

E-1142 (Rev. 26) (UNCLASSIFIED TITLE)

SYSTEM STATUS REPORT

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ACKNOW LEDGMENT

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PREFACE

On September 23, 1964, MIT was directed to hermetically seal all electronic components in the Command Module as the basic approach for humidity and contamination protection. During the period of changing to hermetic sealing, MSC assessed the consequences and now has directed MIT verbally to return to the conformal moisture-proofing concept.

Because of the time factor involved in publishing this report each month, it has not been possible to incorporate this latest requirement by MSC, but next month's report will reflect this latest provision. A CONTRACT OF A CARDINAL

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ABSTRACT

The System Status Report is distributed monthly on the 15th. This month's revision of E-1142 (Rev.26) contains, in general, the following information for the Block I and Block II Command Module and Lunar Excursion Module equipment configuration weights, centers of gravity, moments of inertia, power requirements, status of computer programs, and reliability values.

Section 1

INTRODUCTION

1-1 INTRODUCTION

The definition of what constitutes Block I, Block II, and LEM hardware is contained in the Glossary, section 5 of this report. In Block II and LEM electronic assemblies and components are now to be hermetically sealed.

The following information is included in this month's report:

(1) Command Module, Block I

100 Series: Weights and power requirements Zero Series: Total weight, centers of gravity, and moments of inertia Cuidance and Navigation Lunar Londing Mission: Status of

Guidance and Navigation Lunar Landing Mission: Status of computer programs.

- (2) Command Module, Block II Integrated Guidance Navigation and Control Configuration: Weights and reliability values.
- (3) Lunar Excursion Module
 LEM Integrated Guidance and Control Configuration (configuration "B," Ref: Minutes of LEM Implementation Meeting No. 4): Weights and reliability values.

Also included are appendices which give the chronological weight history (Appendix A) and preliminary estimates of power requirements (Appendix B) for the Command Module and LEM.

1-2 ACCURACY

The accuracy of numerical values reported in this revision should not be considered to within the tolerances implied by the significant figures quoted. The reported values, although based upon the most current information, are subject to normal changes as design and development phases approach completion.

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Section 2

BLOCK I COMMAND MODULE DATA

2-1 WEIGHTS

Table 2-I presents the weights of all Block I flight (100 series systems) equipment, grouped according to specific location within the Command Module. Weights are reported to the component level and to the nearest tenth of a pound.

Given component weights are identified as estimated, calculated, and measured in order of increasing accuracy. These terms are defined by North American Aviation as follows: estimated weights (E) are based on rough calculations; calculated weights (C) are based on detailed calculations made from final production drawings that will be used to build flyable equipment; measured weights (M) are actual weights of equipment built to the production drawings.

North American Aviation will provide and be responsible for cold plate weights that are not integral with guidance and control equipment.

2-1.1 WEIGHTS STATUS REPORTING. Table 2-I also offers a comparison of present 100 series component weight values with those listed in System Status Report, E-1142 (Rev. 25), October 15, 1964. All weight changes are explained in paragraph 2-2.

2-1.2 CONTROL WEIGHT (ZERO SERIES). Column (a) in Table 2-I contains the February 15, 1964 weight status of Apollo G&N zero series equipment. Column (a) adds up to approximately the total control weight specified in letter PG-64-113 (March 6, 1964) from Mr. D. Gilbert, ASPO, to Mr. M. Trageser, MIT/IL.

2-1.3 DESIGN LOAD WEIGHT (ZERO SERIES). At NASA Coordination Meeting No. 15A, MIT agreed to assign "not to exceed" design load weights for individual Block I G&N zero series subsystems. These weights were assigned by MIT in MIT letter AG 594-64, May 18, 1964, and are shown in column (d) of Table 2-I.

2-2 REPORTED 100 SERIES WEIGHT CHANGES

2-2.1 PSA (+0.9 lb). The photometer electronics module and modulator and the loop compensation module are now included in the weight of the PSA and are located in tray 10. The modules were previously included as part of the Horizon Photometer Electronics.

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Table 2-I. Current Weig	ht Status of	Block I (10)) Series) Col	mmand Moc	lule (lbs at 1	g)
	0 Series		100 Series		100 Series	Design
	Status		Status		Status	Load Wt.
Item	2/64		10/64		11/64	5/64
	(a)	(b-a)	(q)	(c-b)	(c)	(q)**
G&N SYSTEMS						
CDU Assy	14.5 (M)	-0°0-	13.6(C)	0°0	13.6(C)	18.0
Optical Subsystem					i	
SXT	18, 2 (C)	+0.5	18.7(E)	0.0	18.7(E)	
SCT	13.8(C)	+0,5	14.3(E)	0.0	14.3(E)	
Optical Base & Gearing	16.7(E)	+0.3	17.0(E)	0°0	17.0(E)	
Optical Eyepieces						100.0
SXT	1.3(E)	+0.3	1.6(C)	0.0	1.6(C)	_
SCT	2.3(E)	+0,3	2,6(C)	0.0	2.6(C)	
NVB & Resilient Mounts	25.0(E)	40 ° 1	25.7(C)	0.0	25.7(C)	
Bellows Assy	13.5 (M)	-0°8	12.7(C)	0°0	12.7 (C)	
IMU	60.2(M)	+0.3	60.5 (C)	0.0	60.5(C)	65.0
Coolant Hoses (two)	1.0(E)	-0.2	0.8(E)	0.0	0.8(E)	_
Power Servo Assy	59.4 (C)	-0.5	58.9(C)	+0°0+	59.8(C)	75.0
G&N Interconnection Assy	35,2(E)	- 5 , 2	30.0(C)	0°0	30°0 (C)	45°0
G&N to S/C Interface Assy	8.0 (E)	+5,0	83.0(E)	0.0	83.0(E)	100.0
AGC (no spares)	70.0(E)		 			
Optical Shroud	3.5 (M)	-0.4	3.1 (C)	0.0	3.1 (C)	4.5
LOWER EQUIPMENT BAY						
D&C		:	č ,	Ţ		
D&C Electronics	2.9(M)	0.0	2.9(C)	+0.1	3°0(E)	e
Control Electronics	2.9(E)	-0.9	2.0(C)	+0.1	2.1 (E)	
G&N Ind Cont Panel	9.5 (M)	+0 .4	9°9(C)	+0°6	10.5(E)	20.0
IMU Control Panel	2.4 (M)	+0°5	2.6(C)	+0.2	2.8(E))
MDV (includes 1 film)	7.7 (C)	+1 ,9	9.6(C)	0.0	9.6(C)	
D&C/AGC	20.6(M)	+0.8	21.4 (C)	0.0	21 °4 (C)	, ,
Horiz, Photo, Elect.	0.0	+3.3	3.3(E)	-1°1	2.2(C)	0.0
Signal Conditioner Assy	0.0	4.6	4.6(E)	-0°1	3.9(C)	8.0

