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E-1142 (Rev. 29) (UNCLASSIFIED TITLE)

SYSTEM STATUS REPORT

February 15, 1965





NSTRUMENTA N BORATORY **CAMBRIDGE 39, MASSACHUSETTS** 

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### ACKNOWLEDGMENT

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### ABSTRACT

The System Status Report is distributed monthly on the 15th. This month's revision of E-1142 (Rev. 29) contains, in general, the following information for the Block I and Block II Command Module and Lunar Excursion Module equipment: configuration weights, centers of gravity, moments of inertia, power requirements, status of computer programs, and reliability values.

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### Section 1

#### INTRODUCTION

#### 1-1 INTRODUCTION

During the reporting period, MIT received TWX NR 289, dated January 26, 1965, from the MSC Project Office informing MIT that action is being undertaken to remove the M&DV from the Block I, series 100, and Block II G&N System. At the time of this reporting, MIT has not received the request via an Engineering Change Proposal. Accordingly, the M&DV still appears in this report until the change authorization is received.

A new Design Reference Mission has been developed by Apollo Mission Planning Task Force. The power requirements of the Command Module G&N and LEM equipment are now being recalculated to reflect these latest requirements and will be reported next month.

The definition of what constitutes Block I, Block II, and LEM hardware is contained in the Glossary, section 5.

The following information is included in this month's report:

- (2) Command Module, Block II Integrated Guidance, Navigation, and Control Configuration: Weights and reliability values.
- (3) Lunar Excursion Module
   LEM Integrated Guidance and Control Configuration (Configuration "B."
   Ref: Minutes of LEM Implementation Meeting No. 4): Weights and
   reliability values.

### 1-2 ACCURACY

The accuracy of numerical values reported in this revision should not be considered to be within the tolerances implied by the significant figures quoted. The reported values, although based upon the most current information, are subject to normal changes as design and development phases approach completion.

### BLOCK I

### COMMAND MODULE

### Section 2

### BLOCK I COMMAND MODULE DATA

#### 2-1 WEIGHTS

Table 2-I presents the weights of all Block I flight (100 series systems) equipment, grouped according to specific location within the Command Module. Weights are reported to the component level and to the nearest tenth of a pound.

Given component weights are identified as estimated, calculated, and measured in order of increasing accuracy. These terms are defined by North American Aviation as follows: estimated weights (E) are based on rough calculations; calculated weights (C) are based on detailed calculations made from final production drawings that will be used to build flyable equipment; measured weights (M) are actual weights of equipment built to the production drawings.

North American Aviation will provide and be responsible for cold plate weights that are not integral with guidance and control equipment.

2-1.1 WEIGHT STATUS REPORTING. Table 2-I also offers a comparison of present 100 series component weight values with those listed in System Status Report, E-1142 (Rev. 28), January 15, 1965. All weight changes are explained in paragraph 2-2.

2-1.2 CONTROL WEIGHT (ZERO SERIES). Column (a) in Table 2-I contains the February 15, 1964 weight status of Apollo G&N zero series equipment. Column (a) adds up to approximately the total control weight specified in letter PG-64-113 (March 6, 1964) from Mr. D. Gilbert, ASPO, to Mr. M. Trageser, MIT/IL.

2-1.3 DESIGN LOAD WEIGHT (ZERO SERIES). At NASA Coordination Meeting No.15A, MIT agreed to assign "not to exceed" design load weights for individual Block I G&N zero series subsystems. These weights were assigned by MIT in MIT letter AG-594-64, May 18,1964, and are shown in column (d) of Table 2-I.

#### 2-2 REPORTED 100 SERIES WEIGHT CHANGES

2-2.1 MAP & DATA VIEWER (-2.4 lbs). The Map and Data Viewer has undergone extensive redesign to provide lighter weight in the basic structure, as well as in the major components, to allow for the addition of electrical and optical moisture proofing features.

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Table 2-I. Current Weig	tht Status of ]	Block I (10(	) Series) Col	mmand Mod	ule (lbs at 1	g)
	0 Series		100 Series		100 Series	Design
	Status		Status		Status	Load Wt.
Item	2/64		1/65		2/65	5/64
	(a)	(b-a)	(q)	(c-b)	(c)	(d)
G&N SYSTEMS						
CDU Assy	14.5 (M)	- 0.5	14.0(E)	0.0	14.0(E)	18.0
<b>Optical Subsystem</b>						
SXT	18.2 (C)	+ 0°2	18.7(E)	0.0	18.7(E)	
SCT	13.8(C)	+ 0.5	14.3(E)	0.0	14.3(E)	
Optical Base & Gearing	16.7(E)	+ 0.3	17.0(E)	0°0	17.0(E)	
<b>Optical Eyepieces</b>						100.0
SXT	1,3(E)	+ 0.3	1.6(C)	0°0	1.6(C)	
SCT	2.3(E)	+ 0.3	2.6 (C)	0.0	2.6(C)	
NVB & Resilient Mounts	25.0(E)	+ 0°4	25.7 (M)	0.0	25.7 (M)	
Bellows Assy	13.5 (M)	- 0.8	12.7 (M)	0°0	12.7 (M),	~
IMU	60.2 (M)	+ 0.3	60.5 (C)	0°0	60.5 (C)	GE O
Coolant Hoses (two)	1 . 0 (E)	- 0.2	0 . 8 (E)	0.0	0.8(E)	0.00
Power Servo Assy	59.4 (C)	+ 0.4	59.8 (C)	0.0	59.8(C)	75.0
G&N Interconnection Assy	35.2 (E)	-10.2	25.0(E)	0.0	25.0 (E)	45.0
G&N to S/C Interface Assy	8.0(E)	+ 2.0	80.0(E)	0.0	80.0(E)	100.0
AGC (no spares)	70.0(E)			)		
Optical Shroud	3.5 (M)	- 0.4	3.1 (E)	0.0	3.1 (E)	4.5
LOWER EQUIPMENT BAY						
D&C						
D&C Electronics	2.9 (M)	+ 0.1	3.0(E)	0.0	3.0(E)	
Control Electronics	2.9(E)	- 0.8	2.1 (E)	0.0	2.1 (E)	
G&N Ind Cont Panel	9.5 (M)	+ 1.0	10.5(E)	0.0	10.5(E)	<u> </u>
IMU Control Panel	2.4 (M)	+ 0.4	2.8(E)	0.0	2.8(E)	
MDV (includes 1 film)	7.7 (C)	+ 3.8	11.5(E)	-2.4	9.1 (E)	
D&C/AGC	20.6 (M)	+ 1.3	21.9(C)	0.0	21.9(C)	_
Horizon Photo. Elect.	0.0	+2.2	2.2(C)	0.0	2.2(C)	0.0
Signal Conditioner Assy	0°0	+ 3.9	3.9 (C)	0.0	3.9 (C)	8.0
			(cont)			

