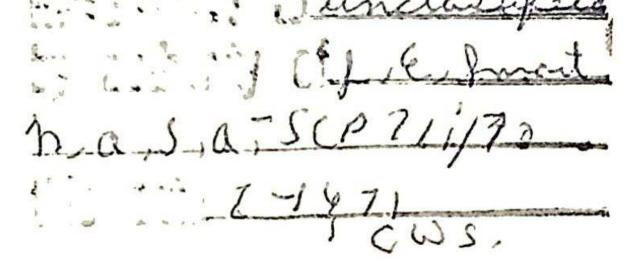
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E-1142 (Rev 33) (UNCLASSIFIED TITLE)

SYSTEM STATUS REPORT

June 15, 1965

## NIII INSTRUMENTATION LABORATORY

CAMBRIDGE 39, MASSACHUSETTS

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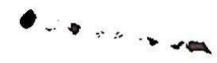
#### ACKNOWLEDGEMENT

This report was prepared under DSR Project 55-238 sponsored by the Manned Spacecraft Center of the National Aeronautics and Space Administration through Contract NAS 9-4065.

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### ABSTRACT

The System Status Report is distributed monthly on the 15th. This month's revision of E-1142 (Rev. 33) contains, in general, the following for the Block I and Block II Command Module and Lunar Excursion Module equipment: configuration weights, centers of gravity, moments of inertia, power requirements, status of computer programs, and reliability values.



#### Section 1

#### INTRODUCTION

### 1-1 INTRODUCTION

Based upon a Request Engineering Change Proposal (RECP) issued from NASA/ MSC dated 12 January 1965 this report incorporates Horizontal Hand Holds on the G&N Panel adjacent to the optics controller and the attitude controller for Block I (100 series) and Block II Systems for use during navigation sightings. These hand holds are a part of the body tethering system for the spacecraft and will be removed during flight and kept as a loose stored item.

At the last Status Review Meeting on May 26, 1965 held at Kollsman, MIT proposed an in-flight lens cleaning kit as a desirable loose stored item for Block I (100 series) and Block II. MSC is now presumably considering this item as part of the flight G&N equipment. RECP action has not yet been initiated.

The definition of what constitutes Block I, Block II, and LEM hardware is contained in the Glossary, section 5.

The following information is included in this month's report:

- (1) Command Module, Block I 100 Series: Weights and power requirements Zero Series: Centers of gravity and moments of inertia Guidance and Navigation Lunar Land Mission: Status of computer and reliability values.
- (2) Command Module, Block II Integrated Guidance, Navigation, and Control Configuration: Weights and reliability values.

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(3) Lunar Excursion Module LEM integrated Guidance and Control Configuration: Weights and reliability values.

### 1-2 ACCURACY

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The accuracy of numerical values reported in this revision should not be considered to be within the tolerances implied by the significant figures quoted. The reported values, although based upon the most current information, are subject to normal changes as design and development phases approach completion.

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### BLOCK I COMMAND MODULE

Section 2

#### BLOCK I COMMAND MODULE DATA

2-1 WEIGHTS

Table 2-I presents the weights of all Block I flight (100 series) systems equipment, grouped according to specific location within the Command Module. Weights are reported to the component level and to the nearest tenth of a pound.

Given component weights are identified as estimated, calculated, and measured in order of increasing accuracy. These terms are defined by North American Aviation as follows: estimated weights (E) are based on rough calculations; calculated weights (C) are based on detailed calculations made from final production drawings that will be used to build flyable equipment; measured weights (M) are actual weights of equipment built to the production drawings.

North American Aviation will provide and be responsible for cold plate weights that are not integral with guidance and control equipment.

2-1.1 WEIGHT STATUS REPORTING. Table 2-I also offers a comparison of pre-

sent 100 series component weight values with those listed in System Status Report, E-1142 (Rev. 32), May 15, 1965. All weight changes are explained in paragraph 2-2.

2-1.2 CONTROL WEIGHT (100 SERIES). Column (a) in Table 2-I contains the total control weight for the Apollo G&N 100 series equipment as specified in letter EG-151-44-65-55 (February 10, 1965) from Mr. R.W. Young, ASPO, to Mr. M. Trageser, MIT/IL.

2-1.3 DESIGN LOAD WEIGHT (100 SERIES). Column (d) of Table 2-I contains the "not to exceed" design load weights for individual Block I G&N 100 series subsystems. These weights were assigned per ICD MH01-01256-416, signed June 3, 1965.

### 2-2 REPORTED BLOCK I 100 SERIES WEIGHT CHANGES

2-2.1 HORIZONTAL HAND HOLDS (+1.0 lb). These will be used by the astronauts during the navigation sightings. For additional information see paragraph 1-1.

2-2.2 LENS CLEANING KIT (+0.1 lb). The cleaning kit will be used during the lunar mission for cleaning the optics lens. For additional information see paragraph 1-1.

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Table 2-1 Current Weight Status of		Block I (100 Series)		Command Module	(lbs at 1	R)
			1 14		0 Series	100 Series Design
	Control Weight	(b-d)	5/65 (b)	(c-b)	6/65 (c)	Load Wt. 1/65 (d)
C.P.N. SVSTEMS	181					
			14.1(M)	0.0	14.1(E)	16.0
CUU Assy				00 51		
Optical subsystem			18.7(E)	0.0	18.7(E)	(
IVC			14.3(E)	0.0	14.3(E)	
Ontinal Base & Gearing			17.0(E)	0.0	17.0(E)	
NVR & Resilient Mounts			25.7 (M)	0.0	25.7 (M)	<b>\155.0</b> †
Bellows Assv			12.7 (M)	0.0	12.7(M)	
INNT			60.5(C)	0.0	60.5(C)	
Coolant Hoses (two)			0.8(E)	0.0	0.8(E)	
Power Servo Assy			59.8(C)	0.0	59.8(C)	120.0
G&N Interconnection Assy			27.3(E)	0.0	27.3(E)	
G&N to S/C Interface Assy			87 0 (MI)	0.0	87.01M)	100.0
AGC (no spares)			(111) 0.10		()	
Optical Shroud			3.1(E)	0.0	3.1 (E)	4.5
LOWER EQUIPMENT BAY						
D&C						
D&C Electronics			3.0(E)	0.0	3.0(E)	5.0
Control Electronics			2.1 (E)	0.0	2.1 (E)	4.0
G&N Ind Cont Panel			10.5(E)	0.0	10.5(E)	15.0
IMU Control Panel			2.8(E)	0.0	2.8(E)	5.0
Condition Annunciator Assy			1.2(E)	0.0	1.2(E)	2.0
D& C/AG C			23.0(M)	0.0	23.0(M)	26.0
Horizon Photo. Elect.			2.2 (C)	0.0	2.2(C)	4.0
Signal Conditioner Assy			3.9 (C)	0.0	3.9 (C)	8.0
MATN DANFT APFA						
D&C/AGC	2		25.2(E)	0.0	25.2(E)	26.0