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g) (cont)	Design Load Wt. 5/64 (d)**	26.0	3.0 5.0 2.5	522.0	, y. Dh
ile (lbs at 1	100 Series Status 11/64 (c)	21.4 (C)	1.5(E) 2.5(C) 1.6(C)	425.9	. D. Gilbert to series on See paragra
nmand Modu	(c-b)	0.0	0.0 0.0 0.0	+0 , 1	14) from Mr oplies to zer 18, 1964).
Series) Con	100 Series Status 10/64 (b)	21.4 (C)	1 . 5 (E) 2 . 5 (C) 1 . 6 (C)	425.8	Iarch 6, 196 h 2-1.2. A _I 94-64 (May
Block I (100	(b-a)	+ 0.9	0.0 + 0.1 - 0.1	10.8	G-64-114 (N ee paragrap ' letter AG 5
ht Status of	0 Series Status 2/64 (a)	20.5 (M)	1.5(E) 2.4(E) 1.7(M)	415.0*	d in letter P MIT/IL. S en from MIT is only.
Table 2-I. Current Weig	Item	MAIN PANEL AREA D&C/AGC LOOSE STORED ITEMS	Eye Relief Eyepieces Film Cartridges (4) Optics Cover	TOTAL	*Total control weight specifie ASPO, to Mr. M. Trageser, **Design Load Weights are tak 2-1.3. Applies to zero serie

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2-2.2 D&C ELECTRONICS (+0.9 lb). The added weight results from the need to moisture-proof the electrical connections.

2-2.3 CONTROL ELECTRONICS (+0.1 lb). The added weight results from the need to moisture-proof the electrical connectors and exposed electrical connections.

2-2.4 G&N INDICATOR CONTROL PANEL (+0.6 lb). The added weight results from the need to moisture-proof all electrical connectors, the sextant hand controller, and all other exposed electrical connections.

2-2.5 IMU CONTROL PANEL (+0.2 lb). The added weight results from the need to moisture-proof all electrical connectors and exposed electrical connections.

2-2.6 HORIZON PHOTOMETER ELECTRONICS (-1.1 lbs). The weight decrease is the result of a refinement of the existing module weight estimate (see paragraph 2-2.1 for further explanation).

2-2.7 SIGNAL CONDITIONER ASSY (-0.7 lb). The calculated weight now available indicates a decrease over previous estimates.

2-3 BLOCK I (ZERO SERIES) WEIGHT, CENTER OF GRAVITY, AND MOMENT OF INERTIA DATA

Block I (100 series) center of gravity and moment of inertia information is unavailable at this time, but is under preparation.

Included for reference are the total Block I (zero series) weight, center of gravity, and moment of inertia values.

Weight	Center of Gravity	Moments of Inertia*
(lb)	(in)	(lb-in ²)
408.9	$ \left(\begin{array}{ccc} X & 55.1 \\ Y & -0.3 \\ Z & 37.3 \end{array}\right) $	Ixx 681,030 Iyy 1,939,064 Izz 1,308,074

Table 2-II. Block I (Zero Series) Weight and Balance Data

*Values determined with respect to the basic X, Y, Z axes of the Command Module.

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2-4 COMMAND MODULE POWER REQUIREMENTS (100 SERIES)

The power requirements of the Command Module G&N 100 series equipment on the primary +28 VDC power supply are shown in figure 2-1 which presents the magnitude and location of dissipated power values on a subassembly level. This chart assumes a 12.85-day lunar mission as defined by S&ID for power profile computation and is based on 28 VDC input at the connectors. The values shown are average values. (Ref: S&ID letter 63 MA 3540.)

The power chart (figure 2-1) represents a total energy consumption decrease of approximately 1500 watt hours over the 12.85-day lunar mission chart shown in last month's report. This is due to a 5-watt decrease in the AGC Standby mode.

Table 2-III shows the magnitude and location of power dissipation for the established G&N activities, each of which consists of various power levels of operation.

Table 2-IV shows the energy requirements for each G&N activity on a power level basis. The table is based upon MIT letter AG 679-6, ''G&N Power Profile Status,'' dated August 14, 1963. The vertical column to the left indicates the various G&N activities (phases of operation) for the model 12.85-day mission submitted by S&ID in S&ID letter 64 MA 3540. The column also indicates the power requirement and operating time for each specific activity. The top row indicates the power requirement and operating time for each G&N power consuming equipment. The table sums up the energy consumptions for each G&N activity and each G&N power consuming equipment.

2-5 STATUS OF COMMAND MODULE AGC PROGRAMS

The integrated guidance and control implementation activity has defined stablization and control functions which must be part of the Block II computer program. Since the current program estimates do not include this S&C function, the computer program status has been moved from section 3 to section 2 where it applies to the Block I configuration used for a lunar mission but without S&C. When the computer estimates include these added functions, the AGC Program Status will be returned to section 3.

