NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

FINAL

APOLLO 10 FLIGHT PLAN

AS-505/CSM-106/LM-4

APRIL 17, 1969

PREPARED BY FLIGHT PLANNING BRANCH FLIGHT CREW SUPPORT DIVISION

> MANNED SPACECRAFT CENTER HOUSTON, TEXAS

SECTION 4

APOLLO 10

APOLLO AS-505/CSM-106/LM-4

FINAL FLIGHT PLAN

APRIL 17, 1969

Submitted by:

E. B. Pippert Jr.

Flight Planning Branch

12M Lindsey **.** R.

Flight Planning Branch

In sin

W. M. Anderson Flight Planning Branch

Approved by:

W. J. Noj

Chief. Might Crew Support Division

Donald K. Slayton

Director of Flight Crew Operations

Concurrence:

George M. Low Manager, Apollo Spacecraft Program

Christopher C. Kraft, Jr. / Director of Flight Operations

Any comments or questions on this document should be forwarded to E. B. Pippert or W. M. Anderson, Flight Planning Branch, mail code CF34, extension 4271.

TABLE OF CONTENTS

Introduction Abbreviations		11 111
	SECTION 1 - GENERAL	
Mission Description Summary Flight Plan (Fig. Rendezvous Profile (Fig. Spacecraft Altitude vs. G Burn Schedules (Table 1-1 Lunar Landing Site and Lan CSM and LM Flight Plan Nor CSM and LM Communications	1-1) 1-2) ET (Fig. 1-3) and 1-2) ndmark Tracking Data (Table 1-3, 1-4) tes and Instrumentation Notes	1-1 1-5 1-6 1-7 1-8, 1-9 1-10 1-11 1-29
	SECTION 2 - MANEUVER UPDATE FORMS	
Maneuver Update Forms Sum CSM Maneuver Update Forms LM Maneuver Update Forms	nary	2-1 2-2 2-24
	SECTION 3 - DETAILED TIMELINE	
Launch S-IVB Orbital Operations Translunar Coast Activition Midcourse Navigation Lunar Orbit Insertion Lunar Orbit Activities First Ingress LM Checkout and Activit LM Undocking thru Und APS Burn to Depletion Landmark Tracking Transearth Injection Transearth Coast Entry	es ation ocking	3-1 3-3 3-6 3-9, 3-18 3-39 3-43 3-52 3-56 3-66 3-75 3-91 3-91 3-116
	SECTION 4 - DETAILED TEST OBJECTIVES	
Detailed Test Objectives Mission Activity/Test Objectives Test Objectives/Mission A Correlation of Test Objectives	ective Cross Reference (Table 4-1) ctivity Cross Reference (Table 4-2) tives with Mission Phases and Activities	4-1 4-2 4-3 4-8, 4-9
	SECTION 5 - CONSUMABLES ANALYSIS	
SM-RCS Summary CSM SPS Summary CSM Crypgenic Summary		5-1 5-1 5-1

LM	RCS Summary	5-1
LM	DPS Summary	5-1
LM	APS Summary	5-1
LM	0 ₂ Summary	5-1
LM	EPS Summary	5-1

۲ ۹

·

.

. . ¢

INTRODUCTION

This Flight Plan has been prepared by the Flight Planning Branch, Flight Crew Support Division, with technical support by TRW Systems.

This document schedules the AS-505/CSM-106/LM-4 operations and crew activities to fulfill, when possible, the test objectives defined in the Mission Requirements, F Type Mission, Change A, dated April 9, 1969.

The trajectory parameters used in this Flight Plan are for May 18, 1969 launch, with a 72° launch azimuth and were supplied by Mission Planning and Analysis Division as defined by the Apollo Mission F Spacecraft Operational Trajectory.

The Apollo 10 Flight Plan is under the configuration control of the Crew Procedures Control Board (CPCB). All proposed changes to this document that fall in the following categories should be submitted to the CPCB via a Crew Procedures Change Request:

- 1. Items that impose additional crew training or impact crew procedures.
- Items that impact the accomplishment of detailed test objectives.
- Items that result in a significant RCS or EPS budget change.
- 4. Items that result in moving major activities to a different activity day in the Flight Plan.
- 5. Items that require a change to the flight data file.

The Chief, Flight Planning Branch (FCSD) will determine what proposed changes fall in the above categories.

Mr. W. M. Anderson will act as co-ordinator for all proposed changes to the Apollo 10 Flight Plan.

Any requests for additional copies or changes to the distribution lists of this document must be made in writing to Mr. W. J. North, Chief, Flight Crew Support Division, MSC, Houston, Texas.

flight Director Attilude Indicator (fDA1) Welecity Change (Differencial) Welecity Change at Engine Cuto Position Change (Differencial) T Conditioning Equipment lization Control System The of Cleast Approach remaposition docking & U rees Earth Coast research Insertion Y B(Third Stage) ropulsion Syste line of Ephemeris Update d Transait Mode No. Vind Component Truenian Angle Tensmerian, Nedagascar Time Rese No. Network Container Micelver Node No nute a Christi, Texas Frensfer Fransmitt of Transmitter Fransponder ifee Cut-off t of lightion is lumar Caust almost Insertion : Nettor Control mitted States Pass kithout Kith Respect to VSNS Natertonn but the 21 Igna 2.1 te) (i di Cer 161 쭕쭕홂붖珠로르텼븕혴렡펔펯쀭햜_こ┛봌봌_뚢 춓 8-balls I ž 222 23s 455 . crol Section elementer nd Gaging System untidirection ingleana Bygan Parpa Satana Bygan Parpa Satana Divit Reta Disylay Earth and Lanar Divintedian Divintedian urigation procession Continution Montener usteal Hiles materi ationi Stee Rate buriti ocal Versical Junch Vehicle Prossure Display ssion Centrol Center a Propulsion System and Space Flight Nets all Threat Vector Con rustion Martice Fuel Ratio Prefabil Angle Operate Presserve latone De Stable Menher (s Reder Ality Individuo isteed, Floride ar Update Ar Update Ar Modelstion r holarizing Santh Africa Landing Site Control Syst atrol thit lin Event Timer In Event Timer In Status Angle in Display Consol lant utsilizat lant utsilizat 14, **5**44 2 SÊ ž=F and Johana (s)lands. Eastern fest Range and Junippe (156R) r Stop Luel Cell Hight Director Attitude Indicator Hight dich Man The Act and Navigation Act And Navigation Act Navigation Control Syste ige Altitude syncila (Camberra, Australia) of Signal or Loss of Site Parking Orbit 1 Madar und Elapsed Time and Elapsed Time of Ignition imerical Nees unmany: Unit Initialitation Initialitation Initiani Denter Initiali Parist Initianitation Unit Initianitation Examples Initianitation Examples ertial Coupling Data Unit entification arapproter Ellerandicelor Transfer Ellerandi Standard The Scular Activity al Threttle Position Frequency Notulated Field of tites Feet per second de lit fain (fui) dely Desirable de Sain Anterne fil Cooled Games BEE BARN (TUN) SNS Huntswille a, This ydrayen peger Altitude Aurich Vehicle iloutt Nou lettison - K<u>ě</u>ste ** E ま 고로東평경병렬교로영로올림 F -2-2-22**2**23-52 of Site seollo Scientific Equipment Parkary creatal Control System nation or Digital Évent Tine cal Deta en Najor Dominiat ala Hiptic Sequence Initiation) and Service Module tion and Marming System of Centry Island tal Commend Assembly Entry and Dispisy Assembly rbit Insertion regulation Sabsystem og Equinance ar Horizon (atrosphere) Interface cal Alignment Sigh interior Assembly note Subsystem autor bita Altitude Point on, Anstralia beule Piliot Dets unit Letton pital Auto Pilot ð ទី៩ទ

ABBREVIATIONS

111

SECTION 1 - GENERAL

`.

•

MISSION DESCRIPTION

- 1. Launch and E.P.O. (Duration 2:33) $T_0 = 2:33$ GET
 - (a) Nominal launch time is Sunday, 12:48 EDT, May 18, 1969, with a launch window duration of 4 hrs. 25 min.
 - (b) Earth orbit insertion into a 100nm circular orbit at 11 min.43 sec. after lift-off
 - (c) CSM systems C/O in earth orbit
 - (d) IMU realign (P52) to the pad REFSMMAT during the first night period
 - (e) TLI occurs at 2:33:26 GET over the Pacific Ocean during the second revolution. (See Table 1-1 for burn data and Figure 1-3 for altitudes)
- 2. Translunar Coast (Duration 73:12) 2:33 75:45 GET

After TLI which places the spacecraft in a free lunar return trajectory, the following major events occur prior to LOI:

- (a) TV at 3:48 p.m. May 18; 4:03 p.m. May 19; 6:48 p.m. May 20;
 1:08 p.m. May 21 (EDT)
- (b) Transposition, docking and LM ejection including SIVB photography
- (c) SIVB separation and a CSM evasive maneuver at 4:28:48 GET
- (d) SIVB propulsive venting of propellants (slingshot)
 - (e) Two batches of P23 cislunar navigation, star/earth horizon, consisting of five sets at 05:30 GET and five sets at 25:00 GET
 - (f) The IMU will be realigned to the PTC REFSMMAT after MCC_1 .
 - (g) Four midcourse corrections which take place at TLI + 9 (SPS) TLI + 24, LOI - 22 and LOI - 5 hours with△V nominally zero (See Table 1-1) for MCC 2, 3, 4

- (h) S-Band reflectivity test with the Ascention 30-ft. cooled antenna at 27:00 GET and at an altitude of 112,000nm.
- The HGA will be checked for the sleep Comm mode at 32:00 GET

•

- (j) Passive thermal control (PTC) will be conducted at all periods when other activities do not require different attitudes
- (k) LOI will be performed at 75:45 GET which ends the TLC phase
- 3. <u>Lunar Orbit</u> (Duration 61:35) 75:45 137:20 GET

LOI Day (Starts at 68:00 GET)

- (a) TV at 1:08 p.m. and 9:33 p.m. May 21
- (b) LOI-1
- (c) Photos of targets of opportunity
- (d) LOI-2
- (e) Post LOI-2 LM entry and inspection. LM S-Band OMNI and steerable antenna tests
- (f) Post LOI-2 Pseudo landmark tracking
 (two sets of sightings) (See Table 1-4)
- (g) Rest period (8 hours)

DOI Day (Starts at 93:00 GET)

- (a) TV at 3:01 p.m. May 22; 1:23 a.m. May 23 (EDT)
- (b) Docked LM activation and checkout
- (c) Docked Apollo landing site number two sighting (one set of sightings) (See Table 1-3)
- (d) Undocking and separation (See Figure 1-2 Rendezvous Profile)
- (e) Undocked Pre-DOI LM activities
- (f) DPS DOI maneuver (See Figure 1-2 and Table 1-2)
- (g) DPS phasing maneuver

- (h) LM staging maneuver '
- (i) APS insertion maneuver
- (j) LM active rendezvous
 - CSI
 - PC
 - CDH
 - TPI
- (k) Docking
- Configure LM for APS burn to depletion and perform communications tests
- (m) Unmanned LM APS burn to depletion
- (n) Rest period (9 hours)

Landmark Tracking Day (Starts at 118:00 GET)

- (a) TV at 7:08 p.m. May 23 (EDT)
- (b) Landmark tracking for four revolutions (four landmarks per rev.) (See Table 1-4)
- (c) One revolution of strip photography
- (d) Rest period (3.5 hours)

TEI Day (Starts at 132:00 GET)

- (a) SPS TEI maneuver at 137:20:22 GET
- (b) Rest period (5.5 hours)
- (c) One revolution of landmark tracking and photography

Lunar Orbit Particulars (Average Values for a 60 x 60nm Orbit)

- (a) Revolutions start at 180° longitude
- (b) Revolution duration 1 hr. 58.5 min.
- (c) S/C night period duration 47 min.
- (d) MSFN coverage per rev. 72 min.
- (e) Orbit inclination 1.3°

- (f) S/C orbital rate $3^{\circ}/\text{min.}$ (.05[°]/sec)
- (g) Lighting change at fixed ground point 1⁰West/Rev.
- (h) Ground track change 1° West/Rev.
- (i) Horizon visibility ⁺ 20⁰ selenocentric angle on the lunar surface
- (j) One lunar degree on lunar surface is 16.38nm
- (k) Site 3 will be visible $(2.5^{\circ} \text{ sun angle})$ at Rev. 30
- (1) S/C sublunar point to horizon 320nm.
- 4. Transearth Coast and Entry (Duration 54:25) 137:20 192:04

Transearth coast begins with TEI at 137:20 GET and consists of the following major events:

- (a) TV at 6:33 a.m. May 24; 9:23 p.m. May 24; 7:38 a.m. May 26 (EDT)
- (b) During transearth coast, 18 sets of navigation sightings will be performed. These are as follows:
 151:00 GET 9 Sets Star lunar landmark
 165:00 GET 3 Sets Minimum sun elevation
 167:30 GET 3 Sets Minimum sun elevation
 171:00 GET 3 Sets Minimum sun elevation
 174:30 GET 3 Sets Minimum sun elevation
- (c) Three midcourse corrections are scheduled at TEI \pm 15, EI 15 and EI - 3 hours with ΔV nominally zero.
- (d) CM/SM separation takes place at 191:35 GET and Entry Interface occurs at 191:50 GET
- (e) Splashdown will occur in the Pacific Ocean at a longitude of about 165⁰ West at 192:04 GET. This will occur about one-half hour prior to sunrise local time on Monday, May 26, 12:52 EDT.

ACTIVITY DAY	1		2	3			4 LOI DA	Y			5 DOI	DAY				6			7 TEI	DAY		8			9		10
REST PERIODS	_																										
DATE/DAY	MAY 18 - SUNDAY	MAY 19 - MONDA	AY	MAY 20 - TUESDAY	MA	Y 21 - WEDNESDAY			MAY 2	2 - THURSDAY				MAY 2	3 - FRIDAY				MAY	24 - SATURD	YAC		M	Y 25 - SUNE	YAY	MAY 26 -	MONDAY
EDT 12:4	8 18 24	6 12	18 24	6 12 18	24 6 12:5	18:50	2		1	2:50	18	24	6	12	:50	18	2	4	6	12:5	50 18	24	6	12	18 24	6	12:52
LUNAR REVOLUTION NO.						1 2	3 4	5 6 7	8 9 10	11 12 13	14 15 16	17 18	19 20 2	1 22 2	3 24 25	26 27	28 29	30 31	32								
GEI 0	4 8 12	16 20 24 2	8 32 36 40	44 48 52 56	60 64 68 7	2 74 76 78	80 82 8	4 86 88	90 92 94	96 98 100	102 104 106	108 110	112 114 1	16 118 1	20 122 124	126 12	28 130 13	2 134 13	6 138 14	10 142 14	44 148	152 156	160 164	168 177	176 18/	184 18	8 192
LM MANEUVER DATA		001 - 0PS 99:33:59 81: 27.7 SEC 6V: 71.1 FPS ULLAGE: 2 JE	PHASING 100.46:21 8T: 42.1 5 17.5 SECV: 195. ULLAGE 5	- DP5 INSERTION SEC 102:43:18 4 FP5 81: 15.2 SI 2 HET 7.5 SEC AV: 207.0 ULLAGE: 2	L - APS C SI - RCS EC 103:33:46 FPS BT: 32:1 EC 3.5 SEC 4/V; 50:5 NO ULLA	SE 104:31:42 SFPS BT: 2,4 SEC AGE AV: 3,4 FPS NO ULLAGE						TPI RCS 105:09:00 BT: 15:6 SEC 2V: 24:6 FP NO ULLAGE	5	wCC-1 105:24:00		A4(10)	CC-2 5:39:00		APS BUR 108:39	V TO DEPLETI	ION - APS						
LM (SNOOPY)								HATCH LMP IVT TO M STATUS CHECK, I NO STOW EQUIP UM S-BAND/VHF CI IVT TO CSM		IMP AND CDR IVT ACTIVATE EPS AND ACTIVATE PGNCS IS-BAND STEERABL IERASABLE MEMO IDOCKED IMU A IACTIVATE ASCE IPGA AND CAI I ACTIVATE ASCE IDOS PRES IDOPS	TO UA S-BAND OMNI AND ECS E CHECKS RY DUMP LIGN NT BATTERY NN PRESSURE CHEC AND INITIALIZE AC RR CHECKS LIBRATION AND AU SURIZATION AND AU INFERION OF REALIGN I AND PRESS., P I UM STAGINI I INSERTION I I I I I I I I I I I I I I I I I	KS SS IGN CHECKOUT CHECKS TRACKING ACE OBSERVAT OPS IN - PS2, COAS ARALLEL ASCEN G - RCS BURN - APS EALIGN I - RCS CHANGE - RCS BURN - RCS NDEZVOUS MC ENDEZVOUS NDEZVOUS NDEZVOUS OOCK S-BAND COMW PREP LM ANI I JETTISO	ION AND PHO ICALIB IT AND DESCEP	TO GRAPHY	N												
CSM (CHARLIE BROWN)	EARTH ORBIT AND S TRANSPOSITION ICSM/AM EVASIA CISLUNAR N MCC	YSTEMS CHECKOUT N, DOCKING AND LA VE MANEUVER FROM AVIGATION OPTICAL C-1 TABLISH PTC MODE	A EXTRACTION S-IVB SIGHTING-STAR/EA CISLUNAR NAVIGATI S-BAND COMM REF	IRTH HORIZON (S SETS) ION OPTICAL SIGHTING -: LECTIVITY TEST IMCC	STAR/EARTH HORIZON (2-3	S SETS)	HOTOGRAPHY SU IMU REALIGN LOI-7 IMU REALIGN DOI-7 IMU REALIGN PS	EEP COMM TEST		INU REALIGN PS2 I INSTALL DROG I LANDING SI I UNDOG I INSPE I CSM S IRR AN I SMU	UE PROBE AND HAT ITE TRACKING CK CT UM AND PHOTO IEPARATION MANE ID VHF RANGING REALIGN PS2 I III I IIII SD IUM PHASING BURI IBACKUP LM IIMU REALIG IBACKUP I IBACKUP I IBACKUP I IBACKUP I IBACKUP I IBACKUP I IBACKUP I IBACKUP I IBACKUP I IBACKUP I IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	GRAPHY UVER C/O INSERTION BU INSERTION BU INSERTION BU IN CSI BURN JP LM CDH BUR KUP LM TPI BUI NDEZVOUS - LA DOCK PREPARE FOR I LM JETTIS	N RN RN A PHOTOGRAPI	1 IA 	U REALIGN STRIP PHOTO I IMU REALI FIRST	S2 GRAPHY SN PS2 REV LANDA REALIGN P SECOND REAL THIR THIR THIR	MARK TRACKI 52 EV LANDMAR IGN P52 D REV LANDA U REALIGN P FOURTH R	NG K TRACKING VARK TRACKI 52 V LANDMAR I IMU REAL IPHOTO LAN	NG K TRACKING GN P52 IGRAPHY MARK TRACI I STRIP PHOT I IMU REALI I TEI BUR	ESTABLISH OGRAPHY GN PS2 N		DE PTC TEST P23 CIS LUN STAR LUN MCC-S (JINAR NAVIG AR LANDMA (TEI + 15)	ATION RK SIGHTIN I P23 CIS LUP STAR EARTH (SET OF (SET OF STAR EARTH STAR EARTH STAR EARTH	GS (SET OF 9 AR NAVIGA I MORIZON 5 INTH HORIZO 3) IAR EARTH HORIZO 3) IAR EARTH H ET OF 3) ISTAR EJ SIGHTI I MC) IGHTINGS IGHTIN DRIZON SIG RTH HORIZC NGS (SET OF C-6 NTRY INTER SPLASH	SET OF 3) GS HTINGS 3) MCC-7 FACE 0 OOWN 1
CSM MANEUVER DATA	TL15-IV8 2:33:26 BT: 5 MIN 22 SEC AV: 10,058 FP5	EVASIVE MÁNEUN (CSM/LM FROM S 4:28:48 BT: 2:8 SEC 2 V: 19.7 FPS NO ULLAGE	After - SPS -JVB) MCC-1: 11:33:49 BT: 8.13 AV: 57.0 NO ULLA	SPS SEC MCC-2 0 0 FPS 26:33	MCC-3 MCC-4 53;45 70;45	LOI-1- SPS 75:45:43 81:6 MIN 2 SEC 2V: 2974,0 FPS NO ULLAGE	01-2 - SPS 01-10-45 N1: 14.4 SEC V1: 138.5 FPS JLLAGE: 2 JET 17	sec	CSM SE 96:35:1 8T: 6.9 8V: 2.5 NO UU	P-RCS 6 SEC 5 FPS LAGE		U 10 10 10 10 10 10 10 10 10 10 10 10 10	M JETTISON-RC 08:09:24 T: 5.6 SEC V: 2.0 FPS IO ULLAGE	3		ТЕ) 137: ВТ: ΔV: ULL	- 5P5 1:20:22 2:MIN 50 5E 3622.5 FP5 AG E: 2 JET 1	c 1 5EC	_			MC 152	C-5 20	MCC-6 176:50		CC-7 8:50	5
·																				L]							
GET	0 4 8 12	16 20 24	28 32 36 44	0 44 48 52 56	60 64 68	72 74 76 78	80 82 8	4 86 88	90 92 94	96 98 100	102 104 106	108 110	112 114 1	16 118 1	0 122 124	126 12	28 130 13	2 134 13	6 138 14	10 142 14	44 148	152 156	160 164	168 17	176 18	18-4 18	8 192
						11	11		8 0 10	11 12 12	14 16 14	17 10	19 20 21	22 2	24 25	26 22	28 39	30 31	32								
LUNAR REVOLUTION NO.	· · · · · · · · ·					1 2	3 4	3 6 7	o y 10	11 12 13	LUNAR OR	17 209.6 - 215.0	8				10 IV	30 31					.!.				
ALTITUDE NM x 103	20 6)	92	117 138	156 172	188 202															196	190	150	132	108	72	2	-
CSM IMU REALIGNS P-52	• ••	•		• •	•	• •	• •		•	•	•			•	• •	•••		•	•••			/			•	•	•
CSM CO2 FILTER CHANGES	•	•	•	•	• •		•		•			•			•			•			•	•		•	•		
ECS REDUNDANT COMPONENT CHES				•					•					•						•				1			
ECS REDUNDANT COMPONENT CHRS		•																									





TABLE 1-1 CSM BURN SCHEDULE

Burn/Mancuver	GETI Burn Time AV	Attitud LH/LV	e (dog) Inertial	Lighting at GET1		Ullage AV (fpå)	TVC Mode	REJSMMAT	AV Result (SC wt., Hp. H.)	Remarks
S-IVB TLI	2:33:26 5 min 22 sec 10, 058 fps	Rı P: Y:	R: P: Y:		ΔVX: ΔVY: ΔVZ:		S-IVB I. U.	PAD		
CSM/LM Evasive Maneuver from S-IVB	4;28;48 2.8 sec 19.7 fps	R: 160.1 P: 282.6 Y: 1.8	R: 180.7 P: 163.3 Y: 0.0	Daylight	ΔVX: 5.1 ΔVY: 0.0 ΔVZ: 19.0	None		PAD	WT; 94, 575	Use Bank A engine ball valves
MCC-1	11:33:49 8.1 sec 57.0 fps	R: 8.3 P: 142.6 Y: 9.2	R: 7.1 P: 3.2 Y: 10.5	Daylight	ΔVX: -42.9 ΔVY: 10.5 ΔVZ: -36.0	Nane		PTC	WT: 94, 392	Use Bank B engine ball valves
Midcourse Corrections (MCC-2 through MCC-4)	26:33 53:45 70:45			Daylight	Nominaliy Zero	Nominally Not Required	G&N Auto	PTC PTC LLS-2		TLI + 24 hours LOI - 22 hours LOI - 5 hours
LOI-1	75:45:43 6 min 2 sec 2974 fpe	R: 356.5 P: 162.8 Y: 345.6	R: 356. 3 P: 232. 0 Y: 340. 5	Daylight '(SS - 8:17)	ΔVX: -2912, 9 ΔVY: -587, 5 ΔVZ: -201, 0	None	G±N Auto	LLS-2	WT: 92,427 Hp: 59.6 H _A : 170.6	-
LOI-2	80:10:45 14.4 eec 138.5 fp#	R: 0.1 P: 182.4 Y: 357.6	R: 0. 1 P; 221. 0 Y: 357. 6	Daylight (8R + 20;45)	ΔVX: -138.5 ΔVY: 0.0 ΔVZ: 0,0	2 Jet 17 sec ΔV :	G&N Auto	LLS-2	WT: 68, 821 Hp: 59, 6 Ha: 60, 2	
CSM Separation Maneuver	98:35:16 6.9 eec 2.5 fp=	R: 0.0 P: 269.9 Y: 0.0	R: 0.0 P: 194.2 Y: 0.0	Daylight (85 - 14:44)	ΔVX: 0.0 ΔVY: 0.0 ΔVZ: 2.5	None	G4N	lls-2	WT: 36,484 Hp: 59,2 Ha: 60.1	
LM Jettison	108:09:24 5.6 sec 2.0 fps	R: 180.0 P: 89.9 Y: 0.0	R: 180.0 P: 70.3 Y: 0.0	Daylight (58 - 32:36)	ΔVX: 0.0 ΔVY: 0.0 ΔVZ: -2.0	None	G4N	L15-2	WT: 36,674 H _P : 59.3 H _A : 60.0	
TEJ	137:20:22 2 min 50 sec 3622.5 fpe	R: 179.9 P: 350.4 Y: 359.9	R: 180. 0 P: 52, 4 Y: \$59, 8	Daylight (SR + 13:22)	ΔVX: 3618.1 ΔVY: -34.8 ΔV2: 1176.4	ζ Jet 14 soc ΔV:	G&N Auto	LLS-2	WT: 36,575	
Midcourse Corrections (MCC-5 through MCC-7)	152:20 176:50 GETI 188:50			Daylight	Nominally Zero		G4N Auto	PTC PTC Entry		TE1 + 15 hours E1 - 15 hours EI 191:50 EI - 3 hours

-8

NOTE: HA & Hp are distances above LLS-2 (not mean radius)

TABLE 1-2 LM BURN SCHEDULE

.