PAGE 2-2

4					·		
) (cont)	Design Load Wt. 5/64 (d)	26.0	3.0 2.5	$522.0^{\dagger}$	ASPO, m 2-1.3.		
e (lbs at 1 g	100 Series Status 2/65 (c)	21.9(C)	1.5(E) 2.5(C) 1.6(C)	418.8	D. Gilbert, mly. see paragral		
mand Modul	(c-b)	0°0	0.0 0.0 0.0	-2.4	) from Mr. ero series c 8, 1964). 5		
eries) Com	100 Series Status 1/65 (b)	21.9(C)	1.5(E) 2.5(C) 1.6(C)	421.2	rch 6, 1964 Applies to z 4-64 (May 1		
lock I (100 S	(b-a)	+ 1.4	0.0 + 0.1 - 0.1	+ 6.2	-64-114 (Ma ph 2-1.2. / etter AG-59		
Status of B	0 Series Status 2/64 (a)	20.5 (M)	1.5(E) 2.4(E) 1.7(M)	415.0*	n letter PG- See paragra from MIT I		
Table 2-I. Current Weight		MAIN PANEL AREA D&C/AGC LOOSE STORED ITEMS	Eye Relief Eyepieces Film Cartridges (4) Optics Cover	TOTAL	*Total control weight specified i to Mr. M. Trageser, MIT/IL. †Design Load Weights are taken	Applies to zero series only.	

# COMMAND MODULE

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# 2-3 BLOCK I (ZERO SERIES) WEIGHT, CENTER OF GRAVITY, AND MOMENT OF INERTIA DATA

Block I (100 series) center of gravity and moment of inertia information is unavailable at this time, but is under preparation.

Included for reference are the total Block I (zero series) weight, center of gravity, and moment of inertia values (Table 2-II).

Weight	Center of Gravity	Moments of Inertia*
(lb)	(in)	(lb-in <sup>2</sup> )
408.9	X 55.1 Y -0.3 Z 37.3	

Table 2-II. Block I (Zero Series) Weight and Balance Data

\*Values determined with respect to the basic X, Y, Z axes of the Command Module.

### 2-4 COMMAND MODULE POWER REQUIREMENTS (100 SERIES)

The power requirements of the Command Module G&N 100 series equipment on the primary +28 VDC power supply are shown in figure 2-1 which presents the magnitude and location of dissipated power values on a subassembly level. This chart assumes a 12.85-day lunar mission, as defined by S&ID for power profile computation, and is based on 28 VDC input at the connectors. The values shown are average values. (Ref: S&ID letter 64 MA 3540.)

Table 2-III shows the magnitude and location of power dissipation for the established G&N activities, each of which consists of various power levels of operation.

Table 2-IV shows the energy requirements for each G&N activity on a power level basis. The table is based upon MIT letter AG-679-6, "G&N Power Profile Status," dated August 14, 1963. The vertical column to the left indicates the various G&N activities (phases of operation) for the model 12.85-day mission submitted by S&ID in S&ID letter 64 MA 3540. The column also indicates the power requirement and operating time for each specific activity. The top row indicates the power requirement and operating time for each G&N power consuming equipment. The table sums up the energy consumption for each G&N activity and each G&N power consuming equipment.

