

E-1142 (Rev. 27) (UNCLASSIFIED TITLE)

SYSTEM STATUS REPORT

December 15, 1964



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ACKNOWLEDGMENT

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ABSTRACT

The System Status Report is distributed monthly on the 15th. This month's revision of E-1142 (Rev. 27) contains, in general, the following information for the Block I and Block II Command Module and Lunar Excursion Module equipment: configuration weights, centers of gravity, moments of inertia, power requirements, status of computer programs, and reliability values.

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Section 1

INTRODUCTION

1-1 INTRODUCTION

The definition of what constitutes Block I, Block II, and LEM hardware is contained in the Glossary, section 5 of this report. In Block II and LEM the electronic CDU's, PSA, and AGC are now to return to the moisture-proofing concepts in practice before the hermetic sealing requirement was established.

The following information is included in this month's report:

- (2) Command Module, Block II Integrated Guidance, Navigation, and Control Configuration: Weights and reliability values.
- (3) Lunar Excursion Module
 LEM Integrated Guidance and Control Configuration (Configuration "B."
 Ref: Minutes of LEM Implementation Meeting No. 4): Weights and
 reliability values.

Also included is Appendix A which shows a comparison of the actual weights of the delivered G&N System No. 6 zero series equipment and the G&N 100 series equipment based on the latest weight estimates.

1-2 ACCURACY

The accuracy of numerical values reported in this revision should not be considered to be within the tolerances implied by the significant figures quoted. The reported values, although based upon the most current information, are subject to normal changes as design and development phases approach completion.

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Section 2

BLOCK I COMMAND MODULE DATA

2-1 WEIGHTS

Table 2-I presents the weights of all Block I flight (100 series systems) equipment, grouped according to specific location within the Command Module. Weights are reported to the component level and to the nearest tenth of a pound.

Given component weights are identified as estimated, calculated, and measured in order of increasing accuracy. These terms are defined by North American Aviation as follows: estimated weights (E) are based on rough calculations; calculated weights (C) are based on detailed calculations made from final production drawings that will be used to build flyable equipment; measured weights (M) are actual weights of equipment built to the production drawings.

North American Aviation will provide and be responsible for cold plate weights that are not integral with guidance and control equipment.

2-1.1 WEIGHTS STATUS REPORTING. Table 2-I also offers a comparison of present 100 series component weight values with those listed in System Status Report, E-1142 (Rev. 26), November 15, 1964. All weight changes are explained in paragraph 2-2.

2-1.2 CONTROL WEIGHT (ZERO SERIES). Column (a) in Table 2-I contains the February 15, 1964 weight status of Apollo G&N zero series equipment. Column (a) adds up to approximately the total control weight specified in letter PG-64-113 (March 6, 1964) from Mr. D. Gilbert, ASPO, Mr. M. Trageser, MIT/IL.

2-1.3 DESIGN LOAD WEIGHT (ZERO SERIES). At NASA Coordination Meeting No.15A, MIT agreed to assign "not to exceed" design load weights for individual Block I G&N zero series subsystems. These weights were assigned by MIT in MIT letter AG 594-64, May 18, 1964, and are shown in column (d) of Table 2-I.

2-2 REPORTED 100 SERIES WEIGHT CHANGES

2-2.1 CDU (+0.4 lb). The increase in weight is due to the need for additional potting for moisture-proofing purposes.

2-2.2 INTERCONNECTION ASSY (-5.0 lbs). The decrease in weight results from a more precise calculation.

COMMAND MODULE

[g)	Design	Load Wt.	5/64	(d)†		18.0					100.0	_			F	د در ا	0.00	75.0	45.0		0.001	4.5			~		70.0			~	0°0	8°0
ule (lbs at]	100 Series	Status	12/64	(c)		14.0(E)		18.7(E)	14.3(E)	17.0(E)		1.6(C)	2.6(C)	25.7 (M)	12.7 (M)	60.5 (C)	0.8(E)	59.8(C)	25.0(E)	00 0 LEV	(ភ) ^ ^ คง	3.1 (E)			3.0(E)	2.1 (E)	10.5 (E)	2.8(E)	11.5 (E)	21.9 (C)	2.2 (C)	3.9 (C)
mmand Mod				(c-b)		+0.4		0.0	0.0	0.0		0.0	0.0	0.0	0.0	0.0	0.0	0.0	-5.0	c	-3.0	0.0			0°0	0.0	0.0	0°0	+1.9	+0.5	0.0	0.0
) Series) Coi	100 Series	Status	11/64	(q)		13.6 (C)		18.7 (E)	14.3(E)	17.0(E)		1.6(C)	2.6(C)	25.7 (C)	12.7 (C)	60.5 (C)	0.8(E)	59.8(C)	30.0(C)		(1)0.68	3.1 (E)			3.0(E)	2.1 (E)	10.5(E)	2.8(E)	9.6 (C)	21.4 (C)	2.2(C)	3.9 (C)
Block I (10)				(b-a)		-0.9		+0.5	+0.5	+0.3		+0.3	+0.3	+0.7	-0.8	+0.3	-0.2	+0.4	-5.2	ې - لرم	0.6+	-0.4			+0.1	-0.8	+1.0	+0.4	+1.9	+0.8	+2.2	+3,9
ht Status of	0 Series	Status	2/64	(a)		14.5 (M)		18.2 (C)	13.8(C)	16.7(E)		1.3(E)	2.3(E)	25.0(E)	13.5 (M)	60.2(M)	1.0(E)	59.4 (C)	35.2 (E)	8.0(E)	70.0(E) -	3.5 (M)			2.9 (M)	2.9(E)	9.5 (M)	2,4 (M)	7.7 (C)	20.6 (M)	0.0	0.0
Table 2-I. Current Weig		Item			G&N SYSTEMS	CDU Assy	Optical Subsystem	SXT	SCT	Optical Base & Gearing	Optical Eyepieces	SXT	SCT	NVB & Resilient Mounts	Bellows Assy	IMU	Coolant Hoses (two)	Power Servo Assy	G&N Interconnection Assy	G&N to S/C Interface Assy	AGC (no spares)	Optical Shroud	LOWER EQUIPMENT BAY	D&C	D&C Electronics	Control Electronics	G&N Ind Cont Panel	IMU Control Panel	MDV (includes 1 film)	D&C/AGC	Horizon. Photo. Elect.	Signal Conditioner Assy

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DATE <u>12/1</u>5/64

	r	1			
(cont)	Design Load Wt. 5/64	26.0	ເມ (0 ເຊິ່ງ ເຊິ່ງ	522,0	, ASPO, ph 2-1.3.
e (lbs at 1 g)	100 Series Status 12/64 (c)	21.9 (C)	1.5 (E) 2.5 (C) 1.6 (C)	421.2	D. Gilbert only. See paragra
nand Module	(c-b)	+0,5	0, 0 0, 0	۲- ۲- ۲-	4) from Mr. zero series 18, 1964).
eries) Comr	100 Series Status 11/64 (b)	21.4 (C)	1.5(E) 2.5(C) 1.6(C)	425 . 9	Applies to 94-64 (May
ock I (100 S	(b-a)	+ 0° 6	0,0 +0,1 -0,1	+11, 2	3-64-114 (M aph 2-1.2. letter AG 5
Status of Bl	0 Series Status 2/64 (a)	20 • 5 (M)	1.5 (E) 2.4 (E) 1.7 (M)	415.0^{*}	in letter PC See paragn n from MIT
Table 2-I. Current Weight	Item	MAIN PANEL AREA D&C/AGC	LOOSE STORED ITEMS Eye Relief Eyepieces Film Cartridges (4) Optics	TOTAL	*Total control weight specified to Mr. M. Trageser, MIT/IL. †Design Load Weights are take Applies to zero series only.