"

	GETI Burn Time	Attitud	le (deg)	Lighting at		Ullage	TVC			_
Burn/Manuever	۵Vc	LH/LV	Inertial	GETI	ΔV (fps)	ΔV (fps)	Mode	REFSMMAT	(SC wt., HP, HA)	Remarks
DOI	99:33:59	R: 0.0	R: 358,6	Darkness	ΔVX: ~69,6	2 Jet	PGNCS	LLS-2	WT: 37,758	DPS 10% thrust 15 sec
	27.7 вес	P; 180.0	P: 286.4	(SR ~ 2 min)	Δ VY : 0,0	7.5 sec	Auto		H _A : 59.5	40% thrust to burn
	71, 1 /ps	¥: 0.0	Y: 4.8		∆VZ: - 0.3	1.5 <i>1</i> pe			H _P : 8,8	completion
										Retrograde face up
Phasing	100:46:21	R: 0.0	R: 0.7	Darkness	AVX: 169.1	Z Jet	PGNCS	LLS-Z	WT: 31,070	DPS 10% thruat 26 sec
	42.1 sec	P: 25.9	P: 261.4	(28 + 5 min)	ΔVY; 0.0	7.5 sec	Auto		HA: 195.1	92, 5% thrust to burn
	195.4 fps	Y: 0.0	Y: 4.9		∆VZ: -94.8	1.6 fp=			Hp: 9.2	completion
										Posigrade face down
Insertion	102:43:18	R; 180.0	R: 177,7	Daylight	ΔVX: -189, 2	2 Jet	PGNCS	LLS-2	WT: 8,412	LM staging 10 min
	15.2 sec	P: 155.6	P: 62, 1	(85 - 5 min)	ΔVY; 0.1	3.5 sec	Auto		HA: 45.8	before insertion burn
	207 fps	¥; 0.0	Y: 355.6		∆VZ; -83.8				Нр: 8.6	Retrograde face down
										Retrograde face up
CSI	103:33:46	R: 0.0	R: 1.4	Darkness	AVX; 50.5	None	PGNCS	LLS-2	WT: 8,241	RCS +X thrust
	32, 1 sec	P: 0.0	P: 106.1	(SR - 3 min)	AVY: 0.0		Auto		HA: 45.2	4 Jet
	50,5 fpe	¥: 0.0	¥: 365, 2		ΔVZ; 0.6				Hp: 45.0	
		_								
CDH	104:31:44	R: 0,0	R: 355, 2	Daylight	ΔVX; -0.7	None	AGS	LLS-2	WT: 8,195	RCS +Z thrust
	2.3 sec	P: 90.0	P: 16.1	(SS - 14 min)	ΔVY: 0.0		Auto		H _A : 44, 4	2 Jet
	3, 4 fps	¥: 0.0	Y; 358.6		ΔVZ: 3.2				Hp: 44,2	
TPI	105:09:00	R: 359.9	R: 4.8	Darkness	ΔVX: 22.1	None	PGNCS	LLS-2	WT: 8,192	RCS +X thrust
	15.6 sec	P: 26.0	P; 189. 5	(SR - 12 min)	AVY: 0.0		Anto		HA: 61.8	4 Jet
	24. 6 fps	Y: 0, 2	¥: 1, 1		ΔVZ: -11.1				Hp: 43.6	Posigrade face down
Rendezvous MCC-1	105:24:00	R: 0.2	R: 2.2	Darkness	TBD	None	TBD	LLS-2	WT: 8.169	Retrograde Jace up
		P: 210.2	P: 246.5							BF
		¥: 0.4	Y: 4.1							
Rendezvous MCC-2	105:39:00	R: 0.2	R: 2.2	Darkness	TBD	None	TBD	LLS-2	WT: 8,158	Betrograde face up
		P; 216, 7	P: 246.5							W
		Y: 0.4	Y: 4.1							
APS Burn to Depletion	108:39						AGS			Start burn in PGNCS
-							Auto			auto and switch to AGS
										auto
	· ·				ł					
_		I	1		I	<u> </u>		1		

	(For General Information Only)										
DAY	SITE DESIG.	LAT	LONG	SUN ELEVA (72 ⁰ L.AZ.	(108 ANGLES*)						
MAY 18	2(II P6)	0 ⁰ 44'N	23 ⁰ 39'E	11.4 ⁰	1 4.3⁰						
MAY 20	3(II P8)	0 ⁰ 22'N	ינ2 ⁰ נו	10.9 ⁰	13.7 ⁰						
MAY 23	4(III P11)	3 ⁰ 39' S	36 ⁰ 42'W	10.3 ⁰	12.9 ⁰						
MAY 24	5(II P13)	1 ⁰ 46'N	41 ⁰ 56 'W	17.0 ⁰	19.0 ⁰						
MAY 25	5(II P13)	`1 ⁰ 46 ' N	41 ⁰ 56'₩	28.0 ⁰	30.0 ⁰						

TABLE 1-3 LUNAR LANDING SITE DATA

*Sun El angles are for approximately 25 hours after LOI

TABLE 1~4 LANDMARK	TRACKING	DATA
--------------------	----------	------

SITE DESIG.	LAT	LONG	SUN EL.	GET (TCA)	
REV. 4					
IP(F1)	ו'71 ⁰ ו	93 ⁰ 50'E	71 ⁰	82 : 32	
F1	1 ⁰ 36'N	86 ⁰ 53'E	64 ⁰	82:34	
IP(B1)	1 ⁰ 30'N	40 ⁰ 06 ' E	18 ⁰	82:49	
81	2 ⁰ 31 'N	35 ⁰ 02 ' E	13 ⁰	82:51	
REV. 11					
IP(130)	ו ⁰ 53'N	28 ⁰ 44'E	13 ⁰	96:40	
130	אי 16 א	23 ⁰ 41'E	8 ⁰	96:42	
REV. 24, 25, 26	, 27**				
IP	0 ⁰ 0'N	178 ⁰ 26'E	4 ⁰	121:28	
CP	0 ⁰ 53'N	170 ⁰ 09 ' E	12 ⁰	121:30	
IP	0 ⁰ 48'N	132 ⁰ 29'E	50 ⁰	121:42	
CP2	1°0'N.	127 ⁰ 24'E	55 ⁰	121:44	
IP(F1)	ו ⁰ ו7יN	93 ⁰ 50 'E	89 ⁰	121 :54	
F1	1 ⁰ 36'N	86 ⁰ 53'E	84 ⁰	121:56	
IP (130)	ו ⁰ 53'N	28 ⁰ 44'E	26 ⁰	122:16	
130	1 ⁰ 16'N	.23 ⁰ 41'E	21 ⁰	122:18	
REV 30 IP(B1)	1 ⁰ 30'N	40 ⁰ 06 ' E	44 ⁰	134:02	
B1	2 ⁰ 31 'N	35 ⁰ 02'E	39 ⁰	134:04	
IP(150) 150	0 ⁰ 18'N 17'0 מי	3 ⁰ 23'E 1 ⁰ 26'W	7 ⁰ 2.6 ⁰	134:14 134:15	

**Sun El. and GET for REV 24 only

CSM FLIGHT PLAN NOTES

•

A. Crew

1. Crew designations are as follows:

Designation	Prime	Backup
Commander (CDR)	Stafford	Cooper
Command Module Pilot (CMP)	Young	Eisele
Lunar Module Pilot (LMP)	Cernan	Mitchell

 Couch positions for thrusting maneuvers during the mission are listed below:

Couch Position	LIFT-OFF, TLI	SPS Burns, Entry
Left	CDR	СМР
Center	СМР	CDR
Right	LMP	LMP

- 3. The CDR will perform the TLI maneuver. The CMP will perform all SPS burns,transposition and docking and all work in the tunnel prior to LM extraction. The LMP will monitor CDR and CMP activities per checklist/timeline.
- 4. The crew will normally follow a 15-hour work.9-hour rest cycle. All crewmen will sleep simultaneously and be awake during all major burns.
- The crew will eat together when possible during meal periods (normally of 1-hour duration). Additional activities will be held to a minimum during meals.
- PGA's will be worn during the following periods, but will not be "hard suited".
 - (a) Launch With helmet and gloves
 - (b) Earth Orbit Without helmet and gloves
 - (c) TLI With helmet and gloves
 - (d) Undocking and docking With helmet and gloves
- 7. Two crew status reports will be made during each

activity day. The first report will be given after the first meal of the day and will concern the sleep obtained during the previous sleep period. The second report will be given following the final meal of the day and will concern the radiation dose received during the previous 24 hours. The following information should be transmitted or logged as appropriate:

- (a) A daily report of each crewman's best estimate as to sleep quantity and quality
- (b) A daily report of the integrated radiation dose each crewman receives
- (c) An onboard record of food not eaten and exercise (no voice report required)
- (d) Used fecal bags will be marked as to crewman and GET
- (e) A daily report of all medication used by each crewman
- General flight plan updates containing changes to the scheduled next day's activities will be voiced up once a day.
- Negative reporting will be used in reporting completion of each checklist.
- 10. No CSM biomedical switching is required. Continuous biomedical data are automatically transmitted to the ground simultaneously for all crewmen.
- 11. Crewmen will sleep simultaneously. Two crewmen will normally be in the sleep stations under the couches and one in the couch. During the LOI Day sleep period, two crewmen will be in the couches because the probe and drogue will be stored in one of the sleep stations.
- 12. One crewman will wear headsets at all times during the mission.
- 13. All onboard gage readings will be read directly from the gages and will not be corrected by the appropriate calibration factors.
- 14. Periodic spacecraft systems monitoring is a continuing task and is not scheduled in the flight plan timeline.

B. <u>Maneuvers</u>

1. CSM/LM and CSM attitude maneuvers will normally be at a rate of

 0.2° /sec. or 0.5° /sec. unless other rates are required to support mission objectives or time critical events.

- Note: At 0.2° /sec. 15 minutes is required to maneuver 180° . At 0.5° /sec, 6 minutes is required to maneuver 180° .
- 2. Passive thermal control mode will be initiated after MCC₁ and maintained throughout the mission (except in lunar orbit) until at least three hours before entry except for interruptions for midcourse corrections, communications orientation, and/or performance of mission objectives (maximum interruption of three hours). PTC will not be initiated until approximately TLI + 12 hours.
- 3. In order to conserve SM RCS, the SPS engine will be used to "back up" all LM burns. The SPS gimbal motors will not be turned on during the "back-up" maneuver preparation.
- 4. The first SPS burn will be on engine valves BANK "A" and the second burn will be on BANK "B".
- 5. The CSM will perform the final docking maneuver after the LM active rendezvous.
- The crew will manually back up all critical engine starts and cut-offs.
- C. Electrical Power System and Water Management
 - Spacecraft lift-off switch positions are listed in the Apollo Operations Handbook (Volume 2) for CSM 106.
 - The spacecraft will remain fully powered up throughout the mission (CMC, IMU and SCS in the "operate" configuration and optics powered up as required).

- 3. Fuel cell H_2 and O_2 purging will be scheduled as follows: O_2 purge - each 12 hours H_2 purge - each 48 hours This schedule may change in real time depending on the purity of the O_2 and H_2 . H_2 purge line heaters are activated 20 minutes before an H_2 purge.
- Hydrogen VAC ION pumps will be inactive throughout the mission. The fuses will be pulled.
- The O₂ VAC ION PUMP MAIN A/MAIN B CB (2) (PANEL NO. 229) will be open for launch and will be closed at 85% - 90% QTY (before pressure about the VAC ION pump increases significantly).
- Potable water will be chlorinated before each sleep period starting at the first sleep period.
- No FC purges or waste water dumps will be scheduled within one hour prior to optical sightings.
- 8. Waste H_20 dumping will be managed to allow:
 - (a) Maximum QTY:85-90%
 - (b) Minimum QTY:25%
 - (c) At LOI:QTY = 75%
 - (d) At CM-SM SEP:QTY = 90%
 - (e) No dumping after MCC-4 until after LOI
 - (f) Dumps will be performed (if required) within 2 hours preceding MCC maneuvers.
 - (g) In lunar orbit if dumping is required, dumps will be performed immediately prior to sleep periods.
 - (h) The water dump will not be operated in the automatic mode at anytime during the mission.

- The cryogenic heaters will be in AUTO during the mission and the fans will be operated manually. The fans will be cycled for one minute before and after each sleep cycle.
- 10. The batteries will be charged after TLI, LOI₂ and TEI. The tentative charging schedule is as follows: Battery A - GET 2:45 (interrupted for evasive maneuver) Battery B - GET 22:00 Battery A - GET 87:30 Battery B - GET 118:00 Battery A - GET 146:00 Battery B - GET 164:30
 - 11. Inverter No. 1 and 2 will be used during the mission even though the C & W temperature light for inverter number one is inoperative. Inverter No. 3 will be used as the backup inverter.
- D. Environmental Control System and Cabin Pressurization
 - One CO₂ odor absorber filter (LiOH canister) is changed every 12 hours or if CO₂ partial pressure is greater than 7.6mm Hg. There are 20 filters (2 in the canisters onboard and 18 stowed).
 - An ECS redundant component check is performed at 24-hour intervals (in order to prevent secondary evaporator dry out) and prior to TLI, LOI (4 to 10 hours before), and entry (2 to 10 hours before).
 - 3. The ECS redundant component checks will include secondary evaporator operation and the secondary evaporator water control valves will be turned "OFF" at deactivation.
 - 4. The evaporator operation will be as follows:
 - (a) Launch -primary loop operation
 - (b) Earth Orbit primary loop operation and secondary loop test plus redundant operation test
 - (c) Post TLI deactivate both evaporators
 - (d) LOI Minus 2 Hours activate primary evaporator
 - (e) Post TEI deactive primary evaporator
 - (f) Entry Interface Minus 1.5 hours activate primary evaporator
 - (g) Secondary evaporator may be activated (EI 1 hour) at crew option for cold soak.

- 5. At lift-off the cabin will contain a $60\% 0_2/40\% N_2$ gas mixture. Cabin 0_2 purge will be initiated after launch and will be terminated after transposition and docking and prior to LM pressurization.
- 6. After the LM is pressurized (before ejection from the SIVB), it will be isolated by placing the LM/CM pressurization value in the OFF position (Panel 12). Eight hours of additional CM 0₂ purge will be performed. A low LM leakage rate may necessitate a delta purge (to be determined in real time by MCC-H).
- 7. After the initial crew entry into the LM, the CM tunnel hatch will be installed during the docked lunar orbit sleep period and the probe and drogue will be stored in one of the sleep stations.
- There is no CSM barbecue PTC mode required in lunar orbit, but a special attitude (see Communications Notes) will be maintained during the sleep period.

E. Guidance and Navigation

- Fuel cell purges or waste water dumps will not be scheduled within one hour prior to optical sightings.
- 2. During lunar orbit, the CSM and LM will utilize the same landing site REFSMMAT such that the gimbal angles would be 0,0,0 at GET 100:43 with the LM sitting face forward on landing site number two and the CSM over the landing site pitched up 90° from local hori-zontal "heads up".
- 3. In order to avoid gimbal lock, the IMU will be pulse-torqued to a PTC REFSMMAT prior to setting up the PTC mode. Prior to a ΔV maneuver or midcourse navigation sightings, if yaw gimbal angle exceeds 60° , the IMU will be pulse-torqued back to the pad or landing site REFSMMAT and an IMU fine align (P52) will be performed. Pulse rate per axis is one-half degree per second. The accuracy for pulsetorquing the platform is 0.002 times the total angle.
- 4. During cislunar coasting flight, two IMU P-52 realignment and state vector updates are planned each day. After actual IMU

drift rates are established the P-52 realignments may be reduced to one a day.

- 5. The CMC will use the COLOSSUS 2 flight program.
- The CSM tracking light will be on continuously from undocking to docking.
- The "P23-NO COMM" navigation sightings are called out for planning purposes. These sightings will not be made unless communications with MSFN are lost.
- 8. During LM P-52 IMU realignments, the LM tracking light will be off and CM optical tracking of the LM will not be possible during these periods of activity.

F. Procedures

- Crew procedures called out in the flight plan may be found in the following documents:
 - (a) Apollo Operations Handbook CSM 106 (AOH), Volume 2
 - (b) Crew Checklist
 - (c) Rendezvous Procedure document
 - (d) Abort Summary document
 - (e) Reentry Procedures document
 - (f) Photography and TV Operations Plan
- Specific procedures for accomplishing a particular DTO test are located in Section IV of this document. All DTO's and the page number location of each are listed in the applicable portion of the timeline, Section III.
- G. CSM Photography
 - There are no DTO requirements for photography or TV but these will be scheduled on a non-interference basis with other mission activities.
 - 2. Cameras and film are provided to photograph the following activities:
 - (a) Transposition/Docking
 - (b) LM Ejection

- (d) SLA/LM/SIVB
- (e) Earth Photography
- (f) Lunar Surface Targets
- (g) IVT (CDR)
- (h) LM Undocking and Inspection
- (i) Rendezvous (to within 300 ft. of CSM)

۰.

- (k) IVA Photography CM Activities Folding, Unfolding Couch Stowing equipment on Aft Bulkhead Donning/Doffing Space Suits
- H. The schedule for TV transmissions to earth is as follows:
 - T&D 3:00 to 3:15
 - TLC-1 27:15 to 27:30
 - TLC-2 54:00 to 54;15
 - PRE LOI-1 72:20 to 72:35
 - POST LOI-2 80:45 to 81:55
 - UNDOCKING 98:13 to 98:23
 - APS BURN TO DEPLETION 108:35 to 108:50
 - AFTER 3RD LANDMARK TRACKING 126:20 127:00
 - POST TEI 137:45 to 138:00
 - TEC 152:35 to 152:45
 - TEC 186:50 to 187:05

I. SM RCS Propellant Usage

Table 1-5 shows RCS propellant usage in pounds for the SM and LM at various S/C weights and maneuver rates.

•

Table 1-6 gives SM RCS propellant usage for +x translation maneuvers at various S/C weights and for 2-jet, 20 second and 4 jet, 15 second ullage maneuvers.

Table 1-7 gives SM RCS propellant usage rates for steady state attitude holds at various S/C weights and deadbands.

J. <u>Block Data Updates</u>

Maneuver data for return to earth contingencies will be passed up to the crew as follows:

Type Data	GET	Type Data	GET
TLI + 90 MIN	1:30	TEI 10	84:40
TLI + 4 HR	1:30	TEI 22	107:00
TLI + 11	5:30	TEI 23	118:30
TLI + 25	12:00	TEI 24	120:40
TLI + 35	12:00	TEI 25	122:40
TLI + 44	12:00	TEI 26	124:30
TLI + 53	12:00	TEI 27	126:30
FLYBY	33:00	TEI 29	128:00
PC + 2	69 :00	TEI 30	132:30
TEI 1	71 :00	TEI 31 (PRELIM)	134:30
TEI 4	71:00	NOM TEI 31 (TGT LO	AD)136:00
TEI 5	79:00	TEI 32	136:00

TABLE 1-5 RCS PROPELLANT USAGE - LBS/MANEUVER

CSM (GNCS)									
1-AX I S	5 (180 ⁰)	3	B-AXIS (180 ⁰)	S/C WT					
0.2 ⁰ /SEC	0.5 ⁰ /SEC	0.2 ⁰ /SEC	0.5°/SEC	IN LBS					
2.2 lbs	5.6 lbs	3.2 lbs	7.7 lbs	94,000					
1.7 lbs	4.5 1bs	2.5 lbs	6.0 lbs	70,000					
1.0 lbs	2.5 1bs	1.5 1bs	3.4 lbs	47,600					
0.3 1bs	0.9 1bs	0.75 lbs	1.3 lbs	38,000					
0.3 1bs	0.75 1bs	0.7 1bs	1.2 lbs	28,600					
ļ		LM (AG	GS)						
0.5 ⁰ /SEC	2 ⁰ /SEC	0.5 ⁰ /SEC	2 ⁰ /SEC						
0.4 1bs	1.3 lbs	0.8 lbs	2.6 lbs	31,000					
0.2 1bs	0.75 1bs	0.4 1bs	1.5 lbs	8,400					
0.2 1bs	0.7 1bs	0.4 1bs	1.4 lbs	8,000					

SPACECRAFT MANEUVERS

TABLE 1-6 CSM G&N RCS TRANSLATION

20 SEC, 2 JET ULLAGE	14.0 1bs	N/A
15 SEC, 4 JET ULLAGE	19.4 lbs	N/A
1 FPS +X TRANSLATION	10.7 lbs	94 ,000
1 FPS +X TRANSLATION	8.0 lbs	70,000
1 FPS +X TRANSLATION	4.3 1bs	38,000
1 FPS +X TRANSLATION	3.3 1bs	28,600

0.5 ⁰ DEADBAND		5.0° DEADBAND		10.0 ⁰ DEADBAND		S/C WT
3-AXIS	2-AXIS P&Y	3-AXIS	2-AXIS P&Y	3-AXIS	2-AXIS P&Y	IN LBS
(lbs/hr)	(lbs/hr)	(lbs/hr)	(lbs/hr)	(lbs/hr)	(lbs/hr)	
0.066	0.011	0.0066	0.001	0.0033	0.0005	98,000
0.216	0.152	0.022	0.015	0.011	0.007	94 ,000
1.015	0.195	0.10	0.020	0,05	0.01	70,000
2.04	1.01	2.20	0.101	0.10	0.05	64,000
1.95	0.55	0.20	0.055	0.10	0.028	45,600
3.0	1.3	0.30	0.13	0.15	0.065	37,600

TABLE 1-7 G&N RCS ATTITUDE HOLD PROPELLANT USAGE RATES -STEADY STATE CONDITIONS (LBS/HR)

۰.

NOTE: 3-Axis is for 2 adjacent quads

2-Axis is for 2 opposite quads

LUNAR MODULE FLIGHT PLAN NOTES

A. LM Crew

- The LM inspection and housekeeping activities will be performed by the LMP in flight coveralls.
- 2. The LMP will initiate the final LM activation and checkout in coveralls. The CDR will enter the LM in his PGA (without donning helmet and gloves). The LMP will return to the CM and don his PGA (without helmet and gloves). The LMP and CDR will don helmets and gloves and perform a PGA/ARS pressure integrity check just prior to the LM cabin regulator check.
- It should not be necessary to change the primary LM LiOH cannister during the LM manned operations.
- 4. One PLSS and two OPS will be carried in the LM. The PLSS will not be checked out or used during the nominal mission. The OPS's will be checked out during the housekeeping activities on LOI day.
- The CM transfer umbilical will not be used during LM activation and checkout.
- The LM crew will be suited (without helmet and gloves) during most of the undocked portion of the mission. For undocking and staging the LM crew will be fully suited.
- 7. The LM switch settings at the initial entry will be as specified in the LM AOH, Volume 2.

B. LM Guidance and Navigation

- 1. The LGC will use the LUMINARY-69 flight program.
- 2. The LM AGS will use Flight Program 5 (Mission G will use Flight Program "X"). Flight Program 5 will not have the RR filter which increases the range for RR data update to AGS. The AGS RR update range will be limited to 100nm.

3. One LGC erasable memory dump and MCC-H verification will be accomplished prior to DOI. If a significant number of errors are found, DOI will be delayed to allow for memory correction and re-verification.

4

- 4. All maneuvers during the undocked manned LM operations will be under PGNCS control except for the LM staging maneuver and the LM CDH maneuver (if required). These two maneuvers will be under AGS control.
- 5. The capability for MCC-H to update the LGC via uplink will normally be blocked by the LM UP-DATA LINK switch (panel 32).
- 6. A LM COAS star sighting will be used during the DOI maneuver to check IMU drift rates. The star should be within 2⁰ of the initial COAS position prior to the maneuver. The AOT will not be used for this purpose. The lunar horizon will not be visible during the DOI maneuver.
- 7. A LM COAS accuracy check will be performed after the IMU alignment prior to staging.
- 8. The Apollo 10 Mission timeline will not include the time required for all PADS that are required on the Apollo 11 mission for LUNAR surface aborts or insertion maneuvers.
- 9. The LM IMU will be manually aligned to the CSM IMU during the DOI day LM activation and checkowt. P-52/AOT alignments will be performed as soon as possible prior to:
 - . DOI
 - . Phasing
 - . Insertion

There will be no "back-to-back" PGNCS/AOT alignments performed during the mission which are not interrupted by a DPS, APS or RCS thrusting maneuver.

10. AGS alignments to the IMU will not be performed when IMU gimbal angles are at 0° or multiples of 45° .

- In order to UPLINK data, TLM should be in HBR in order to facilitate MCC-H verification of LM receipt of the data via LM-TLM.
- 12. The time from rendezvous TPI to the rendezvous MCC-1 is 15 minutes and the time from rendezvous MCC-1 to rendezvous MCC-2 is 15 minutes.
- 13. In order to perform AGS initialization, the LM TLM must be in HBR in order to obtain state vector data from the LM-TLM downlink. AGS initialization is performed prior to each engine burn.

C. LM RCS Operation and Interface Constraints

- LM RCS "+x" two jet ullage (System B) will be used for unstaged ullage maneuvers in order to prevent asymmetrical RCS thrust caused by impingement on the descent stage.
- During CSM/LM docked checkout operations, the SM B3(-x) and C4 (-x) thrusters will be deactivated before the LM steerable and/ or RR antennas have been unstowed in order to prevent SM-RCS impingement on these antennas.
- 3. The RCS interconnect will be used during the APS insertion maneuver and several of the rendezvous maneuvers in order to conserve LM RCS propellant. The interconnect can only be used for +x translations.
- 4. The maximum +x continuous RCS firing time is 55 seconds on LM-4 (85 seconds on LM-6). For multiple pulse firings approximately one minute of "off" time for cooling offsets approximately one second of previous "on" time. (See the Spacecraft Operational Data Book for specifics).

D. LM APS Burn to Depletion

 Prior to LM jettison the CSM will be in narrow deadband attitude control and the LM will be in wide deadband control (CSM control ling CSM/LM attitudes.)

- LM jettison will occur at 90 degrees east longitude approximately 30 minutes prior to the APS burn.
- 3. The LM S-Band steerable antenna will be set at a fixed position during the APS burn and DATA will be in the HBR position.
- 4. The APS burn to depletion will place the ascent stage in orbit around the sun.
- 5. The PGNCS (under MCC-H RTC) will control the start of the ullage maneuver and RTC will be used to switch to AGS control for the remainder of the ullage maneuver and the APS start and burn.
- 6. Both RCS interconnects will be closed during the unmanned APS burn to depletion.
- 7. The probe and drogue will be stored in the LM during the APS burn to depletion.
- 8. The APS will be approximately 50% propellant loaded at the start of the burn in order to ensure adequate backup RCS propellant to stabilize the LM during and after the burn.
- 9. MSFN will attempt to track the LM and obtain TLM data after the APS burn to depletion.

E. Pasive Thermal Control Maneuvers

- 1. There is no requirement to perform any LM passive thermal control maneuvers during lunar orbit.
- There will be no telemetry or crew monitoring of LM temperatures (or any other LM data) between LM pre-launch checkout and the post LOI-2 LM entry and inspection.

F. <u>Rendezvous</u> Radar

- The turn-on and turn-off times for the rendezvous radar will be scheduled in such a manner as to prevent overheating of the rendezvous radar antenna.
- Accurate RR range and range rate telemetry data will not be obtainable on the lunar farside because a HBR TLM capability is not available. This situation prevents MSFN from analyzing the

operation of the RR system on the lunar farside via DSE data playback. LM RR LGC state vector updates will be checked against MSFN computed state vectors after each AOS.