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(cont)	100 Series Design Load Wt. 1/65 (d)	7.2 2.5 1.0	522.0 <sup>§</sup>	R.W. MIT by
(lbs at 1 g)	100 Series Status 6/65 (c)	1.6(C) 2.6(C) 1.6(C) 1.0(E) 0.1(E)	423.3	
and Module	(c-b)	0.0 0.0 +0.1 +0.1	+1.1	ary 10, 1965), from Mr. .2. of the Bellows Assembly. une 3, 1965, submitted by
ries) Comma	100 Series Status 5/65 (b)	1.6(C) 2.6(C) 1.5(E) 1.6(C)	422.2	ified in letter EG-151-44-65-55 (February Trageser, MIT/IL. See paragraph 2-1.2. 5 figured to include only 1/2 the weight of t taken from ICD MH01-01256 (signed June
ck I (100 Sei	(b-a)		-7.8	151-44-65-5 . See parage only 1/2 th H01-01256 (
tatus of Bloc	100 Series Control Weight (a)		430.0*	cified in letter EG-151-44-65-55 (Febru Trageser, MIT/IL. See paragraph 2-1 is figured to include only 1/2 the weight e taken from ICD MH01-01256 (signed Ju
Table 2-I. Current Weight Status of Block I (100 Series) Command Module (lbs at 1 g) (cont)	Item	LOOSE STORED ITEMS Optical Eyepieces SXT SXT SCT Eye Relief Eyepieces Optics Cover Horizontal Hand Holds Lens Cleaning Kit	TOTAL	*Total control weight specified in letter EG-151-44-65-55 (February 10, 1965), from Mr. Young, ASPO, to Mr. M. Trageser, MIT/IL. See paragraph 2-1.2. †This design load weight is figured to include only 1/2 the weight of the Bellows Assembly \$Design Load Weights are taken from ICD MH01-01256 (signed June 3, 1965, submitted b) letter AG-478-65).

### CONFIDENTIAL Block I COMMAND MODULE

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### CONFIDENTIAL BLOCK I COMMAND MODULE

### 2-3 BLOCK I (ZERO SERIES) WEIGHT, CENTER OF GRAVITY, AND MOMENT OF INERTIA DATA

At the present time since Block I (100 series) G&N equipment is not available inhouse and ACSP is not contractually obligated to perform moments of inertia calculations or measurements, MIT is using Block I zero series information and final production drawings to calculate the Block I (100 series) moments of inertia and centers of gravity. These data will appear in future reports. Table 2-II summarizes Block I (300 series) data.

Weight	Center of Gravity	Moments of Inertia*
(lb)	(in)	(slug ft <sup>2</sup> )
408.9	X 55.1 Y -0.3 Z 37.3	Ixx 146.8 Iyy 418.1 Izz 282.1

Table 2-II. Block I (Zero Series) Weight and Balance Data

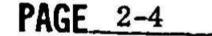
\*Values determined with respect to the basic X, Y, Z axes of the Command Module.

### 2-4 COMMAND MODULE POWER REQUIREMENTS (100 SERIES)

The power requirements of the Command Module G&N 100 series equipment on the primary +28 VDC power supply are shown in figure 2-1 which presents the magnitude and location of dissipated power values on a subassembly level. This chart assumes a 8.27-day mission, as defined by the Apollo Mission Planning Task Force (AMPTF) for power profile computation, and is based on a 28 VDC input at the connectors. The values shown are average values. (Ref: GAEC Report No. LED-540-12, October 30, 1964.)

Table 2-III shows the magnitude and location of power dissipation for the established G&N activities, each of which consists of various power levels of operation.

Table 2-IV shows the energy requirements for each G&N activity on a power level basis. The table is based upon MIT letter AG-679-6, "G&N Power Profile Status," dated August 14, 1963. The vertical column to the left indicates the various G&N activities (phases of operation) for the model 8.27-day mission submitted by the AMPTF (GAEC Report No. LED-540-12, October 30, 1964). The column also indicates the power requirement and operating time for each specific activity. The top row indicates the power requirement and operating time for each G&N power consuming equipment. The table sums up the energy consumption for each G&N activity and each G&N power consuming equipment.



