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.5 REASON(S) FOR CHANGE				
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.6 DESCRIPTION OF CHANGE	······································	18-4- 		
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Page 2 of 2

APOLLO SPACECRAFT SOFTWARE CONFIGURATION CONTROL BOARD

-DATA AMPLIFICATION SHEET -

PROGRAM CHANGE 688 PREPARED BY: <u>Klumpp</u> ORGANIZATION: REQUEST NO. <u>688</u> PREPARED BY: <u>Klumpp</u> ORGANIZATION: DATE: <u>69 01 09</u> MIT/IL

CONTINUATION SECTION (REFER TO BLOCK NUMBER AND TITLE ON PROGRAM CHANGE REQUEST FORM)

1.5 Reasons for Change

The landing guidance equations are solved in a floating coordinate frame which is presently erected each pass thru the guidance equations. The consequence of erecting the guidance coordinate frame (GCF) backward, (rotated 180 degrees about the vertical) is that the LM turns upside down and crashes. This phenomenon has been observed in several independent simulations. The targeting for the previous one-phase trajectories made it impossible for the GCF to be erected backward. With many of the trajectories presently being considered, the criteria precluding backward erection are no longer met. However, it can be shown that the GCF will always be erected forward provided it is only erected when time-to-go is between certain limits. These limits are a function only of the targeting. With the proposed change, trajectory restrictions are eliminated, and we can permit trajectories which are far closer to the desires of the FCSD than were previously considered possible. Without the proposed change, certain of these trajectories would be precluded.

1.6 Description of Change

- A. Establish 4 erasable cells in the W matrix along with the descent targeting parameters for the storage of time-to-go limits for the braking and approach phases.
- B. Branch around erection of the GCF whenever time-to-go is outside the limits for the current phase.

REMARKS

TP#21812