- Rendezvous radar lock will be broken just prior to TPI in order to make a +x axis TPI burn. (This is different from the Apollo 11 Mission).
- The RR shaft and trunion angles will be at zero during each AGS RR update.

G. <u>Rendezvous</u>

 The LM tracking light will be on continuously between separation and docking except during PGNCS/AOT P-52 realignments.

H. LM Pressurization

 The LM cabin will contain N₂ and some ambient air at launch and will bleed down to a pressure of zero psi during the launch insertion maneuver. The LM will be pressurized after transposition and docking and will then be isolated before ejection and allowed to bleed down.

I. LM Procedures

Crew procedures called out in the flight plan may be found in the following documents:

- (a) Apollo Operations Handbook LM-4 (AOH) Volume 2
- (b) Crew Checklist
- (c) LM Rendezvous Procedures Document
- (d) Abort Summary Document
- (e) Photography and TV Operations Plan
- J. Photography

There are no photographic DTO requirements, but cameras and film will be carried aboard the LM to photograph the following:

- (a) Lunar surface strip over landing site
- (b) Braking/formation flying
- (c) Photos of CSM from LM after rendezvous

K. LM Activation and Checkout Notes

Activities will be performed during the periods as shown below:

1. Post LOI-2

LMP IVT to LM and verify CSM to LM roll calibration angle LM entry status check Transfer required crew equipment and housekeeping Transfer to LM power and comm activation S-Band/VHF B comm test OMNI and Steerable Antenna voice/TM Tests LM and MSFN relay Tests Comm deactivation and transfer to CSM power LMP IVT to CSM and close LM hatch

2. Docked Pre-DOI

IVT to LM and verify CSM/LM roll calibration angle Transfer to LM power and EPS Activation, S-Band TLM-LBR on OMNI Activate Mission Timer Backup S-Band comm activation and comm check Primary glycol loop activation Caution and Warning system checkout PGNCS turn on and self test Circuit breaker activation and talkback verification ECS activation and checkout Suit Fan/H₂O Separator check Glycol pump checks (1, 2, and secondary) S-Band Steerable Antenna checks VHF activation and checkout LGC/CMC Clock Sync and TEPHEM update E Memory dump LM docked manual IMU coarse align Install drogue and close LM hatch Ascent batteries activation and checkout ARS/PGA pressure integrity check Regulator checks

AGS activation and self test Rate Gyro check and docked manual fine align IMU LM IMU Drift check AGS initialization ORDEAL initialization DAP data load, gimbal drive and throttle tests RCS pressurization RCS checkout (cold and hot fire) Rendezvous Radar activation and self test AGS accelerometer and gyro calibration Update and align AGS to PGNCS DPS pressurization and checkout Landing gear deploy

3. Undocked Pre-DOI

LM inspection by CSM and formation flying Rendezvous Radar/VHF ranging check IMU AOT realign (P52) System checks Landing radar test Align and update AGS

4. Undocked Prior to APS Insertion Burn IMU Realign/COAS calibration Parallel ascent and descent batteries LM staging Pressurize and check the APS

CSM & LM COMMUNICATIONS AND INSTRUMENTATION NOTES

A. CSM/LM Notes - All Mission Phases

- Table 1-8 is a matrix that shows how the CSM and LM communications will be utilized throughout the mission. The matrix consolidates all communications requirements specified in the Detailed Test Objectives and the Operational Procedures (AOH Volume 2). This matrix shows the following:
 - (a) The mission phase or event where each uplink, downlink, antenna, transceiver, power amplifier and data recorder is exercised
 - (b) All communications modes used for the lunar earth side (MSFN coverage) and the lunar farside (no MSFN coverage)
 - (c) Which S-Band antenna (omni, CSM high gain, LM steerable) is used for each uplink or downlink signal combination.
 - (d) Which uplink signal combinations are exercised for CSM and which uplink signal combinations are exercised for the LM
- 2. The MSFN 85-ft. antennas will normally be used for all lunar distance communication. The Goldstone 210-ft. antenna may not be available for the Apollo 10 Mission. The "uncooled" 30-ft. MSFN antennas may be used for CSM lunar distance simulation communications tests at approximately 70Knm. The "cooled" 30-ft. MSFN antennas may be used at approximately 110Knm for CSM lunar distance simulation communications tests.
- LM to CSM VHF TLM data cannot be transmitted and received during VHF ranging periods.
- 4. During communications, the spacecraft will be referred to by name (Apollo 10) and MCC-H will be referred to as "Houston". Code names assigned to the CSM and LM during undocked operations are: CSM - Charlie Brown LM - Snoopy
- Voice silence (120 seconds) will be required during the CSM PRN ranging code acquisition sequence when the downlink signal combination is in mode 8 (TLM-LBR and Back-up Voice).
- 6. The preferred S-Band communications mode for CSM and LM is:
 - (a) Uplink Mode 6 (Voice, PRN and Updata)
 - (b) Downlink Mode 2 (Voice, PRN, TLM-HBR)
- 7. It is desirable to have the spacecraft TLM in HBR for all MSFN CSM or LM computer updates (via the uplink) in order to facilitate MCC-H verification of the updata receipt.

B. <u>CSM/LM Notes</u> - Lunar Orbit Phase

- All CSM and LM HBR data at lunar distance will normally require the use of the high gain or steerable antennas with 85-ft. MSFN antennas. HBR can also be obtained by MSFN 30-ft. "cooled" antennas.
- After each AOS in lunar orbit, it is desirable for MSFN to use PRN as much as possible.
- During lunar orbit, the CSM and LM S-Band systems will not be shut down on the lunar farside.
- 4. The LM steerable antenna and the CSM HGA will not be in view of MSFN during any CSM tracking of a landing site while the vehicles are docked. TLM-LBR and OMNI antennas will be used during this activity.
- 5. VHF Ranging/Data Switching will be in accordance with the rendezvous procedure. Voice silence between vehicles should be maintained for approximately 10 seconds while acquiring VHF ranging.
- VHF A Simplex is normally used for all VHF Voice Communications except during VHF ranging when VHF Duplex is used.
- MCC-H will not normally switch S-Band antennas. This activity will be a crew action except during crew sleep period.

- C. CSM Notes Launch and Earth Parking Orbit
 - 1. OMNI B and VHF LEFT will be selected for launch. OMNI D will be selected by the crew during boost phase if the launch azimuth is less than 96° . OMNI C will be selected if the launch azimuth is greater than 96° . OMNI D will probably be the best antenna for use during earth orbit.

- 2. VHF Duplex B will be used for launch and VHF Simplex A will be used for earth orbit operations (switch over at CYI LOS). VHF Simplex "A" will be used during entry in order to be compatible with the recovery forces.
- 3. CSM FM Modes are normally used for DSE playbacks and TV. HGA will be required for FM mode operation after TLI.
- CSM S-Band backup communication modes checks will not be made. The LM communication system will be used as the backup communication system, if necessary.
- 5. All CSM communications checkouts and tests may be performed during translunar coast (post TD&E to pre-LOI). The lunar sleep comm mode will be checked in lunar orbit prior to the first sleep period
- 6. The CM communications system switches will be configured to permit MCC-H real time control of routine communications switching and maximum crew control of the communications without the crew having to use CMD RESET.
- 7. The CMC updata link input will normally be blocked by the crew UP TLM ACCEPT/BLOCK switch. This will not prevent MCC-H from using real time command to control the communications system.
- 8. The CSM S-Band system will normally be configured as follows unless preflight tests show that the secondary systems would have higher gain:
 - (a) Primary transponder ON
 - (b) Primary Power Amplifier HI

9. The translunar and transearth sleep communications mode will be as follows:

The CSM x-axis will be placed normal to the ecliptic plane. The CSM will be placed in GNCS $\frac{1}{20}$ pitch and yaw attitude hold. All four SM RCS guads will be used with the roll channel disabled. The CSM will be rolled at a rate of approximately one revolution per hour. During the near earth sleep periods (range less than approximately 120Knm) omni antennas B and D may be used. During the other sleep periods (beyond approximately 120Knm) the high gain antenna may be used in the auto REACO mode (panel 2). The auto REACO configuration will provide almost 210 degrees of HGA coverage per CSM/LM revolution or 35 minutes of MSFN coverage per hour (for a CSM spin rate of one revolution per hour). The auto REACQ configuration will also allow MCC-H to use real time control to select TLM HBR or LBR and to dump the DSE during each spacecraft revolution. The auto REACO sleep mode will be tested before the second translunar coast sleep period.

10. The communications mode for the lunar orbit sleep period will be as follows:

The CSM will be referenced to the landing site number two REFSMMAT and will be in an attitude which will place two RCS quads toward the sun and two RCS quads toward the lunar surface.

The CSM will be placed in an attitude which will allow the HGA to be used.

The CSM will be placed in a GNCS 3-axis $\frac{1}{2}$ 10⁰ inertial hold mode using two adjacent quads.

The HGA will be in the auto REACQ mode (panel 2). The S-Band squelch will be enabled. The S-Band system will be controlled by RTC at HCC-H and will be in TLM-HBR on the lunar earthside and LBR/DSE recording on the lunar farside. This procedure will provide approximately 75 minutes of HBR for each lunar orbit and will permit MCC-H real time control of the DSE and playback of LBR data recorded on the lunar farside. This communications mode will be tested for suitability just prior to the lunar orbit sleep period.

- 11. During translunar and transearth coast crew-awake PTC periods, the crew will use manual antenna switching to maintain continuous communications with MSFN via OMNI and/or HGA. The S-Band squelch will be disabled to allow the crew to use the upvoice discriminator noise as a cue to indicate when to switch to another antenna.
- 12. In lunar orbit the crew will acquire MSFN using the CSM high gain antenna for each AOS unless specified differently in the flight plan timeline.
- 13. A small portable voice recorder will be carried in the CM to be used at the discretion of the crew.
- 14. CSM-TV may be scheduled in real time if the Goldstone 85-ft. antenna is in view of the spacecraft. CSM-TV via the Madrid 85-ft. antenna should be scheduled approximately 15 hours in advance in order to reserve communications satellite time.

D. LM Notes

- LM voice recorder has a maximum utilization of 10 hours. This recorder will be used during LM operations to record all LM voice data during undocked operations (8.5 hours). The recorder will be operated in the continuous mode (not VOX).
- As many LM communications special tests as possible will be performed between docking and LM jettison.
- During "undocked" operation several LM communications test objectives will be performed as part of the normal mission communications procedures.
- 4. The LM S-Band System will normally be configured as follows unless preflight tests show that the secondary systems would have higher gains:
 - (a) Primary transponder ON
 - (b) Primary Power Amplifier ON
- 5. In lunar orbit MSFN will acquire the LM steerable antenna for each AOS unless specified differently in the flight plan timeline.
- LM TLM will be switched to LBR at each LOS and to HBR at AOS by the LMP unless specified otherwise in the flight plan timeline.
- 7. LM Bio-Med switching will be checked out for the CDR and the LMP during LM checkout and will be switched from one crew member to the other approximately every two hours after LM undocking.

8. There will be no TV transmissions from the LM.

E. CSM DSE Notes

The CSM DSE is used as follows:

- 1. The DSE will normally be operated via ground command. In special cases the crew may be asked to operate the DSE.
- DSE will be operated HBR during the launch phase. These data will be dumped if real time launch data are lost.
- 3. During the earth orbit period when the CSM is not over a MSFN station, CSM TLM-LBR data will be recorded on the DSE and will be dumped during the pass over the US and over CRO (if possible) just prior to TLI.
- 4. The DSE will be used for CSM HBR and voice recording during all CSM engine burns and during the accomplishment of certain specified DTO's.
- DSE recordings will be made in CSM LBR mode whenever possible in order to minimize the DSE dump time.
- All critical data will be hand recorded by the crew when not in voice contact with MSFN. DSE voice recording will be used as backup for recording critical data.
- 7. During translunar and transearth PTC simultaneous sleep periods using the HGA auto REACQ communications mode, the DSE will be used to record LBR data when the HGA is not in the MSFN field of view.
- 8. During lunar orbit LM operations, the DSE will be used to record LM-TLM-LBR data during all LM phases/events that occur on the lunar farside (unless VHF ranging is required).

- 9. During lunar orbit, time (in the attitude hold control mode) will be provided in the flight timeline to allow for MCC-H DSE dump, rewind and start of DSE after each MSFN AOS (acquisition of signal), except where a DSE dump would interfere with DSE recording of critical CSM backup TLM data or the HGA is not visible to MSFN.
- LM data will normally be dumped first after each AOS during LM active operations.
- Twenty-five minutes will normally be allowed for the complete data dump cycle for CSM and LM LBR data recorded on the lunar farside. HBR data will require additional dump time depending on the length of the recording.
- 12. DSE will be used to record all entry data in HBR during the blackout region.
- 13. In lunar orbit at LOS, the crew will initiate UP TLM CMD RESET (momentarily) then NORMAL (panel 3) if the DSE motion is not noted. This situation will occur if MSFN does not get the DSE started before LOS.

F. Normal Lunar CSM Comm Configuration

S-BD XPNDR - PRIM	VHF AM B - OFF						
S-BD PWR AMPL - PRIM	WHF AM B RCV ONLY - OFF						
S-BD PWR AMPL HI-HI	VHF RNG - OFF						
S-BD MODE VOICE - VOICE	VHF ANT - SM RIGHT						
S-BD MODE PCM - PCM	TAPE RCDR PCM - PCM/ANLG						
S-BD RNG - RNG	TAPE RCDR RCD - RCD						
S-BD AUX TAPE - DN VOICE BU	TAPE RCDR FWD - FWD						
S-BD AUX TV - OFF (CTR)	PMP PWR - NORM						
UP TLM DATA - DATA	SCE - POWER - NORM PCM BIT RATE - LOW						
UP TLM CMD - NORM							
VHF AM A -OFF							

S-BD SQUELCH - OFF HI GAIN ANT PWR - PWR HI GAIN ANT TRACK - MAN HI GAIN ANT BEAM - WIDE HI GAIN ANT SERVO - PRIM UP TLM SWITCHES (MDC 2 - BLOCK & PNL 122 - ACCEPT)

۰.

SECTION 2 - MANEUVER UPDATE FORMS

MANEUVER UPDATE FORMS SUMMARY

•

This section contains samples of the update pads which are contained in the In Flight Data File on board the spacecraft. The CSM forms are as follows:

- 1. TLI Maneuver
- 2. P37 Block Data
- 3. P27 Update
- P30 Maneuver (External △V)
- 5. Entry
- 6. Earth Orbit Entry Update
- 7. Earth Orbit Block Data
- 8. CSM Sep
- 9. CSM Rescue
- 10. CSM Backup Insertion
- 11. P76 (DOI, Phasing, Insertion)
- 12. CSM Rendezvous Rescue (CSI, CDH, TPI)

The LM forms are:

- 1. P27 Update
- 2. AGS State Vector Update
- 3. P30 LM Maneuver
- 4. P32 CSI Update
- 5. P33 CDH Update
- 6. P34 TPI Update
- 7. P76 (DOI, Phasing, Insertion)

In addition, definitions of abbreviations used on the forms are presented on facing pages.

CSM MANEUVER

÷

•

,

.

UPDATE FORMS

X X X X X X P X X X X X Y Y X X X X X Y Y X X X X X Y Y X X X X X Y Y X X X X X X Y X X X X X X X Y X X X X X X Y Y X X X X X Y Y Y TLI 10 MIN ABORT P	Х				X			-		ТВбр	
x x x x x x y x x x x x y y x x x x x y y x x x x x y y x x x x x y y x x x x x x y x x x x x x y x x x x x y y TLI 10 MIN ABORT P	Х	X	Х		х	X	X			R	
x x	Х	X	Х		Х	Х	X		Τ	P	
x x x x x x x + - - - - - - x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x x	Х	X	Х		X	X	X			Y	
+ + - - - - - - VI X X X X X X R P X X X X X X Y	Х	X	Х		Х	Х	Х			BT	
+ + - VI X X X X X R X X X X X V X X X X X V TLI 10 MIN ABORT P										∆VC'	
X X X X X X X P X X X X X X Y TLI 10 MIN ABORT P =	+				+					VI	
X X X X X Y TLI 10 MIN ABORT P	Х	Х	Х		Х	Х	X			R	
<u>x x x x </u> TLI 10 MIN ABORT P =	Х	Х	Х	 	Х	Х	X			P	
TLI 10 MIN ABORT P =	Х	X	Х		X	X	X			Y	

TLI PAD

TB 6p	X:XX:XX(HRS:MIN:SEC)	PREDICTED TIME OF BEGINNING OF S-IVB RESTART PREPARATION FOR TLI (TB6 ≠ TLI IGN -9 MIN)
R P Y	XXX (DEG) XXX (DEG) XXX (DEG)	PREDICTED SPACECRAFT INU GIMBAL ANGLES AT TLI IGNITION
вт	XX:XX (MIN:SEC)	DURATION OF TLI BURN
∆VC '	XXXXX.X (fps)	NOMINAL TLI AV SET INTO EMS AV COUNTER
۷I	+XXXXX (fps)	NOMINAL INERTIAL VELOCITY DISPLAYED ON DSKY AT TLI CUTOFF
R SEP P SEP Y SEP	XXX (DEG) XXX (DEG) XXX (DEG)	PREDICTED SPACECRAFT IMU GIMBAL ANGLES AT COMPLETION OF S-IVB MNVR TO CSM/S-IVB SEP ATTITUDE
P	XXX (DEG)	PITCH ANGLE FOR TLI + 10 MIN ABORT

•

.

			GET1	
x	X			
x	X		LONG	
			GET _{400K}	
			GETI	
X	X			
X	X		LONG	
		•	GET _{400K}	
•			GETI	
X	X		∆VT	
×	X		LONG	
			GET _{400K}	
		‡	GETI	
.X	X		∆VT	
×	X		LONG	
			GET _{400K}	-
			GETI	
X	X			
×	X			
			GET 400K	
			GETI	
×	X	┫╎╽		
×	_ × _	┩┤┤		
			400K	
	·	╷╷╷	GET1	
×		┪┤╴╎		
× 📕 🕴		┩┈╎╴╎		

4

:

:

GETI	* x x : xx	TIME OF IGNITION (HR. MIN.)
∆ vt	XXXX (FPS)	DELTA V REQUIRED AT GETI.
LONG	⁺ XXX (DEG)	LONGITUDE OF LAND- ING SITE
^{GE T} 400K	XXX : XX	TIME OF ENTRY INTERFACE

.

.



2-7

P27 UPDATE

PURP	XXX	TYPE OF DATA TO BE RECEIVED (SUCH AS: NAV - LIFT-OFF TIME)
۷	XX	TYPE OF COMMAND LOAD (70 - 71 - 72 - 73)
GET	XXX:XX:XX(HR:MIN:SEC)	TIME DATA RECORDED
01	XX (OCTAL)	INDEX NO. OF COMMAND WORDS IN LOAD
02-24	XXXXX	NO. OF CORRECTION COMMAND WORDS
NAV Check		TO CONFIRM POINT ABOVE GROUND TRACK FOR A GIVEN TIME
Т	XX:XX:XX(HRS:MIN:SEC)	TIME
LAT	XX:XX (DEG)	LATITUDE
LONG	XXX:XX (DEG)	LONGITUDE
ALT	XXX.X (nm)	ALTITUDE

P30`M		UVE	R				
							PURPOSE
SET STARS				7			PROP/GUID
	+						WT N47
^R ALIGN		0	0				PTRIM N48
P ALIGN		0	0				YTRIM
Y ALIGN	+	0	0				HRS GETI
	+	0	0	0			MIN N33
	+	0					SEC
ULLAGE							∆V _X №1
	. L.						$^{\Delta V}Y$
							^V <u>Z</u>
	_ <u>×</u>	X	X				R
	X	Х	X				Р
	×	Х	X				Y
	+						H _A N44
							Нр
	+					 	AVT
HORIZON/WINDOW_	<u>,</u> X	X	X		•		BT
	_ ×		-			ļ	۵VC
	_ ×	X	Х	X			SXTS
	- +			ļ ,	•	0	SFT
	+			-	0	0	TRN
	X	X	Х	<u> </u>	ļ		BSS
	X	X				•	SPA
	⊢×	X	X		ļ	 	SXP
OTHER	-	0		<u> </u>	•		LAT N61
	-		L	<u> </u>			LONG
	- +				<u> </u>		RTGO EMS
F	+				ļ		V10
							GET 0.05G

ε

.

P30 MANEUVER

PURPOSE	XXXXXX	TYPE OF MNVR TO BE PERFORMED
PROP/GUID		PROPULSION SYSTEM (SPS/RCS)/ GUIDANCE (SCS/G&N)
WT	XXXXX (1bs)	PREMANEUVER VEHICLE WEIGHT
P TRIM	X.XX (DEG)	SPS PITCH GIMBAL OFFSET TO PLACE THRUST THROUGH C.G.
Y TRIM	X.XX (DEG)	SPS YAW GIMBAL OFFSET TO PLACE THRUST THROUGH C.G.
GETI	XX:XX:XX (HRS:MIN:SEC)	TIME OF MNVR IGNITION
ΔV X ΔV Y ΔV Z	XXXX.X (fps) XXXX.X (fps) XXXX.X (fps)	P30 VELOCITY TO BE GAINED COMPONENTS IN LOCAL VERTICAL COORDINATES
R P Y	XXX (DEG) XXX (DEG) XXX (DEG)	IMU GIMBAL ANGLES OF MANEUVER ATTITUDE
н _А	XXXX.X (nm)	PREDICTED APOGEE ALTITUDE AFTER MANEUVER
н _Р	XXXX.X (nm)	PREDICTED PERIGEE ALTITUDE AFTER MANEUVER
∆VT	XXXX.X	TOTAL VELOCITY OF MANEUVER
BT	X:XX (MIN:SEC)	MANEUVER DURATION
∆VC	XXXX.X (fps)	PREMANEUVER ∆V SETTING IN ÈMS ∆V COUNTER
SXTS	XX (OCTAL)	SEXTANT STAR FOR MANEUVER ATTITUDE CK
SFT	XXX.X (DEG)	SEXTANT SHAFT SETTING FOR MANEUVER ATTITUDE CK
TRN	XX.X (DEG)	SEXTANT TRUNNION SETTING FOR MANEUVER ATTITUDE CK
BSS	XXX (UCTAL)	BORESIGHT STAR FOR MANEUVER ATTITUDE CK USING THE COAS
SPA	XX.X (DEG)	BSS PITCH ANGLE ON COAS

۰.

MANEUVER PAD (CONL Q)	MANEUVE	ER PAD	(cont'd)
-----------------------	---------	--------	----------

SXP	X.X (DEG)	BSS X POSITION ON COAS
LAT LONG	XX.XX XXX.XX	LATITUDE AND LONGITUDE OF THE LANDING POINT FOR ENTRY GUIDANCE
RTGO	XXXX.X	RANGE TO GO FOR EMS INITIALIZATION
VIO	XXXXXX (fps)	INERTIAL VELOCITY AT .05G FOR EMS INITIALIZATION
GET(.05G)	XX:XX:XX	TIME OF .05G
SET STARS		STARS FOR TELESCOPE FOR BACKUP GDC ALIGN
R, P, Y (ALIGN)		ATTITUDE TO BE SET IN ATTITUDE SET TW FOR BACKUP GDC ALIGN
ULLAGE		NO. OF SM RCS JETS USED AND LENGTH OF TIME OF USSAGE
HORIZON WINDOW		WINDOW MARKING AT WHICH HORIZON IS PLACED AT A SPECIFIED TIG (ATT CK)

•

						Lui	NAR	EN	ITRY					
				ł										AREA
	x	X	X					X	X	Х				R.05G
	Х	Х	X					Х	X	Х				P .05G
	X	X	X				1	X	X	Х				Y .05G
					•	ĺ								GET HOR
	X	X	X		Γ			Х	X	Х				PEI-17
		0			•				0					LAT N61
]							LONG
	X	X	Х]	X	X	Х				MAX G
	+							+				l		V400K N60
	-	0	0					-	0	0				Y 400K
	+]	+					•	RTGO EMS
	+							+						∨10
			•		•								 	RRT
	X	X			•			X	X			•		RET .05G
	+	0	0		•			+	0	0		•		DL MAX N69
	+	0	0		•			+	0	0				DLWIN
	+				-			+					}	∨ _L MAX
	+				F			+						
	X	x	X					X	X	X		•		Do
	Х	Х						X	X					
[X	X			†			Х	X				L	RETBBO
	X	X						X	X					RETEBO
	X	Х						Х	X			•		RETORO
	X	X	X	X		i 		Х	X	X	X			SXTS
	+					0		+					0	SFT EI – 2
	+				0	0		+				0	0	TRN
	Х	Х	Х					Х	X	Х				BSS
	X	X						Х	X					SPA EI-2
	Х	X	Х					Х	X	X				SXP
	Х	Х	Х	X				X	X	Х	X			LIFT VECTOR

LUNAR ENTRY PAD

AREA	XXXXX	SPLASHDOWN AREA DEFINED BY TARGET LINE
R .05G P .05G Y .05G	XXX (DEG) XXX (DEG) XXX (DEG)	SPACECRAFT IMU GIMBAL ANGLES REQUIRED FOR AERODYNAMIC TRIM AT .05G
GET (HOR CK)	XXX:XX:XX (HRS:MIN:SEC)	TIME OF ENTRY ATTITUDE HORIZ CHECK AT EI -17 MIN.
P (HOR CK)	XXX (DEG)	PITCH ATTITUDE FOR HORIZON CHECK AT EI -17 MIN.
LAT	+XX.XX (DEG)	LATITUDE OF TARGET POINT
LONG	+XXX.XX (DEG)	LONGITUDE OF TARGET POINT
MAX G	XX.X (G's)	PREDICTED MAXIMUM REENTRY ACCELERATION
V400K	+XXXXX (FPS)	INERTIAL VELOCITY AT ENTRY INTERFACE
400K	-X.XX (DEG)	INERTIAL FLIGHT PATH ANGLE AT ENTRY INTERFACE
RTGO	+XXXX.X (NM)	RANGE TO GO FROM .05G TO TARGET FOR EMS INITIALIZATION
VIO	+XXXXX (fps)	INERTIAL VELOCITY AT .05G FOR EMS INITIALIZATION
RRT	XXX:XX:XX (HRS:MIN:SEC)	REENTRY REFERENCE TIME BASED ON GET OF PREDICTED 400K (DET START)
RET .05G	XX:XX (MIN:SEC)	TIME OF .05G FROM 400K (RRT)
DL MAX	+X.XX (G's)	MAXIMUM ACCEPTABLE VALUE OF PREDICTED DRAG LEVEL (FROM CMC)
DL MIN	+X.XX (G's)	MINIMUM ACCEPTABLE VALUE OF PREDICTED DRAG LEVEL (FROM CMC)
VL MAX	+XXXXX (FPS)	MAXIMUM ACCEPTABLE VALUE OF EXIT VELOCITY (FROM CMC)