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2-2.3 AGC (-3.0 lbs). A more detailed calculation is now possible. The measured weight of the 104B computer without the three rope sticks, rope cores, tray potting, and module potting was 69.0 lbs. It is estimated that these items weigh an additional 11.0 lbs. The total weight for the computer plus the above items is estimated to be 80.0 lbs.

2-2.4 MDV (+1.9 lbs). The total weight increase is the result of moisture sealing of the equipment reported below.

2-2.4.1 Optics Subsystem (+1.4 lbs). A welded one-piece sheet metal enclosure for the projection light system has been added. Passage of air from within to without and vice versa is permitted by a pressure-balancing valve. The characteristics of the value are such that the internal to external pressure differential will never exceed 1 psi.

All the elements of the condenser system will be contained in a one-piece sealed lens housing capable of withstanding pressure, negative or positive, of 15 psi maximum.

2-2.4.2 <u>The Electronics Package (+0.4 lb</u>). The electronics package weight increase is due to the incorporation of waterproof connectors.

2-2.4.3 Lamp and Socket Unit (+0.1 lb). Moisture-proofing of the lamp socket and the interface of the lamp with the socket will be accomplished in the following manner: The socket will be a one-piece drawn cup with leads potted into its base. The interface moisture seal will be especially designed rubber compression grommet sealing the flange of the lamp base with the flanged mouth of the lamp.

2-2.5 D&C/AGC LEB (+0.5 lb). The increase in weight is due to the need for additional potting for moisture-proofing purposes.

2-2.6 D&C/AGC MP (+0.5 lb). The increase in weight is due to the need for additional potting for moisture-proofing purposes.

2-3 BLOCK I (ZERO SERIES) WEIGHT, CENTER OF GRAVITY, AND MOMENT OF INERTIA DATA

Block I (100 series) center of gravity and moment of inertia information is unavailable at this time, but is under preparation.

Included for reference are the total Block I (zero series) weight, center of gravity, and moment of inertia values.

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Weight (lb)	Cente	r of Gravity (in)	Mom	ents of Inertia* (lb-in ²)
408.9	X	55.1	Ixx	681,030
	Y	-0.3	Iyy	1,939,064
	Z	37.3	Izz	1,308,074

Table 2-II. Block I (Zero Series) Weight and Balance Data

*Values determined with respect to the basic X, Y, Z axes of the Command Module.

2-4 COMMAND MODULE POWER REQUIREMENTS (100 SERIES)

The power requirements of the Command Module G&N 100 series equipment on the primary +28 VDC power supply are shown in figure 2-1 which presents the magnitude and location of dissipated power values on a subassembly level. This chart assumes a 12.85-day lunar mission, as defined by S&ID for power profile computation, and is based on 28 VDC input at the connectors. The values shown are average values. (Ref: S&ID letter 63 MA 3540.)

Table 2-III shows the magnitude and location of power dissipation for the established G&N activities, each of which consists of various power levels of operation.

Table 2-IV shows the energy requirements for each G&N activity on a power level basis. The table is based upon MIT letter AG 679-6, "G&N Power Profile Status," dated August 14, 1963. The vertical column to the left indicates the various G&N activities (phases of operation) for the model 12.85-day mission submitted by S&ID in S&ID letter 64 MA 3540. The column also indicates the power requirement and operating time for each specific activity. The top row indicates the power requirement and operating time for each G&N power consuming equipment. The table sums up the energy consumption for each G&N activity and each G&N power consuming equipment.

2-5 STATUS OF COMMAND MODULE AGC PROGRAMS

The integrated guidance and control implementation activity has defined stablization and control functions which must be part of the Block II computer program. Since the current program estimates do not include these S&C functions, the computer program status has been moved from section 3 to section 2 where it applies to the Block I configuration used for a lunar mission but without S&C. When the computer estimates include these added functions, the AGC program status will be returned to section 3.