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Figure 2-1. Electrical Load on Primary +28 VDC Power Supply, Block I (100 Series) Systems

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(3)22 W, "ZERO" G ENVIRONMENT 33W, "ONE" G ENVIRONMENT

	Table 2-III. Nominal Pc	ower Digs	sipation	(watts) v	S G&N AC	stivity fo	IT BLOCK I	(100 Series) by	stems		
G&N Activ	ity	NB	¥	CDU	PS/	4		Thermal Load on S/C	D&C	Optics	Electrical
(power lev	els)	IMU	OBA	JB	IMU	OBA	AGC	Coolant	S&C	External	Load
Accomplish & Confirm Coi Inactivity and Monitor Major Maneuver (1,5)	urse Corrections	74.5	0.0	22.1	228.5	0.0	115.0	440.1	10.7	0.0	450.8
Alignments Sextant Sightings (1, 3, 5, 7)		74.5	40.7	44.0	228.5	76.1	115.0	578.8	25.7	0.5	605.0
Landmark Trackings (Low-Orbit Navigation) (1,4,5,7)		74.5	35.5	44.0	228.5	72.3	115.0	569.8	25.7	0.5	596.0
Star Occultation Sightings (1, 6)		25.5	0.0	0.0	36.2	0.0	115.0	176.7	10.0	0.0	186.7
Sextant Sightings Midcourse Navigation (1,3,6,7)		25.5	40.7	21.9	36.2	76.1	115.0	315.4	25.0	0.5	340.9
Inactivity & Monitor (2, 6)		25.5	0.0	0.0	36.2	0.0	15.0	76.7	0.0	0.0	76.7
Inactivity & Monitor (2,5)		74.5	0.0	22.1	228.5	0.0	15.0	340.1	0.7	0.0	340.8
			SC Opera SC Standi SC Standi SC Opera TLC Opera SC Opera	ute by rrate SXT rrate SXT te te	OFF ON		125.0 w 15.0 w 15.0 w 125.8 w 116.8 w 325.8 w 61.7 w 28.4 w	atts atts atts atts atts atts atts			

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		Total	26.331	8.306	2.056	0.542	0,907	16.724	3.098	57.964
		(7) D&C Operate 28.4 watts 19.84 hours	I	0.390	0.098	1	0.076	1	-	0.563
· Orbit Mission		<ul> <li>(6) IMU</li> <li>Standby</li> <li>61.7 watts</li> <li>223.60 hours</li> </ul>	ł	I	-	0.179	0.164	13,453	I	13.796
12.85-Day Lunar	tion (kwh)	(5) IMU Operate 325.8 watts 84.68 hours	19.030	4.473	1,124	I	-	-	2.962	27.589
ption Profile for	Cnergy Consump	<ul><li>(4) Optics</li><li>Sextant OFF</li><li>116.8 watts</li><li>3.45 hours</li></ul>	ł	I	0.403	ł	I	1	I	0.403
Energy Consum	E	<ul><li>(3) Optics</li><li>Sextant ON</li><li>125.8 watts</li><li>16.39 hours</li></ul>	1	1.727	-	Ι	0.335	I	I	2,062
Command Module		(2) AGC Standby 15.0 watts 227.13 hours	1	4	l	I		3.271	0,136	3.407
κ I (100 Series) C		<ul> <li>(1) AGC</li> <li>Operate</li> <li>125.0 watts</li> <li>81.15 hours</li> </ul>	7.301	1.716	0.431	0.363	0.333	I	I	10.144
Table 2-IV. Block		G&N Activity	Accomplish & Confirm Course Corrections Inactivity and Monitor Major Maneuvers 450.8 watts 58.41 hours	Alignments Sextant Sightings 605.0 watts 13.73 hours	Landmark Trackings (Low-Orbit Navigation) 596.0 watts 3.45 hours	Star Occultation Sightings 186.7 watts 2.90 hours	Sextant Sightings (Midcourse Navigation) 340.9 watts 2.66 hours	Inactivity and Monitor 76.7 watts 218.04 hours	Inactivity and Monitor 340.8 watts 9.09 hours	Total 308.30 hours
1		ХООН	A	щ	U	Q	ы	ы	Ü	

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### 2-5 STATUS OF COMMAND MODULE AGC PROGRAMS

The integrated guidance and control implementation activity has defined stablization and control functions which must be part of the Block II computer program. Since the current program estimates do not include these S&C functions, the computer program status has been moved from section 3 to section 2 where it applies to the Block I configuration used for a lunar mission but without S&C. When the computer estimates include these added functions, the AGC program status will be returned to section 3.

Table 2-V lists current Command Module memory estimates and the status of AGC programs for the lunar landing mission guidance and navigation functions.

A high and low word estimate is given with each program. Each status is defined as follows:

- (1) Planning stage
- (2) Programming stage
- (3) Checkout on AGC simulation
- (4) Checkout on G&N simulation
- (5) Checkout on AGC

		Memory I (word	Estimate ds)
Item	Status	High	Low
List Processing Interpreter	(5)	1712	1712
AGC Executive	(5)	253	253
AGC Waitlister	(5)	145	145
AGC System Exerciser	(5)	500*	294*
G&N System Exerciser	(4)	650	400
Display, Keyboard, and Telemetry	(5)	2000	2000
Input/Output Control	(5)	1750*	1275*
Midcourse & Orbital Navigation	(5)	2000*	1500*
Midcourse & Orbital Guidance	(3)	500	500
Pre-Launch Platform Alignment	(5)	400*	350*
In-Flight Platform Alignment	(4)	1 0 2 4	900
Re-Entry Control	(4)	1800	1200
Injection and De-Boost	(4)	1000	400
Restart	(5)	500*	200*
Aim-Point Determination & Abort	(3)	4000	2000
Totals		18234	13129

### Table 2-V. Current Memory Estimates and the Status of Command Module AGC Programs (2/15/65)

\*Programs in stage (5) whose low and high estimates are not identical reflect an anticipated increase in computation facility.