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Figure 2-1. Electrical Load on Primary +28 VDC Power Supply Block I (100 Series) Systems

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	Table 2-III. Nominal Po	ower Diss	sipation (watts) vs	G&N Ac	tivity fo	r Block I	(100 Series) Sy	stems		
XOA	G&N Activity	NB	¥.	CDU	PS/			Thermal Load on S/C	D&C and	Optics	Electrical
ы	(power levels)	IMU	OBA	JB	IMU	OBA	AGC	Coolant	S&C	External	Load
۲.	Accomplish & Confirm Course Corrections Inactivity and Monitor Major Maneuver (1,5)	74 5	0.0	22. 1	228.5	0.0	115.0	440.1	10.7	0.0	450.8
д	Alignments Sextant Sightings (1, 3, 5, 7)	74.5	40.7	44.0	228.5	76.1	115.0	578.8	25.7	0.5	605.0
0	Landmark Trackings (Low-Orbit Navigation) (1, 4, 5, 7)	74.5	35.5	44.0	228.5	72.3	115.0	569.8	25.7	0.5	596.0
<u>م</u>	Star Occultation Sightings (1, 6)	25.5	0.0	0.0	36.2	0.0	115.0	176.7	10.0	0.0	186.7
ы	Sextant Sightings Midcourse Navigation (1, 3, 6, 7)	25.5	40.7	21.9	36.2	76.1	115.0	315.4	25.0	0.5	340.9
ы	Inactivity & Monitor (2,6)	25.5	0.0	0.0	36.2	0.0	15.0	76.7	0.0	0.0	76.7
U	Inactivity & Monitor (2,5)	74.5	0.0	22. 1	228.5	0.0	15.0	340.1	0.7	0.0	340.8
		1. AC 2. AC 2. AC 3. OP 0. 1. AC 5. IM 0. 0. 1. AC 7. D8	AC Opera AC Standl Ac Standl trics Ope trics Ope U Opera &C Opera	y sy rate SXT rate SXT te te te	ON OFF		125.0 w 15.0 w 125.8 w 116.8 w 325.8 w 61.7 w 28.4 w	atts atts atts atts atts atts			

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	I able 2-1V . Block	r (saliac not) t	ORIERATION MONTH	Trinerion Again	TOTOTI E LOTICE TOT	12.00-Day Dullar			
ХOА	G&N Activity	(1) AGC Operate	(2) AGC Standby 15,0 watts	(3) Optics Sextant ON 125, 8 watts	(4) Optics Sextant OFF 116.8 watts	(5) IMU Operate 325 8 watts	(6) IMU Standby 61 -7 watts	(7) D&C Operate 28 4 watts	
Е		81.15 hours	227.13 hours	16.39 hours	3.45 hours	84.68 hours	223.60 hours	19.84 hours	Total
¥	Accomplish & Confirm Course Corrections Inactivity and Monitor Major Maneuvers 450.8 watts 58.41 hours	1.301	I	1	i	19.030	I	I	261
e e	Alignments Sextant Sightings 605.0 watts 13.73 hours	1.716	ł	1.727	1	4.473	I	0.390	8.306
U	Landmark Trackings (Low-Orbit Navigation) 596.0 watts 3.45 hours	0.431	1	ł	0.403	1.124	1	0.098	2.056
A	Star Occultation Sightings 186.7 watts 2.90 hours	0.363	I	I	1	ŀ	0.179	1	0.542
ы	Sextant Sightings (Midcourse Navigation) 340.9 watts 2.66 hours	0.333	1	0.335	ļ	1	0.164	0.076	0.907
μ	Inactivity and Monitor 76.7 watts 218.04 hours	I	3.271	I	1	1	13.453	1	16.724
U	Inactivity and Monitor 340.8 watts 9.09 hours	ł	0.136	I	1	2.962	Ι		3.098
	Total 308.30 hours	10.144	3.407	2.062	0.403	27.589	13.796	0.563	57.964

Table 2-IV. Block I (100 Series) Command Module Energy Consumption Profile for 12.85-Day Lunar Orb

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BLOCK I COMMAND MODULE

Table 2-V lists current Command Module memory estimates and the status of AGC programs for the lunar landing mission guidance and navigation functions.

A high and low word estimate is given with each program. Each status is defined as follows:

- (1) Planning stage
- (2) Programming stage
- (3) Checkout on AGC simulation
- (4) Checkout on G&N simulation
- (5) Checkout on AGC

Table 2-V. Current Memory Estimates and the Status of Command Module AGC Programs

		Memory I (word	Estimate ls)
Program	Status	High	Low
List Processing Interpreter	(5)	1712	1712
AGC Executive	(5)	253	253
AGC Waitlister	(5)	145	145
AGC System Exerciser	(5)	500*	294*
G&N System Exerciser	(4)	650	400
Display, Keyboard, and Telemetry	(5)	2000	2000
Input/Output Control	(5)	1750*	1275*
Midcourse & Orbital Navigation	(5)	2000*	1500*
Midcourse & Orbital Guidance	(3)	500	500
Pre-Launch Platform Alignment	(5)	400*	350*
In-Flight Platform Alignment	(4)	1024	900
Re-Entry Control	(4)	1800	1200
Injection and De-Boost	(4)	1000	400
Restart	(5)	500*	200*
Aim-Point Determination & Abort	(3)	4000	2000
Totals		18234	13129

*Programs in stage (5) whose low and high estimates are not identical reflect an anticipated increase in computation facility.

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Section 3

BLOCK II COMMAND MODULE DATA

3-1 INTRODUCTION

This section describes the integrated guidance, navigation, and control configuration as defined by the activity of the CM implementation meeting through meeting No.6, August 18, 1964.

The system reported on here is the hermetically sealed configuration as directed by $\ensuremath{\text{MSC}}$.

3-2 RELIABILITY

The reliability figures shown in Table 3-I are the current estimates of the Block II Command Module G&N equipment. They reflect the realignment of the interface configuration which requires the G&N equipment to assume certain stablization and control functions, the elimination of the standby guidance computer, and the most recent estimate of electronic CDU reliability. These estimates of Command Module G&N reliability are based on the 138-hour mission defined in the Lunar Landing Mission Design Plan.

Subsystem	Operation Time (hrs) Full Power	Probability of Mission S uccess
IMU	31	0.9961
AGC	19*	0.9869
DSKY	19	0.99999
PSA	31*	0.99421
CDU (5)	31	0.9923
Optics	18	0.99804
Total G&	N System	0.9679

Table 3-I. Reliability (as of 11/15/64)

*Certain assemblies function continuously.

3-3 WEIGHTS

Table 3-II shows the weights of the hermetically-sealed Block II Command Module Integrated Guidance and Control system.