	COMPUTER			•			P5A	NBA	cDin-18	AGC	DIC	SXT. HEAD	EXT.
	26.32 %	6	10W OPERATE			APOLLO GUIDANCE COMPUTER				100W.	10 W.		
13,551 W HOURS	100%		15.0 W			AGC. STANDBY	+		i	15			
S W STANDBY			6.9W			OPTICS ELECTRONICS 4 RELAYS	6.9W						<u> </u>
3.9 WMISSION AVG.			2.6W			ENCODER ELECTRONKS	2.6 W.						
			39.6 W			OPTICS SERVO AMPLIFIERS	24.0W	10.4W,	5,2 W.				1
			1.5W			800 ~ AAC	1.5 W,						1
				ADD CP5		MOTOR EXCITATION		5.2W	5.2W				
OPTICS	OPR - 6.44 %		35.6W SXT ON	284 5%	L			0-5.2W					
	Y^	DIODES				20W SXT ON - 16.2W SXT. OFF	16.2-20W	۴					-
165 W HOURS	>	LJ				RSVR EXCITATION	"	2.2W	1.5W				1
6.8 W OPP (SAT OFF	•)	1	30.4W	28v 1%	┝╍╌┝	TACH EXCITATION		7.4Wc	3.7We				ŀ
				SUPPLY	ΙL	HAND CONTROLLER					IW,		
				L.,			14.6 W						
			3.7W	25.6 KC		ENCODER EXCITATION			.5W		1		-
				EXCL									
							3.2Wc						
			2.5 W			TRACKER ELECTRONICS	0,3 We					1.7 W,	, 0.
		L	3.0W				3.0Wc			I			
			5			SIGNAL CONDITIONING				L		I	
	THU HEATER		2.1W				5W 2			i		+	
	SW W100 %	BLOCKING	IOW			TEMP CONTROLLER	2.1Wc				ł	+	+
ſ	59.7W IML ON	DIODES	20-22W			HEATERS 20W IMU ON-22W IMU OFF(3)		20.20	 		<u> </u>	┥	+
	61.7W IMU OFF	·			 1	DUCOSYN EXCITATION 2V SINE WAVE]	KO 22W			<u> </u>	╅	+
			19.1W	3200 CPS SUPPLY		TEMP CONT EXCITATION 200 50 WAVE		13.30	ļ	+		+	-+
· · · · · · · · · · · · · · · · · · ·				L			- 50					+	+
	:	:	1.5 1/			3200 ~ AAC	- 0.6 W					+	+
ļ			2W			······································	1.5Wm	·	· · · ·			<u> </u>	+
		ha.a					ZW.				1	+	+
			_ UT.IW	-28VDC		-) PRA PILSE TORRIE ELECTRONICS	OWN	1 we		-		+	
			[POWER SUFFICE	J		1	1.6W	ý	<u> </u>		<u> </u>	
			n end	L		TOIS & PIDA ELECTRONICS	- <u>7</u> 3M	—	<u> </u>		+		
1,385 W HOURS						IRIG & FIFA ELECTRONICS	11.6W	}		i		1	
25.8 1/ DHR 34.2 - MISSION AVG			59.W	PIPA 120V-12VDC		PIPA ELECTRONICS	47 W	1				T	
66.4 W MAX.			ſ	POWER SUPPLY]		м	4		-	-	-	
					 1	······································	- 12 W						
			29.4 W	120V-12VDC		IRIG ELECTRONICS	22.8h	/					1
			(TOW MAL)	POWER, SUPPLY	ļ		<u>м</u>	<u>.</u>	+	+	+	1	+
			3	L		PIPA FIXED HEATERS	- 0.00	4		+			+-
			2.6W			PREAMP]	- <u>~</u> ~	4	+			
			r			GYRO WHEELS		2.6W	1	-			-+
	JOPR SW			800 CPS	ן ר	BLOWERS]	2014	4	+	-		+-
	27.47%	BLOCKING	66.9 W	- 28V 5%	\vdash	LOAD COMPENSATION	2314			+	+		+-
	26610	DIODES	-	(-	COU MOTOR		¥	ZAN	· · · · · · ·		4	+
	3067W(MAX)	<u> </u>					43.6 %		+	1	+		+
						RSVR EXCITATION		2 4141	1.5.	+	+	+	+-
				BOD CPS	ר ו	TACH EXCITATION		+	674		+	+	+
			23.64	- 28V 1%		DEMOD REF	- Iw	+	0.14	<u>*</u>	+	+	+-
					J	FDAT & AUTO PILOT REF .7.W (I) M		<u>\</u>	+			+	+-
		1				-	115	,†	-	+		+	+
						800~ AAC	1.50		+-			+	+
			22.4	25.6 KC	1	ENCODER EXCITATION	-	4—	+	+		+	+-
				ENCODER					.1W	1			
				<u> </u>	-		2.1W						
			12W			SERVO POWER	-6~	1	6W	1		+	+
			2.2W			P-A CONVERTER & RELAYS	-2.2 W	1	1	<u>+</u>		+	+
		1	4.8W			ENCODER ELECTRONICS	-4.8W	<u> </u>					+
		L	8 w 8			·	- 8W	1		-		+	+
		OPTICS!	9W TRANSIENT	^{27,}		SERVO AMP (MEDV) (2)	_ 	+	+	+	9W		+
		DIODES	179 W TRANSIE	VT 5	WITCHI	K CONDITION LIGHTS (2)	_				17.9	Ł	1
139 W HOURS	SPACE CRAET				2- 40	2~ (IEIL ON-SW, 2 FIL ON-IZW)LAMPS (M&D	4				1~		
424 W HOURS	400~ STATIC		21.4 W MAX	6.44% 6V	- 400	D~ INDICATOR 4 ILL UMINATION LIGHTS 28VDC FO		8.64	2 5.8	N.	70	2	
	INVERTER		OW TRANSIENT	27. 60	- 400	NOTOR (MEDV) (2)		1	1-		8W		T
				`			h						
	<u>+ 60 mimaky</u>	ON PRIMARY	CODE (C) CALCULATE (C) ESTIMATEC (H) MEASURED	D POWER D POWER POWER	TOTAL	SI:57,964 W HOURS BASED UPON 308.3 HO 188.0 W MISSION (12.85 DAY) LUNAR ORBI AVG, J(REF SIZ) LETTER, 64 645.6 W WORST POSSIBLE 605.0 W WIRST POSSIBLE	JRS MISSIO MA 354	N.)	NOTE	(1) TC (2) IN (LES (3)22 EN	S &C TERMIT S THAN W, "ZEE VIRONN	ENT 0 ~1% 01 20" G	PER
			(M) MEASURED	Power		645.6 W WORST POSSIBLE 605.0 W ALL SYSTEMS OPERATING				(3)22 EN 33 EN	W, "ZEF VIRONN W, "ON VIRONN	LO" G MENT IE" G NENT	

Figure 2-1. Electrical Load on Primary +28 VDC Power Supply Block I (100 Series) Systems

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	Table 2-III. Nominal Po	wer Diss	ipation (watts) vs	G&N Act	tivity fo	r Block I	(100 Series) Sy	stems		
ZOF	G&N Activity	NB	Ą	CDU	PSA			Thermal Load on S/C	D&C and	Optics	Electrical
а <u>ш</u>	(power levels) .	IMU	OBA	JB	IMU	OBA	AGC	Coolant	S&C	External	Load
A	Accomplish & Confirm Course Corrections Inactivity and Monitor Major Maneuver (1,5)	74 5	0.0	22.1	228.5	0.0	115.0	440.1	10.7	0.0	450.8
ы	Alignments Sextant Sightings (1, 3, 5, 7)	74.5	40.7	44.0	228.5	76.1	115.0	578.8	25.7	0.5	605.0
O	Landmark Trackings (Low-Orbit Navigation) (1,4,5,7)	74.5	35.5	44.0	228.5	72.3	115.0	569.8	25.7	0.5	596.0
9	Star Occultation Sightings (1, 6)	25.5	0.0	0.0	36.2	0.0	115.0	176.7	10.0	0.0	186.7
ы	Sextant Sightings Midcourse Navigation (1, 3, 6, 7)	25.5	40.7	21.9	36.2	76.1	115.0	315.4	25.0	0.5	340.9
E4	Inactivity & Monitor (2, 6)	25.5	0.0	0.0	36.2	0.0	15.0	76.7	0.0	0.0	76.7
U	Inactivity & Monitor (2,5)	74.5	0.0	22.1	228.5	0.0	15.0	340.1	0.7	0.0	340.8
		7 6 6 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	GC Oper GC Stand ptics Ope ptics Ope fU Opera fU Stand	ate by srate SXT srate SXT ute by ate	ON OFF		125.0 v 15.0 v 125.8 v 125.8 v 116.8 v 325.8 v 61.7 v 28.4 v	rattis rattis rattis rattis rattis vattis			