VL MIN	+XXXXX (FPS)	MINIMUM ACCEPTABLE VALUE OF EXIT VELOCITY (FROM CMC)
DO	X.XX (G's)	PLANNED DRAG LEVEL DURING CONSTANT G
RET VCIRC	XX:XX (MIN:SEC)	TIME FROM EI THAT S/C VELOCITY BECOMES CIRCULAR
RETBBO	XX:XX (MIN:SEC)	TIME FROM EI TO THE BEGINNING OF BLACKOUT
RETEBO	XX:XX (MIN:SEC)	TIME FROM EI TO THE END OF BLACKOUT
RETDRO	XX:XX (MIN:SEC)	TIME FROM EI TO DROGUE DEPLOY
SXTS	XX (OCTAL)	SEXTANT STAR FOR ENTRY ATTITUDE CHECK
SFT	+XXX.X (DEG)	SEXTANT SHAFT SETTING FOR ENTRY ATTITUDE CHECK
TRN	+XX.X (DEG)	SEXTANT TRUNNION SETTING FOR ENTRY ATTITUDE CHECK
BSS	XXX (OCTAL)	BORESIGHT STAR FOR ENTRY ATTITUDE CHECK USING THE COAS
SPA	+XX.X (DEG)	BSS PITCH ANGLE ON COAS FOR ENTRY ATTITUDE CHECK
SXP	<u>+</u> X.X (DEG)	BSS X POSITION ON COAS FOR ENTRY ATTITUDE CHECK
LIFT VECTOR	XX (UP/DN)	LIFT VECTOR DESIRED AT .05G's BASED ON ENTRY CORRIDOR

				_	EA	RTH	Of	RBIJ	ΕŅ	ITRY	UF	DA	TE
	Х				<u> </u> -		Х						AREA
	Х	X	-				Х	X	-			•	∆ V TO
	Х	X	X				X	Х	X				R.05G
	Х	Х	X				Х	X	Х				P.05G
	Х	Х	Х				Х	X	Х				Y .05G
	+						+						RTGO EMS
	+						+						01
	X	Х			•		Х	X					RET .05G
		0						0					LAT N61
													LONG
	X	X			•		Х	X					RET 0.2G
						•		ſ				•	DRE (55 [°]) N66
	R	R			7		R	R					bank an
	Х	X			•		X	X					RET RB
	Х	Х			•		X	X					RETBBO
	X	X			•		X	X					RETEBO
	X	X					X	X			-		RETDROG
	Х	Х	X				Х	X	Х				(90°/fps) CHART
	X	X					Х	X					DRE (90°) UPDATE
				•				POS	T BI	URN			
	X	X	X				Х	X	Х				R.05G
	+						+						RTGO EMS
1	+						+						V10
	Х	Х			•		Х	Х					RET .05G
	Х	Х			•		Х	X					RET 0.2G
										Î			DRE ±100-nm N66
	R	R			1		R	R			'		BANK AN
	Х	Х					Х	X		•			RETRB
	Х	X			\$		Х	Х		•			RETBBO
	Х	Х					X	X		•			RETEBO
	X	Х			ŧ		X	X					RETOROG TO MAIN

ENTRY UPDATE AND POSTBURN UPDATE

•

AREA	XXX-X	RECOVERY AREA FIRST 3 DIGITS - LANDING REVOLUTION LAST DIGIT - RECOVERY AREA AND SUPPORT CAPABILITIES
ΔV ΤΟ		△V DUE TO ENGINE TAILOFF
R,P,Y .05G	XXX (DEG)	
RTGO	XXXX.X (nm)	RANGE TO GO FROM .05G TO TARGET
VIO	XXXXX. (fps)	INERTIAL VELOCITY AT .05G
RET	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO .05G
LAT	<u>+</u> XX.XX (DEG)	LATITUDE OF LANDING TARGET POINT
LONG	<u>+</u> XXX.XX (DEG)	LONGITUDE OF LANDING TARGET POINT
RET .2G	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO .2G
DRE	<u>+</u> XXXXX. (nm)	DOWNRANGE ERROR AT .2G
BANK AN	XX/XX (DEG/DEG)	BACKUP BANK ANGLE FOR SCS ENTRY: ROLL RIGHT/ROLL LEFT
RETRB	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO REVERSE BACKUP BANK ANGLE
RETBBO	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO BEGINNING OF COMMUNICATIONS BLACKOUT
RETEBO	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO END OF COMMUNICATIONS BLACKOUT
RETDROG	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO DROGUE CHUTE DEPLOYMENT

J.

:

ENTRY UPDATE AND POSTBURN UPDATE (cont'd)

RET MAIN	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO MAIN CHUTE DEPLOYMENT
CHART UPDATE		
90 ⁰ /FPS DRE (90 ⁰)	+XX +XXX	VALUES USED TO RE-PLOT BACKUP ENTRY CHART - △V AND DRE @ 90° BANK ANGLE
POST BURN UPDATE		
P.05G	XXX	PITCH ANGLE AT ENTRY INTERFACE
RTGO	+xxxx.x	RANGE TO GO FROM .05G TO TGT.
VIO	+XXXXX	INERTIAL VELOCITY AT 0.05G
RET(.05G)	XX:XX	TIME FROM RETROFIRE TO .05G
RET(.2G)		TIME FROM RETROFIRE TO 0.2G
DRE(<u>+</u> 100nm)		DOWNRANGE ERROR (N66)
BANK AN	XX/XX (DEG/DEG)	BACKUP BANK ANGLE FOR SCS ENTRY: ROLL RIGHT/ROLL LEFT
RETRB	CC:CC (MIN:SEC)	TIME FROM RETROFIRE TO REVERSE BACKUP BANK ANGLE
RETBBO	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO BEGINNING OF COMMUNICATIONS BLACKOUT
RETEBO	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO END OF COMMUNICATIONS BLACKOUT
RETDROG	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO DROGUE CHUTE DEPLOYMENT

			E	ARTH	ORB	IT E	LO	скі	DA	ΓA		
Х	X				X	X					AR	Ā
Х	X	Х			X	X	X				LA	г
Х	X				X	X					LO	NG
			+		Т					3	GE	TI
X	X	X			X	X	X				۵V	с
Х	X				X	X					AR	EA
X	X	X			Tx	X	X				LA	
Х	X				X	X					LO	NG
			•		Τ						GE	TI
Х	X	X			Τx	X	X				ΔV	c
Х	X				Tx	X					AR	A
Х	X	X			X	X	X				LA	<u>г</u>
X	X				X	X					LO	NG
					Τ						GE	TI
Х	X	X			X	X	X					c
Х	X				Tx	X					AR	EA
Х	X	Х			Tx	X	X				LA	
X	X				X	X					LO	NG
			•								GE	Γ!
Х	X	Х			X	X	X					c
Х	X				X	X					AR	EA
Х	X	Х			X	X	X					
X	X				X	X					LO	NG
					\bot							FI
	X	X			X	X	X					c

ı

÷

BLOCK DATA

.

ι.

AREA	XXX-X	RECOVERY AREA FIRST 3 DIGITS - LANDING REVOLUTION LAST DIGIT - RECOVERY AREA AND SUPPORT CAPABILITIES
LAT Long	<u>+</u> XX.X <u>+</u> XXX.X	COORDINATES OF THE DESIRED LANDING AREA
GETI	XXX:XX:XX (HR:MIN:SEC)	DEORBIT IGNITION TIME FOR THE DESIRED LANDING AREA
∆VC	XXX.X (fps)	DEORBIT MANEUVER AV TO BE LOADED INTO THE EMS COUNTER.



2-20

EXTERNAL	. ∆ V PADS		
<u>CSM SEP</u>			
33	GETI	XXX : XX : XX	TIME OF IGNITION OF SEP (HR.MIN.SEC.)
81	DELTA VX DELTA VY DELTA VZ	XX.X (FPS) XX.X (FPS) XX.X (FPS)	LOCAL VERTICAL COMPONENTS OF VELOCITY
22	R P Y	XXX. (DEG) XXX (DEG) XXX (DEG)	NEW ICDU ANGLES AT SEPARATION
CSM BACK	UP INSERTION PA	ND (INITIAL UPDATE) AND RESCUE TH	IO PAD
47	WEIGHT	XXXXX	CSM WEIGHT AT IGNITION
48	TRIM ANGLES	XX.X XX.X	SPS P,Y TRIM ANGLES AT IGNITION
33	GETI	XX:XX:XX	TIME OF IGNITION (HR.MIN.SEC.)
81	SAME AS ABOVE	: :	
22	SAME AS ABOVE		
∆¥ _c		XX.X (FPS)	VELOCITY TO BE SET IN EMS COUNTER
11	GETI	XXX:XX:XX	TIME OF IGNITION OF CSI (HR.MIN.SEC.)
37	GETI	XXX:XX:XX	TIME OF IGNITION OF TPI (HR.MIN.SEC.)
N		XX	NUMBER OF HALF-REVO- LUTIONS BETWEEN CSI & CDH
NOMINAL	LM IGNITION TIM	<u>ES</u>	
CSI 11 PC 33		XXX:XX:XX XXX:XX:XX	CSI IGNITION TIME PLANE CHANGE IGNITION TIME
TPI 37		XXX :XX :XX	TPI IGNITION TIME

۱ 4

1

.

CSM RENDEZVOUS RESCUE PADS

۱ 4

CSI ONE AND TWO

11	GETI	XX : XX : XX	TIME OF IGNITION OF CSI (HR.MIN.SEC)
81	DELTA VX DELTA VY DELTA VZ	XX.X (FPS) XX.X (FPS) XX.X (FPS)	LOCAL VERTICAL COMPONENTS OF VELOCITY
N		XX	NUMBER OF HALF- REVOLUTIONS BETWEEN CSI AND CDH
CDH			
13	GETI	XX:XX:XX	TIME OF IGNITION OF CDH (HR.MIN.SEC)
81	DELTA VX DELTA VY DELTA VZ	XX.X (FPS) XX.X (FPS) XX.X (FPS)	LOCAL VERTICAL COMPONENTS OF VELOCITY
TPI			
37	GETI	XX : XX : XX	TIME OF IGNITION OF TPI (HR.MIN.SEC.)
81	DELTA VX DELTA VY DELTA VZ	XX.X (FPS) XX.X (FPS) XX.X (FPS)	LOCAL VERTICAL COMPONENTS OF VELOCITY
59	DELTA V LOS 1 DELTA V LOS 2 DELTA V LOS 3	XX.X (FPS) XX.X (FPS) XX.X (FPS)	DELTA V LINE OF SIGHT COMPONENTS
LOS BT		X:XX X:XX X:XX	BURN TIME FOR LOS

LM MANEUVER UPDATE FORMS

.

•

ı

2-24

PURP	V	V	V
GET		• •	
1174 01	INDEX	INDEX	INDEX
02			
03	···· ···		
04	, 		
05			
06			· · · · · · ·
07	···· • • · · · · ·		
10			
11	· · · · · · · · · · ·	· · · · · ·	
12	· _ · · ·		
13	• • •••		· · · · · · · · · · · · · · · · · · ·
14	···· ·······		
15	1		······································
16	·	·····	
17	· · · · · · · · · · · · · · · · · · ·	· ··· ···	
20		1 ·· ·	- · · · · ·
21	. [· · · · · ·
22	1 · · ·		
23	····· ·····	· · · · · · · · · ·	···· .
24			
N34	HRS X X	'x I	X X X
104	MINIXIX	X X	X X X X
NAV CHECK	SEC X X	; - ₊ , - ,	XX
N43		•	0
		· · · · · •	╺─┥╶╴╷╷╾╷╿╼╎
			+ 0,

P27 UP	DATE	
PURP	XXX	TYPE OF DATA TO BE RECEIVED (SUCH AS: NAV - LIFT-OFF TIME)
۷	XX	TYPE OF COMMAND LOAD (70 - 71 - 72 - 73)
GET	XXX:XX:XX(HR:MIN:SEC)	TIME DATA RECORDED
01	XX (OCTAL)	INDEX NO. OF COMMAND WORDS
02-24	XXXXX	NO. OF CORRECTION COMMAND WORDS
NAV CHECK		TO CONFIRM POINT ABOVE GROUND TRACK FOR A GIVEN TIME
Т	XX:XX:XX(HRS:MIN:SEC)	TIME
LAT	XX:XX (DEG)	LATITUDE
LONG	XXX:XX (DEG)	LONGITUDE
ALT	XXX.X (nm)	ALTITUDE

•



AGS STATE VECTOR UPDATE

PURP		PURPOSE FOR AGS STATE Vector update
240	XXXXX	LM STATEVECTOR-POSITION
241	XXXXX	COMPORENTS
242	XXXXX	
260	XXXXX	LM STATE VECTOR-VELOCITY
261	XXXXX	CUMPUNENTS
262	XXXXX	
254	XXXXX	LM TIME FOR WHICH THE STATE VECTOR IS ACCURATE
244	XXXXX	CSM STATE VECTOR-POSITION
245	XXIXX	COMPONENTS
246	XXXXX	
264	XXXXX	CSM STATE VECTOR-VELOCITY
265	XXXXX	COMPONENTS
266		
[,] 272	XXXXX	CSM TIME FOR WHICH The state vector is Accurate
+ 0 0 + 0 0 HR N3 + 0 0 + 0 0 MIN TIG + 0 + 0 0 0 MIN TIG + 0 + 0 0 AVX N8 AVY LOCA AVZ VER AVZ VER		
--		
+ 0 0 0 0 + 0 0 0 MIN 11G + 0 + 0 ↓ + 0 ↓ SEC ΔVX N8 ΔVY LOCA		
+		
X X X X X BT		
X X X X X R FDA		
X X X X X P INE		
AVZ AGS		
X X X X X X COAS		
X X X AZ		
X X EL		

•

LM MANEUVER UP	DATE	
PURPOSE		PURPOSE OF MANEUVER (SUCH AS DOCKED DPS, PHASING, INSERTION)
TIG		IGNITION TIME FOR THE MANEUVER
HR	XXX	
MIN	XX	
SEC	XX.XX	
LOCAL VERT		
∆V X	+XXXX.X(fps)	LOCAL VERTICAL AV
ΔVY	+XXXX.X(fps)	MANEUVER
∆ V Z	<u>+</u> XXXX.X(fps)	
∆VR	XXXX.X(fps)	TOTAL AV REQUIRED
BT FDAI INER	X : XX	BURN DURATION
R	XXX (DEG)	INERTIAL FDAI
Ρ	XXX (DEG)	BURN ATTITUDE
∆VX AGS	<u>+</u> XXXX.X(fps)	LOCAL VERTICAL AV
∆VY AGS	+XXXX.X(fps)	MANEUVER USED TO
∆VZ AGS	<u>+</u> XXXX.X(fps	ROTATED THROUGH THE HALF-ANGLE OF THE BURN
COAS	XX(OCTAL)	IDENTIFIER FOR COAS STAR USED TO VERIFY SPACECRAFT ATTITUDE AT THE BURN ATTITUDE
AZ	XXX (DEG)	THE AZIMUTH AND ELEVATION
EL	XXX (DEG)	ANGLES OF THE COMS STAR

•

	P32 CS1 UPDATE		
	+ 0 0 + 0 0	HR	רוא
		MIN SEC CSI	
	+ 0 0 + 0 0	HR TIG	N37
	+ 0 0 0 + 0 0 0	MÍN TPI SEC	
		AVX LOCAL	N81
	00 00	ΔVY VERŤ	
	X X X X X	PLM FDAI	
		AVX AGS	N86
	0 0 • 0 0	∆VY AGS	
CSI		ΔVZ AGS	CSI
	ONBOARD LOG	-	
			N8 I
		AVZ VERT	
	0 0 0 0		N81
	x x x x x x x x x x x x	AVY LOCAL	
	x x x x x x x x x x x x x	AVZ VERT	
	REMARKS:		

CSI UPDATE		
TIG CSI		IGNITION TIME FOR THE CSI MANEUVER
HR	XXX	
MIN	XX	
SEC	XX.XX	
TIG TPI		IGNITION TIME FOR THE TPI MANEUVER
HR	XXX	
MIN	XX	
SEC	XX.XX	
LOCAL VERT		
ΔVX	<u>+</u> XX.X (fps)	
ΔVΥ	<u>+</u> XX.X (fps)	AV COMPONENTS OF THE CSI MANEUVER
PLM FDAI	XXX (DEG)	LM FDAI INERTIAL PITCH ANGLE AT CSI BURN ATTITUDE
AVX AGS	<u>+</u> XX.X (fps)	LOCAL VERTICAL AV
∆VY AGS	<u>+</u> XX.X (fps)	USED TO TARGET AGS
∆VZ AGS	<u>+</u> XX.X (fps)	THROUGH THE HALF-ANGLE
NUM DOMOG	ON BOARD LOGS	OF THE BORN
AVX PGNCS	<u>+</u> xx.x	
AVY LOCAL	<u>+</u> XX.X	
∆VZ VERTICAL	<u>+</u> XX.X	
∆VX CHARTS	<u>+</u> XX.X	
AVY LOCAL	<u>+</u> XX.X	
∆VZ VERTICAL	<u>+</u> XX.X	

4

r			
	P33 CDH UPDATE		
	+ 0 0 + 0 0	HR N13	
	+ 0 0 0 + 0 0 0	MIN CDH	
		Δγχ Ν81	
	0 0	AVY LOCAL	
	00 00	Δ٧Ζ	
	X X X X X X	PLM FDAI	
		AVX AGS N86	
		AVY AGS	
		4VZ AGS	
	UNBUARD LUG	ANY NOT	
		AVX PGNCS NOT	
		AV7 VERT	
0	x x x x x x x x x x x x x	LOCAL	_ l
DH	00 00	AVZ VERT	CO
	REMARKS:		

•

CDH	UPDATE
5011	

TIG CDH		IGNITION TIME FOR THE COH MANEUVER
HR	XXX	
MIN	XX	
SEC	XX.XX	
LOCAL VERT		
ΔVX	<u>+</u> XX.X (fps)	
ΔVY	<u>+</u> XX.X (fps)	COMPONENTS OF
۵VZ	+XX.X (fps)	THE CON MANEOVER
PLM FDAI	XXX (DEG)	LM FDAI INERTIAL PITCH ANGLE AT CDH BURN ATTITUDE
AVX AGS	<u>+</u> XX.X (fps)	LOCAL VERTICAL AV
∆VY AGS	<u>+</u> XX.X (fps)	USED TO TARGET AGS
∆VZ AGS	<u>+</u> XX.X (fps)	THROUGH THE HALF-ANGLE
AVX PGNCS	ONBOARD LOG +XX.X (fps)	OF THE BURN
AVY LOCAL	+XX.X (fps)	
∆VZ VERTICAL	<u>+</u> XX.X (fps)	
	<u>+</u> XX.X (fps)	

•

ΔVZ	VERTICAL	<u>+</u> XX.X	(fps)

	-	P34 TPI UPDATE		
	+ 0 0 + 0 0 0 + 0	+ 0 0 0 + 0 0 0 + 0	HR TIG N37 MIN TPI SEC TPI	
	•		∆VX N81 ∆VY LOCAL ∆VZ VERT	
 	+ 0 0 X X X X X X	+ 0 0 • X X X X X X	△VR RLM FDAI N42 PLM INER	
			R TPI R TPI F/A(+/-) N59	
.			R/L(+/-) ∆V D/U(+/-) LOS	
	XX	ONBOARD LOG	B1	
			F/A PGNCS N59 R/L ∆V D/U LOS	
ТРЈ	0 0 X X X X X X 0 0	0 0	F/A CHARTS N59 R/L ΔV D/U LOS	IdT
	REMARKS:		-	

TPI UPDATE

TIG 1	TPI		IGNITION TIME FOR THE TPI MANEUVER
HR		XXX	
MIN		XX	
SEC		XX.XX	
LOCA	L VERT		
Δγχ		<u>+</u> XX.X (fps)	
Δγγ		<u>+</u> XX.X (fps)	COMPONENTS OF THE
۵VZ		<u>+</u> XX.X (fps)	IFI MANEOVER
FDAI	INER		
R LM		XXX (DEG)	LM FDAI ROLL & PITCH
P LM		XXX (DEG)	ATTITUDE
R TP	I	XX.XX (ft)	RANGE AT TPI TIG -5 MIN
R TP	I	<u>+</u> XXX.X (fps)	RANGE RATE AT TPI TIG -5 MIN
∆V L(05		
F/A		F/AXX.X(fps)	I INE_OE_SIGHT AV
L/R		L/RXX.X(fps)	COMPONENTS OF THE
U/D		U/DXX.X(fps)	
BT		XX:XX	DURATION OF THE MANEUVER (MINUTES SECONDS)
F/A	PGNCS	ONBOARD LOGS	FRALEVER (FINDLES, SECONDS)
·//	AV	$\frac{1}{2}$	
	105	$\frac{1}{2}$	
0/0	203	<u>+</u> xx.x ((ps)	
F/A	CHARTS	<u>+</u> XX.X (fps)	
L/R	ΔV	<u>+</u> XX.X (fps)	
U/D	LOS	<u>+</u> XX.X (fps)	

•

2-36

						P	76	UPD	ATE	PAD			
				-							PURPOSE		
	+	0	0			+	0	0		-	HR	N33	
	+	0	0	0		+	0	0	0		MÏN	TIG	
	+	0				+	0		٠		SEC		
					٠					٠	ΔVX	N84	
					٠					٠	ΔVΥ		
					٠					٠	ΔVZ		-
PJ											PURPOSE		9
6	+	۵	0			+	0	0			HR	N33	P7
	+	0	0	0		+	0	0	0		MIN	IIG	
_	+	0			•	+	0		•		SEC		
					٠					٠	ΔVX	N84	
					٠					٠	ΔVY	TIG	
					٠					٠	∆VZ		
											PURPOSE		
	+	0	0			+	0	0			HR	N33	
	+	0	0	0		+	0	0	0		MIN	TIG	
	+	0	•	(+	0		٠		SEC		
					٠					٠	ΔVX	N84	
					٠					٠	ΔVY		
					٠					•	۵VZ		
											PURPOSE		
	+	0	0			+	0	0			HR	N33	
	+	0	0	0		+	0	0	0		MIN	TIG	
	+	0			•	+	۵		٠		SEC		
					٠					٠	ΔVX	N84	
					٠					٠	∆VY		
					•					٠	ΔVZ		

•

Ŀ

.

33	GETI	XX:XX:XX	TIME OF IGNITION (HR.MIN. SEC)
84	DELTA VX(O VEH) DELTA VY(O VEH) DELTA VZ(O VEH)	XX.X (FPS) XX.X (FPS) XX.X (FPS)	COMPONENTS OF ▲V APPLIED ALONG LOCAL VERTICAL AXIS AT TIG

6

4

.

SECTION 3 - DETAILED TIMELINE

۰,

TIME		EVENT		REMARKS
-00:09	LCC:	REPORT IGNITION		FIRST OPPORTUNITY LIFT-OFF MAY 18,
00:00	LCC: CDR:	REPORT LIFT-OFF		SITE 2. LIFT-OFF: 1648 GMT
00:02	CDR:	REPORT YAW MNVR		1148 EST 1148 CDT
00:11	CDR:	<u>REPORT</u> ROLL AND PITCH PROGRAM INITIATE		1048 (S)
00:30	CDR:	REPORT ROLL COMPLETE		
00:42	MCC:	REPORT MARK MODE IB		PROP DUMP TO RCS CMD
00:50	LMP:	REPORT CABIN PRESS DECREASING		ALTITUDE 14,000 ft
01:17	MAX Q			
01:56	MCC:	REPORT MARK MODE IC		ALTITUDE 100,000 ft
02:00	MCC: CDR:	REPORT GO/NO GO FOR STAGING		
02:16	CDR:	REPORT INBOARD OUT		
02:40	CDR:	REPORT OUTBOARD OUT		
02:41	CDR:	REPORT STAGING		
03:11	CDR:	REPORT S-II SEP LIGHT OUT		
03:16	CDR:	REPORT TWR JETT AND MODE II		
03:21	CDR:	REPORT GUIDANCE		
03:53	MCC:	REPORT TRAJECTORY AND GUIDANCE GO	/NO GO	
MISSON F	-	EDITION FINAL	DATE	APRIL 17, 1969 PAGE 3-1

MSC FORM 2114C (JUL 67)

.