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### Section 3

### BLOCK II COMMAND MODULE DATA

### 3-1 INTRODUCTION

The Block II PSA has been divided into two environmentally sealed assemblies, the PSA (which will be referred to in this report as the "new PSA") and PIPA Electronics Assembly, each with separate cold plates. Because of the split and change in PSA mounting imposed by the movable cold plate configuration (MIT/NAA meeting January 7, 1965), new weight estimates are in-process and will be reported in the next issue.

### 3-2 RELIABILITY

A new Design Reference Mission has been developed by the Apollo Mission Planning Task Force (See GAEC Report No. LED-540-12, October 30, 1964). The reliability values are now in the process of being recalculated to reflect these new mission requirements and will be reported in next month's report. Table 3-I shows reliability figures in effect before implementation of the new requirements.

Subsystem	Operating Time (hrs) Full Power	Probability of Mission Success
IMU AGC DSKY PSA CDU (5) Optics	31 19* 31* 31 18	0.9961 0.9869 0.99999 0.99421 0.9923 0.99804
Total G&N S	ystem	0.9679

Table 3-I. Reliability (as of 1/15/65)

\*Certain assemblies function continuously.

### 3-3 WEIGHTS

Table 3-II shows the weights of the Block II Command Module Integrated Guidance and Control system.

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Table 3-II. Currei	nt Weight Sta	tus of Bloc	s II Commar	nd Module (	lbs at 1 g)	
						Design
	Status		Status		Status	Load Wt.
Item	2/64		1/65		2/65	5/64
	(a)	(b-a)	(q)	(c-b)	(c)	(d)
G&N SYSTEMS						
CDU Assy	15.0(E)	+18,0	33.0(E)	0°0	33.0(E)	
<b>Optical Subsystem</b>						
SXT	18.2(C)	+ 0°5	18.7(E)	0.0	18.7(E)	
SCT	13,8(C)	+ 0.5	14.3(E)	0°0	14.3(E)	
Optical Base & Gearing	16.7(E)	+ 0.3	17.0(E)	0°0	17.0(E)	
<b>Optical Eyepieces</b>						
SXT	1.3(E)	+ 0.3	1.6(E)	0°0	1.6(E)	
SCT	2,3(E)	+ 0.3	2.6(E)	0.0	2.6(E)	
NVB & Mounts	22.0(E)	- 5.0	17.0(E)	0°0	17.0(E)	
Bellows Assy	13.5(C)	0.8	12.7(E)	0.0	12.7(E)	
IMU	42.0(E)	+ 0.1	42.1 (E)	0.0	42.1 (E)	
Coolant Hoses (two)	1.0(E)	- 0.2	0.8(E)	0.0	0.8(E)	
Power Servo Assy*	45.1 (E)	+ 2.6	47.7(E)	0.0	47.7(E)	
G&N Interconnection Assy	35.2(E)	- 4.2	31.0(E)	0.0	31.0(E)	
G&N to S/C Interface Assy	8.0(E)	+ 0.5	8.5(E)	0.0	8.5(E)	
AGC	92.5 (E)	-34.5	58.0(E)	0.0	58.0(E)	
Optical Shroud	3.5 (C)	- 0.4	3.1 (E)	0.0	3.1 (E)	
LOWER EQUIPMENT BAY						
D&C						
D&C Electronics	1.5(E)	- 1,5	0.0	0.0	0.0	
Control Electronics	2.9(E)	- 2.9	0°0	0.0	0.0	
G&N Ind Cont Panel	11.1(E)	+ 1.0	12.1 (E)	0.0	12.1 (E)	
MDV (including 1 film		1			() ; ;	
cartridge)	8.3(E)	+ 3.2	11.5(E)	-2.4		
D&C/AGC	20.6(E)	- 3.1	17.5(E)	0.0	17.5(E)	
Signal Conditioner Assy	0.0	+ 3.9	3.9(C)	0.0	3.9(C)	

MEUNENIEU

CONFIDENTIAL Block II COMMAND MODULE

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(cont)

	Design Load Wt. 5/64 (d)			492°6 <sup>§</sup>	0, to include
at 1 ø) (cont	Status 2/65 (c)	17.5(E)	1.5(E) 2.5(E) 1.6(C)	373.8	ilbert, ASP It does not
Module (lbs.	(c-b)	0°0	0°0 0.0	-2.4	n Mr. D. G 11, 1964).
Command N	Status 1/65 (b)	17.5(E)	1.5(E) 2.5(E) 1.6(C)	376.2	i, 1964) froi 2 (February
s of Block II	(b-a)	- 3.0	0.0 + 0.7 - 0.1	-23.8	13 (March 6 2-1.2. : 64 MA 203
Veight Status	Status 2/64 (a)	20.5(E)	1.5(E) 1.8(E) 1.7(E)	400°0 <sup>†</sup>	Cover. ter PG-64-1 e paragraph i S&ID letter
Table 3-II. Current W	Item	MAIN PANEL AREA D&C/AGC	LOOSE STORED ITEMS Eye Relief Eyepieces Film Cartridges (4) Optics Cover	TOTAL	*Includes the weight of the PSA †Control Weight specified in let. Mr. M. Trageser, MIT/IL. See <sup>§</sup> Design Load Weight taken from loose stored items.