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F									
ХООЫ	G&N Activity	(1) AGC Operate 125.0 watts 81.15 hours	(2) AGC Standby 15.0 watts 227.13 hours	(3) OpticsSextant ON125, 8 watts16, 39 hours	(4) OpticsSextant ·OFF116, 8 watts3.45 hours	(5) IMU ⁻ Operate 325.8 watts 84.68 hours	(6) IMU Standby 61.7 watts 223.60 hours	(7) D&C Operate 28.4 watts 19.84 hours	Total
4	Accomplish & Confirm Course Corrections Inactivity and Monitor Major Maneuvers 450.8 watts 58.41 hours	7,301	l	1	1	19.030	I	1	26.331
A	Alignments Sextant Sightings 605.0 watts 13.73 hours	1.716	1	1.727	1	4.473	I	0.390	8.306
U	Landmark Trackings (Low-Orbit Navigation) 596.0 watts 3.45 hours	0.431	ł	I	0.403	1.124	1	0.098	2.056
P	Star Occultation Sightings 186.7 watts 2.90 hours	0.363	1	1	1	. 1	0.179	I	0.542
ы	Sextant Sightings (Midcourse Navigation) 340.9 watts 2.66 hours	0.333	1	0.335	-	I	0.164	0.076	0.907
Γ4	Inactivity and Monitor 76.7 watts 218.04 hours	1	3.271	I	1	I	13.453	I	16.724
U	Inactivity and Monitor 340.8 watts 9.09 hours	I	0.136	1		2.962	ł	1	3.098
	Total 308.30 hours	10.144	3.407	2.062	0.403	27.589	13.796	0.563	57.964
1									

Table 2-IV. Block I (100 Series) Command Module Energy Consumption Profile for 12.85-Day Lunar Orbit Mission

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BLOCK I COMMAND MODULE

BLOCK I

COMMAND MODULE

Table 2-V lists current Command Module memory estimates and the status of AGC programs for the lunar landing mission guidance and navigation functions.

A high and low word estimate is given with each program. Each status is defined as follows:

- (1) Planning stage
- (2) Programming stage
- (3) Checkout on AGC simulation
- (4) Checkout on G&N simulation
- (5) Checkout on AGC

Table 2-V. Current Memory Estimates and the Status of Command Module AGC Programs (12/15/64)

Item		Memory H (word	Estimate ls)
	Status	High	Low
List Processing Interpreter	(5)	1712	1712
AGC Executive	(5)	253	253
AGC Waitlister	(5)	145	145
AGC System Exerciser	(5)	500*	294*
G&N System Exerciser	(4)	650	400
Display, Keyboard, and Telemetry	(5)	2000	2000
Input/Output Control	(5)	1750*	1275*
Midcourse & Orbital Navigation	(5)	2000*	1500*
Midcourse & Orbital Guidance	(3)	500	500
Pre-Launch Platform Alignment	(5)	400*	350*
In-Flight Platform Alignment	(4)	1024	900
Re-Entry Control	(4)	1800	1200
Injection and De-Boost	(4)	1000	400
Restart	(5)	500*	200*
Aim-Point Determination & Abort	(3)	4000	2000
Totals		18234	13129

*Programs in stage (5) whose low and high estimates are not identical reflect an anticipated increase in computation facility.



Section 3

BLOCK II COMMAND MODULE DATA

3-1 INTRODUCTION

On September 23, 1964, MIT was directed to hermetically package all electronic components in the Command Module as the basic approach for humidity and contaminant protection. During the period of changing to hermetic sealing, MSC assessed the consequences and now has directed MIT to return to the conformal moisture-proofing of the CDU's, PSA, and the AGC.

3-2 RELIABILITY

The reliability figures shown in Table 3–I are the current estimates of the Block II Command Module G&N equipment. They reflect the realignment of the interface configuration which requires the G&N equipment to assume certain stablization and control functions, the elimination of the standby guidance computer, and the most recent estimate of electronic CDU reliability. These estimates of Command Module G&N reliability are based on the 138-hour mission defined in the Lunar Landing Mission Design Plan.

Subsystem	Operation Time (hrs) Full Power	Probability of Mission Success
IMU	31	0.9961
AGC	19*	0.9869
DSKY	19	0.99999
PSA	31*	0.99421
CDU (5)	31	0.9923
Optic s	18	0.99804
Total G&N	System	0.9679

Table 3-I. Reliability (as of 12/15/64)

*Certain assemblies function continuously.

3-3 WEIGHTS

Table 3-II shows the weights of the Block II Command Module Integrated Guidance and Control system.

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Table 3-II. Curren	t Weight Sta	tus of Block	II Command	1 Module (lt	is at 1 g)	
						Design
	Status		Status		Status	Load Wt.
	2/64		11/64		12/64	5/64
	(a)	(b-a)	(q)	(c-b)	(c)	(p)
G&N SYSTEMS						
CDU Assy	15.0(E)	+21.0	36.0(C)	-3.0	33.0(E)	
Optical Subsystem						
SXT	18.2(C)	+ 0.5	18.7 (E)	0.0	18.7(E)	
SCT	13.8(C)	+ 0.5	14.3(E)	0.0	14.3(E)	
Optical Base & Gearing	16.7(E)	+ 0.3	17.0(E)	0.0	17.0(E)	
Optical Eyepieces			/			
SXT	1.3(E)	+ 0.3	1.6(E)	0.0	1.6(E)	
SCT	2.3(E)	+ 0.3	2.6(E)	0.0	2.6(E)	
NVB & Mounts	22.0(E)	- 5.0	17.0(E)	0.0	17.0(E)	
Bellows Assy	13.5(C)	- 0.8	12.7 (E)	0.0	12.7 (E)	
IMU	42.0(E)	+ 0.1	42.1 (E)	0.0	42.1 (E)	
Coolant Hoses (two)	1.0(E)	- 0.2	0.8(E)	0.0	0.8(E)	
Power Servo Assy*	45.1 (E)	+ 9,6	54.7 (E)	-9.6	45.1 (E)	
G&N Interconnection Assy	35.2(E)	- 4.2	31.0(E)	0.0	31.0(E)	
G&N to S/C Interface Assy	8.0(E)	+ 0.5	8.5(E)	0.0	8.5(E)	
AGC	92.5(E)	-26.5	66.0(E)	-8.0	58.0(E)	
Optical Shroud	3.5(C)	- 0.4	3.1 (E)	0.0	3.1(E)	
LOWER EQUIPMENT BAY						
D&C						
D&C Electronics	1.5(E)	0.0	1.5(E)	0.0	1.5(E)	
Control Electronics	2.9(E)	- 0.9	2.0(E)	0.0	2.0(E)	
G&N Ind Cont Panel	11.1 (E)	+ 1.0	12.1 (E)	0.0	12.1 (E)	
MDV (including 1 film					·	
cartridge)	8.3(E)	+ 3.2	11,5(E)	0.0	11.5(E)	
D&C/AGC	20.6(E)	- 1.6	19.0(E)	-1.5	17.5(E)	
Signal Conditioner Assy	0.0	+ 3.9	3.9 (C)	0.0	3.9 (C)	

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(cont)

	<u></u>							
	Design Load Wt.	5/64 (d)				492.6§	O, to clude	
at 1 g) (cont)	Status	12/64 (c)	17.5(E)	1.5(E) 2.5(E)	2.0(E) 1.6(C)	377.1	ilbert, ASP Does not in	
Module (lbs a		(c-b)	- 1.5	0.0	0.0	-23.6	om Mr. D.G	
Command N	Status	11/6 4 (b)	19°0 (E)	1 . 5 (E) 9 E (E)	1.6(C)	400.7	6, 1964) fro 2, February	
of Block II		(b-a)	- 1.5	0.0	- 0.1		113, March 12-1.2. r 63 MA 203	
Veight Status	Status 9.77	2/0 4 (a)	20.5(E)	1.5 (E) 1.8 (E)	1.7(E)	400.0 [†]	Cover. tter (PG-64- ee paragraph n S&ID lettel	
Table 3-II. Current V	Item		MAIN PANEL AREA D&C/AGC	LOOSE STORED ITEMS Eye Relief Eyepieces Film Contridues (A)	Optics Cover	TOTAL	*Includes the weight of the PSA [†] Control Weight specified in let Mr. M. Trageser, MIT/IL. S [§] Design Load Weight taken fror loose stored items.	