TIME		EVENT	REMARKS
04:00	CMP:	REPORT S/C GO/NO GO	
05:00	LMP:	REPORT S/C GO/NO GO	
05:50	MCC:	REPORT S-IVB TO ORBIT CAPABILITY	
06:00	CDR:	REPORT S/C GO/NO GO	
07 00	CDR:	REPORT S/C GO/NO GO	
08:00	CDR:	REPORT S/C GO/NO GO	
08:30	MCC: CDR:	REPORT GO/NO GO FOR STAGING	_
08:37	MCC:	REPORT MODE IV	
09:00	CDR:	REPORT S/C GO/NO GO	
	MCC:	REPORT TRAJECTORY AND GUIDANCE GO/NO GO	
10:00	MCC: CDR:	REPORT GO/NO GO FOR ORBIT	
	MCC:	REPORT PREDICTED SECO	
11:43	CDR:	REPORT SECO $TB_5 = 0$	IMU GIMBAL ANGLES @ INSERTION R 180°
		S-IVB MAINTAINS COMMANDED CUTOFF INERTIAL ATTITUDE	H pad 103.3 NM Y 0°
MISSON	F	EDITION FINAL DATE	APRIL 17, 1969 PAGE 3-2

MSC FORM 2114C (JUL 67)

TIME	EVENT	REMARKS
SECO +10 SEC	MCC: <u>REPORT</u> ORBITAL GO/NO GO	INSERTION
SEC0 +20 SEC	S-IVB MANEUVERS TO LH AND ITITIATES ORB RATE (HEADS DOWN)	
SECO +59 SEC 1	INSERTION CHECKLIST S-IVB INITIATES CONTINUOUS LH ₂ VENTING (TERMINATES AT TB ₆ + 42.2 S	EC)
12:41	BDA LOS	
16:28	CYI AOS MCC UPDATE: GO FOR DSE REWIND	
23:35	CYI LOS POST INSERTION ECS CONFIGURATION	
MISSON F	EDITION FINAL	ATE APRIL 17, 1969 PAGE 3-3

TIME	EVENT	REMARKS
		CONFIGURE CAMERA FOR T & D AND S-IVB PHOTO
		CM/SEQ/18/CEX-BRKT(RH WIN)
		MIR (f11,250.∞)12 fps, 7 MIN)
32:00	S/C SUNSET	CM/EL/80/CEX-SPOT (5,250,focus)20
36:30	TAN AOS	
	MCC UPDATE: AAZ CORRECTION	
42:32	TAN LOS	
	CDR INSTALL COAS	-
	CMP JETTISON OPTICS COVERS	
	P52 IMU REALIGN (Option 3-REFSMMAT)	REALIGNS to PAD ORIENTATION
52:11	CRO AOS	
MISSON	F EDITION FINAL	DATE APRIL 17, 1969 PAGE 3-4

MSC FORM 2114C (JUL 67)



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	01:00 - 02:00	1/1-2	3-5

FLIGHT PLAN 02:00 DON HELMETS AND GLOVES - ALL :10 TAN Т :20 2:23:48 TB₆ (TIG - 9m 38 sec) UPDATE GO/NO GO TLI CRO :30 2:33:26 S-IVB TLI 5m 22 sec BT: TB7=0 @ S-IVB C/0 ∆V: 10,058 fps TB₇+20 sec S-IVB V66 TRANSFER CSM SV TO LM SLOT MNVRS TO LH ATT :40 (HDS DN) APOLLO 10: POST BURN REPORT CMP TO LH COUCH, CDR TO CENTER COUCH UNSTOW TV (A7) М 2:54 S-IVB MNVRS TO R 180° WRT LH @ 1°/SEC S F :50 P 120° N Y 040° R <u>358</u>° S-IVB GOES INERTIAL INERTIAL ATT @ SEP P 151° 03:00 Y 040° DATE TIME EDITION MISSION DAY/REV PAGE APRIL 17, 1969 02:00 - 03:00 1/TLC 3-6 F FINAL

REV A FLIGHT PLA BRANCH

MCC

NOTES

FLIGHT PLAN

UPDATE	Г	03:00	ΙĨ	\sim 03:00 CSM/S	-IVB SEP	<u>T&D MNVR</u> - P47 J	10NITOR DOCK	ATT R <u>302</u> °
GU NO/GO FOR PYRO ARM AND T & D		:10		DOCKING PHO TV(GDS): 2 ~ 3:10 DOCKIN	DTOGRAPHY 3:00 - 3:15 HGA to W NG (PG 4-11) P - <u>53°</u> Y	PLUS X 0.8 FPS COAST 35 SEC IDE MINUS X TO 0.3 FF 39° PITCH UP 180° @ 0 ROLL LEFT 60° @ 0 PLUS X TO NULL RE	PS 2.0/SEC 0.5°/SEC 1 ATIVE VELOCITIO	P <u>331</u> ° Y <u>320</u> °
				TERMINATE C CSM/LM CA	ABIN PURGE AND BEGIN BIN PRESSURE EQUALIZA	TION		-
	-	:20	 M	CONFIGURE F	OR LM EJECTION			
<u>UPDATE</u> SPS EVASIVE MNVR PAQ		:30	S F N	TUNNEL PR REMOVE AN CHECK DOC VENT DOCK CONNECT U REINSTALL TUNL VEN REINITIA	ESSURE INTEGRITY CHEC ID TEMPORARILY STOW FW CKING LATCHES UNG PROBE JMBILICALS _ HATCH T VALVE - LM/CM ∆P TE CABIN PURGE FOR 8 1	K D HATCH IOURS		
	-	:40						
	-	:50		CONFIGURE C 16/18/CEX (f8,250,∞ OBTAIN RADI	CAMERA FOR LM EJECTION -BRKT (RH WIN) MIR) 12 fps, 4 MIN ATION METER from G&N	I SIG COND PANEL, LEB		
	Ł	04:00		APOLLO 10: F RESTOW METER	REPORT RADIATION DOSIM READING AND GET R AFTER USE	ETER		
		MISSI	ON	EDITION	DATE	TIME	DAY /REV	PAGE
		F		FINAL	APRIL 17, 1969	03:00 - 04:00	1/TLC	3-7

REV A FLIGHT PLANNING BRANCH



FLIGHT PLAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	04:00-05:00	1/TLC	3-8
	REV A	FLIGHT PLAN G BRAN	1CH		







MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	07:00-08:00	1/TLC	3-10

FLIGHT PLA MA BRANCH

1-

.

		FLIGHT FLAN	
□ 08:00	ΙŤ		45,000 NM from EARTH
- - - - - - - - - -		BATTERY VENT RECORD BATTERY MANIFOLD PRESSURE (4A) BEFORE, AFTER BATTERY VENT	
- - - - -	M S F N	EVENING MEAL	
		F/C O2 PURGE	
- 10:00		CANISTER A CHANGE (3 to A, T to B5)	

FLICHT DIAN

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	08:00-10:00	1/TLC	3-11
		FLIGHT PLANNING BRA	NCH		

MCC-H

FLIGHT PLAN

UPDATE GO/NO GO MCC ₁ STATE VECTOR MCC ₁ TGT LOAD MCC ₁ MNVR PAD	- :30 	P27 UPDATE P30 EXTERN P52 IMU RE (Option	AL AV AND DAP LOAD CH ALIGN 3 - REFSMMAT)	ECK	48,000 NM fro 2300 EDT P52 OPT N71: N05: N93: X Y - Z BURN STATUS X X	m EARTH
	- S F - 11:00 N - - - -	DISCONTINU P40 SPS TH SXT/STAR C	E BATT A CHARGE Rust Not Wil Ban Heck Ban If	E: SECOND SPS BURN L ALWAYS START ON K B AND THE SECOND K WILL BE ACTIVATED THE BURN IS >5 SEC.	X X TRIM TRIM X X X X X X X X X X X X X X X T X X X X X X X T X X X X X X X X X X X X X X X X X X X	BT_ Vgx R P Y Vax
<u>update</u> PTC Refsmmat	- :30 -TLI + 9h - 12:00	11:33 SPS V66 TRANSF APOLLO 10: P27 UPDATE P52 IMU RE (Option	MCC] NO TRIM ER CSM SV TO LM SLOT POST BURN REPORT ALIGN	NO ULLAGE BT: 8.1 SEC $\Delta V: 57$ FPS AV: 57 FPS ALIGNS IMU TO PTC REFSMMAT	X X X X X X X X X REMARKS:	V gy V gz AV FUEL OX UNBAL
	MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
	F	FINAL	APRIL 17, 1969	10:00 to 12:00	1/TLC	3-12

FLIGHT PI VING BRANCH

NOTES

.

MCL-..

FLIGHT PLAN

UPDATE 12:00 ESTABLISH PTC MODE MNVR R 58,000 NM from EARTH P37 PAD (TLI MONDAY MAY 19, 0100 EDT P 090° +25, 35, 44, TERMINATE CABIN PURGE AND 53) Y 000° REPORT LM/CM AP to MSFN PTC established in G&N + 20° db P & Y. R rate CREW OPTION TO of 0.1°/sec, four quad REPORT OMNI POINT X AXIS control with roll SELECTED NORTH or SOUTH disabled. S/C plus X normal to ecliptic. North (090°); South (270°) :30 CREW STATUS REPORT PRESLEEP CHECKLIST ONBOARD READOUTS to MSFN ONBOARD READOUT NOTE CYCLE H2, O2 FANS CHLORINATE POTABLE WATER Close POT TK IN vlv BAT C 10min after water VERIFY chlorination PYRO BAT A WASTE MNGT OVBD DRAIN viv - OFF PYRO BAT B WASTE STOW VENT VIV - CLOSED CREW 9 HR Μ EMER CABIN PRESS VIV - ON RCS A REST PERIOD S 13:00 SURGE TK 02 v v - ON В F PLSS 02 vlv - OFF Ν LM TUNNEL VENT VIV - LM/CM AP ſ COMM BASIC EXCEPT D S-BD SQUELCH - ENABLE S-BD NORM MODE VOICE - OFF DC IND sel - MNB or A S-BD AUX TAPE - OFF OMNI OPS S-BD ANT OMNI - OMNI S-BD ANT A - B :30 TAPE RCDR FWD - OFF PTC + 20° DBPXY 12h 33m to MCC, 14:00

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	12:00 to 14:00	1/TLC	3-13
	REV A	FLIGHT PLANNING BR	ANCH		



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	14:00 - 15:00	1/110	3-14
	F	LIGHT PLANN BR/	NCH		/



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE			
F	FINAL	APRIL 17, 1969	16:00 - 20:00	1/TLC	3-15			
	FLIGHT PLANNING BRANCH							



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	20:00 - 22:00	1/TLC	3-16
	F	LIGHT PLAN MG BRA	ANCH		



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	22:00 - 24:00	1/TLC	3-17
	REV A F	LIGHT PLANNING BRA	ANCH	-	



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	24:00 - 26:00	2/TLC	3-18
	REV A	FLIGHT PLAN BI	RANCH		



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	26:00 - 28:00	2/TLC	3-19
	REV A	FLIGHT PLANNING BRA	NCH		

S-BAND REFLECTIVITY TEST MNVR R ____ P ____ Y ____ HGA P ____ Y ____ COMM BASIC EXCEPT S-BD RANGING - OFF GO TO HGA OPS, VERIFY LOCK ATT HOLD 0.5° db DO STEPS 1-6 TEST 1 TEST NO 3 2 -30° -20° 1. MNVR HGA METER P -10° 340° 350° 360° -20° -30° 2. SET HGA CNTL Ρ -10° 320° 330° 340° Y 3. HI GAIN ANT BEAM - WIDE HI GAIN ANT TRACK - MANUAL 4. WHEN HGA METER COMPARES TO HGA CNTL HI GAIN ANT TRACK - AUTO HI GAIN ANT BEAM - NARROW TEST NO. 5. RECORD 3 2 HGA METER P Y **%** SIGNAL 6. EVALUATE VOICE COMM REPEAT STEPS 1-6 TEST 2 REPEAT STEPS 1-6 TEST 3 7. RETURN TO COMM COAST AWAKE S-BD AUX TAPE - OFF TAPE RCDR FWD - OFF

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	26:00 - 28:00	2/TLC	3-19A
	REV A' F	LIGHT PLANNING BRA	ANCH		

NOTE

THE S-BAND REFLECTIVITY TEST WITH THE CSM/LM HAS BEEN DELETED. THE TEST MAY BE SCHEDULED REAL TIME WITH THE CSM DURING TEC.

20.00	8			
28:00 - - - - - - :30 -	M S	GA PTC AUTO REAQ CHECK COMM COAST AWAKE EXCEPT HI GAIN OPS Y <u>270° P 40°</u> (roll right) Y <u>90° P -40°</u> (roll left) HI GAIN ANT BEAM - NARROW HI GAIN ANT TRACK - REACQ S-BD ANT OMNI - HI GAIN	Τ db, p & y	
- 29:00	F			
F	n			
F				
F				
- :30				
-			PTC	
F				
		CLOSE O2 VAC ION MN A/B CB(2)		Closed at 85% to 90% total O ₂ OTY
00100	L			

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	28:00 - 30:00	2/TLC	3-20
	REV A	FLIGHT PLANNING BRI			

MCC-H

NOTES

FLIGHT PLAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	30:00 - 32:00	2/TLC	3-21
		FLIGHT PLANN' RA	NCH		



REV A	FLIGHT	PLANNING	BRANCH

MCL





MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	34:00 - 36:00	2/TLC	3-23

FLIGHT PLANNING BRANCH



.

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE	
F	FINAL	APRIL 17, 1969	36:00 - 42:00	2/TLC	3-24	






MISSION	EDITION	DATE	TIME	DAY/REV	PAGE		
F	FINAL	APRIL 17, 1969	42:00 - 44:00	2/TLC	3-25		
FLIGHT PLATING BRANCH							

FLIGHT PLAN



 46:00
 F/C 02, H2 PURGE

 F/C 02, H2 PURGE

 F/C 02

M S F N 47:00 NOON MEAL PTC :30 48:00

NOTES

7h 45m to MCC $_3$

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	46:00 - 48:00	2/TLC	3-27
	F	LIGHT PLAN BRA	NCH		



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE		
F	FINAL	APR1L 17, 1969	48:00 - 50:00	3/TLC	3-28		



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	50:00 - 52:00	3/TLC	3-29
	F	LIGHT PLAN 'S BRA	NCH		

MCC-H

NOTEL



FLIGHT PLANNING BRANCH





MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	54:00 - 56:00	3/TLC	3-31
	F	LIGHT PLA; G BR/	NCH		· =

55.00		FLIG	HT PLAN	
				, 180,000 NM from EARTH 35,000 NM from MOON
_ L			PTC	
_				
- :30 -				
-			~	
-	 м		CREW STATUS REPORT ONBOARD READOUTS to MSFN CYCLE H2, O2 FANS CHLORINATE POTABLE WATER	ONBOARD READOUT
- 57:00	S F N	PRESLEEP CHECKLIST	VERIFY WASTE MNGT OVBD DRAIN VIV - OFF WASTE STOW VENT VIV - CLOSED	PYRO BAT B
-			EMER CABIN PRESS VIV - BOTH SURGE TK O2 VIV - ON PLSS O2 VIV - OFF	B
_			LM TUNNEL VENT v1v - LM/CM ∆P COMM BASIC EXCEPT	D
20			S-BD SQUELCH - ENABLE S-BD NORM MODE VOICE - OFF	DC IND SEL - MNA or B
- :50			OMNI OPS	OMNI OR HGA OPS per MSFN
-		CANISTER <u>A</u> CHANGE (7 to A, 5 to B6)	S-BD ANT OMNI - OMNI S-BD ANT A - B TAPE RCDR FWD - OFF OR HI GAIN OPS Y 270 P40 (roll right)	
58:00		F/C O ₂ PURGE	Y 90 P-40 (roll left) HI GAIN ANT BEAM - NARROW HI GAIN ANT TRACK - REACQ	
	<u> </u>		S-BD ANT OMNI - HI GAIN	2300 EDT, TUES, MAY 20

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	56:00 - 58:00	3/TLC	3-32
	REV A I	LIGHT PLANNING BRA	NCH		

·



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	58:00 - 60:00	3/TLC	3-33
		FLIGHT PLANN BRA	NCH		

.



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	60:00 - 66:00	3/TLC	3-34

FLIGHT PLANNING BRANCH



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	64:00 - 68:00	3/TLC	3-35
	F	LIGHT PL ING BRA	ANCH		





MU221014	EDITION	DAIL	IIME	DAY/KEV	PAGE	Ł
F	FINAL	APRIL 17, 1969	68:00 - 70:00	3/TLC	3-36	ļ

UPDATE



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	70:00 - 72:00	3/TLC	3-37
	REV A	FLIGHT PLA' 'G BRA	NCH		

· ·



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
£	FINAL	APRIL 17, 1969	72:00-74:00	4/TLC	3-38
	REV A E	LIGHT PLANNING BRA	(NC)I		



FLIGHT PLANNING BRANCH

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	76:00-78:00	4	3-39/

- S/C SUNSET
- O S/C SUNRISE





MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17,81969	76:00-78:00	4/2	3-40
	REVA	LIGHT PLANNING BR	ANCH		

1



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	78:00~80:00	4/2	3-40A



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	78:00-80:00	4/2	3-41
	REV A	FLIGHT PLANNING BRA	NCH		



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	80:00-82:00	4/3	3-43A

FLIGHT PLAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	80:00-82:00	4/3	3-42
	RFV A	FLIGHT PLANNING BRA	NCH		

CSM LM LMP MCC-H 81:00 _ HOLD R 180° HGA UPDATE CONFIGURE SEQ CAMERA LDMK TRACKING P 205° P ∽62° FOR IVT PHOTOGRAPHY: PAD REV 4 16/5/CIN-SPOT (NOM f2.8,60) 6fps, Y 000° Y 168° **REV 4 MAP UPDATE** 1 MAG P52 IMU REALIGN :10 (Option 3 - REFSMMAT) P52 0PT TRANSFER THE FOLLOWING REPRESS LM N71: TO THE LM: N05: 1. RAD SURV METER CANISTER <u>A</u> CHANGE (9 TO A, 7 TO B6) 16mm FILM (6 mags 2. :20 N93: in 1 bag) Х 70mm FILM (3 mags VERIFY TUNNEL PRESSURE 3. in 1 bag) MONOCULAR 4. 5. FLT DATA FILE ITEMS NOTE CLEAR TUNNEL OF HATCH :30 VISUALLY INSPECT TUNNEL & DOCKING LATCHES NO P27 UPDATE REMOVE & STOW PROBE & DROGUE THIS PASS F/C 02 PURGE :40 CSM VERIFY DSE MOTION @ LOS OPEN LM HATCH COPY ROLL CAL ≹ RELAY ROLL CAL € IVT TO LM MNVR R 000° TO LDMK :50 TRACK ATT P 326° Y 000° LM ENTRY STATUS CK , 82:00

FLIGHT PLAN

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	80:00-82:00	4/3	3-43
MSC ENTE 8458 /					

Form 8458 (Jan 69) REV A

FLIGHT P'ANNING BRANCH



F FINAL APRIL	17, 1969 82:00-8	4:00 4/4	3-43A





,

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	80:00-82:00	4/3	3-43B
	F	LIGHT PLANNING BRA	NCH		

82.00			CSM FLIGHT	PLAN				МСС-Н
REV 4	DU ON 25 OM	NOTES: RING P22 DO NOT PRO FINAL N89 SEC BETWEEN MARKS NI <u>C</u> FOR LDMK T	D RACK		PERFORM HO 1. UNSNAP BAGS & 2. UNSTOW LIST, D & CONFI 3. STOW IS RECHG S	DUSEKEEPING CHO HELMET STOWAGE STOW ON FLOOR MIRROW, CHECK- DISPOSAL ASSY, IGURE FOR USE SA OVER PLSS STN	DRES E	
:20	P2	2 ORBITAL NAVIGATIC 82:27 F-1 @ 0° EL 82:32 F-1 ₪ 35° EL :35 STOP PITCH AT <u>2</u> :38 MNVR P 274°	CSM PWR T - SUN § <u>64°</u> VHF AM(B) <u>REPORT</u> ROLL 272°	TO LM - OFF) - DUPLEX CAL TO MSFN	5. CONFIGU 6. STOW CF XFI	FORM & FORM CF JRE CMR'S FOR L EW LOG ER TO LM PWR MM ACTIVATION		
:40	Т ₁ Т ₂ ММ	82:45 B-1 @ 0° EL 82:49 B-1 @ 35° EL VR R <u>135°</u> HGA P <u>208°</u> P <u>-4</u> Y <u>000°</u> Y <u>234</u>	SUN ≩ <u>13°</u> 5° DEACTIVATE JET PRIOR TO LM S- 4° ACTIVATION DAP LOAD [21 11	S B-3, C-4 BD STEERABLE 112 001	OMNI VO	VOICE/TM TESTS	S	
	MISSION	EDITION	DATE	TIM	E	DAY/REV	PAGE	
	F	FINAL	APRIL 17, 1969	<u>82:00-</u> 83	3:00	4/4	3-44	

FLIGHT PLA	NNING BI	RANCH
------------	----------	-------

WSC Form 8458 (Jan 69) REV A



CSM/LM TYPICAL LANDMARK TRACKING PROFILE

.



.

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	83:00-84:00	4/4	3-45
WSC Form 8458 (Jan 69) REV A	FLIGHT	PLANNING BRANCH		

CSM COMM PROCEDURES FOR CSM/LM COMM TESTS



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	83:00-84:00	4/4	3-45A
MSC Form 8458 (Jan 88)		FLIGHT	PLANNING BRANCH		



MSC Form 845B (Jan 69)REV A

FLIGHT PLANNING BRANCH





MISSION	EDITION	DATE	TIME	DAY/REV	PAGE	
F	FINAL	APRIL 17, 1969	85:00 - 86:00	4/5	3-47	
FLIGHT PLANNING BRANCH						



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	86:00 - 88:00	4/6	3-48

-





MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	88:00 - 90:00	4/7	3-49
	ـــــــــــــــــــــــــــــــــــــ	LIGHT PLA NG BRA	NCH		



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	90:00 - 92:00	4/8	3-50
FLIGHT PLANNING BRANCH					





MISSION	EDITION	DATE		TIME	DAY/REV	PAGE
E \	FINAL	APRIL 17	1969	92:00 - 94:00	4/9	3-51
	F	LIGHT PL,	VG BRA	ANCH		_



STATE VECTOR LLS 2 REFSMMAT LLS 2 TRACK PAD MAP UPDATE REV 11 MSFN RCD OPS Source pressure P52 OPT N71: N05: N93:

•

χ

Y

CSM UPDATE

MCC-H

L 95:00 ↓ ż ■						
MISSION	EDITION	DATE	TIME	DAY/REV	PAGE	
۶	FINAL	APRIL 17, 1969	94:00 - 95:00	5/11	3-52	
	REV A FLIGHT PLANNING BRANCH					

REV 10/11



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE	
F	FINAL	APRIL 17, 1969	95:00-96:00	4/10-11	3-52A	
L	REV A					

.

.


MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	95:00 - 96:00	4/10	3-53
	REV A	FLIGHT PLA	NNING RRANCH		

P22 MAN	ACQ P dn 2^{0}	0° Y0°
$T_1 T_2$		- 130
R	°P	ογο
N or S NM	SA	
130)	N89
LAT +01	.266	•
LONG/2 +11	.839	•
ALT -OC	01.73	

ι

,

MAP	UPDATE	REV _	_10
LOS	:		_:
1509	°W:	;	_:
AOS	:	:	

.

MAP U	PDATE	REV _	
LOS	:	_:	: <u> </u>
150°W	:	_:	-:
AOS	:		_:

- -

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	92:00 - 94:00	4/9	3-53A







FLISHT PLANNING BRANCH

FLIGHT PLAN



FLIGH LAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	100:00 - 101:00	5/13	3-58
	REV A	FLIGHT PLAN	NNING BRANCH		



FLIGHT LAN







CSM

FLIGHT PLANNING BRANCH

FLIGHT PLAN



FLIGHT PI IG BRANCH

FLIG, PLAN



FLIGHT PLANNING BRANCH



FLIGH1 LAN







MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	107:00 - 108:00	5/17	3-65
	REV A	FLIGHT P	NG BRANCH		



REV A FLIGHT PLANNING BRANCH



МСС-Н

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	109:00 - 110:00	5/18	3-67
		CLEANE ON NUMBER OF			

FLIGHT PLANNING BRANCH



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	110:00 - 112:00	5/19	3-68

FLIGHT PLANNING BRANCH



MISSION	EDITION	DATE		TIME	DAY/REV	PAGE
ç	FINAL	APRIL 17	1 96 9	112:00 - 114:00	5/20	3-69
	F	LIGHT PLA	BR	ANĆH		



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE	
F	FINAL	APRIL 17, 1969	114:00 - 116:00	5/21	3-70	
ELIGHT PLANNING BRANCH						

HCL



MCC-H



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	118:00-119:00	5/22	3-71A

REV A

. 1



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	118:00 - 119:00	5/22	3-72
REV A FLIGHT PLAN G BRANCH					

NOTES



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	119:00 - 120:00	5/23	3-73
	REV Á	FLIGHT PLANNING BRA	ANCH		

REV 23



/

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	119:00-120:00	5/23	3 -73₽
	REV A				·

ЮTE!





CSM TYPICAL LANDMARK TRACKING PROFILE 3-74A

REV 24



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	121:00-122:00	5/24	3-74B

MCC-H

FLIGHT PLAN



NOTES

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	121:00 - 122:00	5/24	3-75



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	122:00 - 123:00	5/25	3-76
	r	1 1 AUX - AL ANNINA - AA			



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	123:00-124:00	5/25	3-76A

MCC-H

L

NOTES

		1	rligi	11 PI	.AN			
- 123:00 - :04	Ĩ	NOTE: IF N GO C OMNIC	0 DSE MO MC RESET	TION & LO Then Noi	DS CONT RM HOLD	INERTIAL	2nd REV LDMK TRACKIN	IG
- :10 - :12 - :18 - :18 - :18 - :18 - :18 - :30		123:13 INIT NOTE: USE TRAC P22 ORBITAL T ₁ 123:24 T ₂ 123:27	IATE ORB UPDATED KING (RE NAVIGAT IP-1 CP-1	RATE (3 N89 VALU V 25, 26 TON - RE AOS AOS	38° ORDEAL) JES FOR LDMK , AND 27) V 25 SUN ≹ 11°	P22 MAN T ₁ T ₂ R N or S NM CP LAT +01 LONG/2 +63 ALT +02	ACQ P dn 22°	R0° Y0° - CP-2 °Y - TA - N89
- - - - - - - - - - - - - - - - - - -		T ₁ 123:39 T ₂ 123:41 T ₁ 123:52 T ₂ 123:54	IP-2 CP-2 IP-F-1 F-1	AOS AOS AOS AOS	SUN ≹ 54° SUN ≹ 85.5°	P22 MAN T ₁ T ₂ R N or S NM F-1 LAT +01 LONG/2 +43 ALT +00	ACQ P dn 22° 	I R0° Y0° F-1 °Y^ N89

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE	
F	FINAL	APRIL 17, 1969	123:00 - 124:00	5/25	3-77	

NOTES

FLIGHT PLAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE		
F	FINAL	APRIL 17, 1969	124:00 - 125:00	5/25	3-78		

FLIGHT PLANNT'S BRANCH



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	125:00-126:00	5/26	3-78A

MCC-H

NOTES

	Ĩ	NOTE: IF NO DSE MOTION @ LOS CONT IN GO CMD RESET THEN NORM HOLD	NERTIAL 3rd REV LDMK TRACKING
		OMNI <u>C</u>	P22 MAN ACO P dp 22° RO° VO°
F			
- :10		125:11 INITIATE ORB RATE (338° ORDEAL)	$r_{2} CP-2$
F			R °P °Y °
۰ ₁₇		P22 ORBITAL NAVIGATION - REV 26	N or S NM SA TA
17			CP-2 N89
		T, 125:22 IP-1 AOS	LAT +01.000 •
- <u>REV 26</u>		T ₂ 125:25 CP-1 AOS SUN ≩ 10°	LONG/2 +63.700 •
		2	ALT +000.00
:30			
-			
Γ		T ₁ 125:37 IP-2 AOS	
F		T ₂ 125:39 CP-2 AOS SUN ₹ 53°	P22 MAN ACQ P dn 22° RO [®] YO [®]
- :40		2	
F			
-			R °P °Y °
- :48			Nor SNM SA TA
- :50		T1 125:50 IP-F-1 AOS	F-1 N89
F		T ₂ 125:52 F-1 AOS SUN ≹ 86.5°	LAT +01.600 •
–			LONG/2 +43.440
F			ALT +000.00
L _{126:00}	ا ملر ا		

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
				5/26	3-79
	F				

MCC-h

NOTES



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE		
F	FINAL	APRIL 17, 1969	126:00 - 127:00	5/26	3-80		
FLIGHT PLANNING BRANCH							

MCC-H

NOTES


MCC-H



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	128:00 - 129:00	5/27	3-82
	REVA	FLIGHT PLANNING BRA	NCH		



بلر

L 130:00

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	129:00 - 130:00	5/28	3-83

NOTES

.