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### BLOCK II

### COMMAND MODULE

#### 3-4 REPORTED WEIGHT CHANGES

### 3-4.1 MAP & DATA VIEWER (-2.4 lbs). See paragraph 2-2.1.

### 3-5 POWER REQUIREMENTS

The power requirements of the Block II Command Module G&N equipment on the primary +28 VDC power supply are shown in figure 3-1, which presents the magnitude and location of dissipated power values on a subassembly level. This chart assumes a 12.85-day lunar orbit mission as defined by S&ID for power profile computation and is based on 28 VDC input at the connectors. These values are average values (Ref: S&ID letter 64 MA 3540).

Table 3-III shows the magnitude and location of power dissipation for the established G&N activities, each of which consists of various power levels of operation.

Table 3-IV shows the energy requirements for each G&N activity on a power level basis. The table is based on MIT letter AG 679-6, "G&N Power Profile Status," dated August 14, 1963. The vertical column to the left indicates the various G&N activities (phases of operation) for the model 12.85-lunar day mission submitted by S&ID in S&ID letter 64 MA 3540. This column also indicates the power requirements and operating time for each specific activity. The top row indicates the power requirements and operating time of each G&N power consuming equipment. The total power consumption for each G&N activity and each G&N power consuming equipment is also given.

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	Table 3-III. Nominal P	ower Dis	sipation	(watts) v	s G&N Ac	tivity for	Block II S	systems		
۶o	G&N Activity	IN	3A		P	SA		Thermal	D&C	
Aы	(power levels)	IMU	OBA	CDU	IMU	OBA	AGC	Load on S/C Coolant	and S&C	Electrical Load
¥	Accomplish & Confirm Course Corrections Major Maneuvers Inactivity & Monitor (1,4)	78.6	0.0	44.9	154.3	0.0	100.0	377.8	10.7	388.5
æ	Alignments Sextant Sightings Landmark Trackings (Low-orbit navigation) (1, 3, 4, 6)	78.6	52.1	74.9	154.3	62.7	100.0	522.6	26.7	549.3
C	Star Occultation Sightings (1, 5)	28.0	0.0	0.0	18.0	0.0	100.0	146.0	10.0	156.0
Q	Sextant Sightings (Midcourse navigation) (1, 3, 5, 6)	28.0	52.1	30.0	18.0	62.7	100.0	290.8	26.0	316.8
ы	Inactivity & Monitor (2, 5)	28.0	0.0	0.0	18.0	0.0	10.0	56.0	0.0	56.0
Έł	Inactivity & Monitor (2, 4)	78.6	0.0	44.9	154.3	0.0	10.0	287.8	0.7	288.5
		1. AC 3. AC 5. IM 0. D8 0. D8	AC Opera AC Standl tics Ope U Opera U Standt & Opera	te oy rate te te	110 10 138.2 138.2 46 46 22.6	watts watts watts watts watts watts				

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Table 3-III Nominal Dowar Dissination (u

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22.6930.84212.210Total 9.4370.452 2.62348.257 (6) D&COperate22.6 watts19.84 hours 0.388 0.4480.060ł ł I ł (5) IMUStandby46.0 watts223.60 hours Table 3-IV. Block II Command Module Energy Consumption Profile for 12.85-Day Lunar Orbit Mission 0.12210.030 0.13310.285 I I ł Energy Consumption (kwh) (4) IMUOperate278.5 watts84.68 hours 16.2684.785 2.532 23.585١ ł ļ (3) OpticsOperate138.2 watts19.84 hours 2.7412.3740.367 ł 1 Т I (2) AGC Standby 10.0 watts 227.13 hours 2.180 2.2710.091 I T Т ł (1) AGC Operate 110.0 watts 81.15 hours 0.3196.4251.890 0.2938.927 I ł Alignments Sextant Sightings Landmark Trackings (Low-orbit Navigation) 549.3 watts 17.18 hours Accomplish & Confirm Course Corrections Major Maneuvers Inactivity & Monitor 388.5 watts 58.41 hours Sextant Sightings (Midcourse Navigation) 316.8 watts 2.66 hours G&N Activity Star Occultation Sightings 156.5 watts 2.90 hours Inactivity & Monitor 56.0 watts 218.04 hours Inactivity & Monitor 288.5 watts 9.09 hours Total 308.30 hours щ NDON ۷ ပ р ы ъ

### BLOCK II COMMAND MODULE

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#### Section 4

### LUNAR EXCURSION MODULE DATA

#### 4-1 INTRODUCTION

The LEM PSA has been divided into two environmentally sealed assemblies, the PSA (referred to here as the "new PSA") and the Pulse Torque Assembly (PTA). The "new PSA" will be in the area known as the Aft Equipment Bay, which is located behind the astronauts. The Pulse Torque Assembly will be located in the IMU "bubble."

### **4-2 RELIABILITY**

The LEM G&N reliability values are now in the process of being recalculated to reflect the new Design Reference Mission requirements and will be reported in next month's report (for further explanation see paragraph 3-2). Table 4-I shows the reliability figures in effect before implementation of the new requirements.

Subsystem	Operating Time (hrs)	Probability of Mission Success		
IMU	6.25	0.99914		
LGC	6.25	0.9976		
PSA	6.25	0.99928		
CDU (5)	6.25	0.99822		
OMU	0.75	0.99997		
DSKY	6.25	0.9976		
Total G&	0.9918			

Table 4-I. Reliability (as of 1/15/65)

#### 4-3 WEIGHTS FOR LEM

Lunar Excursion Module weights are presented in Table 4-II. In general the data conform to the information contained in paragraphs 2-1, 2-1.1, and 2-1.2.