COMMAND MODULE

SOMPOENTIME

3-4 REPORTED WEIGHT CHANGES

3-4.1 CDU (-3.0 lbs). The weight decrease is a result of the return to the previously established moisture-proofing of the CDU package. The weight did not revert to the original estimate because of a more refined calculation of the final layout.

3-4.2 PSA (-9.6 lbs). The weight decrease is a result of the return to the conformal moisture-proofing of the PSA package. This weight includes the PSA cover.

3-4.3 AGC (-8.0 lbs). The weight decrease is a result of the return to the conformal moisture-proofing of the AGC.

3-4.4 D&C/AGC LEB (-1.5 lbs). The weight decrease is a result of a more detailed calculation of the hermetically sealed design configuration.

3-4.5 D&C/AGC MP (-1.5 lbs). The weight decrease is a result of a more detailed calculation of the hermetically sealed design configuration.

3-5 POWER REQUIREMENTS

The power requirements of the Block II Command Module G&N equipment on the primary +28 VDC power supply are shown in figure 3-1, which presents the magnitude and location of dissipated power values on a subassembly level. This chart assumes a 12.85-day lunar orbit mission as defined by S&ID for power profile computation and is based on 28 VDC input at the connectors. These values are average values. (Ref: S&ID letter 64 MA 3540.)

Table 3-III shows the magnitude and location of power dissipation for the established G&N activities, each of which consists of various power levels of operation.

Table 3-IV shows the energy requirements for each G&N activity on a power level basis. The table is based on MIT letter AG 679-6, "G&N Power Profile Status," dated August 14, 1963. The vertical column to the left indicates the various G&N activities (phases of operation) for the model 12.85-lunar day mission submitted by S&ID in S&ID letter 64 MA 3540. This column also indicates the power requirements and operating time for each specific activity. The top row indicates the power requirements and operating time of each G&N power consuming equipment. The total power consumption for each G&N activity and each G&N power consuming equipment is also given.

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	LADIE 3-111, INUILIIAI	Lower DI	Intraction	(subw) 1	A NOD CA	CLIVILY 14		empled		
X O A	G&N Activity	NB	Ā		PS	A		Thermal Load on S/C	D&C and	Electrical
ы	(power levels)	IMU	OBA	CDU	IMU	OBA	AGC	Coolant	S&C	Load
A	Accomplish & Confirm Course Corrections Major Maneuvers Inactivity & Monitor (1, 4)	76.5	0.0	44.1	163.9	0.0	100.0	384.5	10.7	395.2
æ	Alignments Sextant Sightings Landmark Trackings (Low-orbit navigation) (1, 3, 4, 6)	76.5	52.1	73.5	163.9	61.2	100.0	527.2	25.7	552.9
U	Star Occultation Sightings (1,5)	25.5	0.0	0.0	28.0	0.0	100.0	153.5	10.0	163.5
D	Sextant Sightings (Midcourse Navigation) (1, 3, 5, 6)	25.5	52.1	29.4	28.0	61.2	100.0	296.7	25.0	321.2
ы	Inactivity & Monitor (2,5)	25.5	0.0	0.0	28.0	0.0	10.0	63.5	0.0	63.5
ίΞ.	Inactivity & Monitor (2, 4)	76.5	0.0	44.1	163.9	0.0	10.0	294.5	0.7	295.2
		1. AG 2. AGG 3. Opti 4. IMU 5. IMU 6. D&G	C Operat S Standby ics Oper ics Operate Standby Operat	e e e		110 wat 10 wat 135.1 v 285.2 v 53.5 v 22.6 v	ts ts /atts /atts /atts	·		

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C (2) AGC (3) Optics (4) IMU (5) IMU (6) D&C atts 10.0 watts 135.1 watts 285.2 watts 53.5 watts 22.6 watts Total urrs 227.13 hours 19.84 hours 58.6 hours 53.5 watts 22.6 watts Total urrs 227.13 hours 19.84 hours 285.2 watts 53.5 watts 22.6 watts Total urrs 227.13 hours 19.84 hours 285.2 watts 53.5 watts 22.6 watts Total urrs 227.13 hours 19.84 hours 285.2 watts 53.5 watts 22.3 00 0 23.0 0 urrs 227.13 hours 19.84 hours 285.2 watts 223.60 hours 19.84 hours 704a urrs 227.13 hours 19.84 hours 23.06 0.043 0.44 urrs 2.321 4.900 - 0.155 - 0.4 urrs - 2.321 4.900 - 0.142 0.600 0.8 urrs - - - <th></th> <th></th> <th></th> <th></th> <th>Fnergy</th> <th>Consumption (kw</th> <th></th> <th></th> <th></th>					Fnergy	Consumption (kw			
(2) AUC (3) Optics (4) Math (5) Much (5) Much (5) Optics (4) Math (5) Standby (5) Watts (5) Standby (5) Standby					control ((6) D&C	
15 10.0 watts 135.1 watts 285.2 watts 53.5 watts 22.5 watts Tota rs 227.13 hours 19.84 hours 84.68 hours 223.60 hours 19.84 hours 23.00 - - - 16.659 - - 23.00 - - 16.659 - 0.388 9.4 - 2.321 4.900 - 0.388 9.4 - 2.321 4.900 - 0.388 9.4 - 2.321 4.900 - 0.388 9.4 - - 2.321 4.900 - 0.388 9.4 - - 2.014 - 0.388 9.4 - - 0.155 - 0.4 0.4 - - 0.155 - 0.4 0.4 - - 0.155 - 10.4 10.4 - - 0.142 0.060 0.8 10.4 <t< td=""><td>G&N Activity Operate</td><td>(1) AGC Operate</td><td></td><td>(2) AGC Standby</td><td>(3) Uptics Operate</td><td>(4) IMU Operate</td><td>(a) IMU Standby</td><td>Operate</td><td>1</td></t<>	G&N Activity Operate	(1) AGC Operate		(2) AGC Standby	(3) Uptics Operate	(4) IMU Operate	(a) IMU Standby	Operate	1
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	110.0 wat	110.0 wat 81.15 hour	ts rs	10.0 watts 227.13 hours	135.1 watts 19.84 hours	285.2 watts 84.68 hours	53.5 watts 223.60 hours	22.6 watts 19.84 hours	Total
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Accomplish & Confirm Course Corrections 6.425	6.425		I	1	16.659	ł	I	23.084
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Major maneuvers Inactivity & Monitor 395.2 watts 58.41 hours								
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Alignments Sextant Sightings Landmark Trackings (Low-orbit Navigation) 552.9 watts 17.18 hours	1.890		1	2.321	4.900	, 1	0.388	9.499
- 0.359 - 0.142 0.060 0.8 2.180 - - 11.665 - 13.8 0.091 - 2.592 - 13.8 0.2211 2.680 24.151 11.962 0.448 50.4	Star Occultation Sightings 0.319 163.5 watts 2.90 hours	0.319		1			0.155	I	0.474
2.180 - 11.665 - 13.8 0.091 - 2.592 - 2.6i 2.271 2.680 24.151 11.962 0.448 50.4:	Sextant Sightings (Midcourse Navigation) 0.293 321.2 watts 2.66 hours	0.293		1	0.359	ļ	0.142	0.060	0.85
0.091 - 2.592 - 2.6i 2.51 2.680 24.151 11.962 0.448 50.4:	Inactivity & Monitor 63.5 watts 218.04 hours	1		2.180	1	ł	11.665	ł	13.84
2.271 2.680 24.151 11.962 0.448 50.4	Inactivity & Monitor			0.091	1	2.592	I	1	2.68
	Total 308.30 hours 8.927	8.927		2.271	2.680	24.151	11.962	0.448	50.43