FLIGHT PLANNING BRANCH



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE	
F	FINAL	APRIL 17, 1969	130:00 - 131:00	5/28	3-84	
FLICHT PLANN' S BRANCH						



	EDITION	DATE		DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	131:00-132:00	5/29	3-84A



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	131:00 - 132:00	5/29	3-85
	REV A F	LIGHT PLANNING A	NCH		



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	132:00 - 133:00	5/29	3-86
	ł	LIGHT PLANNING BRA	ANCH		



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	132:00-133:00	5/30	3-86A

	FLIGHT PLAN	
- 133:00 - -	133:00 PITCH UP <u>315</u> ° ORDEAL AND GO ORB RATE FOR PHOTOS OF OPPORTUNITY (HEADS DOW	v)
- :11 - REV 30	CANISTER <u>A</u> CHANGE (13 to A, 11 to A3)	
- :20 - - :30 -	PHOTOS OF OPPORTUNITY	PHOTOGRAPHS WILL BE OBTAINED, AT CREW OPTION, OF SELECTED AREAS ON THE LUNAR SURFACE. AREAS OF INTEREST ARE SPECI- FIED ON THE TARGET OF OPPORTUNITY CHART:
- :41 		
- :50 -	133:50 MNVR TO LDMK TRACK ATT R <u>ODO</u> ° AND GO ORB RATE 338° ORD OMNI <u>C</u>	EAL (HEADS UP)
L _{134:00}	P22 ORBITAL NAVIGATION	

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	133:00 - 134:00	5/30	3-87
	REV A	ELIGHT PLANNING BR.	ANCH		

FLIGHT PLAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	134:00 - 135:00	5/30	3-88
	REV A	FLIGHT PLANNING BRA	NCH		

RE√ 31



4

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	136:00-137	6/31	3-88A
	REV A			·	

FLIGHT PLAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	135:00 - 136:00	5/31	3-89
	REV A	FLIGHT PLAN	NCH		



FLICHT	DIANNTNG	RRANCH
ILIUNI	FLANNING	DUVICI

136:00 - 137:00

5/31

3-90

APRIL 17, 1969

FINAL

F





MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	137:00 - 138:00	5/31	3-91
	REV A	FLIGHT PLANNING BRA	ANCH		

FLIGHT PLAN

	DEACTIVATE GLY EVAP GLY EVAP GLY EVAP P52 IMU REA	PRIMARY EVAPORATOR H2O FLOW - OFF STM PRESS AUTO - MAN STM PRESS INCR - INCR LIGN	for 58 sec Pulse torque to	
- :30 	(Option 1	- preferred)	PTC REFSMMAT ESTABLISH PTC <u>+</u> 20°DB P&Y	P23 NO COMM (1) TEI + 1:30 5 SETS LH Arcturus(31)F Regulus(22)N Regulus(22)N Alphard(21)N Alpharad(21)N
- 139:00 F	H ₂ PURGE LI	CREW STATUS ONBOARD REA CYCLE H2, C VERIFY	REPORT NOUTS to MSFN 2 FANS	ONBOARD READOUT
- :30 	PRESLEEP	CHECKLIST CHECKLIST CHECKLIST CHECKLIST CHECKLIST CHECKLIST SURGE TK PLSS 02 V LM TUNNEL COMM BASIC S-BD SQUE S-BD NORM S-BD AUX	W VENT VIV - CLOSED W VENT VIV - CLOSED N PRESS VIV - BOTH 02 VIV - ON VIV - OFF VENT VIV - OFF EXCEPT ELCH - ENABLE MODE VOICE - OFF TAPE - OFF	PYRO BAT A PYRO BAT B RCS A B C D DC IND sel - MNA or B
MISSION	EDITION	PURGE Y 270 P40 Y 270 P40 Y 90 P-40 HI GAIN A HI GAIN A S-BD ANT) (roll right)) (roll left) NNT BEAM - MARROW NNT TRACK - REACQ OMNI - HI GAIN TIME	

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	138:00 - 140:00	6/TEC	3-92
	REV A	FLIGHT PLANN BRA			

MCL-..

NOTES

~

			FLIGHT PLAN		-		
UPDATE State vector	Γ ^{140:00}	T	ECS REDUNDANT COMPONENT CHECK	1		03,000 NM 1 2h 20m to	from EARTH MCC _E
	-		P27 UPDATE	PTC +2	2	5h 50m to I	MCC6
				P &	ř		•
	F i			1			
	-						
	-						
	-		CDEW 5 1/2 HD DEST DEDIAD			930 FDT	
	- :30				Ĩ	1h 50m to 1	MCC5
					Í		
	-			ļ			- '
	- I	м					
	-	S	W-MAIKIX				
	- 141:00 -	F N	In the event of a loss of COMM the W-MATR be initialized to the values listed befor the next scheduled batch of sightings.	IX will e	BATCH Nr		S TO BE D VIA V67
	-		NOTE The W-MATRIX is initialized only once on	the		$\frac{R1}{R1}$	R2
			Transearth leg.		I	+00094	+00057
			Batch 2 has two sets of values listed; if	the not	2	+02928 +00998	+00039
	- :30		been received, the first set should be use	ed; if	3	+00000	100000
			set should be used. If loss of COMM occurr, the	rs	5	+00336	+00008
	F		after E1-30 hrs (GET 161:50), and provided E1-30 hrs entry pad update has been reciev	d the ved, the	4	+00998	+00008
	-		current CMC state vector will provide reer capability, and no navigation marks will b	ntry be made.	5	+00998	+00008
	- 142:00		• • • • • •		6	+00998	+00008

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	140:00 - 142:00	6/TEC	3-93
		· · · · · · · · · · · · · · · · · · ·			

FLIGHT PLANNING BRANCH





MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	142:00 - 144:00	6/TEC	3-94
		FLIGHT PLAT NG BRA			



MCC-H

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	144:00 - 146:00	7/TEC	3-95
	F	LIGHT PLANNING BRA	NCH		

FLIGHT PLAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	146:00 - 148:00	7/TEC	3-96
	REV A F	LIGHT PLA S BRA	NCH		6



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	148:00 - 150:00	7/TEC	3-97
		FLIGHT PLANNING BR	ANCH		

MCC----

UPDATE

STATE VECTOR





MISSION	EDITION	DATE	TIME	DAY	/REV	PAGE			
F	FINAL	APRIL 17, 1969	150:00 - 152:00	7	/TEC	3-98			

MCC-

NOTES



FLIGHT PLANNING BRANCH

FLIGHT PLAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE			
F	FINAL	APRIL 17, 1969	154:00 - 156:00	7/TEC	3-100			

FLIGHT PLANTING BRANCH



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE			
F	FINAL	APRIL 17, 1969	156:00 - 162:00	7/TEC	3-101			
	FLIGHT PLANNING BRANCH							

4



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	162:00 - 164:00	7/TEC	3-102
	ş	LIGHT PLAY 'G BR	ANCH		

MCC-h

FLIGHT PLAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	164:00 - 366:00	7/TEC	3-103
	REV A	FLIGHT PLANNING BRA	\N C H		





MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	166:00 - 168:00	7/TEC	3-104
	REV A F	LIGHT PLANNING BRA	ANCH		

МСС-Н

168.00		FLIGHT	PLAN	
		NOON MEAL		1300 EDT
F .			, DTC	
-			PIL	
i i i i i i i i i i i i i i i i i i i				
- :30				
L				
-				
-				
- 169:00	M S			
-	N N			
-				
-			PTC	
- :30				
Ē				
F				
Ē.				
L 170:00				

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	168:00 - 170:00	8/TEC	3-105
	REV A				





2

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	170:00 - 172:00	8/TEC	3-106
REV A FLIGHT PLANNI BRANCH					



MCC-H

.

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE				
F	FINAL	APRIL 17, 1969	172:00 - 174:00	8/TEC	3-107				

	17	74.00		FLIGHT PLA	N		
							95,000 NM from EARTH
		:30	P23 OPTICS P23 MIDCOU (3 mar SET 1: SET 2:	CALIBRATION RSE NAVIGATION-STAR/E ks each SET) Diphda(2)N Enif(44)F	ARTH HORIZON	PTC CREW MANAGES OMNI SELECTION	MINIMUM SUN ELEVATION CONSTRAINT TEST INCORP P23 MARK DATA AND UPDATE ONBOARD STATE VECTOR
JPDATE STATE VECTOR	- - - 17	75:00 S N	SET 3:	Fomalhaut(45)F			P23 NO COMM (9) TEI + 37:00 3 SETS LH Regulus(22)N Spica(26)F Spica(26)F
ICC ₆ TGT LOAD ICC ₆ MNVR PAD ENTRY PAD (ASSUMES MCC ₆)		:30	P27 UPDATE P30 EXTERN P52 IMU RE (Option 3	IAL ∆V AND DAP CHECK ALIGN - REFSMMAT)			P23 NO COMM (10) TEI + 38:30 5 SETS EH Enif(44)F Diphda(2)N Diphda(2)N Alpheratz(1)N Alpheratz(1)N P52 OPT
		MISSION	EDITION	DATE	TIM	£	N05: N93: X Y Z
		F	FINAL	APRIL 17, 1969	174:00 - 1	76:00	8/TEC 3-108

REV A FLIGHT PLAN

.



REV A FLIGHT PLANNING BRANCH

FLIGHT PLAN

/

	T PI	RESLEEP CHECKLIST (FOR 177:30)	CREW STATUS REPORT ONBOARD READOUTS to MSFN CYCLE H2, O2 FANS CHLORINATE POTABLE WATER VERIFY WASTE MNGT OVED DRAIN VIV - OFF	80,000 NM from EARTH SUNDAY, MAY 25, 2300 EDT 11h 50m to MCC ₇
- :30 - :30			WASTE STOW VENT VIV - CLOSED EMER CABIN PRESS VIV - BOTH SURGE TK 02 VIV - ON PLSS 02 VIV - OFF LM TUNNEL VENT VIV - OFF COMM BASIC EXCEPT S-BD SQUELCH - OFF S BD NORM MODE - OFF S-BD AUX TAPE - OFF OMNI OPS	ONBOARD READOUT BAT C PYRO BAT A PYRO BAT B RCS A B
- - 179:00 -	M S F C N	REW 8 HR REST PERIOD	S-BD ANT OMNI - OMNI S-8D ANT A - B TAPE RCDR FWD - OFF	D D DC IND sel - MNA or B
- - - - :30			PTC	

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE				
F	FINAL	APRIL 17, 1969	178:00 - 180:00	PITEC	3-110				
	FLIGHT PLANY BRANCH								



FLIGHT PLANNING BRANCH



MISSION	EDITION	DATE	<u> </u>	DAY/REV	PAGE		
F	FINAL	APRIL 17, 1969	184:00 - 186:00	8/TEC	3-112		

FLIGHT PLATING BRANCH



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	186:00 - 188:00	8/TEC	3-113
	REV A	_	· · · · · ·		

UPDATE

GO/NO GO

PYRO ARM



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	188:00 - 190:00	8/TEC	3-114
REV A FLIGHT PLANTING BRANCH					
MCC-

UPDATE

ENTRY PAD

FLIGHT PLAN



MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
F	FINAL	APRIL 17, 1969	190:00 - 192:00	8/TEC	3-115
	REV A	ELIGHT PLANNING BR.	ANCH		

200- c.

FLIGHT PLAN

1

NOTES

	192:04 TOUCHDOWN	MONDAY, MAY 26 1252 EDT
-	TYPICAL DATA - EI to TOUCHDOWN	
	EVENT TIME FROM EI - mir	n:sec
- :30 	400,000 FT 00:00 ENTER S-BAND BLACKOUT 00:26 0.05 G 00:30 KA - INITIATE CONSTANT DRAG 00:52 RDOT≈-700 FPS 01:20 PEAK G 01:24 P64 T0 P67 02:10	
- - 193:00 -	EXIT S-BAND BLACKOUT03:26GUIDANCE TERMINATION07:30DROGUE DEPLOYMENT08:33.2MAIN DEPLOYMENT09:22.0TOUCHDOWN14:15.2	
- - -	L/D = 0.286 V = 36,221 R= γ = -6.48	1350
- :30 -		
- 194:00		

EDITION	DATE	TIME	DAY/REV	PAGE
FINAL	APRIL 17, 1969	192:00 - 194:00	8/TEC	3-116
	EDITION FINAL	EDITIONDATEFINALAPRIL 17, 1969	EDITION DATE TIME FINAL APRIL 17, 1969 192:00 - 194:00	EDITION DATE TIME DAY/REV FINAL APRIL 17, 1969 192:00 - 194:00 8/TEC

SECTION 4 - DETAILED TEST OBJECTIVES

1

SECTION 4

DETAILED TEST OBJECTIVE ACTIVITIES

This section contains the activity summaries which reflect the test objectives for Mission F as described in "Mission Requirements F Type Mission", SPD9-R-037, dated February 11, 1969. These activity summaries are presented in the approximate sequence in which they are planned to occur during the mission. In the case of activities which are repeated in the mission plan, they are described only once in this summary. Those test objectives which do not relate to specific mission activities and require minimal support for accomplishment are grouped at the end of this section as "Passive Tests." Test objective requirements which are not scheduled in this flight plan are identified as being not implemented, "N.I."

Each activity summary provides the following information:

- A. TEST OBJECTIVES. This is the listing of the Functional Test Objectives (complete or partial) which relate to the particular activity;
- B. TEST REQUIREMENTS. Here the special test prerequisites (and mission phase if necessary) are presented in addition to brief statements of the requirements for performing the activity;
- C. TEST PROCEDURES/CHECKLISTS. These are the procedural references for the performance of the activity as far as the test objectives are concerned; and
- D. DATA REQUIREMENTS. This part of the summary identifies the gross data which are needed for evaluation of test results in terms of flight crew and ground support requirements.

Cross references for relating Detailed and Functional Test Objectives with the activity summaries and relating activities to Functional Test Objectives, are provided as the initial part of this section.

The following ground rules are to be used in implementing data requirements:

- A. The collection of highly desirable (HD) data should not constrain the timeline of the crew procedures.
- B. CSM data storage equipment (DSE) HBR recording is needed only when MSFN coverage is not available and when mandatory data are required.
- C. Post-flight debriefing requirements which are fulfilled by real time transmission of data per the DATA REQUIREMENTS sections may be deleted from the post-flight debriefing.

TABLE 4-1 MISSION ACTIVITY/TEST OBJECTIVE CROSS REFERENCE

۰,

ACTIVITY	<u>FT0</u>
Trans/Docking/Ejection	20.46-1, 2
PTC	7.26-1; 20.79-1, 2, 3, 4
Midcourse Navigation	1.39-1, 2, 3, 4
MCC	20.95-1
LOI	20.117-1, 2
LM Sensor Biases	11.17-1; 12.6-1
LM IMU Alignment	11.17-2
Lunar Landmark Tracking	20.91-1, 2, 3, 4, 5; 20.121-1, 2, 3
LM Inspection by CSM	20.86-1, 3
DOI	11.15-2; 13.14-1; 16.14-2; 20.82-1, 2;
	20.86-2, 3
Near Lunar Surface Activity	16.14-1; 20.86-4; 16.10-3
Phasing	11.17-3; 13.14-1; 11.15-1; 12.6-1;
	16.14-2; 20.82-1, 2
Insertion and Rendezvous	12.10-1, 2; 16.15-1, 2, 3, 4, 5;
	20.77-1; 20.78-1, 2; 20.82-1, 2;
	20.86-2, 3
Station Keeping	12.8-1, 2, 5, 6, 7, 8; 20.78-2
APS Burn to Depletion	11.17-3; 12.9-1, 3; 13.13-1, 2
Telecommunications	6.9-1; 16.10-1, 2,3; 16.12-1; 16.17-1,
	2, 3, 4, 5
LM Consumables	20.83-1, 2, 3, 4, 5
Passive Tests	7.26-1, 2; 20.66-1, 2; 20.80-1

.

DTO/FTO NUMBER	TEST OBJECTIVE	MISSION ACTIVITY	SECTION PAGE NO.
S1.39 S1.39-1 S1.39-2 S1.39-3 S1.39-4	Midcourse Navigation/Star-Lunar Landmark Star/Lunar Landmark Navigation Accuracy OSS Adequacy for Star/Lunar Landmark Navigation Coordinate Optics and Maneuvers/Identify LMK Propellant Usage/Time for Navigation	Midcourse Navigation Midcourse Navigation Midcourse Navigation Midcourse Navigation	4-16 4-16 4-16 4-16
53.22 ⁻ 53.22-1	PUGS Evaluation DELETED	Lunar Orbit Insertion Transearth Injection	4-18 4-56 -
S6.9 S6.9-1	CSM High Gain Antenna Reflectivity CSM HGA Reflectivity Region - Docked	Telecommunications	4-42
S7.26 S7.26-1	Space Environment Thermal Control TC System - Translunar and Transearth	Passive Thermal Control Passive Test	4-14 4-54
P7.26-2	TC System - Lunar Orbit	Passive Test	4-54
P11.15 P11.15-1 P11.15-2	PGNCS Undocked DPS Performance PGNCS/DPS High Thrust Burn PGNCS/DPS Descent Orbit Insertion	Phasing Descent Orbit Insertion	4-32 4-26
S11.17 -S11.17-1 S11.17-2 S11.17-3	LM IMU Performance LM PIPA Bias LM IMU Drift Rate LM PGNCS Errors	LM Sensor Biases LM IMU Alignment Phasing APS Burn to Depletion	4-20 4-21 4-32 4-41
-			

DTO/FTO NUMBER	TEST OBJECTIVE	MISSION ACTIVITY	SECTION PAGE NO.
S12.6 S12.6-1	AGS Performance AGS/PGNCS Gyro and Accelerometer Data	LM Sensor Biases Phasing	4-20 4-32
S12.8 S12.8-1 S12.8-2 S12.8-3 S12.8-4 S12.8-5 S12.8-6 S12.8-7 S12.8-8	AGS/CES Attitude/Translation Control AGS/CES Auto Hold-Minimum Deadband AGS/CES Auto Hold - Maximum Deadband Deleted AGS/CES Man Attitude - Pulse Mode AGS/CES Man Attitude - Proportional Rate AGS/CES Man Translation - THC Propellant Usage	Station Keeping Station Keeping Station Keeping Station Keeping Station Keeping Station Keeping Station Keeping Station Keeping	4-38 4-38 4-38 4-38 4-38 4-38 4-38 4-38
S12.9 S12.9-1 S12.9-2 S12.9-3	Unmanned AGS Controlled APS Burn AGS/APS Burn - Range of Inertias Deleted RCS Propellant Usage	APS Burn to Depletion APS Burn to Depletion APS Burn to Depletion	4-41 4-41 4-41
\$12.10 \$12.10-1 \$12.10-2	LM/AGS Rendezvous Evaluation AGS Controlled CFP Rendezvous AGS/CES - RCS ΔV Maneuver	Insertion and Rendezvous Insertion and Rendezvous	4-34 4-34
\$13.13 \$13.13-1 \$13.13-2	Long Duration Unmanned APS Burn APS Performance APS Propellant Depletion	APS Burn to Depletion APS Burn to Depletion	4-41 4-41
S13.14 S13.14-1	LM Supercritical Helium Supercritical Helium Pressure Profile	Descent Orbit Insertion Phasing Passive Tests	4-26 4-32 4-54

4-4

DTO/FTO NUMBER	TEST OBJECTIVE	MISSION ACTIVITY	SECTION PAGE NO.
P16.10 P16.10-1 P16.10-2 P16.10-3 S16.12 S16.12-1	LM Steerable Antenna Performance LM S-Band Steerable Antenna - Lunar Distance Steerable Antenna Pattern Steerable Antenna Procedures LM Omni-Antennas Lunar Distance LM Omni-Antennas Lunar Distance	Telecommunications Telecommunications Telecommunications Near Lunar Surface Telecommunications	4-42 4-42 4-42 4-28 4-28
P16.14 P16.14-1 P16.14-2 S16.15 S16.15-1 S16.15-2 S16.15-3 S16.15-4 S16.15-5	Landing Radar Test Landing Radar Lock-on Spurious Signal Lock-on Rendezvous Radar Performance Maintain Lock at Maximum Range Range Data Accuracy Range Rate Data Accuracy Tracking Angle Data LM -X RCS Plume Effect on RR	Near-Lunar Surface Descent Orbit Insertion Phasing Insertion and Rendezvous Insertion and Rendezvous Insertion and Rendezvous Insertion and Rendezvous Insertion and Rendezvous	4-28 4-26 4-32 4-34 4-34 4-34 4-34 4-34
S16.17 S16.17-1 S16.17-2 S16.17-3 S16.17-4 S16.17-5	Relay Modes Voice/TM LM/MSFN via S-Band, LM/CSM via VHF, CSM/MSFN via S-Band LM/MSFN/CSM S-Band Conference, MSFN Relay LM/CSM via VHF, CSM/MSFN via S-Band, CSM Relay LM Voice and LBR to CSM - CSM Dump LM/CSM via VHF, CSM/MSFN via S-Band, LM Relay	Telecommunications Telecommunications Telecommunications Telecommunications Telecommunications	4-42 4-42 4-42 4-42 4-42
S20.46 S20.46-1 S20.46-2	Transposition/Docking/LM Ejection Trans/Dock/Ejection Demonstration Trans/Dock/Ejection Procedures and Time	Trans/Dock/Ejection Trans/Dock/Ejection	4-11 4-11
P20.66 P20.66-1 P20.66-2	Crew Activities Lunar Distance Pre-LOI Through DOI Timeline Lunar Orbit Mission Procedures	Passive Tests Passive Tests	4-54 4-54

4-5

DTO/FTO NUMBER	TEST OBJECTIVE	MISSION ACTIVITY	SECTION PAGE NO.
S 20.77 S20.77-1	VHF Ranging Accuracy of VHF Ranging During Rendezvous	Insertion and Rendezvous	4-34
P20.78 P20.78-1 P20.78-2 S 20.79 S 20.79-1 S 20.79-2 S 20.79-3	CSM/LM Rendezvous Capability LM Rendezvous Demonstration LM Rendezvous Procedures Passive Thermal Control Modes PTC-Docked-Roll 0.1 Deg/Sec PTC-Docked-Roll 0.3 Deg/Sec PTC-CSM-Roll 0.1 Deg/Sec	Insertion and Rendezvous Insertion and Rendezvous Station Keeping Passive Thermal Control Passive Thermal Control Passive Thermal Control	4-34 4-34 4-38 4-14 4-14 4-14
S 20.79-4 S 20.80 S 20.80-1	PTC-CSM-Roll 0.3 Deg/Sec Ground Support Lunar Distance Ground Support Lunar Distance	Passive Thermal Control Passive Tests	4-14
S 20.82 S 20.82-1 S 20.82-2	PGNCS/AGS Monitoring Ground Monitor of PGNCS/AGS Crew Monitor of PGNCS/AGS	Descent Orbit Insertion Phasing Insertion and Rendezvous Descent Orbit Insertion Phasing	4-26 4-32 4-34 4-26 4-32
S20,83 S20,83-1 S20,83-2 S20,83-3 S20,83-4 S20,83-5	LM Consumables Lunar Orbit Electrical Loads Water and Oxygen Requirements LiOH Requirements Propellant Requirements Food Requirements	Insertion and Rendezvous Lm Consumables LM Consumables LM Consumables LM Consumables LM Consumables	4-34 4-53 4-53 4-53 4-53 4-53

4-6

. •

DTO/FTO NUMBER	TEST OBJECTIVE	MISSION ACTIVITY	SECTION PAGE NO.
\$20.86 \$20.86-1 \$20.86-2 \$20.86-3	Lunar Orbit Visibility Illumination/Time for LM Inspection Optical Tracking of LM Visual Phenomena When Viewing LM	LM Inspection Descent Orbit Insertion Insertion and Rendezvous LM Inspection Descent Orbit Insertion Insertion and Rendezvous Near Lupar Surface	4-24 4-26 4-34 4-24 4-26 4-34 4-28
P20.91 P20.91-1 P20.91-2 P20.91-3 P20.91-4 P20.91-5	Lunar Surface Optical Washout Lunar Landing Site Determination Landmark Tracking Error Uncertainties Coordinate Sightings and Maneuvers Propellant and Time for Landmark Tracking Equipment for Landmark Tracking Low Sun Angle Landmark Tracking	Lunar Landmark Tracking Lunar Landmark Tracking Lunar Landmark Tracking Lunar Landmark Tracking Lunar Landmark Tracking	4-22 4-22 4-22 4-22 4-22 4-22
S20.95 S20.95-1	Midcourse Correction Capability GNCS and SPS/RCS Performance for MCC	Midcourse Corrections	4-17
\$20.117 \$20.117-1 \$20.117-2	LOI Maneuver Preparation and Execution of LOI Procedures and Timeline for LOI	Lunar Orbit Insertion Lunar Orbit Insertion	4-18 4-18
P20.121 P20.121-1 P20.121-2 P20.121-3	Lunar Orbit Determination Improve Lunar Gravity Model Equipment for Landmark Tracking Propellant and Time for Landmark Tracking	Lunar Landmark Tracking Lunar Landmark Tracking Lunar Landmark Tracking	4-22 4-22 4-22