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### BLOCK I COMMAND MODULE

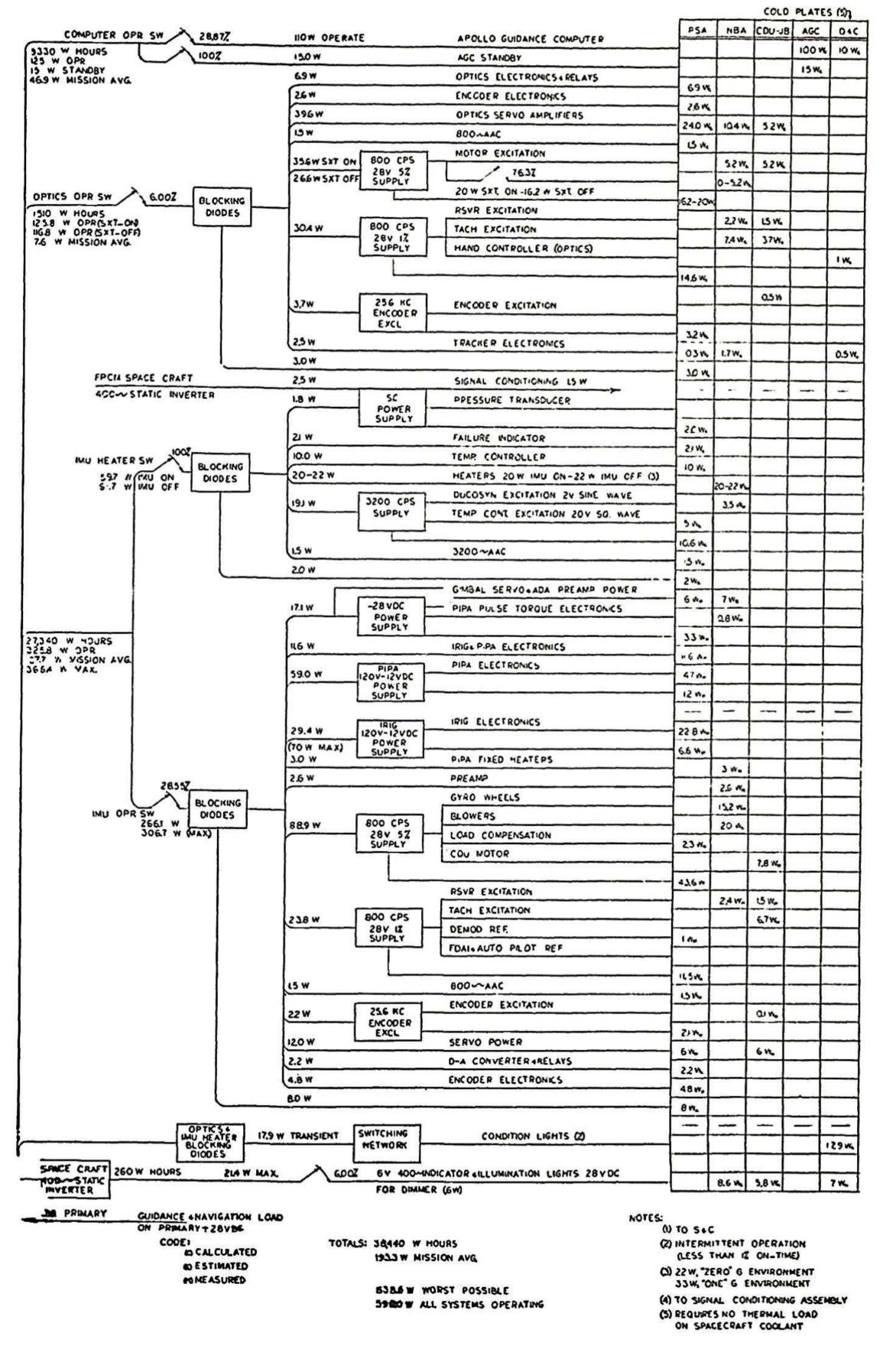


Figure 2-1. Electrical Load on Primary +28 VDC Power Supply for Block I (100 Series) Systems

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	Table 2-III. Nominal Pow	er Diss	ipation	(watts)	vs G&N	Activity	IOL TOL	ONT I HON	Nominal Power Dissipation (watts) vs G&N Activity for Block I (100 Series) Systems				
Z		E	NBA	CDU JB	I JB	PSA	A		,				
0 0	G&N Activity (power levels)		D&C		D&C and	1			Thermal Load on S/C	D&C	Optics	Electrical	
ы		IMU	OBA	IMU	OBA	IMU	OBA	AGC	Coolant	Suc	External	Load	
4	Accomplish & Confirm Course Corrections Inactivity & Monitor Major Mancuvers (1, 5)	74.5	0.0	22.1	0.0	228.5	0.0	115.0	440.1	10.7	0.0	450.8	
B	IMU Alignments Sextant Sightings (Midcourse Navigation) (1, 3, 5, 7)	74.5	40.7	22.1	21.9	228.5	76.1	115.0	578.8	18.7	0.5	598.0	
U	Landmark Trackings (Low-orbit Navigation) (1, 4, 5, 7)	74.5	35.5	22.1	21.9	228.5	72.3	115.0	569.8	18.7	0.5	589.0	
A	Inactivity & Monitor (1, 6)	25.5	0.0	0.0	0.0	36.2	0.0	115.0	176.7	10.0	0.0	186.7	
ы	Sextant Sightings (Midcourse Navigation) (1, 3, 6, 7)	25.5	40.7	0.0	21.9	36.2	76.1	115.0	315.4	18.0	0.5	333.9	
54	Inactivity & Monitor	25.5	0.0	0.0	0.0	36.2	0.0	15.0	76.7	0.0	0.0	76.7	
		1. AGC	AGC Operate	te	12	125.0 watts	ß						

Activity for Block I (100 Series) Systems C.S.N

125.0 watts 15.0 watts 125.8 watts 116.8 watts 325.8 watts 61.7 watts 21.4 watts Optics Operate SXT On 1 Optics Operate SXT Off 1 IMU Operate 3 IMU Standby D&C Operate AGC Standby 

COMMAND MODULE

### BLOCK I

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20.340 10.838 38.440 5.429 1.666 0.066 Total 0.101 (7) D&C Operate 21.4 watts 11.91 hours 0.060 0.006 0.260 0.194 I 1 I (6) IMU Standby 61.7 watts 141.96 hours 8.719 8.760 0.022 0.019 1 I I (5) IMUOperate325.8 watts56.73 hours 14.700 2.958 18.580 Energy Consumption (kwh) 0.922 1 I 1 (4) Optics Sextant OFF 116.8 watts 2.83 hours 0.330 0.330 I 1 L 1 I (3) OpticsSextant ON125.8 watts9.08 hours 0.038 1.142 1.181 1 1 1 I

ergy Consumption Profile for 8.27-Day Lunar Orbit Mission

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### COMMAND MODULE

BLOCK I

Table 2-IV. Block I (100 Series) Command Module En

<ul> <li>C</li> <li>D</li> <li>C</li> <li>C</li> <li>A</li> <li>A Accomplish &amp; Confil</li> <li>Major Maneuvers</li> <li>Major Maneuvers</li> <li>Inactivity &amp; Monitor</li> <li>450.8 watts 45.12</li> <li>450.8 watts 45.12</li> <li>598.0 watts 9.08 h</li> <li>589.0 watts 2.83 h</li> <li>D</li> <li>Inactivity &amp; Monitor</li> </ul>	G&N Activity	(I) AGC	I'VI ALVI
		Operate 125.0 watts 57.38 hours	Standby 15.0 watts 141.31 hours
	Accomplish & Confirm Course Correction Major Maneuvers Inactivity & Monitor 450.8 watts 45.12 hours	5.640	I
	ents tings (Midcourse Navigation) 9.08 hours	1.135	1
	Landmark Tracking (Low-Orbit Navigation) 589.0 watts 2.83 hours	0.354	1
	Monitor 0.35 hours	0.044	I
E Sextant Sightings 333.9 watts 0.	tings (Midcourse Navigation) 0.30 hours	0.038	1
F Inactivity & Monitor 76.7 watts 141.31	Monitor 141.31 hours	I	2.119
Total 1	198.55 hours	7.211	2.119

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### BLOCK I COMMAND MODULE

### 2-5 STATUS OF COMMAND MODULE AGC PROGRAM

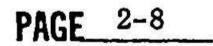
The Block I Command Module program status (Table 2-V) reflects the lunar landing mission exclusive of the stablization and control function.

The Block II Command Module computer program, which contains S&C functions, is in the process of being calculated and will be reported when the values become established

Item	Memory words
List Processing Interpreter	1762
AGC Executive	318
AGC Waitlister	190
AGC Self-Check	889
G&N System Test	1699
Display & Keyboard	2847
Input/Output Control	1769
Navigation	1775
Powered Flight Guidance & Attitude Control	1052
Prelaunch Alignment*	782
In-Flight Alignment*	925
Re-Entry	1543
Re-Start and First Start	468
Mission Sequencing (202)	960
Miscellaneous	497
	17476

Table 2-V. Current Memory Capacity of Command Module AGC Programs (6/15/65)

\*Estimated.





### BLOCK II COMMAND MODULE

Section 3

#### BLOCK II COMMAND MODULE DATA

3-1 RELIABILITY

The operating times and associated mission success probabilities in Table 3-I are based upon the Apollo Mission Planning Task Force (AMPTF) time line listed in GAEC Report LED-540-12, dated October 30, 1965, which uses the interval of Command Module operation from earth launch until LEM separation.

#### 3-2 WEIGHTS FOR THE BLOCK II COMMAND MODULE

Table 3-II shows the weights of the Block II Command Module Integrated Guidance and Control System.

### 3-3 REPORTED BLOCK II WEIGHT CHANGES

3-3.1 IMU (-0.8 lb). The decrease is due to the measured weight of IMU (200-4) which will be used with system 600-F.