Table 3-IV. Block II Command Module Energy Consumption Profile for 12.85-Day Lunar Orbit Mission

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Section 4

LUNAR EXCURSION MODULE DATA

4-1 INTRODUCTION

Because of the possibility of the requirement for hermetic sealing in the LEM as a result of the rule for common usage in the CM and LEM vehicle, last month's issue reported hermetic packaged weights for the CDU's, PSA, LGC, and the LGC Display and Control. Continuing with this common usage rule, the CDU's, PSA, and LGC will now conform to the previously existing moisture-proofing method. (For further explanation, see paragraph 3-1.)

4-2 RELIABILITY

There have been no significant changes in the G&N equipment design this month that would warrant a re-evaluation of the reliability figures presented in the last month's report. Table 4-I presents the latest figures.

The LEM G&N reliability values are based on a mission of the same duration as the CM G&N equipment.

Subsystem	Operating Time (hrs)	Probability of Mission Success
IMU	6.25	0.99914
LGC	6.25	0.9976
PSA	6.25	0.99928
CDU (5)	6.25	0.99822
OMU	0.75	0.99997
DSKY	6.25	0.9976
Total	G&N System	0.9918

Table 4-I. Reliability (as of 12/15/64)

4-3 WEIGHTS FOR LEM

Lunar Excursion Module weights are presented in Table 4-II. In general the data conform to the information contained in paragraphs 2-1, 2-1.1, and 2-1.2.

The row labeled "Bare Guidance System" is inserted to provide for comparisions with similarly specified systems.

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Table 4-II. Est	timated Weig	thts of LEN	I G&N Comp	onents (lbs	at 1 g)	
	:					Design
	Status		Status		Status	Load Wt.
Item	2/64	,	11/64		12/64	7/64
	(a)	(b-a)	(q)	(b-a)	(c)	(q)
CDU's	15.0(E)	+18.2	33.2 (E)	-0.2	33.0(E)	*
Telescope and All Eyepieces	24.5(E)	+ 1.0	25.5(E)	0.0	25.5(E)	
Landing Point Designator	2.0(E)	0.0	2.0(E)	0.0	2.0(E)	
IMU	42.0(E)	+ 0.1	42.1 (E)	0.0	42.1 (E)	
LGC/PSA Interconnection					•	
Assy	10.0(E)	0.0	10.0(E)	0.0	10.0(E)	
LGC Display and Controls	19.5(E)	- 0.5	19.0(E)	-1.5	17.5(E)	
Book of Procedures, etc.	2.0(E)	0.0	2.0(E)	0.0	2.0(E)	
LGC	45.8(E)	+20.2	66.0(E)	-8.0	58.0(E)	
PSA†	27.2(E)	8.0	35.2 (E)	-8.0	27.2(E)	
NVB	0.0	+ 6.0	6.0(E)	0.0	6.0(E)	
Total	210.0 [§] Control Weight	+53.0	241,0	-17.7	223.3	
	0					
Bare Guidance System (IMU, PSA, and LGC)	110.7	+28.3	143.3	-16.0	127.3	
*No design load weight has been	assigned. Cover					
© Control Weight specified in Let	tter PG-64-1	113 (March	6, 1964) fro	m Mr. D. (Filbert, ASF	0,
to Mr. M. Trageser, MIT/IL.	See section	2-1.2.	• •			

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. . .

4-4 REPORTED LEM WEIGHT CHANGES

4-4.1 CDU (-0.2 lb). Last month's report neglected to include the weight increase due to the incorporation of the guidance and control functions as part of the CDU subsystem. Therefore the weight decrease due to the return to previously existing moisture-proofing method will not conform with the Block II CDU decrease.

4-4.2 PSA (-8.0 lbs). The weight decrease is a result of the return to the conformal moisture-proofing of the PSA. This weight includes the PSA cover.

4-4.3 LGC (-8.0 lbs). The weight decrease is a result of the return to the conformal moisture-proofing of the AGC.

4-4.4 D&C/LGC (-1.5 lbs). The weight decrease is a result of a more detailed calculation of the hermetically sealed design configuration.

4-5 POWER REQUIREMENTS

The estimate for LEM power and energy consumption shown in figure 4-1 is based upon Command Module G&N Block II Data and Preliminary ICD LIS-390-2, LEM Electrical Load Analysis Form.

Table 4-III shows the energy requirements for each G&N activity on a power level basis. The table is also based upon LEM ICD LIS-390-2. The vertical column on the left indicates the various G&N activities (phases of operation). This column also indicates the power requirements and operating time for each activity. The top row indicates the power requirements and operating time of each G&N power consuming equipment. The table sums up the energy consumption for power consuming equipment.