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Table 3-II. Current	Weight Statu	is of Block I	I Command	Module (Ibs	at 1 g)	
	Pre-June*		Post-June*		Post-June*	Design
Item	Status		Status		Status	Load Wt, 5 /64
IIIOII	2/64		10/64		11/64	-1/0+
	(a)	(b-a)	(q)	(c-b)	(c)	(n)
G&N SYSTEMS						
CDU Assy	15.0(E)	+18.2	33.2(E)	+2.8	36 . 0 (C)	
Optical Subsystem	-					
SXT	18.2 (C)	+ 0.5	18.7(E)	0.0	18.7 (E)	
SCT	13.8(C)	+ 0.5	14.3(E)	0.0	14.3(E)	
Optical Base & Gearing	16.7(E)	+ 0,3	17,0(王)	0°0	17.0(E)	
Optical Eyepieces						
SXT	1.3(E)	+ 0°3	1.6(E)	0.0	1.3(E)	
SCT	2.3(E)	+ 0.3	2.6(E)	0°0	2.6(王)	
NVB & Mounts	22.0(E)	+ 1.0	23.0(E)	-6.0	17.0(E)	
Bellows Assy	13 .5 (C)	- 0°8	12.7(E)	0°0	12.7 (E)	
IMU	42.0(E)	+ 0.1	42.1 (E)	0°0	42.1(E)	
Coolant Hoses (two)	1.0(E)	- 0.2	0.8(E)	0°0	0.8(E)	
Power Servo Assy	41.6(E)	+14.7	56.3(E)	-1.6	54.7(E)	
G&N Interconnection Assy	35.2 (E)	- 4.2	31.0(E)	0°0	31.0(E)	
G&N to S/C Interface Assy	8 ° 0 (E)	+ 0.5	8.5(E)	0°0	8 .5 (E)	
AGC	92.5(E)	-24.2	68.3(E)	-2.3	66.0(E)	
Optical Shroud	3.5 (C)	- 0.4	3 .1 (E)	0°0	3.1 (E)	
LOWER EQUIPMENT BAY D&C						
D&C Electronics	1.5(E)	0°0	1.5(E)	0°0	1.5(E)	
Control Electronics	2,9(E)	- 0.9	$2_{.0}(E)$	0.0	2.0(E)	
G&N Ind Cont Panel	11.1(E)	+ 1.0	12.1(E)	0.0	12.1 (E)	
MDV (includes 1 film cartridge)	8.3(E)	+ 3.8	12.1 (E)	-0°6	11.5(E)	
D&C/AGC	20.6(E)	- 0.6	20.0(E)	-1°0	19.0(E)	
Signal Conditioner Assy				+3°9	3.9 (C)	

(c ont)

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		1			
	Design Load Wt. 5/64 (d)			492.6†	PO, to clude
at 1 g) (cont	Post-June* Status 10/64 (c-b)	19.0(E)	1.5(E) 2.5(E) 1.6(C)	400.7	Gilbert, ASI Does not in
Module (lbs	(c_b)	-1.0	0.0 9.0+	-5.2	om Mr. D.
I Command	Post-June* Status 10/64 (b)	20,0(E)	1.5(E) 1.9(E) 1.6(C)	405,9	1 6, 1964) fr 32, Februar
is of Block I	(b-a)	-0.5	0.0 +0.1 -0.1	+5,9	-113, March ph 2-1.2. r 63 MA 208
Weight Statu	Pre-June* Status 2/64 (a)	20.5(E)	1.5(E) 1.8(E) 1.7(E)	400,0** Control Weight	stter (PG-64 See paragra m S&ID lette
Table 3-II. Current		<u>MAIN PANEL AREA</u> D&C/AGC	LOOSE STORED ITEMS Eye Relief Eyepieces Film Cartridges (4) Optics Cover	TOTAL	*See paragraph 3-1. **Control Weight specified in le Mr. M. Trageser, MIT/IL. †Design Load Weight taken fro loose stored items.

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COMMAND MODULE

3-4 REPORTED WEIGHT CHANGES

3-4.1 CDU (+2.8 lbs). The increase in weight is due to the incorporation of the guidance and control functions in the CDU subsystem.

3-4.2 NVB MOUNTS (-6.0 lbs) This decrease is due to a better weight estimate and the use of the strain isolation hard-mount.

3-4.3 PSA (-1.6 lbs). The decrease in weight results from further refinement of the PSA design configuration.

3-4.4 AGC (-2.3 lbs). This decrease results from the fact that the AGC cover weight was recorded twice in the report dated October 15, 1964.

3-4.5 MDV (-0.6 lb). The Map and Data Viewer will carry one film cartridge rather than the two cartridges previously reported.

3-4.6 D&C/AGC LEB (-1.0 lb). The decrease in weight results from further refinement of the design configuration.

3-4.7 SIGNAL CONDITIONER ASSY (+3.9 lbs). The increase in weight is due to the addition of the Signal Conditioner Assembly in the Block II configuration. This assembly is located in the volume occupied by the CDU's in Block I.

3-4.8 D&C/AGC MP (-1.0 lb). The decrease in weight results from further refinement of the design configuration.

3-4.9 FILM CARTRIDGES (+0.6 lb). The increase in weight is due to the addition of one additional film cartridge as a loose stored item.

3-5 POWER REQUIREMENTS

The power requirements of the Block II Command Module G&N equipment on the primary +28 VDC power supply are shown in figure 3-1, which presents the magnitude and location of dissipated power values on a subassembly level. This chart assumes a 12.85-day lunar orbit mission as defined by S&ID for power profile computation and is based on 28 VDC input at the connectors. These values are average values. (Ref: S&ID letter 64 MA 3540.)

Table 3-III shows the magnitude and location dissipation for the established G&N activities, each of which consists of various power levels of operation.

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Table 3-IV shows the energy requirements for each G&N activity on a power level basis. The table is based upon MIT letter AG 679-6, "G&N Power Profile Status," dated August 14, 1963. The vertical column to the left indicates the various G&N activities (phases of operation) for the model 12.85-lunar day mission submitted by S&ID in S&ID letter 64 MA 3540. The column also indicates the power requirements and operating time for each specific activity. The top row indicates the power requirements and operating time of each G&N power consuming equipment. The total power consumption for each G&N activity and each G&N power consuming equipment is also given.