3-3.2 SIGNAL CONDITIONER ASSY (+2.6 lbs). The Signal Conditioner Assy weight has been recalculated to reflect the latest information from the circuitry groups.

3-3.3 HORIZONTAL HAND HOLDS (+1.0 lb). These will be used by the astronauts during navigation sightings. For additional information see paragraph 1-1.

3-3.4 LENS CLEANING KIT (+0.1 lb). This kit will be used during the lunar mission for cleaning the optics lens. For additional information see paragraph 1-1.

#### 3-4 POWER REQUIREMENTS

The power requirements of the Block II Command Module G&N equipment on the primary +28 VDC power supply are shown in figure 3-1, which presents the magnitude and location of dissipated power values on a subassembly level. This chart assumes an 8.27-day lunar orbit mission as defined by the Apollo Mission Planning Task Force (AMPTF) for power profile computation and is based on a 28 VDC input at the connectors. These values are average values (Ref: GAEC Report LED-540-12, October 30, 1964). A decrease of 536 watt-hours was reported this month due to measuring the CDU Block II & LEM breadboard power values.

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Variations of AMPTF Design Reference Mission (Probability of success of CSM PGNCS from earth launch until LEM separation. Elapsed time of approximately 68 hours.) **Reliability Estimates For** Table 3-I.

	1					
	Operate	Onerate	Standby Failure	Standby	Failures	
	Rate	Time	Rațe	Time	Per 10 <sup>6</sup>	Success
PGNCS Subsystem	Per 10 <sup>6</sup> hrs	(hrs)	Per 10 <sup>6</sup> hrs	(hrs)	Missions	Probability
IMU	129	12.5	7.8	55.6	2046	0.99796
IMU Electronics	110	12.5	6.3	55.6	1725	0.99827
CDU (IMU)	171	12.5	0	55.6	2138	0.99797
Optics	94	7.8	0	59.1	733	0.9993
<b>Optics Electronics</b>	77	7.8	0	59.1	601	0.9994
CDU (Optics)	114	7.8	0	59.1	889	0.9992
AGC	357	12.5	96.4	55.6	9822	0.991
DSKY (2)	117/12.5 hrs	12.5	0	55.6	117	*66666.0
D&C	13	12.5	0	55.6	163	0.99994
Total					18234	0.982

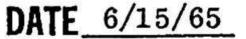
# CONFIDENTIAL BLOCK II COMMAND MODULE

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### BLOCK II COMMAND MODULE

Table 3-III shows the magnitude and location of power dissipation for the established G&N activities, each of which consists of various power levels of operation.

Table 3-IV shows the energy requirements for each G&N activity on a power level basis. The table is based on MIT letter AG 679-6, "G&N power Profile Status," dated August 14, 1963. The vertical column to the left indicates the various G&N activities (phases of operation) for the model 8.27-day lunar mission submitted by AMPTF (GAEC Report LED-540-12, October 30, 1964). This column also indicates the power requirements and operating time for each specific activity. The top row indicates the power requirements and operating time of each G&N power consuming equipment. The total power consumption for each G&N activity and each G&N power consuming equipment is also given.



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Table 3-II. Current	<b>Current Weight Status</b>	of Block	II Command	Module (lbs	at 1 g)	
Item	Control Weight		Status 5/65		Status 6/65	Design Load Wt. 5/64
	(a)	(b-a)	(q)	(c-b)	(c)	(n)
G&N SYSTEMS				c c	1910 00	
CDU Assy			33.0(म)	0.0	33.0(±)	
Optical Subsystem				0		
SXT			18.7(E)	0.0	18.7 (E)	
SCT			14.3(E)	0.0	14.3(比)	
Optical Base & Gearing			17.0(E)	0.0	17.0(E)	
<b>Optical Eyepieces</b> *						
SXT			4.4(E)	0.0		
SCT			4.7 (E)	0.0	4.7(E)	
NVB & Mounts			6	0.0		
Bellows Assy			12.7 (E)	0.0	12.7 (E)	
IMU			Н	-0.8	41.3 (M)	
Coolant Hoses (two)			8	0.0	0.8(E)	
Power Servo Assy <sup>†</sup>			S	0.0	41.5(E)	
PIPA Electronics Assy			7.9(E)	0.0	7.9(E)	
Interconnect Harness Assy			30.0(E)	0.0	30.0(E)	
AGC			58.0(E)	0.0	58.0(E)	
Optical Shroud			3.1 (E)	0.0	3.1(E)	
LOWER EQUIPMENT BAY						
D&C						
G&N Ind Cont Panel			12.1 (E)	0.0	12.1 (E)	
D&C/AGC			17.5(E)	0.0	17.5(E)	
Signal Conditioner Assy			3.9(C)	+2.6	6.5 (C)	
•						
MAIN PANEL AREA						
D&C/AGC			17.5 (E)	0°0	17.5 (E)	

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# CONFIDENTIAL Block II COMMAND MODULE

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3				
	Design Load Wt. 5/64 (d)		492.6**	ces to which oung, include
it 1 g) (cont)	Status 6/65 (c)	1.6(E) 1.0(E) 0.1(E)	357.5	elief eyepieces tructions as to whic Ar. R.W. Young, It does not include
Iodule (lbs a	(c-b)	0.0 +1.0 +0.1	+1.8	2.2-inch eye-relief eyepieces iting NASA instructions as to which ), 1965) from Mr. R.W. Young, ary 11, 1964). It does not include
of Block II Command Module (lbs at 1 g) (cont)	Status 5/65 (b)	1,6(E)	355.7	<ul> <li>full magnification 2.2-inch eye-relief eyepieces</li> <li>his time MIT is awaiting NASA instructions as to whet the Block II G&amp;N.</li> <li>151-44 (February 10, 1965) from Mr. R.W. Young, aragraph 2-1.2.</li> <li>64 MA 2-32 (February 11, 1964). It does not incluited in the second statement of the second state</li></ul>
of Block II	(b-a)		-44.3	le full magnification his time MIT is awa the Block II G&N. 151-44 (February 1 aragraph 2-1.2. 64 MA 2-32 (Febru

### CONFIDENTIAL BLOCK II COMMAND MODULE

\*The eyepiece weights quoted here are for the <sup>§</sup>Total Control Weight specified in letter EG-1 See pa designed by MIT under NASA direction. At th of the two possible eyepiece designs to use in \*\*Design Load Weight taken from S&ID letter **Current Weight Status** Control Weight 400.0 § (a) <sup>†</sup>Includes the weight of the PSA Cover. ASPO, to Mr. M. Trageser, MIT/IL. LOOSE STORED ITEMS Horizontal Hand Holds Table 3-II. loose stored items. Item Lens Cleaning Kit **Optics** Cover Total

