode module, a Demod. Elect.

module, a saturable reactor, a time delay module, a connector, and wiring. Used to support displays and control functions.

CM BLOCK II Similar and probably identical to Block I.

LEM Not defined in LEM at this time.

#### Eye Register for Reticule

 $\underline{CM}$  Not in  $\underline{CM}$ .

<u>LEM</u> Device or equipment not defined yet in detail to position the LEM pilot's eye to use the window marking reticule pattern for landing point observation and selection during the constant flight path phase of landing.

#### Film Cartridges

<u>CM BLOCK I and BLOCK II</u> Consists of film cartridges and film for map and data viewer.

LEM Does not exist in LEM.

#### G&N Indicator Control Panel

<u>CM BLOCK I and BLOCK II</u> Consists primarily of controls and displays for the operation of the optics, and the IMU temperature control. Includes display and control elements, panel, panel writing, and supporting hardware.

LEM Not defined at this time for LEM.

#### **G&N** Interconnection Assembly

<u>CM BLOCK I</u> Consists of PSA End Connector Assembly and interconnect wiring harness which electrically ties together the assemblies that constitute a completely integrated system. This term does not include the G&N to CM Interface Assembly weight or the weights of harness support brackets which are a NAA responsibility.

CM BLOCK II Similar to Block I but not interchangeable with Block I.

<u>LEM</u> Not clearly defined at present, was called in earlier reports the AGC/PSA Interconnection Assy. Because of the wide separation of G&N components, most interconnection will be accomplished as part of spacecraft wiring.

#### <u>G&N to S/C Interface Assembly</u>

<u>CM BLOCK I</u> Interconnections between the spacecraft wiring channel, the computer end connector, and the PSA end connector. Contains no active electronics.

<u>CM BLOCK II</u> Similar in function to Block I except the configuration is much different and not interchangeable with Block I.

**LEM** Not identified yet as a separate item in LEM.

#### Horizon Photometer

<u>CM BLOCK I</u> Not all Block I systems will contain this function, but to support expected early unmanned flights using Block I this will be incorporated into later Block I systems for preflight qualification and flight test. Equipment is defined below. Block I weights assume horizon photometer.

<u>CM BLOCK II</u> An earth horizon brightness photometer and automatic star tracker for navigation measurements against the earth's illuminated limb. The sensors are incorporated into the head of the SXT, the weight of which includes this function. The PSA includes support electronics.

LEM Not part of LEM.

#### Inertial Measurement Unit (IMU)

<u>CM BLOCK I</u> Size 14 IMU (14-inch case diameter) gimbal assembly including all parts inside hermetic case and including entrapped coolant.

<u>CM BLOCK II</u> Size 12.5 IMU functionally interchangeable with Block I unit, but not physically interchangeable with Block I.

<u>LEM</u> Size 12.5 IMU as described above.

#### IMU Control Panel

<u>CM BLOCK I</u> Consists of panel, wiring, attitude error meter, CDU transfer switch, manual alignment switch, CDU mode control switches, connector, and supporting hardware.

<u>CM BLOCK II</u> Does not exist in Block II. Moding is done by AGC program and AGC push buttons.

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LEM Not defined at this time for LEM.

#### Indicator Control Panel

<u>CM BLOCK I and BLOCK II</u> Consists primarily of controls and displays for the operation of the optics and the IMU temperature control. Includes display and control elements, panel, panel wiring, and supporting hardware.

LEM Not defined at this time for LEM.

#### Long-Eye-Relief Eyepieces

<u>CM BLOCK I and BLOCK II</u> Consists of a SXT and a SCT eyepiece to provide eye relief of at least 1.6 inches for closed-visor operation. Used in place of normal eyepieces of SXT and SCT.

 $\underline{\text{LEM}}$  Long-eye-relief eyepieces for the AOT is included as part of the AOT in this accounting.

#### Map and Data Viewer (MDV)

<u>CM BLOCK I and BLOCK II</u> Film viewer for display of maps, charts, procedures, etc. Weight includes one film cartridge for Block I MDV and tentatively two for Block II MDV.

LEM Not in LEM; see Book of Procedures.

#### NVB and Isolation Mounts

<u>CM BLOCK I</u> Rigid beryllium structure supporting the IMU and the optical subsystem with its associated hardware. The NVB is attached to the spacecraft using flexible isolation mounts to prevent spacecraft strains from distorting the NVB and the alignment between the IMU and Optics. These mounts also provide shock and vibration attenuation.

<u>CM BLOCK II</u> Functionally similar to Block I but will be lighter and provide for mounting the size 12.5 IMU.

<u>LEM</u> The need for tieing the AOT and IMU together exists but is accomplished using structure provided by the spacecraft contractor.

#### Optical Eyepieces

<u>CM BLOCK I</u> Removable SXT eyepiece and removable SCT 1- and 3-power eyepiece combination.