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XOA¤	Table 3-III. Nominal G&N Activity (nower levels)	Power D	issipation 3A 3A	n (watts)	vs G&N A	Activity fo SA	or Block II	Thermal Load on S/C	D&C and sec	Electric
ਹ	(DOMET LEASES)	1 INT O	NBN	n n n	D INT	UBA	AGC	Coolant	2000	гоад
V	Accomplish & Confirm Course Corrections Major Maneuvers Inactivity & Monitor (1, 4)	76.5	0.0	44.1	163.9	0.0	100.0	384.5	10.7	395.2
£	Alignments Sextant Sightings Landmark Trackings (Low-orbit navigation) (1, 3, 4, 6)	76.5	52.1	73.5	163.9	61.2	100.0	527.2	25.7	552.9
U	Star Occultation Sightings (1,5)	25.5	0.0	0.0	28.0	0.0	100.0	153.5	10.0	163.5
A	Sextant Sightings (Midcourse Navigation) (1, 3, 5, 6)	25.5	52.1	29.4	28.0	61.2	100.0	296.7	25.0	321.2
ы	Inactivity & Monitor (2, 5)	25.5	0.0	0.0	28.0	0.0	10.0	63.5	0.0	63.5
μ	Inactivity & Monitor (2, 4)	76.5	0.0	44.1	163.9	0.0	10.0	294.5	0.7	295.2
		 AG A	C Operat C Standby C Standby ics Operate J Operate C Operate	e ate		110 wat 10 wat 135.1 w 285.2 w 53.5 w 22.6 w	ts ts atts atts atts atts			

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	Total	23.0%4	9.499	0.474	0.854	13.845	2.683	50.439
	(6) D&C Operate 22.6 watts 19.84 hours		0.388	1	0.060	1	1	0.448
h)	 (5) IMU Standby 53.5 watts 223.60 hours 	1	I	0.155	0.142	11.665	1	11.962
Consumption (kw	(4) IMU Operate 285.2 watts 84.68 hours	16.659	4.900	I	1	I	2.592	24,151
Energy	(3) OpticsOperate135.1 watts19.84 hours	l	2.321	1	0.359	1	1	0 6 80
	(2) AGC Standby 10.0 watts 227.13 hours	1	i	1	1	2.180	0.091	120 0
	 (1) AGC Operate 110.0 watts 81.15 hours 	6.425	1.890	0.319	0.293		[
	G&N Activity	Accomplish & Confirm Course Corrections Major Maneuvers Inactivity & Monitor 395.2 watts 58.41 hours	Alignments Sextant Sightings Landmark Trackings (Low-orbit Navigation) 552.9 watts 17.18 hours	Star Occultation Sightings 163.5 watts 2.90 hours	Sextant Sightings (Midcourse Navigation) 321.2 watts 2.66 hours	Inactivity & Monitor 63.5 watts 218.04 hours	Inactivity & Monitor 295.2 watts 9.09 hours	
	Operating Mode	A	E .	C	Q	ы	Гц.	

Table 3-IV. Block II Command Module Energy Consumption Profile for 12.85-Day Lunar Orbit Mission

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BLOCK II COMMAND MODULE



Section 4

LUNAR EXCURSION MODULE DATA

4-1 INTRODUCTION

It was intended by MSC that at the end of the fifth LEM integrated guidance and control implementation meeting, the overall configuration of the control system as it affects the hardware reported here would be defined. However, since no decision concerning the functional interfaces was reached at this fifth meeting, which took place on October 27 and 28, 1964, MIT proposed a LEM guidance, navigation, and control system with sufficient function interfaces to meet probable future requirements as they become defined. This system provides one basis for estimating the hardware weight reported below. Because of the possibility of a future requirement for hermetic sealing in the LEM and because of the rule for common usage in the two vehicles, the report below assumes the hermetic packaging of the CDU's, PSA, LGC, and the LGC Display and Control. Since the above areas as yet are not clearly defined, only best-guess estimates can be made for weight, reliability, and power requirements.

4-2 **RELIABILITY**

There have been no significant changes in the G&N equipment design this month that would warrant a re-evaluation of the reliability figures presented in the last month's report. Table 4-I presents the latest figures.

The LEM G&N reliability values are based on a mission of the same duration as the CM G&N equipment.

Subsystem	Operating Time (hrs)	Probability of Mission Success
IMU	6.25	0.99914
LGC	6.25	0.9976
PSA	6.25	0.99928
CDU (5)	6.25	0.99822
OMU	0.75	0.99997
DSKY	6.25	0.9976
Total G&N Sy	vstem	0.9918

Table 4–I.	(Reliability as a	of 11/	′15/64)
------------	-------------------	--------	--------	---

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and the other states of the second	Design Load Wt. 7/64 (d)	* * * *		ed ,
	Status 11/64 (c)	33.2 (E) 25.5 (E) 2.0 (E) 42.1 (E) 19.0 (E) 19.0 (E) 2.0 (E) 66.0 (E) 35.2 (E) 0.0 6.0 (E)	241.0 143.3	ilbert, ASP rmetic seal
ents (lbs at	(c-b)	+10.3 + 1.0 0.0 0.0 + 4.0 + 4.0 +10.4 +10.4 - 2.4	+31.3 ` 0.0	n Mr. D. G on use of he
&N Comon	Status 10/64 (b)	22.9(E) 24.5(E) 24.5(E) 2.0(E) 42.1(E) 15.0(E) 15.0(E) 26.0(E) 24.8(E) 24.8(E) 24.8(E) 24.8(E) 24.8(E) 26.0(E)	209.7 124.9	i, 1964) from the commo
ts of LEM G	(b-a)	$\begin{array}{c} + 7.9 \\ 0.0 \\ - 0.0 \\ + 0.1 \\ - 4.5 \\ 0.0 \\ + 12.2 \\ - 0.0 \\ - 0.0 \\ + 6.0 \end{array}$	+ 1.7	13 (March 6 1 2-1.2 b are due t II.
mated Weigh	Status 2/64 (a)	15.0(E) 24.5(E) 2.0(E) 42.0(E) 19.5(E) 2.0(E) 45.8(E) 24.8(E) 2.4(E) 0.0	210.0* Control Weight 108.3	ter PG-64-1 See sectior assigned. in column c CM Block J
Tahle 4-Π Rati	Item	CDU's Telescope and All Eyepieces Landing Point Designator+ IMU LGC/PSA Interconnection Assy LGC Display and Controls Book of Procedures, etc. LGC PSA PSA Cover NVB	Total Bare Guidance System (IMU, PSA, and LGC)	*Control Weight specified in Let to Mr. M. Trageser, MIT/IL. **No design load weight has been fSee paragraph 4-4.7. Note: The weight changes listed packages produced for the