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### BLOCK II COMMAND MODULE

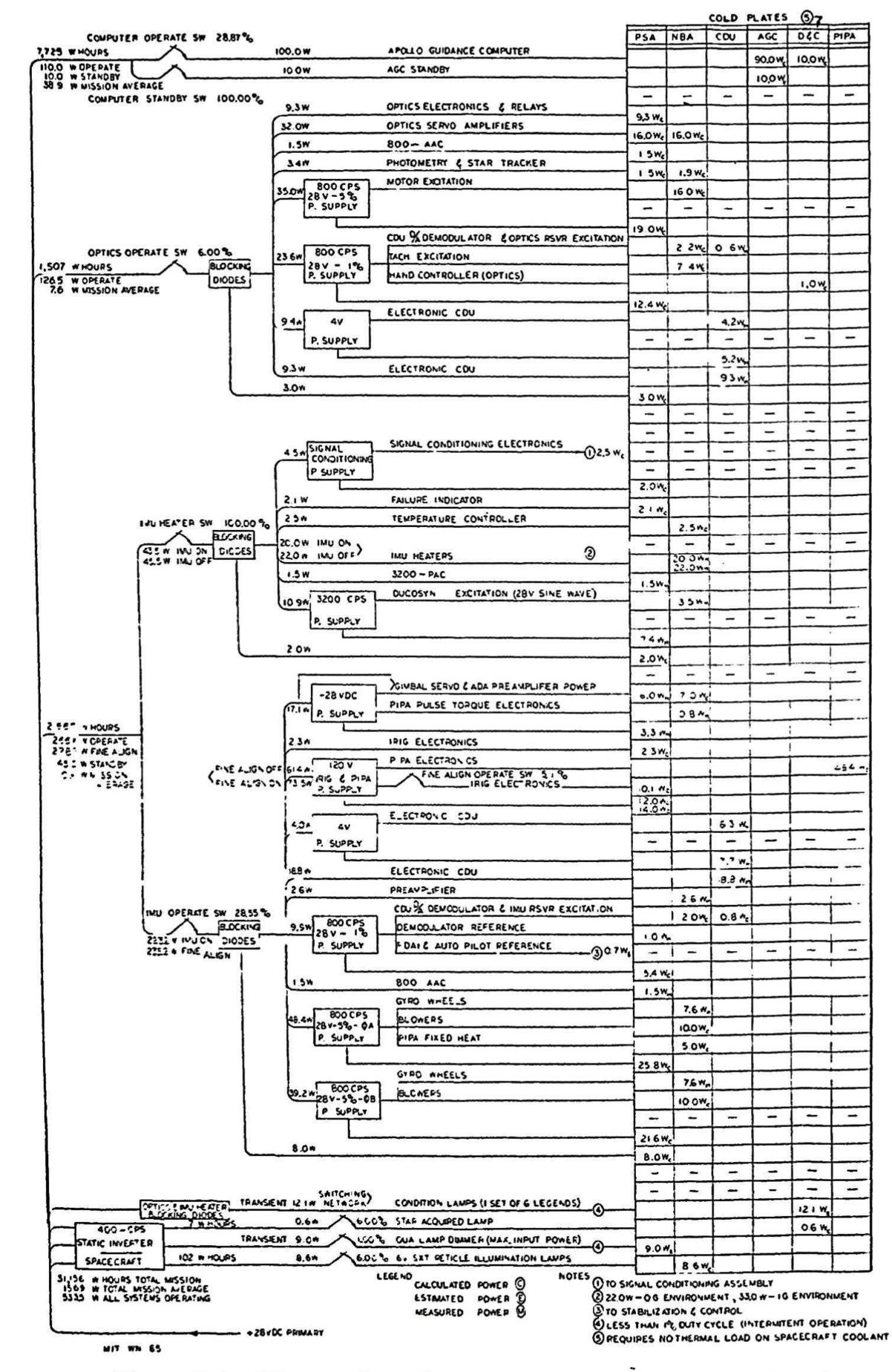


Figure 3-1. Electrical Load on Primary +28 VDC Power Supply

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	Tavic o TH. MOMINIAL FORCE DISSIPATION (Marie) VS UNIT ALL IN DIVIDUAL DISSIPATION	WCT TIM	Annytree	manul II	so an li	ATANTS LTO	117 101 1	N T VN01	anima a		
×o	G&N Activity	NBA	ŝA	CDU	U	PSA	A		Thermal	D&C	Elootui anl
AШ	(power levels)	IMU	OBA	UMI	OBA	IMU	OBA	AGC	Coolant	S&C	Load
A	Accomplish & Confirm Course Corrections Inactivity & Monitor Major Maneuvers (1, 4)	78.6	0.0	32.8	0.0	154.3	0.0	100.0	365.7	10.7	376.7
щ Д	IMU Alignments Sextant Sightings (Midcourse Navigation) Landmark Tracking (Low-orbit Navigation) (1, 3, 4, 6)	78.6	32.8	44.9	18.7	154.3	62.7	100.0	491.5	33.8	525.3
U	Inactivity & Monitor (1, 5)	28.0	0*0	0.0	0.0	18.0	0.0	100.0	146.0	10.0	156.0
A	Sextant Sightings (Midcourse Navigation) (1, 3, 5, 6)	28.0	43.7	0.0	18.7	18.0	62.7	100.0	271.5	33.1	304.6
ы	Inactivity & Monitor (2,5)	28.0	0.0	0.0	0.0	18.0	0.0	10.0	56.0	0.0	56.0
				1000							

110.0 watts 10.0 watts 126.5 watts 266.7 watts 46.0 watts 22.1 watts

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### COMMAND MODULE

BLOCK II

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Nominal Power Dissipation (wa Table 3-III.

AGC Operate AGC Standby Optics Operate

IMU Operate IMU Standby D&C Operate

umption Profile for 8.27-Day Lunar Orbit Mission

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### BLOCK II COMMAND MODULE

able 3-IV. Block II Command Module Energy Co

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Section 4

### LUNAR EXCURSION MODULE DATA

### 4-1 RELIABILITY

The operating times and associated mission success probabilities in Table 4-I are based upon the Apollo Mission Planning Task Force (AMPTF) time line listed in GAEC Report No. LED-540-12, dated 30 October 1964, which uses the interval of LEM operation from earth launch to lunar touchdown.

### 4-2 WEIGHTS FOR LEM

Lunar Excursion Module weights are presented in Table 4-II. In general the data conform to the information contained in paragraphs 2-1, 2-1.1, and 2-1.2.

The row labeled "Bare Guidance System" is inserted to provide for comparisons with similarly specified systems.

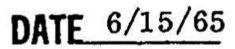
### 4-3 REPORTED LEM WEIGHT CHANGES

4-3.1 IMU (-0.8 lb). The decrease is due to the measured weight of IMU (200-4) which will be used with systems 600-F.

### 4-4 POWER REQUIREMENTS

The estimate for LEM power and energy consumption shown in figure 4-1 is based upon the 8.27-day lunar orbit mission as defined by the Apollo Mission Planning Task Force (AMPTF) for power profile computation (Ref: GAEC Report LED-540-12, dated October 30, 1964). A decrease of 115 watt-hours was reported this month due to measuring the CDU Block II & LEM breadboard power values.