<u>CM BLOCK II</u> Same as Block I for SXT but only a 1-power eyepiece will be used with the SCT.

LEM Included as part of the AOT.

#### Optical Subsystem

<u>CM BLOCK I</u> Consists of SXT, SCT, Optical base, and associated hardware defined as follows:

SXT:	Sextant a two-line-of-sight, narrow-field, two-degree- of-freedom sextant and its attached gearing		
SCT:	Scanning Telescope a single-line-of-sight, wide-field- of view, two-degree-of-freedom articulation optical instrument and its attached gearing		
OPTICAL BASE:	Base for SXT and SCT with associated gearing and internal cooling.		

<u>CM BLOCK II</u> Similar to Block I except for changes in the sextant to provide line-ofsight velocity control directly without CDU's. The horizon photometer is incorporated into the SXT.

LEM Not in LEM, see AOT.

Optical Shroud & Cover Assembly

CM BLOCK I and BLOCK II Consists of the optical shroud and protective cover.

<u>LEM</u> Does not exist in LEM.

#### Power Servo Assembly (PSA)

<u>CM BLOCK I</u> Consists of most of the support electronics: power supplies; IMU, Optics, and CDU servos; IMU temperature control; and accelerometer and gyro pulse torquing. Consists of 10 trays with replaceable modules which plug into the PSA end connector assembly. Includes front toe plate but not the cold plate.

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<u>CM BLOCK II</u> Similar in function to Block I but does not contain the CDU servos needed in Block I. Consists of a single plane matrix header to mount onto the cold plate with the modules plugging onto the top.

LEM See Appendix A for weight breakdown.

#### **PSA End Connector Assembly**

<u>CM BLOCK I</u> Electrical interconnection between the PSA trays, the G&N interconnection Assy, and the G&N to CM interface Assy.

<u>CM BLOCK II</u> Not identified as a separate item; will be part of the PSA matrix header.

LEM Not yet defined. Will probably not exist in LEM.

#### PSA Covers

CM BLOCK I Not required.

<u>CM BLOCK II</u> Protective cover to protect the PSA module connections from moisture during flight.

LEM Same as Block II except lighter in weight.

#### Two-Digit Readout for Reticule

CM Bot in CM.

<u>LEM</u> A 2-digit readout driven by the AGC from 00 to 99 to indicate range component of landing point using fixed numbered scale on window reticule.

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#### Appendix A

#### VOLUMES AND WEIGHTS FOR LEM PSA MODULES

### Table A-I shows weights and volumes for the LEM PSA modules.

			· · · · · · · · · · · · · · · · · · ·
	No. of	Total Vol.	Total Wt.
Module	Modules	(ca. in.)	(lbs)
GYRO PULSE TORQUING			
DC Amp. and PVR	1	4.57	0.173(M)
Switch Module	1	7.55	0.242 (E)
Pulse Torque Gyro Calib.	1	3.00	0.200 (E)
	3	15.12	0.615
ACCEL. PULSE TORQUING		1	
DC Amp. and PVR	3	13.71	0.518(C)
Binary Current Switch	3	22.65	0.800 (C)
PIPA Calibration	3	15.72	0.610 (C)
AC Amp. and Interrogator	3	<u>17.70</u>	0.710
	12	69.78	2.638
POWER SUPPLIES			
120-Volt Supply	1	18.50	1.200 (C)
-28 VDC Power	1	12.55	0.708 (M)
3200-cps 1% Amp.	1	6.24	0.281 <b>(M)</b>
3200-cps AAC, Filter & Multi	1	6.24	0.287 (M)
800-cps 1% Amp.	1	9.23	0.704 (M)
800-cps 5% Amp.	2	25.10	2 010 ( <b>M</b> )
800-cps AAC, Filter & Multi	2	13.12	0.612 (M)
G&N Sub-system Filters	$\underline{2}$	14.00	<u>0.771 (C)</u>
	11	104.98	6.573
4			
IMU			
Gimbal Servo Amp.	3	31.89	1.749 <b>(M)</b>
Gimbal Coarse Align.	3	14.76	0.753 <b>(M)</b>
Temp. Control	1	16.51	0.972 (E)
	L		

Table A-I. LEM PSA Weight and Volume

(cont)

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IMU Mode Relays Failure and Warning	1 <u>1</u> 9	$   \begin{array}{r}     2.64 \\     \underline{10.21} \\     76.01   \end{array} $	0.106(E) <u>0.498(E)</u> 4.078	
Total Number of Modules	35			
Total Module Volume	265.9 cu. in.			
Total Module Weight	13.9 lbs.			
Header Weight (60% of Block II CM)	10.9 lbs.			
Cover Weight	<u>2.4 lbs</u> .			
TOTAL LEM PSA WEIGHT	27.21	bs.		

Table A-I. LEM PSA Weight and Volume (cont)

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