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LUNAR EXCURSION MODULE

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4-3 WEIGHTS FOR LEM

Lunar Excursion Module weights are presented in Table 4-II. In general the data conform to the information contained in paragraphs 2-1, 2-1.1, and 2-1.2.

The row labeled "Bare Guidance System" is inserted to provide for comparisions with similarly specified systems.

4-4 REPORTED WEIGHT CHANGES

4-4.1 CDU (+10.3 lbs). The increase in weight is due to the requirement for hermetic sealing. (For further explanation, see "System Status Report," Rev. 25, paragraph 3-4.1.)

4-4.2 TELESCOPE AND ALL EYEPIECES (+1.0 lb). The increase in weight results from the additon of X, Y, and REJECT buttons for alignment of the IMU (Ref: LEM Implementation Meeting No. 4, October 21, 1964, at GAEC).

4-4.3 LGC DISPLAY AND CONTROL (+4.0 lbs). The LGC DSKY is to be hermetically sealed by encasing the unit in a box of sufficient strength to support the pressure differential.

4-4.4 LEM GUIDANCE COMPUTER (+8.0 lbs). The increase in weight results from the requirement for hermetic sealing. (For further explanation, see "System Status Report," Rev. 25, paragraph 3-4.7.)

4-4.5 PSA (+10.4 lbs). The increase in weight results from the requirement for hermetic sealing. (For further explanation, see "System Status Report," Rev 25, paragraph 3-4.4.)

4-4.6 PSA COVER (-2.4 lbs). The need for this dust cover is eliminated by the sealing of the PSA structure.

4-4.7 LANDING POINT DESIGNATOR (No Change). The eye register for the reticle component has now been incorporated into a newer optical sighting device known as the Landing Point Designator. This unit will provide unit magnification of the target area with a light-line reticle pattern superimposed on the target image. The weight remains the same.

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4-5 POWER REQUIREMENTS

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The estimate for LEM power and energy consumption shown in figure 4-1 is based upon Command Module G&N Block II Data and Preliminary ICD LIS-390-2, LEM Electrical Load Analysis Form.

Table 4-III shows the energy requirements for each G&N activity on a power level basis. The table is also based upon LEM ICD LIS-390-2. The vertical column on the left indicates the various G&N activities (phases of operation). This column also indicates the power requirements and operating time for each activity. The top row indicates the power requirements and operating time of each G&N power consuming equipment. The table sums up the energy consumption for power consuming equipment.

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Figure 4-1. Electrical Load on Primary +28 VDC Power Supply

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	Total	4.676	5.060	0.086	1.273	0.997	12.092
	(7) OMU (AOT) Operate Neglighle watts 27.42 hours	1	negligtble	1	1	negligible	negligible
90-2	(6) Two Radar CDU Operate 29.4 watts 11.92 bours	P	0.345	0.006	I	ł	0.351
n LEM ICD LIS-39	(5) IMU (5) IMU Standby 53.5 watts 123.15 hours	4.676	t	1	1.073	0.840	6.589
Profile Based o	(4) IMU (4) IMU Operate 297.3 watts 11.92 hours	١	3,484	0.059	1	1	3.543
on Module Power	(3) LGC Standby 10.0 watts 35.75 hours	1	1	I	0.200	0.157	0.357
Lunar Excursic	(2) LGC. Operate 105.0 watts 11.92 hours	1	1. 231	0.021	I	1	1.252
Table 4-III.	(1) LGC Off 0.0 watts 87.40 hours	0.000	1	1	1	I	0.000
	M D LEM G&N Activity	Inactivity 53.5 watts 87.40 hours	I Inactivity Alignment Midcourse Measurements 431.7 watts 11.72 hours	II Guidance During Major Event 431.7 watts 0.20 hours	V Inactivity 63.5 watts 20.05 hours	/ Inactivity 63.5 watts 15.70 hours	Total 135.07 hours
	M D LEM G&N Act	I Inactivity 53.5 watts 87.40 ł	II Inactivity Alignment Midcourse Measurer 431.7 watts 11.72	III Guidance During Ma. 431.7 watts 0.201	IV Inactivity 63.5 watts 20.05 h	T	v Inacuvity 63.5 watts 15.70 h

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Section 5

GLOSSARY AND SYSTEM DEFINITION

Apollo Guidance Computer (AGC)

<u>CM BLOCK I</u> A single complete flight computer containing all logic, memory, associated power supplies, and all interface circuits except those identified with the CDU's. Does not contain the associated displays and controls.

Consists of one case containing factory replaceable electronic modules. Includes cover for moisture-proofing, but does not include the necessary cold plate or the G&N to S/C Interface Assembly which is located in the adjacent area.

<u>CM BLOCK II AND LEM</u> Same as Block I except that associated power supplies are in a separate case and the CDU's are either adjacent to or on the opposite side of the same cold plate as the AGC. Memory capacity is increased over Block 1. Computer includes a hermetically sealed container for protection from contamination.

Alignment Optical Telescope (AOT)

CM BLOCK I AND BLOCK II Not in CM; see Optical Subsystem.

LEM A 3-position periscope with single-degree-of-freedom manually read reticule for alignment of the IMU. Includes the weight of the bellows assembly, a long-eyerelief eyepiece, and regular eyepiece.

Bellows Assembly

<u>CM BLOCK I AND CM BLOCK II</u> Two flexible pressure seals between CM structure and optical subsystem for penetration of pressure hull with optics.