Table 4-III shows the energy requirements for each G&N activity on a power level basis. The table is also based upon GAEC Report LED-540-12. The vertical column on the left indicates the various G&N activities (phases of operation). This column also indicates the power requirements and operating time for each activity. The top row indicates the power requirements and operating time of each G&N power consuming equipment. The table sums up the energy consumption for power consuming equipment.



Reliability Estimate for LEM G&N Based on AMPTF Design Reference Mission probabilities for LEM PGNCS from earth launch until LEM touchdown.)

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	Operate Failure Rate	Operate Time	Standby Failure Rate	Standby Time	Failures Per 10 <sup>6</sup>	Success
PGNCS Subsystem	Per 10 <sup>6</sup> hrs	(hrs)	Per 10 <sup>6</sup> hrs	(hrs)	Missions	Probability
IMU	129	3.25	7.8	66.2	936	0,9991
IMU Electronics	105	3.25	6.3	66.2	753	0.9993
CDU (IMU)	183	3.25	0	0	595	0.9995
Optics	38	3.25	0	0	124	0.99988
Optics Electronics	38	3.25	0	0	124	0.99988
CDU (Optics)	122	3.25	0	0	397	0.9997
AGC	357	3.25	0	0	1160	0.9989
DSKY	293	3.25	0	0	952	0.9991
D&C	13	3.25	0	0	42	0.99996
Total					5038	0.995

LUNAR EXCURSION MODULE

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à Table 4-I.

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Table 4-II. Estime	Estimated Weights	of LEM G&N	N Command	Module (lbs	s at 1 g)	
	Control Weight (a)	(b-a)	Status 5 / 65 (b)	(c-b)	Status 6/65 (c)	Design Load Wt. 7/64 (d)
CDU's Telescope and All Eyepieces IMU LGC/PSA Interconnection Assy LGC Display and Controls Book of Procedures, etc. LGC NVB PSA Pulse Torque Assy (PTA) Signal Conditioner Assy			33.0(E) 25.5(E) 42.1(E) 17.5(E) 2.0(E) 58.0(E) 6.0(E) 15.2(E) 12.0(E) 6.2(E) 6.2(E)	0.0 0.0 0.0 0.0 0.0 0.0	33.0(E) 25.5(E) 41.3(M) 17.5(E) 2.0(E) 58.0(E) 6.0(E) 15.2(E) 12.0(E) 6.2(E) 6.2(E)	*
	240.0 <sup>†</sup>	-12.5	227.5	-0.8	226.7	
Bare Guidance System (IMU, PSA, PTA & LGC)			127,3	-0.8	126.5	
*No design load weight has been assigned † Total Control Weight specified in Letter ASPO, to Mr. M. Trageser, MIT/IL. Se	• •	er EG-151-44-65 (Februar See section 2-1.2.	(Februar 2.	y 10, 1965) f	1965) from Mr. R.	R.W. Young,

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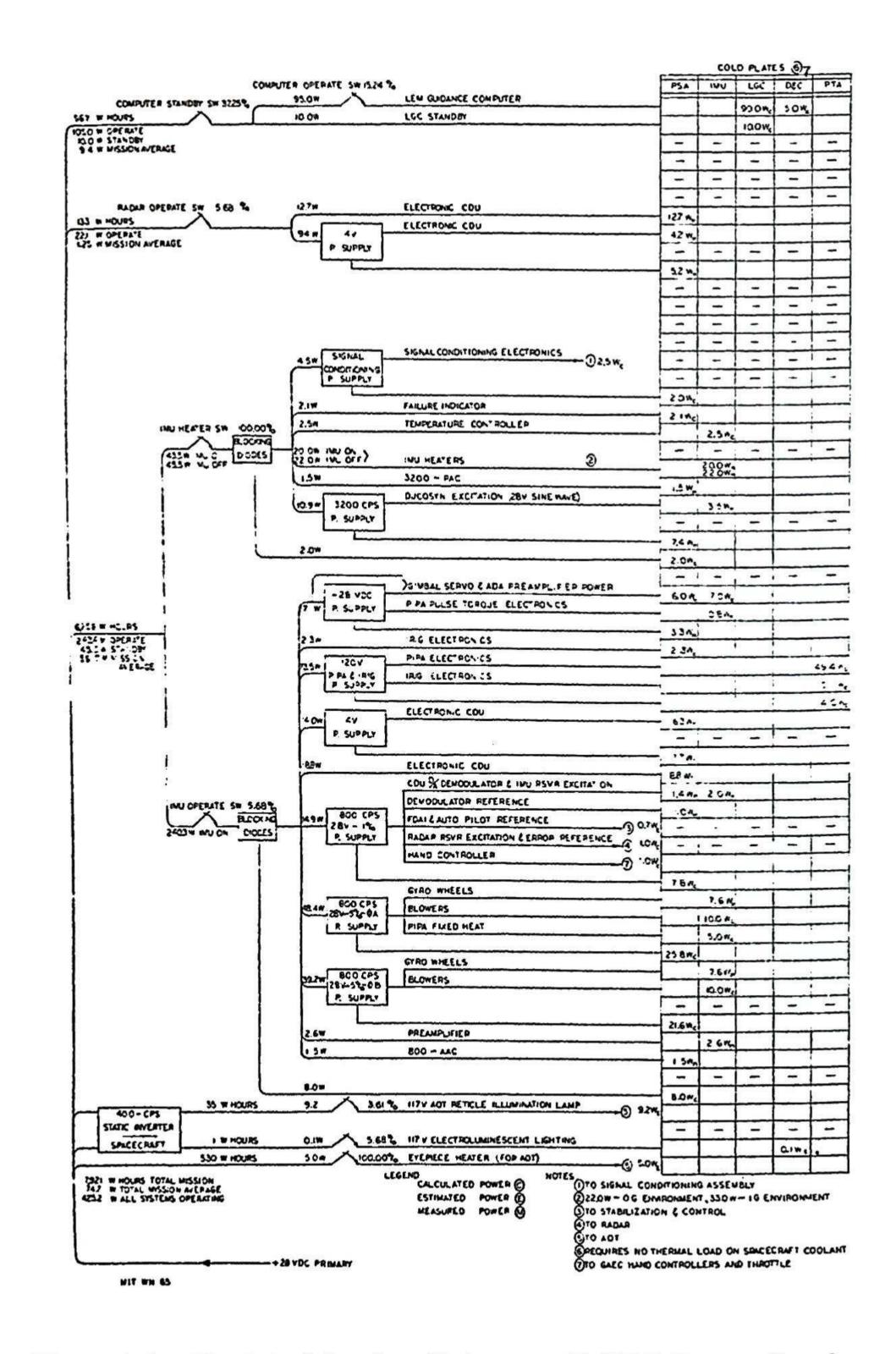