The row labeled "Bare Guidance System" is inserted to provide for comparisons with similarly specified systems.

### 4-4 REPORTED LEM WEIGHT CHANGES

4-4.1 PSA. The weight of the "new PSA" is 15.2 lbs; the Pulse Torque Assembly weights 12.0 lbs. For a discussion of this equipment see paragraph 4-1.

COMEND BY TIME

Table 4–II. Estim	lated Weight	s of LEM G	kN Comman	d Module (1	bs at 1 g)	
		n Pringer og				Design
	Status	n kardin Nijerya <del>k</del>	Status		Status	Load Wt.
Item	2/64	تىرتىرى	1/65		2/65	7/64
	(a)	(b-a)	(q)	-(c-b)	(c)	(q)
CDU's	15.0(E)	+18.0	33.0(E)	0.0	33.0(E)	*
Telescope and All Eyepieces	24.5(E)	+1.0	25.5(E)	0.0	25.5(E)	
Landing Point Designator	2.0(E)	0.0	2.0(E)	0.0	2.0(E)	
IMU	42.0(E)	+ 0.1	42.1 (E)	0.0	42.1 (E)	
LGC/PSA Interconnection Assy	10.0(E)	0.0	10.0(E)	0.0	10.0(E)	
LGC Display and Controls	19.5(E)	- 2.0	17.5(E)	0.0	17.5(E)	-
Book of Procedures, etc.	2.0(E)	0.0	2.0(E)	0.0	2.0(E)	
LGC	45.8(E)	+12.2	58.0(E)	0.0	58.0(E)	
PSA <sup>†</sup>	27.2(E)	0.0	27.2(E)	-27.2	0.0	
NVB	0.0	+ 6.0	6.0(E)	0.0	6.0(E)	
"New PSA"	0.0	0.0	0.0	+15.2	15.2(E)	
Pulse Torque Assy (PTA)	0.0	0.0	0.0	+12.0	12.0 (E)	
Total	210.0 <sup>§</sup>	+13.3	223.3	0.0	223.3	
1 (141						
Bare Guidance System						
(IMU, New PSA, PTA, & LGC)	115.0	+12.3	127.3	0°0	127.3	
*No design load weight has been a <sup>†</sup> Includes the weight of the PSA C <sup>§</sup> Control Weight specified in Lett to Mr. M. Trageser, MIT/IL. S	assigned. Jover. er PG-63-11 see section 2	13 (March 6	1964) fron	1 Mr. D. Gi	lbert, ASP(	Ó
		ng tuế thủ Đười hoa	n na gan <b>k</b> ul <b>hya</b> n T			

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### **4-5 POWER REQUIREMENTS**

The estimate for LEM power and energy consumption shown in figure 4-1 is based upon Command Module G&N Block II Data and Preliminary ICD LIS-390-2, LEM Electrical Load Analysis Form.

Table 4-III shows the energy requirements for each G&N activity on a power level basis. The table is also based upon LEM ICD LIS-390-2. The vertical column on the left indicates the various G&N activities (phases of operation). This column also indicates the power requirements and operating time for each activity. The top row indicates the power requirements and operating time of each G&N power consuming equipment. The table sums up the energy consumption for power consuming equipment.





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		Total	4.021	5.041	0.086	1.122	0.879	11.149
Table 4-III. Lunar Excursion Module Power Profile Based on LEM ICD LIS-390-2		(7) OMU (AOT) Operate Negligtble watts 27.42 hours	1	negligible	1	1	negligible	negligible
		(6) Two Radar CDU Operate 29.4 watts 11.92 hours	I	0.345	0.006	1	-	0.351
	Energy Consumption (kwh)	(5) IMU Standby 46 watts 123,15 houre	4.021	1	I	0.922	0.722	5.665
		(4) IMU Operate 295.6 watts 11.92 hours	1	3.465	0.059	I	ł	3.524
		(3) LGC Standby 10.0 watts 35.75 hours	9	1	i i i i i i i i i i i i i i i i i i i	. 0.200	0.157	0.357
		(2) LGC Operate 105.0 watts 11.92 hours	1	1.231	0.021	f	I	1.252
		(1) LGC Off 0.0 watts 87.40 hours	0.000	I	I	I	I	0.000
		LEM G&N Activity	Inactivity 46 watts 87.40 hours	Inactivity Alignment Mideourse Measurements 430 watts 11.72 hours	Guidance During Major Event 430 watta 0.20 hours	Inactivity 56 watts 20.05 hours	Inactivity 56 watts 15.70 hours	Total 135.07 hours
	;	NDON	I	Ħ	Ħ	5	>	
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# LUNAR EXCURSION MODULE

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### Section 5

### GLOSSARY AND SYSTEM DEFINITION

### Apollo Guidance Computer (AGC)

<u>CM BLOCK I</u> A single complete flight computer containing all logic, memory, associated power supplies, and all interface circuits except those identified with the CDU's. Does not contain the associated displays and controls.

Consists of one case containing factory replaceable electronic modules. Includes cover for moisture-proofing, but does not include the necessary cold plate or the G&N to S/C Interface Assembly which is located in the adjacent area.

<u>CM BLOCK II AND LEM</u> Same as Block I except that associated power supplies are in a separate case and the CDU's are either adjacent to or on the opposite side of the same cold plate as the AGC. Memory capacity is increased over Block I.