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Figure 4-1. Electrical Load on Primary +28 VDC Power Supply

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		Table 4-III.	Lunar Excursio	n Module Power	Profile Based on	a LEM ICD LIS-3	90-2		
					Energy Cons	umption (kwh)			
NODE	LEM G&N Activity	(1) LGC Off 0.0 watts 87.40 hours	(2) LGC. Operate 105.0 watts 11.92 hours	(3) LGC Standby 10.0 watts 35.75 hours	 (4) IMU Operate 297.3 watts 11.92 hours 	 (5) IMU Standby 53.5 watts 123.15 hours 	 (6) Two Radar CDU Operate 29.4 watts 11.92 hours 	(7) OMU (AOT) Operate Negligible watts 27.42 hours	Total
-	Inactivity 53.5 watts 87.40 hours	0.000	1	I		4.676	I	1	4.676
Ħ	Inactivity Alignment Midcourse Measurements 431.7 watts 11.72 hours	1	1.231	1	3 .484	1	0.345	negligible	5.060
Ħ	Guidance During Major Event 431.7 watts 0.20 hours	I	0.021		0.059	I	0.006	ł	0.086
5	Inactivity 63.5 watts 20.05 hours	I	I	0.200	1	1.073	I	I	1.273
>	Inactivity 63.5 watts 15.70 hours	I	1	0.157	1	0.840		negligtble	0.997
	Total 135.07 hours	0.000	1.252	0.357	3.543	6.589	0.351	negligible	12.092

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Section 5

GLOSSARY AND SYSTEM DEFINITION

Apollo Guidance Computer (AGC)

<u>CM BLOCK I</u> A single complete flight computer containing all logic, memory, associated power supplies, and all interface circuits except those identified with the CDU's. Does not contain the associated displays and controls.

Consists of one case containing factory replaceable electronic modules. Includes cover for moisture-proofing, but does not include the necessary cold plate or the G&N to S/C Interface Assembly which is located in the adjacent area.

<u>CM BLOCK II AND LEM</u> Same as Block I except that associated power supplies are in a separate case and the CDU's are either adjacent to or on the opposite side of the same cold plate as the AGC. Memory capacity is increased over Block I.

Alignment Optical Telescope (AOT)

CM BLOCK I AND BLOCK II Not in CM: see Optical Subsystem.

<u>LEM</u> A 3-position periscope with single-degree-of-freedom manually read reticule for alignment of the IMU. Includes the weight of the bellows assembly, a long-eyerelief eyepiece, and regular eyepiece.

Bellows Assembly

<u>CM BLOCK I AND CM BLOCK II</u> Two flexible pressure seals between CM structure and optical subsystem for penetration of pressure hull with optics.

<u>LEM</u> One bellows with a double convoluted wall and two seals providing a flexible seal for pressure penetration of the AOT in the spacecraft. This weight is included in the AOT value.

Book of Procedures

 \underline{CM} Not in CM; see MDV.

<u>LEM</u> Book or other form of maps, charts, procedures, instructions, and the like, needed for lunar operations.

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Coupling Data Unit (CDU) Assembly

The CDU provides the necessary signal interfaces among the IMU gimbal angles, optics gimbal angles, radar gimbal angles, angle registers in the AGC, the spacecraft autopilot attitude error signals, and the tracking radar command error signals.

<u>CM BLOCK I</u> Five interchangeable gear boxes each with necessary motor tachometer, resolver synchros, and encoder with mounting frame work. Does not include associated electronics which are located in the PSA.

<u>CM BLOCK II</u> Functionally identical to Block I except the instrumentation is all electronic. Includes all support electronics (including special power supply) and header. Changes in resolver synchro characteristics and mode controls make Block I and II CDU's noninterchangeable.

LEM Interchangeable with CM Block II CDU's except for the headers.

Cold Plates

<u>CM BLOCK I, BLOCK II, AND LEM</u> Cold plates for the IMU are built into the IMU. Necessary cold plates for electronics are part of the equipment supplied by the spacecraft manufacturer. All surfaces over glycol coolant passages and open to the cabin environment will be insulated to prevent moisture condensation.

Control Electronics Assembly

<u>CM BLOCK I</u> Consists of one power transformer, one relay and diode module, and a bracket end connector. Used to support display and control functions. Includes moisture-proofing.

CM BLOCK II May be relocated with other similar functions.

LEM Not defined in LEM.

Coolant Hoses

<u>CM BLOCK I AND CM BLOCK II</u> Consists of (1) two steel flex coolant hoses, one between IMU and spacecraft and one between optics and spacecraft, (2) bracket assembly screws and clamp, and (3) entrapped coolant.

LEM Not identified as part of LEM.

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Display and Control/Apollo Guidance Computer (D&C/AGC)

<u>CM BLOCK 1</u> Number displays and keyboard control associated with the operation of the AGC. Two functionally identical and parallel operating units: one in lower equipment bay and one on main panel between left and center couches.

<u>CM BLOCK II</u> Mechanically and electrically identical to Block I but smaller configuration because of smaller relays. The Block II display and keyboard controls will be hermetically sealed by encasing the unit in a container.

LEM Identical to Block II except only a single unit is required.

D&C Electronics Assembly

<u>CM BLOCK I</u> Consists of a chassis, a relay and diode module, a demod. elect. module, a saturable reactor, a time delay module, a connector, and wiring. Used to support display and control functions. Connectors will be moisture-proofed.

CM BLOCK II Not defined at this time.

LEM Not defined in LEM at this time.

Landing Point Designator

 \underline{CM} Not in \underline{CM}

<u>LEM</u> An optical sighting device consisting of a reticle, plane mirror, collimating lens, and a beam splitter to magnify the target area with a light-line reticle pattern.

Film Cartridges

<u>CM BLOCK I AND BLOCK II</u> Consists of film cartridges and film for map and data viewer.

<u>LEM</u> Does not exist in LEM.

G&N Indicator Control Panel

<u>CM BLOCK I AND BLOCK II</u> Consists primarily of controls and displays for the operation of the optics, MDV, IMU temperature control, panel brightness control, and attitude impulse control. It includes display and control elements, panel, panel wiring, supporting hardware, and moisture-proofing.

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LEM Does not exist in LEM.

G&N Interconnection Assembly

<u>CM BLOCK I</u> Consists of PSA End Connector Assembly and interconnect wiring harness, which electrically ties together the assemblies that constitute a completely integrated system. This term does not include weights of harness support brackets, which are an NAA responsibility, or the G&N to S/C Interface Assembly weight.

<u>CM BLOCK II</u> Similar to Block I but not interchangeable. The connectors in the upper harness are now to be sealed against moisture and contamination.

<u>LEM</u> Not clearly defined but at present is called the AGC/PSA Interconnection Assy. Because of the wide separation of G&N components, most interconnection will be accomplished as part of spacecraft wiring.

G&N to S/C Interface Assembly

<u>CM BLOCK I</u> Cable interconnections between the spacecraft wiring channel, the computer connector, and the PSA end connector. Contains no active electronics.

<u>CM BLOCK II</u> Similar in functions to Block I except the configuration is much different and not interchangeable with Block I. The connectors in the lower harness are now to be sealed against moisture and contamination.

LEM Not identified yet as a separate item in LEM.

Horizon Photometer

<u>CM BLOCK I AND BLOCK II</u> An earth horizon brightness photometer and automatic star tracker used for navigation measurements against the earth's illuminated limb. The sensors are incorporated into the head of the SXT the weight of which includes this function. The PSA includes all support electronics for Block II and some of the support electronics for Block I.

LEM Not a part of LEM.

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Horizon Photometer Electronics

<u>CM BLOCK I</u> Additional horizon photometer and star tracker electronics mounted on an auxiliary header and attached to the right-hand wall behind the MDV.