Figure 4-1. Electrical Load on Primary +28 VDC Power Supply

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	Total	3,360	1.625	0.911	2.025	7.921
	<ul> <li>(8) AOT</li> <li>(8) Eyeplece</li> <li>heater</li> <li>5 watts</li> <li>106.02 hours</li> </ul>	0.333	0.019	0.011	0.167	0.530
	(7) OMU (AOT) Operate 9.2 watts 3.83 hours	I	0.035	1	1	0.035
vh)	<ul> <li>(6) Two</li> <li>Radar CDU</li> <li>Operate</li> <li>22.1 watts</li> <li>6.02 hours</li> </ul>	ı	0,085	0.048	I	0.133
Energy Consumption (kwh)	(5) IMU Standby 45.5 watts 100 hours	3.027	I	1	1.523	4.550
Energy Consumption (k	<ul> <li>(4) IMU</li> <li>Operate</li> <li>283.8 watts</li> <li>6.02 hours</li> </ul>	I	1.084	0.622		1.706
	iC by tts hours				35	335

(3) LGC Standby 10 watt 33.48 hc 0.35 0.3 1 1 1 (2) LGC Operate 105 watts 6.02 hours 0.632 0.402 0.230 I I (1) LGC Off 0 watts 66.52 hours 0.000 0.000 1 I 1 Table 4-DI. Guidance During Major Event 66.52 hours 3.83 hours 2.19 hours 106.02 houre 33.48 hours Activity Midcourse Measurements 425.1 watts 415.9 watts 50.5 watts 60.5 watts Alignment Inactivity Inactivity Inactivity Total 日 ≥ MODW -

Lunar Excursion Module Power Profile Based on GAEC Report LED-540-12

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### DATE 6/15/65

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#### Section 5

### GLOSSARY AND SYSTEM DEFINITION

Apollo Guidance Computer (AGC)

<u>CM BLOCK I</u> A single complete flight computer containing all logic, memory associated power supplies, and all interface circuits except those identified with the CDU's. Does not contain the associated displays and controls.

Consists of one case containing factory replaceable electronic modules. Includes cover for moisture-proofing, but does not include the necessary cold plate or the G&N to S/C Interface Assembly which is located in the adjacent area.

<u>CM BLOCK II AND LEM</u> Same as Block I except that associated power supplies are in a separate case and the CDU's are either adjacent to or on the opposite side of the same cold plate as the AGC. Memory capacity is increased over Block I.

Alignment Optical Telescope (AOT)

CM BLOCK I AND CM BLOCK II Not in CM; see Optical Subsystem.

LEM A three-position periscope with single-degree-of-freedom, manually read reticule for alignment of the IMU. Includes the weight of the bellows assembly, a long-eye-relief eyepiece, and regular eyepiece.

### Bellows Assembly

<u>CM BLOCK I AND CM BLOCK II</u> Two flexible pressure seals between CM structure and optical subsystem for penetration of pressure hull with optics.

<u>LEM</u> One bellows with a double convoluted wall and two seals providing a flexible seal for pressure penetration of the AOT in the spacecraft. This weight is included in the AOT value.

### Condition Annunciator Assembly

<u>CM BLOCK I</u> Visually displays G&N system malfunctions. This function was previously part of the Map & Data Viewer.

CM BLOCK II AND LEM Not defined as yet for Block II and LEM.

### Coupling Data Unit (CDU) Assembly

The CDU provides the necessary signal interface among the IMU gimbal angles, optics gimbal angles, radar gimbal angles, angle registers in the AGC, the space-craft autopilot attitude error signals, and the tracking radar command error signals.

<u>CM BLOCK I</u> Five interchangeable gear boxes each with necessary motor tachometer, resolver synchros, and encoder with mounting frame work. Does not include associated electronics which are located in the PSA.

<u>CM BLOCK II</u> Functionally identical to Block I except the instrumentation is all electronic. Includes all support electronics (including special power supply) and header. Changes in resolver synchro characteristics and mode controls make Block I and II CDU's noninterchangeable.

LEM Interchangeable with CM Block II CDU's except for the headers.

### Cold Plates

<u>CM BLOCK I, BLOCK II, AND LEM</u> Cold plates for the IMU are built into the IMU. Necessary cold plates for electronics are part of the equipment supplied by the spacecraft manufacturer. All surfaces over glycol coolant passages and open to the cabin environment will be insulated to prevent moisture condensation.

Control Electronics Assembly

<u>CM BLOCK I</u> Consists of one power transformer, one relay and diode module, and a bracket end connector. Used to support display and control functions. Includes moisture-proofing.

<u>CM BLOCK II</u> Not required in Block II. These functions are now incorporated into the PSA.

LEM Not defined in LEM.

### <u>Coolant Hoses</u>

<u>CM BLOCK I AND CM BLOCK II</u> Consists of (1) two steel flex coolant hoses, one between IMU and spacecraft and one between optics and spacecraft, (2) bracket assembly screws and clamp, and (3) entrapped coolant.

LEM Not identified as part of LEM.

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### Display and Control/Apollo Guidance Computer (D&C/AGC)

<u>CM BLOCK I</u> Number displays and keyboard control associated with the operation of the AGC. Two functionally identical and parallel operating units: one in lower equipment bay and one on main panel between left and center couches.

<u>CM BLOCK II</u> Mechanically and electrically identical to Block I but smaller configuration because of smaller relays. The Block II display and keyboard controls will be hermetically sealed by encasing the unit in a container.

LEM Identical to Block II except only a single unit is required.

### D&C Electronics Assembly

<u>CM BLOCK I</u> Consists of a chassis, a relay and diode module, a demod. elect. module, a saturable reactor, a time delay module, a connector, and wiring. Used to support display and control functions. Connectors will be moisture-proofed.

CM BLOCK II Not required in Block II. These functions now incorporated in the PSA.

LEM Not defined in LEM at this time.

Flight Data Book/Book of Procedures

<u>CM BLOCK I, CM BLOCK II, AND LEM</u> Book or other form of maps, charts, procedures, instructions and the like, needed for use during the Apollo Mission.

### **G&N** Indicator Control Panel

<u>CM BLOCK I AND BLOCK II</u> Consists primarily of controls and displays for the operation of the optics, MDV, IMU temperature control, panel brightness control, and attitude impulse control. It includes display and control elements, panel, panel wiring, supporting hardware, and moisture-proofing.

LEM Does not exist in LEM.

### G&N Interconnection Assembly

<u>CM BLOCK I</u> Consists of PSA End Connector Assembly and interconnect wiring harness, which electrically ties together the assemblies that constitute a completely integrated system. This term does not include weights of harness support brackets, which are an NAA responsibility, or the G&N to S/C Interface Assembly weight.

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### CM BLOCK II Not in Block II.

<u>LEM</u> Not clearly defined but at present is called the LGC/PSA Interconnection Assy. Because of the wide separation of G&N components, most interconnection will be accomplished as part of spacecraft wiring.

### G&N Interconnection Harness Assembly

<u>CM BLOCK I</u> Not required.

<u>CM BLOCK II</u> Consists of nine cables that electrically tie together the assemblies that make up the G&N system and interface with the spacecraft.

LEM Not required.

### G&N to S/C Interface Assembly

<u>CM BLOCK I</u> Cable interconnection between the spacecraft wiring channel, the computer connector, and the PSA end connector. Contains no active electronics.