LEM One bellows with a double convoluted wall and two seals providing a flexible seal for pressure penetration of the AOT in the spacecraft. This weight is included in the AOT value.

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Book of Procedures

CM Not in CM; see MDV_{*}

LEM Book or other form of maps, charts, procedures, instructions, and the like, needed for lunar operations.

Coupling Data Unit (CDU) Assembly

The CDU provides the necessary signal interfaces among the IMU gimbal angles, optics gimbal angles, radar gimbal angles, angle registers in the AGC, the spacecraft autopilot attitude error signals, and the tracking radar command error signals.

<u>CM BLOCK I</u> Five interchangeable gear boxes each with necessary motor tachometer, resolver synchros, and encoder with mounting frame work. Does not include associated electronics which are located in the PSA.

<u>CM BLOCK II</u> Functionally identical to Block I except the instrumentation is all electronic. Includes all support electronics (including special power supply) and header. Changes in resolver synchro characteristics and mode controls make Block I and II CDU's noninterchangeable. The CDU Assembly includes a hermetically sealed container for protection from contamination.

LEM Interchangeable with CM Block II CDU's except for the headers.

Cold Plates

<u>CM BLOCK I, BLOCK II, AND LEM</u> Cold plates for the IMU are built into the IMU. Necessary cold plates for electronics are part of the equipment supplied by the spacecraft manufacturer. All surfaces over glycol coolant passages and open to the cabin environment will be insulated to prevent moisture condensation.

Control Electronics Assembly

<u>CM BLOCK I</u> Consists of one power transformer, one relay and diode module, and a bracket end connector. Used to support display and control functions. Includes moisture-proofing.

CM BLOCK II May be relocated with other similar functions.

LEM Not defined in LEM.

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Coolant Hoses

<u>CM BLOCK I AND CM BLOCK II</u> Consists of (1) two steel flex coolant hoses, one between IMU and spacecraft and one between optics and spacecraft, (2) bracket assembly screws and clamp, and (3) entrapped coolant.

LEM Not identified as part of LEM.

Display and Control/Apollo Guidance Computer (D&C/AGC)

<u>CM BLOCK I</u> Number displays and keyboard control associated with the operation of the AGC. Two functionally identical and parallel operating units: one in lower equipment bay and one on main panel between left and center couches.

<u>CM BLOCK II</u> Mechanically and electrically identical to Block I but smaller configuration because of smaller relays. The Block II display and keyboard controls will be hermetically sealed by encasing the unit in a container.

LEM Identical to Block II except only a single unit is required.

D&C Electronics Assembly

<u>CM BLOCK I</u> Consists of a chassis, a relay and diode module, a demod. elect. module, a saturable reactor, a time delay module, a connector, and wiring. Used to support display and control functions. Connectors will be moisture-proofed.

CM BLOCK II Not defined at this time.

LEM Not defined in LEM at this time.

Landing Point Designator

CM Not in CM

LEM An optical sighting device consisting of a reticle, plane mirror, collimating lens, and a beam splitter to magnify the target area with a light-line reticle pattern.

Film Cartridges

<u>CM BLOCK I AND BLOCK II</u> Consists of film cartridges and film for map and data viewer.

LEM Does not exist in LEM.

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G&N Indicator Control Panel

<u>CM BLOCK I AND BLOCK II</u> Consists primarily of controls and displays for the operation of the optics, MDV, IMU temperature control, panel brightness control, and attitude impulse control. It includes display and control elements, panel, panel wiring, supporting hardware, and moisture-proofing.

LEM Does not exist in LEM.

G&N Interconnection Assembly

<u>CM BLOCK 1</u> Consists of PSA End Connector Assembly and interconnect wiring harness, which electrically ties together the assemblies that constitute a completely integrated system. This term does not include weights of harness support brackets, which are an NAA responsibility, or the G&N to S/C Interface Assembly weight.

<u>CM BLOCK II</u> Similar to Block I but not interchangeable. The connectors in the upper harness are now to be sealed against moisture and contamination.

<u>LEM</u> Not clearly defined but at present is called the AGC/PSA Interconnection Assy. Because of the wide separation of G&N components, most interconnection will be accomplished as part of spacecraft wiring.

G&N to S/C Interface Assembly

<u>CM BLOCK 1</u> Cable interconnections between the spacecraft wiring channel, the computer connector, and the PSA end connector. Contains no active electronics.

<u>CM BLOCK II</u> Similar in functions to Block I except the configuration is much different and not interchangeable with Block I. The connectors in the lower harness are now to be sealed against moisture and contamination.

LEM Not identified yet as a separate item in LEM.

Horizon Photometer

<u>CM BLOCK I AND BLOCK II</u> An earth horizon brightness photometer and automatic star tracker used for navigation measurements against the earth's illuminated limb. The sensors are incorporated into the head of the SXT the weight of which includes the this function. The PSA includes all support electronics for Block II and some of the support electronics for Block I.

LEM Not a part of LEM.

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Horizon Photometer Electronics

<u>CM BLOCK I</u> Additional horizon photometer and star tracker electronics mounted on an auxiliary header and attached to the right-hand wall behind the MDV.

CM BLOCK II All electronics are located in the PSA or on the sextant head.

LEM Not required.

Inertial Measurement Unit (IMU)

<u>CM BLOCK I</u> Size 14 IMU (14-inch case diameter) gimbal assembly including all parts inside hermetic case, entrapped coolant, and heat exchanger insulation.

<u>CM BLOCK II AND LEM</u> Size 12.5 IMU functionally interchangeable with Block I unit, but not physically interchangeable with Block I.

IMU Control Panel

<u>CM BLOCK I</u> Consists of panel, wiring, attitude error meter, CDU transfer switch, manual alignment switch, CDU mode control switches, connector, supporting hard-ware, and associated moisture-proofing.

<u>CM BLOCK II</u> Does not exist in Block II. Moding is done by AGC program and AGC push buttons.

LEM Does not exist in LEM.

Long-Eye-Relief Eyepieces

<u>CM BLOCK I AND BLOCK II</u> Consists of a SXT and a SCT eyepiece to provide eye relief of at least 1.6 inches for closed visor operation. Used in place of normal eyepieces of SXT and SCT.