4-7

CORRELAT MISSION I	TABLE 4-3 ION OF TEST OBJECTIVES WITH PHASES AND ACTIVITIES FOR MISSION F	FUNCTIONAL TEST OBJECTIVE	STALALUMAR LANDMARK NAVIGATION ACCURACY	COMPINATE OFFICE AND MANEURIS/DENTIFY LMK COORDINATE OFFICE AND MANEURIS/DENTIFY LMK MORELLANT USGE/TME FOR NAVIGETION	DELETED CSM MGA REFLECTIVITY REGION - DOCKED	TC SYSTEM - TRANSLUMMA AND TRANSLARTH TC SYSTEM - LUMAR ORBIT	PGMCS/DPS HIGH THRUST BUBN PGMCS/DPS DESCENT ORBIT INSERTION	LM PIPA BIAS LM WU DRIFT EATE	VUM PGINCS EMILORS AGS/PGINCS GYILD AND ACCELEROMETER DATA	AGS/CES AUTO HOLD-MIN MULA DE ADALND AGS/CES AUTO HOLD - MAXIMUM DE ADAAND	OULIFIED DELIFIED	AGS/CES MAN ATTRUGE PRIZE MODE AGS/CES MAN ATTRUGE PROPERIONAL RATE AGS/CES MAN TRAVSLATION - THC	MOPEULANT USAGE AGS/ANS BURN - RANGE OF INERTIAS	ORLETED NCS PROPELANT USAGE	AGS CONTROLLED CFP REMOZZYOUS AGS/CES - RCS AV MANEUVER	AIS PERCOMMANCE AIS PROPELLANT DEFLETION	AVENCRITCAT PELONA PROSPACE PECPEC. LM S-LAND STERABLE ANTENNA - LUNAR DISTANCE STERABLE ANTENNA PATTEN	SREEMALE ANTENNAL PROCEDURES LA CAMINI-ANTENNALS DISTANCE	LUNDING SHOWN LOCK-ON	MAINTAIN LOCK AT MAXIMUM RANGE RANGE DATA ACCURACY	RANGE RATE ACCURACY TRACKING ANGLE DATA	LM -X RCS PLUME EFFECT ON MR LM/MSFN VIA 5-PAND, LM/CSM VIA VHF, CSM/MSFN VIA 5-BAND	LUXASHY/CSM PEARO CONFERENCE, MSFN RELAY LUXASH VIA CVANSASH VIA S-BANUD, CSM RELAY	LAN VOICE AND LINE IO CSM - CSM SUMMP LANCEM VIA VIIF, LANVASEN VIA SARNAD, LANEBAY	TRANS/DOCK/A KCTION PROCEDURES AND TWE me. 17. DAMAN PARAMENTANA M. 17.	UNAL OF MISSON PROCEDURES	ALCURACT OF THE PARAGING UNITAR IS NUCLEARDS	IM REAVELY POLIS PROCEDURES	FTC-DOCKED-ROLL AT 0.3 DEG/SEC FTC-CSM-ROLL AT 0.1 DEG/SEC	PTC-CAM-ROLL AT 0.3 DEG/SEC GROUND SUPPORT LUNIAR DESTANCE	GROUND MONITOR OF PGNCS/AGS CREW MONITOR OF PGNCS/AGS	ELECTRICAL LOADS WATER AND OXYCEN REOUREMENTS		FOOD REQUIREMENTS	OFFICAL TRACKING OF LM VISUAL FRENOMENA WIEN VIEWING LM	LUNAR SUBSACE OFFICAL WASHOUT 1 AMOUNT FRACEINGE PROM LANCERTAINIES		PRUTELIANI AND THE FOR EXPLANATION INCLUTION	LOW SUN ANGLE LANDMARK TLACKING CHICS AND SPS/RCS REPORMANCE FOR MICC	PREPARATION AND EXECUTION OF LOI PROCEDURES AND TAKENE FOR LOI	IMPROVE EURAN GRAVITY MODEL EQUIPMENT FOR LANDMARK TRACKING	PROPELLANT AND TIME FOR LANDMARK TRACKING
MISSION PHASE	MISSION ACTIVITY	GET	1-96-15	F 46.15	53.22-1	57.24-1	P11.15-1	511.12-1 51.12-2	511 17-3 512.6-1	512.0-1 512.0-2	512.0-4	512.8-5 512.8-6 512.8-7	\$12.8+8 \$12.9-1	512.9-2 512.9-3	512.10-1 512.10-2	513.13-2	PI6.10-1	P16.10-3 \$16.12-1	P16.14-1 P16.14-2	516.15-1 516.15-2	516.15-4	516.15-5	516.17-2 516.17-3	516.17-4 516.17-5	520.46-2	P20.44-2	1-120-02-4	520.79-1	5.80-79-2 5.80.79-3	520.74-4	520.82-1 520.82-2	520.83-1 520.83-2	520.00-5	520.43-5 520.46-1	520.64-2 520.64-3	520.M-4	P20, 91-2	1-16,061	1-54-025	520,117-E 520.117-2	P20, 121-1	F20.121-3
	NOT SCHEDULED			Π		\prod			TT	Π		TT		Π	Π	Π	PF	P			ĪT	X	TT		Π		T	T	Π	TT		xx	মম	ज्ञा	Π	Π	Π	$\overline{\Pi}$	Π	Π	Π	Ť
TRANS LUNAR COAST	TRANSPOSITION/DOCKING	03:00					Ш										$\dagger \dagger$					Π	Ħ	TÞ	k		11		\dagger	\dagger						IT	Ħ	Ħ	Ħ	-	+	t
	MIDCOURSE CORRECTION #1	11:33		11					\square			Π					Π	\square	\prod										T				\square			Π	Ħ	Π	X			Ť
	PASSIVE THERMAL CONTROL	12:00		11		X			Ш														Π					∣∢					\square	T	\square	Π	Π	Π	Π	Π	Π	Ť
	MIDCOURSE CORRECTION #2	26:30				ļĻ			Ш		11					Ш							I			\Box								\Box		ŀ		Π	X		\Box	Τ
	TELECOMMUNICATIONS	26:45			X	1			\downarrow	\square		Ц.			Ц						11		Ţ						Ц					T		\square	\prod	Π	Π	\Box	Π	T
	PASSIVE THERMAL CONTROL	45:10		Ш.	Ц.				\downarrow	$\downarrow \downarrow$						Ш		Ш.			Ш	Ш		\square					X								\prod	Π		\square	\Box	Ι
	MIDCOURSE CORRECTION #3	<u>53:45</u>		11	\prod	\square	Ш		╢	11	┿	┿							Ш			Ш				1				\square			Ш				\prod	\prod	X			Ι
 	MIDCOURSE CORRECTION #4	70:45			11	11	11		╢	Ш	11	1					Ц.				4		$\downarrow\downarrow$	Ц			Ц	$\downarrow \downarrow$	Ц	\downarrow					Ш			Ш	X			
LUNAR ORBIT INJECTION	LOI #1 PREPARATION	74:40			11		μ.	$\left \right \right $	\parallel	44					Ш	\parallel	11				$\downarrow \downarrow$	Ш				1X],			$\downarrow \downarrow$				Ш	Ш	Ш		Ш	Ш		хx		
	PASSIVE THERMAL CONTROL	76:00		11		X	⇇	╏┟╽	╢	\downarrow	11		\square	-11			\prod			Щ	44	11	11	Щ	Ц				11				Ц	┛			Ш				Ш	
	LOI #2 PREPARATION	79:00	IЦ	11	Ц.	\square	↓	\square	+	+	11	$\downarrow \downarrow$			-		\square	11			\downarrow	Ц	┵╂	11	Ц	11	╨		Щ				Ш	┉┷┛	Ш	LL.	Ш	\square	Ш	xХ		
LUNAR ORBIT	MCCH UPDATE	81:00	lЦ	11		\downarrow	⊥	╎╷╷	╉	++	\downarrow	∔∔			+	$\downarrow\downarrow$	╄	┼┠╴			$\downarrow\downarrow$	44	┼┼	╢		11		╧	$\downarrow\downarrow$	X			ĻЦ	+	Ш	\square	₩	Ш	Ш	Ш	Ш	
	LUNAR LANDMARK TRACKING	82:25		$\downarrow \downarrow$			↓	┟┼∔	╉┼	++	╄	+			+	#	₩			\square	$\downarrow \downarrow$	╢	\downarrow	\blacksquare	$\left \right $	<u> </u>	↓↓	┿	41	\downarrow	╢		41	╷┼┤	\square	ЦX	¥×	犂	4	Ш		L
	TELECOMMUNICATIONS	83:05		11	11		μ.	H	╫	++	$\downarrow\downarrow$	╨		+	╇	┿	\downarrow			+	-	Ĥ	41	X	4			\parallel	\square	┥┦				┯┯┥	Ш	┝┶╴	Ш	1	11	Ш	Щ	L
	MCCH UPDATE (TIMELINE)	94/107	╢╷	11	Ш	ļĻ	∏-	┟┟┤	╢	┼┼	╇	┼┿		╫	╉╟	┼┼	++			+	-+-+	\prod	₩	╢		╢	↓	#	┼┼	X	┼┤		Ш	-44			Ш.	11	Щ			L
	TELECOMMUNICATIONS	96:20	IЦ	11	$\downarrow \downarrow$	ļĻ	$\downarrow \downarrow$	┟┟╽	╫	\mathbf{H}		+		-	\downarrow	 	$\left \right $	╎╎		++	+	╢	₽₽	44	╎╎	<mark>↓</mark>	₩		11	\downarrow			Ш	11	Ш	μĻ.	11	11	11	Ш		
	LUNAR LANDMARK TRACKING	96:35	IЦ	Ш		$\downarrow\downarrow$	╨	┞┼┼	╂	╈	┼┼			+	++		++			+	┥┥	╢	╁╀	╂┟	┟┟	┥┥	╎┝	++	╇	╢	┽╽		-1-1	┿┤	\square	Ľ	<u>X</u> X	铧	4	Ш	\downarrow	
	LM SENSOR BIASES	96:55	Ш	11	11	11	₽-	M	╢	┥╀	44				+	\downarrow	╇	\square	┞╌╿╴╏		++	+	┼┼	4	╁╂	╞┝	\prod		++	\downarrow	\downarrow		4	╺┼┤	\square	LL.	Ш	Ш	\square	Ш	Ш	
	LM INSPECTION BY CSM	98:10	IЦ	\parallel	11	↓	↓	┟┼┦	╢	+	╉╢	┼┼	+	╢	┽┼	╀	H	$\left[\right]$		┼╂	\parallel	╨	∔∔	╢		╢		$\left \right $	╢	╇			╷┼┤	<u> </u>	X		#	$\downarrow\downarrow$	Щ	\parallel	Ш	
	DESCENT ORBIT INSERTION	99:30	IЦ	\parallel	#	╟	ЦX	┞┼╿	╬	+	+	++	+	╢	╫	┼偝		$\left + \right $		┿	┿╋	╢	┼┼	╢	╀┠	┼┼	$\downarrow \downarrow$	╢	┽╀	╢	XX	4	-44	Ш	×Х	<u> </u> -	Щ	Щ	Ц	\square	\square	╇
	TELECOMMUNICATIONS	100:10	╢凵	11	11	₩	₩-	╎ ╎ ╎ ╎	┼╂	┽╂	++	┿╂╴		+	╢	╂╂	<u>IXIX</u>	\square	Ц.	┼┨	+	╁╂	╀┼	╢	↓ ↓	╞╏	↓↓	$\downarrow\downarrow$	H	\downarrow		\parallel	44	4	H		μ.	$\downarrow\downarrow$	44	Щ	4	╞
LUNAR ORBIT	NEAR LUNAR SURFACE	100:20	ĮЦ	\parallel	Ш	$\downarrow\downarrow$	╟	┟╂⋠	삮	┿╂	┼┼	╈	$\left \right $	┼┦	╢	╢	╫	μ.	ГĻ,	+	╫	╢	╂╂	╢	╂┠	┢╟	┼┼	╀	╓	╀			-#-	44	$\left \right $	4	μ.	Щ	\square	1	Щ	L
[PHASING MNVR	100:45					X	Шł	<u>^rl</u>	Ш			LL			Ľ	<u>1</u> .].		L X						<u>LL</u>	Ц	Ц	Ш	Ш		시지		Ш		Ш		Ш	Ш			Ш	

•

.

T. CORRELATION MISSION PHA M	ABLE 4-3 N OF TEST OBJECTIVES WITH ISES AND ACTIVITIES FOR ISSION F	FUNCTIONAL TEST OBJECTIVE	STARALINAAL LANGAAAK MAVIGATION ACCURACY DSS ADEGLACY FOILSTARA LANAAL LANDAARK MAVIGATION	COORDINATE OFTICS AND MAREUNES/IDENTIFY LMK PROFELLANT USAGE/TWE FOR NAVVIGATION	DELETED CS4 MGA MERLECTIVITY REDOM - DOCKED	TC SYSTEM ~ TEAMSLIMAA AND TRANSLARTH TC SYSTEM ~ UTMAR ONET POONSCAPS INCH THEIRST IMAN	PGMCS/DIS DEXCENT OBJIT INSEEDON LM SPA BAS	LM PGMCS (BODIS)	AG5/PGNC5 GYBO AND ACCLLEROMETER DATA AG5/PES AUTO HOLD-MINIMICAN DEADAA ND	AGS/TES AUTO HOI D - MAX MAUM DE ADBAND DELETED	ORLETED Arsactes many applitude - Purise mode	AGS/CES MAN ATTITUDE - MONORYDONAL BATE AGS/CES MAN RANSLATHON - THC	PEOPELLANT USAGE AGS/APS BURN - RANGE OF INEERIAS	DELITED HCS MOPELIANT USAGE	AGS CONTRONLED CFP RE MOEZ VOUS AGS/CES + RCS 4V MANEUVER	APS PERFORMANCE APS PROPELLANY DEPERTION	SUPERCRITICAL HELTUM PRESSURE PROFILE UM S-BAND STEERABLE ANTENNA - LUNAAR DISTANCE	STEERABLE ANTERNA PATTERN Steerable Antenna Procedules	LA CANNENNTINHAS LUNAR DISTANCE LANDING RADAL LOCK-ON	AUTOR STORAGE COLONAL	RANGE BATE DATA ACCURACY TRACKING ANGLE DATA	LM -X ACS FLLME FFFECT ON RE UMANSPA VIA 5-AUND, LM/CSM VIA VIA 5-BAND	LAMASAUCSA S-BAND CONFRENCE, MSFN RELAY LAMCSM VIA VHF, CSM/MS5N VIA S-BAND, CSM RELAY	LAI VOICE AND LINE TO CSM ~ CSM DUMP LINCESM VIA VHIE, LAV/MSFIN VIA S-BAND, LANREAV	TRANS/DOCK/LISCTION DEMONSTRATION TRANS/DOCK/LISCTION PROCEDURES AND TWE	THE-LOT THEOUGH DON TIMELINE LUNARE ORBIT MISSION PROCEDURES	ACCURACY OF WAF LANGING DURING REMORZYOUS LAN REMORZYOUS DEMONSTRATION	LA RENDEZMOUS PROCEDURES PTC-DOCKED-ROLLATO.I DEG/SEC	PTC-DOCKED-ROLL AT 0.3 DEG/SEC PTC-CSM-ROLL AT 0.7 DEG/SEC	PTC-CSM-ROLL AT 0.3 DEG/SEC GROEND SUPPORT (UNAUR DES/ANCE	GROUND MONITOR OF POINCS/AGS CREW MONITOR OF POINCS/AGS	ELECTRICAL ŁOADS WATER AND OXYGEN REQUMEMENTS	LIDH REQUIREMENTS PROFELLANT REQUIREMENTS	1000 ECUIEBARNIS	UPPIKAL IPACKINAG OF LM VISUAL IPENDAKINA WHEN VIEWING LM	LUNAR SUBSACE OFTICAL WASHOUT LANDMARK TRACKING EMON UNCERTAINTIES	COORDINATE SIGHTINGS AND MANEUVERS PROFELANT AND TIME FOR LANDMARK TRACKING	FOULIMMENT FOR LANDMARK TRACKING LOW SUN ANGLE LANDMARK TRACKING	SAUCS AND SEARCY FEROMANCE FOR MCC MEMALATION AND EXECUTION OF LOI	MOCEDURES AND TWILINE FOR LOI IMPROVE LUNAR GRAVITY MODEL	FOURSMENT FOR LANDMARK TRACKING PROFELLANT AND TIME FOR LANDMARK TRACKING
MISSION PHASE	MISSION ACTIVITY	GET	1-96-12	51.39-3 51.79-4	1-22-1	57.28-1 57.38-2 F11.15-1	511.15-2	5-41.112 5-41.112	512.6~1 512.8~1	512.6-2	\$12.8-4 \$17.9-5	\$12.8-4 \$12.8-7	512.8-8 512.9-1	5-6-215 E-6-215	512.10-2	1-61.618 5-61.618	1-01.019	F16.10-2	516.12-1 P14.14-1	516.15-1	516. 15-2 514. 15-4	514. 15-5 514. 17-1	516, 17~2 516, 17~3	510.17-4 516.17-5	520.44-1 520.44-2	P20.06-1	-1-12-102.4	1-12-12-12-12-12-12-12-12-12-12-12-12-12	520-79-2	520.77-4 520.60-1	520.82-1	520.01-1	C-CO.DS2	1-99-02S	2-94-92 20-94-92	1-14-024	P20:91-2	5-14-024 1-16-024	520.95-1 520.117-)	520.117-2 P20.121-)	F20.121-2
	RENDEZVOUS RADAR TESTS	102:05	Π				Π								Π	Ĩ	T	П		X	XX	X		T	Π		Π	Π		Π				Π	Π	TT	Π	П	T	T	Т
	INSERTION & RENDEZVOUS	102/106							X	X	Þ	ХX	X		××						††						XX	X			хx			TÞ	٨X	11			Ш	\square	T
	LM SENSOR BIASES & COMM	106:30				TT	ΓÞ		X	$[\top]$	T				\square		X	Τ	Π	T	Π		\square					Π						ŢŢ	\square	\square	\square		П		\mathbf{T}
	TELECOMMUNICATIONS	106:55														\Box	\square	Π	Π				X	Ţ]		Π	Π	Π	Π					Π	Π	TT	Π	Π	Π	Π	Π
	APS BURN TO DEPLETION	108:39][[X					X	×		×х											Π	\square					Π	Π	Π	Π	Π	Π	Π	T	Т
	LUNAR LANDMARK TRACKING	121:15	JП																	Π	T							T					Π	Π	TI	Π	T	\square	П	X	xX
	LUNAR LANDMARK TRACKING	123:18																T						TI				\prod		Τ					Π	Π	Π	T	Π	X	젞
	LUNAR LANDMARK TRACKING	125:15														П		Π		Π							Π	\square							Π	Π	Π	Π	Π	X	袮
	LUNAR LANDMARK TRACKING	127:15							Ш										TT	Π	ГШ												П	Π	Π	\square	T	Π	Π	X	xX
TRANS EARTH COAST	PASSIVE THERMAL CONTROL	138:40				×																		T			Π						Т	Π	П	T	T	Π		\square	\mathbf{T}
	MIDCOURSE NAVIGATION	151:00		XX				1																			Π	TT		Τ			\square	Π	TT	Π		Π		TT	\mathbf{T}
	MIDCOURSE CORRECTION #5	152:20					1		2																		T							T	TT	Π	П	Π	X	T	Π
	PASSIVE THERMAL CONTROL	165:30				×				Ш																	Π			X			Т	Π	Π	Π	Π	Π		TT	T
	MIDCOURSE CORRECTION #6	176:50								Ш								T		Π				T	Π	\prod	Π	Π					Π	Π	Π	TT	Π	Π	хT	Π	T
1	MIDCOURSE CORRECTION #7	188:50								Ш																	Π							Π	Π	Π	Π	T	$\overline{\mathbf{x}}$	T	\mathbf{T}
					Ш				Ц																·	\Box	Π			Π				Π		Π	Π	T	П	T	\mathbf{T}
																								Π			Π						Π	Π	Π		Π	Π	Π		\mathbf{T}
								Π			ŢĮ			\prod		T				\prod				TI									Π	11	Π	Ħ		Ħ		1	T
														Π					Π					ŢĮ			TT	Π		Π		Π		Π	Π	Ħ	Ħ	11		11	₶
				\prod						Ш	Π		\square					II									Π	\prod	Π	Π		Π		Π	11	$\uparrow \uparrow$	11	11	$\uparrow \uparrow$	11	
			ЦШ							Ш	Π		Π	\prod	Π	Π		II	\prod	\prod				T		Π	Π			Π	\square	\Box	T		Π			$\uparrow \uparrow$	11	11	11
		┥┝───┉	┛╟	Ш											Ц	\square	\prod									Ţ	\prod	\prod		\square			\prod	Π		\prod	\square	\prod	T	\mathbf{H}	
			ЦЦ	Ш				\square					Ш		Ш												\prod	Π		Π				Π	Π	TT	T	T	\square	\mathbf{T}	
															\prod		П	Π		[]				Π	Π	Π	Π	Π	Π	Π	П	Π	Π	Π	Π	TT	T	T	TT	Ħ	\mathbf{H}

.

REMARKS :

- LM IMU back-to-back alignments will not be conducted per FTO S11.17-2 requirement. The station keeping time after rendezvous would have to be extended to implement the subject DTO requirement.
- Some of the AGS controlled RCS maneuvers required by DTO S12.8 will be accomplished during the normal rendezvous activities and may be conducted without the benefit of HBR TM as required.
- LR temp data per DTO P16.14 will not be recorded after the Phasing Burn. The Phasing Burn is done within MSFN line-of-sight and TM should be available.
- 4) Required data will be voiced to the ground rather than recorded by the crew during the communications tests per DTO's 16.10, 16.12 and 16.17
- 5) DTO 16.10 and 16.12 will be partially implemented.

A. TEST OBJECTIVES

S20.46-1 Transposition/Docking/Ejection Demonstration S20.46-2 Transposition/Docking/Ejection Procedures and Timeline

- **B. TEST REQUIREMENTS**
 - 1. Accomplish transposition, docking and LM ejection. [20.46]
 - 2. Following S-IVB TLI burn and in sunlight. [20.46]
 - S-IVB attitude and maximum limit cycle rates during docking and ejection will be in accordance with the Apollo Inter-Center ICD 80M90505, "Flight Mechanics Panel Interface Control Document for the Apollo-Saturn 505". Paragraph TBD. [20.46]
 - 4. S-IVB in inertial hold. [20.46]
 - Lighting constraints as specified in MSC/MSFC Trajectory Document No. <u>TBD</u>, "Joint Operational Mission Constraints" for Mission F will be met. [20.46]
 - 6. Photograph view through right hand rendezvous window from end of transposition until initial probe and drogue capture latching using 16 mm sequence camera with 18 mm lens and color film at 6 frames per second. [20.46]
 - 7. MSFN coverage required for entire test. [20.46]
- C. TEST PROCEDURES/CHECKLISTS
 - 1. CSM-AOH "LM Interface"
 - 2. FCAC "Separation Through Withdrawal", L9-1 through 3
- D. DATA REQUIREMENTS
 - 1. Flight Crew Reports/Logs
 - a. Comment on CSM handling characteristics during transposition and docking. [20.46] (M)
 - b. Comment on adequacy of docking alignment target on the LM . [20.46] (M)
 - c. Comment on vehicle dynamics of CSM/LM during ejection from the S-IVB-[20.46] (M)
 - d. Comment on adequacy of attitude control and stability characteristics of S-IVB prior to, during and immediately after the separation and ejection of the LM from the S-IVB/SLA- [20.46] (M)

- e. Comment on any adverse effects of the SM RCS plumes on astronaut visibility or on S-IVB stability.[20.46] (HD)
- f. Comment on adequacy of sunlight and CSM docking lights. [20,46] (HD)
- g. Comment on adequacy of contact with ground operational facilities. [20.46] (M)
- h. Log
 - (1) GET when transposition initiated. [20.46] (M)

4

- (2) Radial, angular and rotational alignment at time of initial probe and drogue contact.[20.46] (M)
- (3) Axial, radial and angular relative velocities at time of initial probe and drogue contact. [20.46] (M)
- (4) After docking, the included angle between the CM and LM Z-X planes, measured about the CM X axis.[20.46] (M)
- (5) GET when CSM/LM ejection was completed. [20.46] (M)
- (6) Separation rate during ejection. [20.46] (HD)
- 2. Photographs
 - a. Photos through right hand rendezvous window from end of CSM transposition until initial probe and drogue capture latching.
 [20.46] (HD)
 - b. Log film mag, footage in Photographic Log. [20.46] (HD)
- 3. Ground Support
 - a. CSM TM HBR.[20.46] (HD)
 - b. CSM TM LBR.[20.46] (M)
 - c. LVDC TM Data.[20.46] (M)
 - Flight Director will assess ground operational support and determine its adequacy. [20.46] (M)



FIGURE 4-1 DOCKING VELOCITY AND ALIGNMENT

PASSIVE THERMAL CONTROL MODES

A. TEST OBJECTIVES

S7.26-1 TC System for Translunar and Transearth Flight S20.79-1 PTC-Docked-Roll 0.1 DEG/SEC S20.79-2 PTC-Docked-Roll 0.3 DEG/SEC S20.79-3 PTC-CSM-Roll 0.1 DEG/SEC S20.79-4 PTC-CSM-Roll 0.3 DEG/SEC

B. TEST REQUIREMENTS

- 1. At least four uninterrupted hours for each PTC Mode. [20.79-1,2,3,4]
- 2. MSFN Coverage. [7.26, 20.79-1,2,3,4]
- Roll Modes Orient the S/C to place the X axis perpendicular to the LOS to the sun within +5 degrees attitude deadband. Roll about the X axis at the rate and within the attitude deadband specified below:
 - a. 0.1 DEG/SEC roll, pitch & yaw D/B $+20^{\circ}$
 - (1) Translunar Docked CSM/LM [20.79-1]
 - (2) Transearth CSM only [20.79-3]
 - b. 0.3 DEG/SEC roll, pitch & yaw D/B +30°
 - (1) Translunar Docked CSM/LM [20.79-2]
 - (2) Transearth CSM only [20.79-3]
- Roll jets should be disabled when the required roll rate is established & the computer procedure for PTC should be terminated before re-enabling the roll jets. [20.79-1,2,3,4]
- C. TEST PROCEDURES/CHECKLISTS
 - 1. CSM AOH 4.10.2.9 Passive Thermal Control
 - 2. FCAC, "Passive Thermal Control", G2-95
- D. DATA REQUIREMENTS
 - 1. Flight Crew Reports/Logs
 - a. Voice record of sequence of events. [20.79-1,2,3,4] (M)
 - b. Comment on ease of operation and adequacy of procedures to accomplish required communications. [20.79] (M)

- c. Comment on preferred technique for initiating and maintaining PTC. [20.79-1, 2, 3, 4] (M)
- 2. Ground Support
 - a. CSM TM HBR. [7.26, 20.79-1, 2, 3, 4] (M)

`.

- b. CSM TM LBR. [7.26, 20.79-1, 2, 3, 4] (M)
- c. BET. [20.79-1, 2, 3, 4] (M)

MIDCOURSE NAVIGATION

A. TEST OBJECTIVES

- S1.39-1 Star/Lunar Landmark Navigation Accuracy
- S1.39-2 OSS Adequacy for Star/Lunar Landmark Navigation
- S1.39-3 Crew Ability to Coordinate Optics and Vehicle Maneuvers and Identify Lunar Landmarks
- S1.39-4 RCS Propellant and Time Required Star/Lunar Landmark Navigation
- B. TEST REQUIREMENTS
 - The trunnion calibation routine of P23 to be used if more than about 30 minutes has elapsed since the previous P23 trunnion calibration. [1.39]
 - 2. The onboard state vector to be updated, utilizing the navigation sighting data, after each set of sightings. [1.39]
 - 3. MSFN coverage. [1.39]
 - Transearth, less than 30,000 NM from moon center, five Star/Lunar Landmark sightings. [1.39]
 - 5. RCS consumption data required during one tracking set. [1.39]
 - NOTE: The above sightings are defined as at least three marks on a common Star/LDMK combination.
- C. TEST PROCEDURES/CHECKLISTS
 - 1. CSM-AOH "Cislunar Navigation (P23)"
 - 2. FCAC "P23 Cislunar Midcourse Navigation Measurement", G2-26 thru 31
- D. DATA REQUIREMENTS
 - 1. Flight Crew Reports/Logs
 - a. Comments on ease of handling optics and spacecraft. [1.39] (M)
 - b. Comments on ability to identify lunar landmarks. [1.39] (M)
 - c. Log star, LMK/horizon and GET. [1.39] (M)
 - 2. Ground Support
 - a. CSM TM HBR. [1.39] (M)
 - b. CSM TM LBR. [1.39] (M)
 - c. BET. [1.39] (M)

MIDCOURSE CORRECTIONS

A. TEST OBJECTIVES

S20.95-1 GNCS, SPS & RCS Performance on Midcourse Corrections

- B. TEST REQUIREMENTS
 - 1. Perform translunar MCC with SPS or RCS while docked. [20.95]
 - 2. MSFN coverage. [20.95]
- C. TEST PROCEDURES/CHECKLISTS
 - CSM AOH "CSM/CMC Update P27"
 - 2. CSM AOH "G&N/SPS Orbit Change Thrusting (P40)" or
 - 3. CSM AOH "G&N SM RCS Orbit Change Thrusting (P41)"
 - 4. FCAC "P27 CMC Update", G2-32 and 33
 - 5. FCAC "P40 SPS Thrust", G2-44 thru 50
 - 6. FCAC "P41 RCS Thrust", G2-51 thru 54

D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
 - Comments on adequacy of procedures to prepare for and accomplish Midcourse Corrections. [20.95] (M)
- 2. Ground Support
 - a. CSM TM HBR. [20.95] (M)
 - b. CSM TM LBR. [20.95] (M)
 - c. BET. [20.95] (M)

LUNAR ORBIT INSERTION

.