CM BLOCK II All electronics are located in the PSA or on the sextant head.

LEM Not required.

Inertial Measurement Unit (IMU)

<u>CM BLOCK I</u> Size 14 IMU (14-inch case diameter) gimbal assembly including all parts inside hermetic case, entrapped coolant, and heat exchanger insulation.

<u>CM BLOCK II AND LEM</u> Size 12.5 IMU functionally interchangeable with Block I unit, but not physically interchangeable with Block I.

IMU Control Panel

<u>CM BLOCK I</u> Consists of panel, wiring, attitude error meter, CDU transfer switch, manual alignment switch, CDU mode control switches, connector, supporting hard-ware, and associated moisture-proofing.

<u>CM BLOCK II</u> Does not exist in Block II. Moding is done by AGC program and AGC push buttons.

LEM Does not exist in LEM.

Long-Eye-Relief Eyepieces

<u>CM BLOCK I AND BLOCK II</u> Consists of a SXT and a SCT eyepiece to provide eye relief of at least 1.6 inches for closed visor operation. Used in place of normal eyepieces of SXT and SCT.

LEM Long-eye-relief eyepiece is included as part of the AOT.

Map and Data Viewer (MDV)

<u>CM BLOCK I AND BLOCK II</u> Film viewer for display of maps, charts, procedures, and the like. Weight includes one film cartridge and a moisture-proofing enclosure.

LEM Not in LEM; see Book of Procedures.

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NVB and Mounts

<u>CM BLOCK I</u> Rigid beryllium structure supporting the IMU and the optical subsystem with its associated hardware. The NVB is attached to the spacecraft using flexible resilient mounts to prevent spacecraft strains from distorting the NVB and the alignment between the IMU and optics. These mounts also provide shock and vibration attenuation.

<u>CM BLOCK II</u> Functionally similar to Block I but will be lighter and provide for mounting the size 12.5 IMU. The Block II NVB is attached to the spacecraft by use of strain isolation hardmounts and will have a transition piece as a result of the reorientation of the NVB so that the IMU axes will be parallel to the Command Module axes.

<u>LEM</u> A toroidal aluminum ring with: (1) four tubular aluminum posts to provide for IMU mounting, (2) four tubular aluminum posts for AOT mounting, and (3) three aluminum inserts to provide strain isolation ball mounting to the GAEC structure.

Optical Eyepieces

CM BLOCK I AND BLOCK II Removable SXT eyepiece and SCT eyepiece.

LEM Included as part of the AOT.

Optical Subsystem

<u>CM BLOCK I AND BLOCK II</u> Consists of SXT, SCT, Optical Base, and associated hardware defined as follows:

SXT:	Sextant. A two-line-of-sight, narrow-field, two-degree-of-freedom sextant and its attached gearing. The horizon photometer and automatic star tracker sensors are incorporated into the SXT head.
SCT:	Scanning Telescope. A single-line-of-sight, wide-field-of-view, two-degree-of-freedom articulation optical instrument and its attached gearing.
Optical Base:	Base for SXT and SCT with associated gearing and internal cooling.

LEM Not in LEM; see \underline{AOT} .

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Optical Shroud & Cover Assembly

CM BLOCK I AND BLOCK II Consists of the optical shroud and protective cover.

LEM Does not exist in LEM.

Power Servo Assembly (PSA)

<u>CM BLOCK I</u> Includes most of the support electronics: power supplies; IMU, Optics, and CDU servos; IMU temperature control; accelerometer and gyro pulse torquing; and horizon phtometer and automatic star tracker electronics. Consists of 10 trays and replaceable modules which plug into the PSA end connector assembly. Includes a beryllium front toe plate.

<u>CM BLOCK II</u> Similar in function to Block I except that all horizon photometer electronics are included in the Block II PSA, and the CDU servoes are deleted. Consists of a single plane matrix header, mounted to a cold plate, with the modules plugging onto the top. To permit removal of the calibration modules at IMU adjustment or replacement, these modules are contained in a separate assembly located on a cold plate adjacent to the Signal Conditioner Assembly.

<u>LEM</u> Consists of electronics similar to those identified in the Block II PSA minus various electronics modules. Does not include optics and photometry electronics associated with the Block I and II PSA's.

PSA End Connector Assembly

<u>CM BLOCK I</u> Electrical interconnection between the PSA trays, the G&N Interconnection Assy, and the G&N to S/C Interface Assy. The End Connector weight is reported in the G&N to S/C Interconnection Assembly weight.

<u>CM BLOCK II AND LEM</u> Not identified as a separate item; will be part of the PSA matrix header.

PSA Covers

<u>CM BLOCK I</u> Ten plastic connector covers, gaskets, and mounting screws (one for each tray) for moisture-proofing. Weight included in PSA weight value.

<u>CM BLOCK II AND LEM</u> Cover required for moisture-proofing during flight. Weight is reported in PSA weight value.

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Signal Conditioner Assembly

CM BLOCK I Conditions signals for telemetry.

<u>CM BLOCK II</u> These modules are located in the same volume now occupied by the Block I CDU's.

LEM Same as for Block I.

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Appendix A

COMPARISON OF ACTUAL WEIGHTS OF DELIVERED G&N ZERO SERIES EQUIPMENT AND ESTIMATED WEIGHTS FOR G&N 100 SERIES EQUIPMENT

The following table, Table A-1, presents a comparison between the actual weights of System No. 6 equipment and the estimated weights for G&N 100 series equipment reported in section 2 of this report.

	System No. 6 Zero Series (lbs)	Dec '64 Weight Estimates 100 Series (lbs)
CDU	13.9	14.0(E)
Nav/Base	94.7	92.6(E)
IMU	61.1	60.5 (C)
PSA	58.5	59.8(C)
G&N Interconnect*	20.5	25.0(C)
AGC [†]	64.9	80.0(E)
Optical Shroud	3.1	3.1 (C)
D&C Electronics	2.9	3.0(E)
Control Electronics	2.1	2,1(E)
G&N Indicator	10.1	10.5(E)
IMU Control Panel	2.6	2.8(E)
MDV	9.1	9.8(C)
D&C/AGC LEB	not available	21.9(C)
D&C/AGC MP	22.2	21.9(C)
Optics Cover	1.6	1.6(C)
Coolant Hoses (2)	not available	0.8(E)

Table	A-1.	Weight	Comparison
		··· ··	

*The G&N Interconnection Assembly for the 100 series system is moisture-proofed and contains an extra cable to the Horizon Photometer Electronics located in back of the Map and Data Viewer.

[†]The AGC for the 100 series system includes the weight of the G&N to S/C Interface Cable Assembly, not included in the zero series system AGC.

NOTE: Basic changes in the 100 series Block I G&N system include: (1) redesigned packaging of the flight computer, (2) modification of the electronics packaging to achieve moisture-proofing and to correct deficiencies in the S&ID thermal interface material, (3) less flammable wiring insulation, and (4) addition of insulation to the cold surfaces.



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