LEM Long-eye-relief eyepiece is included as part of the AOT.

Map and Data Viewer (MDV)

<u>CM BLOCK I AND BLOCK II</u> Film viewer for display of maps, charts, procedures, and the like. Weight includes on film cartridge and a moisture-proofing enclosure.

LEM Not in LEM; see Book of Procedures.

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NVB and Mounts

<u>CM BLOCK I</u> Rigid beryllium structure supporting the IMU and the optical subsystem with its associated hardware. The NVB is attached to the spacecraft using flexible resilient mounts to prevent spacecraft strains from distorting the NVB and the alignment between the IMU and optics. These mounts also provide shock and vibration attenuation.

<u>CM BLOCK II</u> Functionally similar to Block I but will be ligher and provide for mounting the size 12.5 IMU. The Block II NVB is attached to the spacecraft by use of strain isolation hardmounts and will have a transition piece as a result of the reorientation of the NVB so that the IMU axes will be parallel to the Command Module axes.

LEM A toroidal aluminum ring with: (1) four tubular aluminum posts to provide for IMU mounting, (2) four tubular aluminum posts for AOT mounting, and (3) three aluminum inserts to provide strain isolation ball mounting to the GAEC structure.

Optical Eyepieces

CM BLOCK I AND BLOCK II Removable SXT eyepiece and SCT eyepiece.

<u>LEM</u> Included as part of the AOT.

Optical Subsystem

<u>CM BLOCK I AND BLOCK II</u> Consists of SXT, SCT, Optical Base, and associated hardware defined as follows:

- SXT: Sextant. A two-line-of-sight, narrow-field, two-degree-of-freedom sextant and its attached gearing. The horizon photometer and automatic star tracker sensors are incorporated into the SXT head.
 SCT: Scanning Telescope. A single-line-of-sight, wide-field-of view, two-degree-of-freedom articulation optical instrument and its attached gearing.
- Optical Base Base for SXT and SCT with associated gearing and internal cooling.

LEM Not in LEM; see AOT.

Optical Shroud & Cover Assembly

CM BLOCK I AND BLOCK II Consists of the optical shroud and protective cover.

LEM Does not exist in LEM.

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Power Servo Assembly (PSA)

<u>CM BLOCK I</u> Includes most of the support electronics: power supplies; IMU, Optics, and CDU servos; IMU temperature control; accelerometer and gyro pulse torquing; and horizon photometer and automatic star tracker electronics. Consists of 10 trays and replaceable modules which plug into the PSA end connector assembly. Includes a beryllium front toe plate.

<u>CM BLOCK II</u> Similar in function to Block I except that all horizon photometer electronics are included in the Block II PSA, and the CDU servos are deleted. Consists of a single plane matrix header, mounted to a cold plate, with the modules plugging onto the top. To permit removal of the calibration modules at IMU adjustment or replacement, these modules are contained in a separate assembly located on a cold plate adjacent to the Signal Conditioner Assembly. The PSA now includes a hermetically sealed container for protection from contamination.

LEM Consists of electronics similar to those identified in the Block II PSA minus various electronics modules. Does not include optics and photometry electronics associated with the Block I and II PSA's.

PSA End Connector Assembly

<u>CM BLOCK I</u> Electrical interconnection between the PSA trays, the G&N Interconnection Assy, and the G&N to S/C Interface Assy. The End Connector weight is reported in the G&N Interconnection Assembly weight.

<u>CM BLOCK II AND LEM</u> Not identified as a separate item; will be part of the PSA matrix header.

PSA Covers

<u>CM BLOCK I</u> Ten plastic connector covers, gaskets, and mounting screws (one for each tray) for moisture proofing.

CM BLOCK II AND LEM Not required.

Signal Conditioner Assembly

CM BLOCK I Conditions signals for telemetry.

<u>CM BLOCK II</u> These modules are located in the same volume now occupied by the Block I CDU's.

LEM Same as for Block I.

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COMMAND MODULE



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Appendix A

and contamination protection.

Appendix B

PRELIMINARY ESTIMATES OF THE POWER REQUIREMENTS OF THE COMMAND MODULE AND LEM G&N EQUIPMENT

The following table, Table B-I, presents preliminary estimates of the power requirements of the Command Module and Lunar Excursion Module G&N equipment.

	Block I Z	ero Series (w	vatts)	
		Max.	Nom.	Min,
AGC*	Operate Standby	150 18	130 15	100 12
Optic s	SXT ON SXT OFF	140 130	110 100	50 40
IMU	Operate Standby	400 80	330 60	220 50
Displays an	d Control	70	50	30
Total	, <u>, , , , , , , , , , , , , , , , , , </u>	760	620	400
	Block I 1	00 Series (w	attsi	
		Max.	Nom.	Min.
AGC *	Operate Standby	150 18	120 15	100 12
Optics		150	130	50
IMU	Operate Standby	400 80	330 60	230 50
Displays an	nd Controls	70	50	30
Total		770	630	410

Table B-I.	Power	Requirement	ts
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Based on nominal line voltage of 28 VDC. Line voltage varies between 24.0 and 32.0 VDC.

*The variation is based on load variation; for a particular computer, power drain is independent of line voltage variation.

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	Blo	ock II (watts)		
		Max.	Nom.	Min.
AGC*	Operate Standby	130 12	110 10	90 8
Optics		150	130	90
IMU*	Operate Standby	380 80	300 60	220 40
Display and	Control	75	60	20
Total	······································	740	600	420
	Lunar Excu	rsion Module	(watts)	
		Max.	Nom.	Min.
LGC†	Operate Standby	120 11	110 10	100 9
Radar†		40	30	25
IMU	Operate Standby	380 80	300 60	$\begin{array}{c} 220\\ 40 \end{array}$
Display and	Control	-	-	-
Total		540	440	345

Table B-I. Power Requirements (cont.)

*Variations for AGC and electronic CDU are based on load variations. For any particular unit, power drain is independent of supply voltage variations.

Total energy: 50 kilowatt hours for a 308-hour mission.

+Variations for LGC and electronic CDU are for load variations. For any particular unit, power drain is independent of supply voltage variations. Total energy: 12 kilowatt hours for a 135-hour mission.

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