CM BLOCK II Not in Block II.

<u>LEM</u> Not identified yet as a separate item in LEM.

### Horizon Photometer

<u>CM BLOCK I AND BLOCK II</u> An earth horizon brightness photometer and automatic star tracker used for navigation measurements against the earth's illuminated limb. The sensors are incorporated into the head of the SXT the weight of which includes this function. The PSA includes all support electronics for Block II and some of the support electronics for Block I.

LEM Not a part of LEM.

### Horizon Photometer Electronics

<u>CM BLOCK I</u> Additional horizon photometer and star tracker electronics mounted on an auxiliary header and attached to the right-hand wall in the lower equipment bay.

<u>CM BLOCK II</u> All electronics are located in the PSA or on the sextant head.

LEM Not required.

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### Horizontal Hand Holds

<u>CM BLOCK I AND CM BLOCK II</u> Hand holds on the G&N Panel for use during navigation sightings. These Hand Holds are a part of the body tethering system for the S/C and will be removed during flight.

LEM Not defined in LEM.

### Inertial Measurement Unit (IMU)

<u>CM BLOCK I</u> Size 14 IMU (14-inch case diameter) gimbal assembly including all parts inside hermetic case, entrapped coolant, and heat exchanger insulation.

### IMU Control Panel

<u>CM BLOCK I</u> Consists of panel, wiring, attitude error meter, CDU transfer switch, manual alignment switch, CDU mode control switches, connector, supporting hardware, and associated moisture-proofing.

<u>CM BLOCK II</u> Does not exist in Block II. Moding is done by AGC program and AGC push buttons.

LEM Does not exist in LEM.

### Landing Point Designator

CM Not in CM.

 $\underline{\text{LEM}}$  An optical sighting device consisting of a reticle, plane mirror, collimating lens, and a beam splitter to magnify the target area with a light-line reticle pattern.

### Lens Cleaning Kit

<u>CM BLOCK I AND CM BLOCK II</u> Not specially defined but appropriate cloths for cleaning the accessible surfaces of the optics lens.

LEM Not defined in LEM.

### Long-Eye-Relief Eyepieces

<u>CM BLOCK I</u> Consists of a SXT and a SCT eyepiece to provide eye relief of at least 1.6 inches for closed visor operation. Used in place of normal eyepieces of SXT and SCT.

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<u>CM BLOCK II</u> Combination eyepiece, regular and long-eye-relief, that has full power and full field of view.

LEM Long-eye-relief eyepieces: are included as part of the AOT.

### NVB and Mounts

<u>CM BLOCK I</u> Rigid beryllium structure supporting the IMU and the optical subsystem with its associated hardware. The NVB is attached to the spacecraft using flexible resilient mounts to prevent spacecraft strains from distorting the NVB and the alignment between the IMU and optics. These mounts also provide shock and vibration attenuation.

<u>CM BLOCK II</u> A polyurethane filled aluminum skinned structure functionally similar to Block I but lighter and will provide for mounting the size 12.5 IMU. The Block II NVB is attached to the spacecraft by use of strain isolation hardmounts and will have a transition piece as a result of the re-orientation of the NVB so that the IMU axes will be parallel to the Command Module axes.

<u>LEM</u> A toroidal aluminum ring with: (1) four tubular aluminum posts to provide for IMU mounting, (2) four tubular aluminum posts for AOT mounting, and (3) three aluminum inserts to provide strain isolation ball mounting to the GAEC structure.

### **Optical Eyepieces**

<u>CM BLOCK I</u> Removable SXT eyepiece and SCT eyepiece.

<u>CM BLOCK II</u> Combination eyepiece, regular and long-eye-relief, that has full power and full field of view.

LEM Included as part of the AOT.

### Optical Subsystem

CM BLOCK I AND CM BLOCK II Consists of SXT, SCT, Optical Base, and associated hardware defined as follows:

SXT: Sextant: A two-line-of-sight, narrow-field, two-degreeof-freedom sextant and its attached gearing. The horizon photometer and automatic star tracker sensors are incorporated into the SXT head.

SCT: Scanning Telescope: A single-line-of-sight, wide-fieldof-view, two-degree-of-freedom articulation optical instrument and its attached gearing.

Optical Base: Base for SXT and SCT with associated gearing.



LEM Not in LEM; see AOT.

### Optical Shroud & Cover Assembly

CM BLOCK I AND BLOCK II Consists of the optical shroud and protective cover.

LEM Does not exist in LEM.

#### PIPA Electronics Assembly

CM BLOCK I Does not exist separately in Block I.

<u>CM BLOCK II</u> Consists of electronics which directly support the function of the PIPA loop, including the calibration modules, containing selected components, assigned to each IMU. This sealed assembly is located in the Block I CDU location.

LEM Not required.

### Power Servo Assembly (PSA)

<u>CM BLOCK I</u> Includes most of the support electronics: power supplies; IMU, Optics, and CDU servos; IMU temperature control; accelerometer and gyro pulse torquing; and horizon photometer and automatic star tracker electronics. Consists of 10 trays and replaceable modules which plug into the PSA end connector assembly. Includes a beryllium front toe plate.

<u>CM BLOCK II</u> Similar in function to Block I except that all horizon photometer electronics are included in the Block II PSA, and the CDU servos are deleted. Also, electronics to support the PIPA loop have been transferred. See "PIPA Electronics Assembly." Consists of a single plane matrix header, mounted to a cold plate, with the modules plugging onto the top.

<u>LEM</u> Consists of electronics similar to those identified in the Block II PSA minus various electronics modules. Does not include optics and photometry electronics associated with the Block I and II PSA's. Also, the LEM PSA does not include electronics for the PIPA and IRIG loops. See "Pulse Torque Assembly."

### PSA End Connector Assembly

<u>CM BLOCK I</u> Electrical interconnection between the PSA trays, the G&N Interconnection Assy, and the G&N to S/C Interface Assy. The End Connector weight is reported in the G&N to S/C Interconnection Assembly weight.

<u>CM BLOCK II AND LEM</u> Not identified as a separate item; will be part of the PSA matrix header.

### PSA Covers

<u>CM BLOCK I</u> Ten plastic connector covers, gaskets, and mounting screws (one for each tray) for moisture-proofing. Weight included in PSA weight value.

<u>CM BLOCK II AND LEM</u> Cover required for moisture-proofing during flight. Weight is reported in PSA weight value.

### Pulse Torque Assembly

<u>CM BLOCK I</u> Does not exist separately in Block I.

CM BLOCK II Not required.

LEM This assembly consists of electronics contained in the PIPA and IRIG loops, including the pulse torque power supply and PIPA and IRIG calibration modules. The PIPA calibration modules, containing selected components, are assigned to each IMU. This sealed assembly is located adjacent to the IMU in LEM.

Signal Conditioner Assembly

<u>CM BLOCK I</u> Conditions signals for telemetry.

<u>CM BLOCK II</u> These modules are located in the same volume now occupied by the Block I lower equipment bay DSKY.

LEM Same as for Block I.



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