### Alignment Optical Telescope (AOT)

### CM BLOCK I AND CM BLOCK II Not in CM; see Optical Subsystem.

LEM A three-position periscope with single-degree-of-freedom, manually read reticule for alignment of the IMU. Includes the weight of the bellows assembly, a long-eye-relief eyepiece, and regular eyepiece.

### Bellows Assembly

<u>CM BLOCK I AND CM BLOCK II</u> Two flexible pressure seals between CM structure and optical subsystem for penetration of pressure hull with optics.

<u>LEM</u> One bellows with a double convoluted wall and two seals providing a flexible seal for pressure penetration of the AOT in the spacecraft. This weight is included in the AOT value.

### Book of Procedures

 $\underline{CM}$  Not in CM; see  $\underline{MDV}$ .

<u>LEM</u> Book or other form of maps, charts, procedures, instructions, and the like, needed for lunar operations.

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### Coupling Data Unit (CDU) Assembly

The CDU provides the necessary signal interface among the IMU gimbal angles, optics gimbal angles, radar gimbal angles, angle registers in the AGC the spacecraft autopilot attitude error signals, and the tracking radar command error signals.

<u>CM BLOCK I</u> Five interchangeable gear boxes each with necessary motor tachometer, resolver synchros, and encoder with mounting frame work. Does not include associated electronics which are located in the PSA.

<u>CM BLOCK II</u> Functionally identical to Block I except the instrumentation is all electronic. Includes all support electronics (including special power supply) and header. Changes in resolver synchro characteristics and mode controls make Block I and II CDU's noninterchangeable.

LEM Interchangeable with CM Block II CDU's except for the headers.

### Cold Plates

<u>CM BLOCK I, BLOCK II, AND LEM</u> Cold plates for the IMU are built into the IMU. Necessary cold plates for electronics are part of the equipment supplied by the spacecraft manufacturer. All surfaces over glycol coolant passages and open to the cabin environment will be insulated to prevent moisture condensation.

### Control Electronics Assembly

<u>CM BLOCK I</u> Consists of one power transformer, one relay and diode module, and a bracket end connector. Used to support display and control functions. Includes moisture-proofing.

<u>CM BLOCK II</u> Not required in Block II. These functions are now incorporated into the PSA.

LEM Not defined in LEM.

### Coolant Hoses

<u>CM BLOCK I AND CM BLOCK II</u> Consists of (1) two steel flex coolant hoses, one between IMU and spacecraft and one between optics and spacecraft, (2) bracket assembly screws and clamp, and (3) entrapped coolant.

LEM Not identified as part of LEM.

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### Display and Control/Apollo Guidance Computer (D&C/AGC)

<u>CM BLOCK I</u> Number displays and keyboard control associated with the operation of the AGC. Two functionally identical and parallel operating units: one in lower equipment bay and one on main panel between left and center couches.

<u>CM BLOCK II</u> Mechanically and electrically identical to Block I but smaller configuration because of smaller relays. The Block II display and keyboard controls will be hermetically sealed by encasing the unit in a container.

LEM Identical to Block II except only a single unit is required.

### D&C Electronics Assembly

<u>CM BLOCK I</u> Consists of a chassis, a relay and diode module, a demod. elect. module, a saturable reactor, a time delay module, a connector, and wiring. Used to support display and control functions. Connectors will be moisture-proofed.

CM BLOCK II Not required in Block II. These functions now incorporated in the PSA.

LEM Not defined in LEM at this time.

### Landing Point Designator

CM Not in CM.

<u>LEM</u> An optical sighting device consisting of a reticle, plane mirror, collimating lens, and a beam splitter to magnify the target area with a light-line reticle pattern.

### Film Cartridges

<u>CM BLOCK I AND BLOCK II</u> Consists of film cartridges and film for map and data viewer.

LEM Does not exist in LEM.

### G&N Indicator Control Panel

<u>CM BLOCK I AND BLOCK II</u> Consists primarily of controls and displays for the operation of the optics, MDV, IMU temperature control, panel brightness control, and attitude impulse control. It includes display and control elements, panel, panel wiring, supporting hardware, and moisture-proofing.

LEM Does not exist in LEM.

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### G&N Interconnection Assembly

<u>CM BLOCK I</u> Consists of PSA End Connector Assembly and interconnect wiring harness, which electrically ties together the assemblies that constitute a completely integrated system. This term does not include weights of harness support brackets, which are an NAA responsibility, or the G&N to S/C Interface Assembly weight.

<u>CM BLOCK II</u> Similar to Block I but not interchangeable. The connectors in the upper harness are now to be sealed against moisture and contamination.

<u>LEM</u> Not clearly defined but at present is called the AGC/PSA Interconnection Assy. Because of the wide separation of G&N components, most interconnection will be accomplished as part of spacecraft wiring.

### G&N to S/C Interface Assembly

<u>CM BLOCK I</u> Cable interconnections between the spacecraft wiring channel, the computer connector, and the PSA end connector. Contains no active electronics.

<u>CM BLOCK II</u> Similar in functions to Block I except the configuration is much different and not interchangeable with Block I. The connectors in the lower harness are now to be sealed against moisture and contamination.

LEM Not identified yet as a separate item in LEM.

### Horizon Photometer

<u>CM BLOCK I AND BLOCK II</u> An earth horizon brightness photometer and automatic star tracker used for navigation measurements against the earth's illuminated limb. The sensors are incorporated into the head of the SXT the weight of which includes this function. The PSA includes all support electronics for Block II and some of the support electronics for Block I.

LEM Not a part of LEM.

### Horizon Photometer Electronics

CM BLOCK I Additional horizon photometer and star tracker electronics mounted on an auxiliary header and attached to the right-hand wall behind the MDV.

CM BLOCK II All electronics are located in the PSA or on the sextant head.

LEM Not required.

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### Inertial Measurement Unit (IMU)

<u>CM BLOCK I</u> Size 14 IMU (14-inch case diameter) gimbal assembly including all parts inside hermetic case, entrapped coolant, and heat exchanger insulation.

<u>CM BLOCK II AND LEM</u> Size 12.5 IMU functionally interchangeable with Block I unit, but not physically interchangeable with Block I.

### IMU Control Panel

<u>CM BLOCK I</u> Consists of panel, wiring, attitude error meter, CDU transfer switch, manual alignment switch, CDU mode control switches, connector, supporting hard-ware, and associated moisture-proofing.

<u>CM BLOCK II</u> Does not exist in Block II. Moding is done by AGC program and AGC push buttons.

LEM Does not exist in LEM.

### Long-Eye-Relief Eyepieces

<u>CM BLOCK I AND BLOCK II</u> Consists of a SXT and a SCT eyepiece to provide eye relief of at least 1.6 inches for closed visor operation. Used in place of normal eyepieces of SXT and SCT.

LEM Long-Eye-relief eyepiece is included as part of the AOT.

### Map and Data Viewer (MDV)

<u>CM BLOCK I AND BLOCK II</u> Film viewer for display of maps, charts, procedures, and the like. Weight includes one film cartridge and a moisture-proofing enclosure.

LEM Not in LEM; see Book of Procedures.

### NVB and Mounts

<u>CM BLOCK I</u> Rigid beryllium structure supporting the IMU and the optical subsystem with its associated hardware. The NVB is attached to the spacecraft using flexible resilient mounts to prevent spacecraft strains from distorting the NVB and the alignment between the IMU and optics. These mounts also provide shock and vibration attenuation.

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<u>CM BLOCK II</u> Functionally similar to Block I but will be lighter and provide for mounting the size 12.5 IMU. The Block II NVB is attached to the spacecraft by use of strain isolation hardmounts and will have a transition piece as a result of the reorientation of the NVB so that the IMU axes will be parallel to the Command Module axes.

LEM A toroidal aluminum ring with: (1) four tubular aluminum posts to provide for IMU mounting, (2) four tubular aluminum posts for AOT mounting, and (3) three aluminum inserts to provide strain isolation ball mounting to the GAEC structure.

### **Optical Eyepieces**

CM BLOCK I AND BLOCK II Removable SXT eyepiece and SCT eyepiece.

LEM Included as part of the AOT.

### Optical Subsystem

<u>CM BLOCK I AND BLOCK II</u> Consists of SXT, SCT, Optical Base, and associated hardware defined as follows:

SXT:	Sextant. A two-line-of-sight, narrow field, two-degree- of-freedom sextant and its attached gearing. The horizon photometer and automatic star tracker sensors are in- corporated into the SXT head.
SCT:	Scanning Telescope. A single-line-of-sight, wide-field- of-view, two-degree-of-freedom articulation optical instrument and its attached gearing.
Optical Base:	Base for SXT and SCT with associated gearing.

<u>LEM</u> Not in LEM; see <u>AOT</u>.

### Optical Shroud & Cover Assembly

CM BLOCK I AND BLOCK II Consists of the optical shroud and protective cover.

LEM Does not exist in LEM.

Power Servo Assembly (PSA)

CM BLOCK I Includes most of the support electronics: power supplies; IMU, Optics, and CDU servos; IMU temperature control, accelerometer and gyro pulse torquing; and

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horizon photometer and automatic star tracker electronics. Consists of 10 trays and replaceable modules which plug into the PSA end connector assembly. Includes a beryllium front toe plate.

<u>CM BLOCK II</u> Similar in function to Block I except that all horizon photometer electronics are included in the Block II PSA, and the CDU servos are deleted. Consists of a single plane matrix header, mounted to a cold plate, with the modules plugging onto the top. To permit removal of the calibration modules at IMU adjustment or replacement, these modules are contained in a separate assembly located on a cold plate adjacent to the Signal Conditioner Assembly.

<u>LEM</u> Consists of electronics similar to those identified in the Block II PSA minus various electronics modules. Does not include optics and photometry electronics associated with the Block I and II PSA's.

PSA End Connector Assembly

<u>CM BLOCK I</u> Electrical interconnection between the PSA trays, the G&N Interconnection Assy, and the G&N to S/C Interface Assy. The End Connector weight is reported in the G&N to S/C Interconnection Assembly weight.

<u>CM BLOCK II AND LEM</u> Not identified as a separate item; will be part of the PSA matrix header.

### PSA Covers

<u>CM BLOCK I</u> Ten plastic connector covers, gaskets, and mounting screws (one for each tray) for moisture-proofing. Weight included in PSA weight value.

<u>CM BLOCK II AND LEM</u> Cover required for moisture-proofing during flight. Weight is reported in PSA weight value.

### Signal Conditioner Assembly

<u>CM BLOCK I</u> Conditions signals for telemetry.

<u>CM BLOCK II</u> These modules are located in the same volume now occupied by the Block I CDU's.

LEM Same as for Block I.

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