A. TEST OBJECTIVES

S20.117-1 Crew/Spacecraft/MSFN Preparation and Execution of LOI Maneuver S20.117-2 Procedures and Timeline Adequacy for LOI Maneuver

- B. TEST REQUIREMENTS
 - SPS operation to insert the docked CSM/LM into lunar orbit in two stages as follows; [20.117]
 - a. The first burn of approximately 352 seconds in duration will insert the CSM into a 60×170 NM orbit.
 - b. The second burn of approximately 10 seconds in duration will circularize the orbit to 60 NM.
 - 2. DSE recording 40 seconds before, during and 2 minutes after both burns. [20.117]
 - IMU realignment performed as soon prior to LOI-1 as practicable. [20.117]
 - 4. MSFN tracking prior to LOS before LOI. [20.117]
 - 5. MSFN record dumped DSE data at AOS after LOI. [20.117]
- C. TEST PROCEDURES/CHECKLISTS
 - 1. CSM AOH "G&N SPS Orbit Change Thrusting (P40)"
 - 2. FCAC "SPS Thrusting (P40)", G2-44 thru 50

D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
 - a. Procedural and/or timeline difficulties or inadequacies. [20.117] (M)
 - b. Feasibility of monitoring abort parameters on FDAI's. [20.117] (M)
 - c. Adequacy of contact with ground operational support facilities. [20.117] (HD)
- 2. Ground Support
 - a. CSM TM LBR from DSE after AOS. [20.117] (M)

b. CSM TM HBR from DSE after AOS. [20.117] (HD)

•

- c. BET before LOS and after AOS. [20.117] (M)
- d. Flight Director's reports of procedural and/or timeline difficulties or inadequacies. [20.117] (M)

LM SENSOR BIASES

.

A. TEST OBJECTIVES

S11.17-1 LM PGNCS PIPA Bias During Coasting Flight S12.6-1 AGS Gyro Bias and Accelerometer Data and PGNCS Gyro Data During Drifting Flight

- **B. TEST REQUIREMENTS**
 - 1. MSFN collection of LM PGNCS PIPA bias data at least three times during the mission using uninterrupted TM for at least five minute intervals as follows: [11.17]
 - a. During LM systems activation and checkout.
 - b. During LM activation prior to rendezvous.
 - c. After LM rendezvous.
 - 2. IMU and LGC on [11.17, RCS off. [11.17, 12.6]
 - 3. MSFN collection of AGS gyro bias and accelerometer data and PGNCS gyro data during drifting flight using uninterrupted TM for at least five minutes. [12.6]
 - 4. MSFN coverage. [11.17, 12.6]
- C. DATA REQUIREMENTS
 - 1. LM TM HBR. [11.17 , 12.6] (M)

LM IMU ALIGNMENT

- A. TEST OBJECTIVES
 - S11.17-2 PGNCS IRIG Drift Rates During Coasting Flight

٠.

- B. TEST REQUIREMENTS
 - One set of back-to-back LM IMU alignments during coasting flight. [11.17] N.I.
 - At least one hour between IMU alignments with no intervening thrust maneuvers. [11.17] N.I.
 - 3. PGNCS powered up between alignments in a set. [11.17]
 - 4. MSFN coverage. [11.17]

C. TEST PROCEDURES/CHECKLISTS

- 1. LM-AOH "IMU Orientation Determination Program (P51)" or
- 2. LM AOH "IMU Realign (P52)"
- 3. FCAC "P51 IMU Orientation" or
- 4. FCAC "P52 IMU Realign"

D. DATA REQUIREMENTS

LM TM HBR following the second alignment of each set of alignments. [11.17] (M) N.I.

A. TEST OBJECTIVES

P20.91-1 Error Uncertainties - LDMK Tracking
P20.91-2 Crew Coordination of Sighting and Maneuvers
P20.91-3 RCS Propellant and Time Required Docked
P20.91-4 Adequacy of Equipment for LDMK Tracking Docked
P20.91-5 Low Sun Angle LDMK Tracking Evaluation
P20.121-1 Improve Lunar Gravity Model
P20.121-2 Adequacy of Equipment for LDMK Tracking Undocked
P20.121-3 RCS Propellant and Time Required Undocked

- B. TEST REQUIREMENTS
 - 1. IMU must be realigned on the dark side preceding each tracking pass. [20.91, 20.121]
 - MSFN coverage is reacquired on each earth side pass. [20.91, 20.121]
 - Time between marks should be a minimum of 25 seconds [20.91, 20.121]
 - First mark with S/C 45 to 55⁰ above local horizontal. [20.91, 20.121]
 - 5. MSFN will support the tracking schedule with updates if necessary. If HBR TM data cannot be recorded in real time by MSFN, the data will be recorded on the DSE and dumped at the first opportunity during the same revolution. [20.91, 20.121]
 - 6. With CSM/LM docked, track each of the following one time:
 - a. One preselected landmark on the orbit preceding undocking. [20.91]
 - b. Surveyor spacecraft. [20.91]
 - c. A landmark at a sun elevation approximately 3 degrees.
 [20.91]
 - 7. With the CSM/LM undocked one day after rendezvous, track each of the following three landmarks on each of four orbits:
 - a. One landmark 27 degrees after the morning terminator. [20.121]
 - b. The second landmark 57 degrees after the morning terminator. [20.121]
 - c. The third landmark 8 degrees before the evening terminator. [20.121]

Photograph the above landmark through the S/C window using the highest resolution camera/lens combination. [20.121]

- C. TEST PROCEDURES/CHECKLISTS
 - 1. CSM-AOH "Orbital Navigation (P22)"
 - 2. FCAC "P22 Orbital Navigation," G2-18 thru 24
- D. DATA REQUIREMENTS
 - 1. Flight Crew Reports/Logs
 - a. Comments on ease of handling optics and spacecraft. [20.91, 20.121] (M)
 - b. Comments on minimum sun elevation angle for lunar LDMK tracking.
 [20.91] (M)
 - c. Comments on the lunar landmark recognition on each successive revolution. [20.91, 20.121] (M)
 - d. "Landmark Tracking Log" (Flight Plan) [20.91, 20.121] (M)
 - e. Photographs of Landmarks. [20.121] (HD)
 - 2. Ground Support
 - a. BET. [20.91] (M)
 - b. CSM TM HBR from DSE after AOS. [20.91] (M) [20.121] (HD)
 - c. CSM TM LBR from DSE after AOS. [20.91, 20.121] (M)

LM INSPECTION BY CSM

A. TEST OBJECTIVES

S20.86-1	Illumination and Time Required for CSM Inspection of LM
\$20.86-3	Visual Phenomena Observed from CSM During LM Inspection and LM Descent and Ascent

B. TEST REQUIREMENTS

- 1. Undocked. [20.86]
- 2. CSM pilot visually inspects LM in lunar orbit prior to DOI. [20.86]
- C. DATA REQUIREMENTS
 - CSM pilot comment on illumination of LM and any unexpected visual phenomena during LM inspection. [20.86] (M)
 - CSM pilot comment on adequacy of time allotted for LM inspection. [20.86] (HD)

low
null ation
ec
in
through
t

à

A. TEST OBJECTIVES -

PII.15-2	Capadility of PGNLS to Execute the DUI Maneuvers
s1 3.14-1	Supercritical Helium Pressure Profile
S16.14-2	No Velocity/Altimeter Frequency Tracker Lock On to Spurious
	Doppler Signals
S20.82-1	Ground Monitoring of LM PGNCS/AGS
S20.82-2	Crew Monitoring of LM PGNCS/AGS
S20.86-2	Optical Tracking of LM by CSM Pilot During LM Descent to
	50,000 Feet
S20.86-3	Unusual Visual Phenomena Observed by the CSM Pilot During
	LM Descent to 50,000 Feet

- B. TEST REQUIREMENTS
 - 1. DOI, including orientation, to be performed under PGNCS control with DPS. [11,15]
 - 2. Burn profile to be the same as that planned for the LLM. (HD) [11.15]
 - 3. CSM pilot to track LM with the SXT. [20.86]
 - 4. DSE on HBR while taking marks and processing data. [20.86]
 - 5. VHF ranging required during tracking. [20.82, 20.86]
 - 6. LR to be operated during DOI/DPS burn with antenna in position 1. [16.14]
 - 7. LM crew displays, procedures and computational aids shall be used in monitoring LM PGNCS/AGS performance to determine if guidance should be transferred at any point during the burn. [20.82]

C. TEST PROCEDURES/CHECKLISTS

- LM AOH paragraph 4.10.1, "DPS Thrust Program (P40) with AGS Follow-Up/ In Control"
- 2. CSM AOH paragraph 4.6.2, "CSM Rendezvous Navigation", steps 1 through 7
- 3. FCAC, "P20 Rendezvous Navigation", G2-15
- 4. LM AOH paragraph 4.6.3.2, "Landing Radar Power Up"

D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
 - a. Confirm that false LR lock did not occur. [16.14] (HD)

- Comments on adequacy of procedures necessary to accomplish the DOI. [11.15] (M)
- c. Comments on PGNCS performance during DOI. [11.15] (HD)
- d. CSM pilot comments on LM tracking with SXT during LM descent including GET of loss of view. [20.86] (HD)
- Comments on any significant unexpected visual phenomena.
 [20.86] (M)
- f. Record LR antenna temperature at end of DPS burn and two minutes later. [16.14] (HD)
- g. Comments on adequacy of LM displays, onboard procedures and onboard charts used to perform guidance monitor functions during lunar orbit operations. [20.82] (M)
- h. Comments on adequacy and clarity of MSFN data concerning PGNCS/ AGS residuals during lunar orbit operations as furnished by voice link to the LM. [20.82] (M)
- Comments on adequacy and clarity of GNCS and VHF derived range rate data as furnished by voice link from the CM to the LM. [20.82] (M)
- 2. Ground Support
 - a. LM TM LBR [1].15, 13.4-1, 16.14] (M), recorded on DSE
 - b. BET LM [11.15, 20.86] (M); BET CSM/LM [20.82] (HD); [20.86] (M)
 - c. Flight Director's reports of timeline and/or procedural difficulties.
 (M)
 - d. Real time S-band ranging data from LM. [20.82, 20.86] (M)
 - e. Real time S-band ranging data from CSM. [20.82, 20.86] (HD)
 - f. MSFN doppler data during powered phases. [20.82, 20.86] (M)
 - g. CSM TM HBR. [20.86] (M)

NEAR LUNAR SURFACE ACTIVITY

A. TEST OBJECTIVES

P16.10-3 Evaluate Steerable Antenna During Simulated "G" Descent Maneuvers

- P16.14-1 Lock on for Landing Radar Beams and Generation of Velocity/Altitude Data
- S20.86-4 Extent/Severity of Washout When Viewing the Lunar Surface from the LM

B. TEST REQUIREMENTS

- 1. Landing radar to be operated during the 200 sec. period prior to and during the 200 sec. period after pericynthion.
 - a. LR antenna in position 2. [16.14]
 - b. Constant pitch rotation rate of .052 deg/sec. (Lunar Orb. Rate). [16.14]
 - c. LM +X axis vertical, +Z axis forward, 0 degrees yaw. [16.14]
 - d. Roll angle 0 (± 1) degree. [16.14]
 - e. Altitude above lunar surface not to exceed 10 NM. [16.14]
 - f. Steerable antenna operational procedures to be exercised during 180° roll face up and 90° pitch up to local vertical. [16.10]
- Commander to observe lunar surface near point of closest approach. [20.86]

C. TEST PROCEDURES/CHECKLISTS

- 1. LM AOH paragraph 4.6.3.2, "Landing Radar Power-Up"
- 2. LM AOH paragraph 4.6.3.4, "Landing Radar Checkout"

D, DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
 - a. Commander comments on extent and severity of observed surface washout. [20.86] (M)
 - b. LPD coordinates defining the area of loss of useful detail and time of observation. [20.86] (M)
 - c. Data <u>TBD</u> for the steerable antenna test. [16.10] (M)

- 2. Ground Support
 - a. BET [16.14] (M)

Ь. LM TM HBR [16.14] (М)

- c. LM TM LBR [16.14] (M)
- d. MSFN records of received S-band signal strength. [16.10] (M)

NEAR LUNAR SURFACE ACTIVITY

P16.10 LM/MSFN Comm Lunar Distance P16.14 Landing Radar S20.86 Lunar Surface Washout.

REQUIRED

LR Powered Up Ordeal - Orb Rate Steerable Antenna - MSFN Acquisition To - Pericynthion Antenna Position - 2

PROCEDURE

To -900 Sec. Acquire MSFN (Steerable Antenna) Yaw Right 180° (Face Down to Face Up) Pitch Up to Within 10° of Local Vertical Start Orbit Rate $\approx .052$ Deg/Sec Pitch Down To -400 Sec, Checkout LR To -200 Sec, Pitch Down 10° To Local Vertical Observe Lunar Surface Through Front Window Use LPD Markings to Designate Washout Area Record Washout Area Coordinates and Time Observed

	TO		DEG.			HRS.
	TO		AHEAD	x		MIN.
			BEHIND	X		SEC.

To +200 Sec, Pitch Down 90° (Face Down) Observe Landing Site (Photographs HD) Terminate LR Test Terminate Orbit Rate To +600 Sec, Mnvr to Phasing Burn Attitude



ORBIT RATE (0.05 DEG/SEC PITCH DOWN) FROM -400 TO + 200 SEC FROM PERICYNTHION

FIGURE 4-2 NEAR LUNAR SURFACE ACTIVITY

PHASING

4

A. TEST OBJECTIVES

P11.15-1	Capability of the PGNCS to Execute a DPS High Thrust Level Undocked Maneuver
\$11.17-3	Overall PGNCS Errors During Thrusting Maneuvers
\$12.6-1	AGS Overall Inertial Sensor Performance During an Undocked DPS Burn at Fixed Throttle
s13.14-1	Supercritical Helium Pressure Profile
S16.14-2	No Velocity/Altimeter Frequency Tracker Lock On to Spurious Doppler Signals
S20.82-1	Ground Monitoring of LM PGNCS/AGS
S20.82-2	Crew Monitoring of LM PGNCS/AGS

B. TEST REQUIREMENTS

- 1. At least 15 seconds of phasing DPS burn to be performed at a thrust level of 40 percent or higher, [11.15] with fixed throttle. [12.6].
- 2. AGS to be aligned to PGNCS prior to DPS burn. [12.6]
- 3. AGS sensor performance data and LM IMU performance data to be acquired during the DPS burn at fixed throttle point. [11.17, 12.6]
- 4. LR to be operated in position 2 during the DPS burn. [16.14]
- 5. MCC data, displays, procedures and computations shall be utilized in support monitoring of LM PGNCS/AGS performance to permit recommending guidance transfer if necessary in real time. [20.82]
- 6. LM crew displays, procedures and computational aids shall be used in monitoring LM PGNCS/AGS performance to determine if guidance should be transferred at any point during the burn. [20.82]
- 7. MSFN coverage. [11.17, 11.15]
- C. TEST PROCEDURES/CHECKLISTS
 - 1. LM AOH paragraph 4.10.1, "DPS Thrust Program (P40) With AGS Follow-Up/ In Control"
 - 2. LM AOH paragraph 4.9.2.1, "PGNCS/AGS Align"
 - 3. LM AOH paragraph 4.6.3.2, "Landing Radar Power Up"

D. DATA REQUIREMENTS

- Flight Crew Reports/Logs
 - a. Comments on adequacy of procedures necessary to accomplish the high thrust maneuver. [11.15] (M)
 - b. Comments on PGNCS performance during the high thrust maneuver and on control response during start and throttle up periods. [11.15] (HD)
 - c. Confirm that false LR lock did not occur. [16.14] (HD)
 - d. Record LR antenna temperature at end of DPS burn and two minutes later. [16.14] (HD)
 - e. Comments on adequacy of LM displays, onboard procedures and onboard charts used to perform guidance monitor functions during lunar orbit operations. [20.82] (M)
 - f. Comments on adequacy and clarity of MSFN data concerning PGNCS/AGS residuals during lunar orbit operations as furnished by voice link to the LM. [20.82] (M)
 - g. Comments on adequacy and clarity of GNCS and VHF derived range rate data as furnished by voice link from the CM to the LM. [20.82] (M)

2. Ground Support

- a. MSFN tracking 60 seconds prior to, during and 60 seconds after the high thrust maneuver. [11.15] (M)
- b. BET LM [11.15] (M); BET CSM/LM [20.82] (HD)
- c. LM TM HBR [11.17, 11.15, 12.6, 16.14, 20.82] (M)
- d. LM TM LBR [13.14-1, 16.14, 20.82] (M)
- e. Flight Director reports of timeline/procedural difficulties. (M)
- f. Real time S-band ranging data from LM. [20.82] (M)
- g. Real time S-band ranging data from CSM. [20.82] (HD)
- h. MSFN doppler data during powered phases. [20.82] (M)
- AGS/PGNCS downlink data on uninterrupted TM for at least 5 minutes during drifting flight prior to phasing with astronaut motions minimal. [12.6] (M)
INSERTION AND RENDEZVOUS

A. TEST OBJECTIVES

S12.10-1	Capability of AGS to Perform Guidance Functions Required to
	Accomplish a CFP Rendezvous
S12.10-2	AGS/CES Performance During an RCS △V Maneuver
\$16.15-1	RR Capability of Monitoring Lock Near Maximum Range
\$16.15-2	Accuracy of RR Range Data Obtained Near Maximum Range
\$16.15-3	Accuracy of RR Range Rate Data Obtained Near Maximum Range
\$16.15-4	RR Tracking Angle Data Near Maximum Range
\$16.15-5	LM -X RCS Plume Effects On RR at Maximum Range
\$20.77-1	Accuracy of VHF Ranging
S20.78-1	Demonstrate Nominal LM Rendezvous in Lunar Orbit
S20.78-2	Update Simulations Data for Nominal LLM Rendezvous
\$20.82-1	Ground Monitoring of LM PGNCS/AGS
S20.82-2	Crew Monitoring of LM PGNCS/AGS
S 20.86-2	Optical Tracking of LM by CSM Pilot During LM Ascent From
	50.000 Feet
S 20.86-3	Unusual Visual Phenomena Observed by CSM Pilot During LM
	Ascent From 50,000 Feet

B. TEST REQUIREMENTS

- AGS to be aligned to PGNCS per "PGNCS/AGS Align" prior to insertion. [12.10]
- AGS to be updated per "AGS Initialization Routine (R47)" prior to APS insertion burn. [12.10]
- 3. RR to be operated as much as feasible with SC separation distance between 350 and 450 NM. [16.15]
- 4. LM/CSM orientation at a separation of at least 300 NM to be such that the LM RR beam will illuminate the CSM transponder beam. [16.15]
- 5. LM -X RCS engines 1U and 4U to be fired at least once while the RR is tracking the CSM transponder at a range of 300 to 400 NM. [16.15]
- 6. Solutions for all rendezvous maneuvers through TPF to be computed by PGNCS, MSFN, GNCS and AGS. [12.10]
- 7. All PGNCS, AGS, GNCS solutions for the CFP maneuvers will be compared to MSFN solutions prior to $\triangle V$. [20.78] (CSI not implemented)
- 8. PGNCS solutions to be used for targeting all burns. [12.10, 20.78]
- 9. All burns except CDH under PGNCS control. [20.78]
- 10. CDH burn to be under AGS/CES control. [12.10]

- 11. AGS state vector to be updated every 3 minutes from CDH +10 minutes to TPI. [12.10]
- 12. Prior to TPI, AGS to be updated for the last time. [12.10]
- 13. AGS will not be used as a reference post TPI. [12.10]

4

- 14. MCC data, displays, procedures and computations shall be utilized in support monitoring of LM PGNCS/AGS performance to permit recommending guidance transfer if necessary in real time. [20.82]
- 15. LM crew displays, procedures and computational aids shall be used in monitoring LM PGNCS/AGS performance to determine if guidance should be transferred at any point during the burn. [20.82]
- 16. CSM pilot to track LM with SXT from insertion through Rendezvous. [20.86]
- 17. DSE on HBR for all burns conducted during MSFN LOS. [20.77]
- 18. VHF ranging required during tracking except during DPS/APS burns conducted outside the MSFN line-of-sight. [20.77, 20.82, 20.86]
- C. TEST PROCEDURES/CHECKLISTS
 - 1. LM AOH paragraph 4.9.2.1, "PGNCS/AGS ATign"
 - 2. LM AOH paragraph 4.6.1.18, "AGS Initialization Routine (R47)"
 - 3. LM AOH paragragh 4.8.2.2, "AGS Manual Rendezvous Radar LM State Vector Update"
 - 4. CSM AOH paragraph 4.6, "Rendezvous"
 - 5. LM AOH paragraph 4.6.3.1, "Rendezvous Radar Power Up"
 - CSM AOH paragraph 4.7.6.9, "Rendezvous Transponder Activation and Self Test"
 - 7. MSC Document, "LM Rendezvous Procedures F Mission"
 - 8. FCAC, "P17 TPI Search or P77 LM TPI Search", G2-14
 - 9. FCAC, "P20 Rendezvous Navigation", G2-15
 - 10. FCAC, "P34 TPI Prethrust (P74 LM)", G2-38
 - 11. FCAC, "P35 TPM Prethrust (P75 LM)", G2-39
 - 12. FCAC, "P38 SOR Targeting (P78 LM)", G2-42

- 13. FCAC, "P39 Stable Orbit Mid (P79 LM)", G2-43
- 14. FCAC, "V83 Rndz Parameter Display #1", G2-73
- 15. FCAC, "V85 Rndz Parameter Display #2", G2-74
- 16. FCAC, "V90 Out of Plane Display", G2-75

- 1. Flight Crew Reports/Logs
 - a. Comments on adequacy of AGS/CES procedures and performance during the CDH burn. [12.10] (HD)
 - b. Comments on ability to maintain RR lock at a range greater than 350 NM. [16.15] (HD)
 - c. GET ± 1 minute at any deliberate break of RR lock. [16.15] (M)
 - d. Min/Max transponder AGC voltage readings during LM -X RCS firings. [16.15] (HD)
 - e. Comments on planned and actual crew procedures used. [20.78] (M)
 - f. Comments on AGS & RR performance. [20.78] (M)
 - g. Comments on PGNCS & RR performance. [20.78] (M)
 - h. Comments on single crewmember LM rendezvous capability.
 [20.78] (M)
 - i. Comments on usefulness of CSM rendezvous beacon light. [20.78] (M)
 - j. CSM crewman comments on adequacy of rendezvous procedures using VHF ranging and optics. [20.77] (M)
 - Rendezvous targeting solution data as recorded by the CSM and LM crewman. [20.77] (M)
 - Comments on adequacy of LM displays, onboard procedures and onboard charts used to perform guidance monitor functions during lunar orbit operations. [20.82] (M)
 - m. Comments on adequacy and clarity of MSFN data concerning PGNCS/ AGS residuals during lunar orbit operations as furnished by voice link to the LM. [20.82] (M)
 - n. Comments on adequacy and clarity of GNCS and VHF derived range rate data as furnished by voice link from the CM to the LM. [20.82] (M)

- 4
- o. Comments on LM tracking with SXT. [20.86] (HD)
- p. Comments on significant unexpected visual phenomena. [20.86] (M)
- 2. Ground Support
 - a. BET of CSM and LM [16.15, 20.77, 20.78, 20.86] (M); [12.10, 20.82] (HD)
 - b. MSFN tracking data prior to, during and after CDH burn. [12.10] (M)
 - c. Flight Director's Post Mission Report. [20.78] (M)
 - d. LM TM HBR [12.10, 16.15, 20.78, 20.82] (M)
 - e. LM TM LBR [12.10, 20.82] (M); [16.15, 20.78] (HD)
 - f. Real time S-band ranging data from LM. [20.82, 20.86] (M)
 - g. Real time S-band ranging data from CSM. [20.82, 20.86] (HD)
 - h. MSFN doppler data during powered phases. [20.82, 20.86] (M)
 - i. CSM TM LBR [12.10, 16.15, 20.78] (M); [20.82] (HD)
 - j. CSM TM HBR [20.86] (M)
 - k. MSFN-RTCC trajectory profile. [20.77] (M)

STATION KEEPING

A. TEST OBJECTIVES

S12.8-1 AGS Automatic Attitude Hold - Min. Deadband S12.8-2 AGS Automatic Attitude Hold - Max. Deadband S12.8-3 Deleted S12.8-4 Deleted S12.8-5 AGS Manual Attitude Control - Pulsed Mode S12.8-6 AGS Manual Attitude Control - Proportional Rate S12.8-7 AGS Manual Translation Control S12.8-8 RCS Propellant Usage During AGS Control P20.78-2 Update Simulations Data for Nominal LLM Rendezvous

- B. TEST REQUIREMENTS
 - 1. AGS/CES attitude hold/control and translation to be demonstrated with a staged LM. [12.8]
 - MSFN coverage required for all modes. [12.8]
 - The following modes are to be demonstrated during normal operation or as special tests.
 - a. Automatic hold in minimum deadband. MSFN coverage required with HBR for 0.5 minute. It is HD that the vehicle rates exceed 1 deg/sec in all axes prior to enabling attitude hold. [12.8]
 - b. Automatic hold in maximum deadband. MSFN coverage required with HBR for 5 minutes. It is HD that the vehicle rates exceed 1 deg/sec in all axes prior to enabling attitude hold. [12.8]
 - c. Manual attitude control using minimum pulse mode. [12.8]
 - (1) Two jets operation, pitch and roll.
 - (2) Four jets operation, yaw.
 - d. Manual attitude control using proportional rate command in all axes (+ and -). [12.8]
 - e. Manual translation control in + and axes using THC. [12.8]
- C. TEST PROCEDURES/CHECKLISTS
 - 1. LM AOH paragraph 4.10.5, "AGS RCS Axis-by-Axis Thrust"
 - 2. LM AOH Paragraph 4.5.1.6 "AGS Attitude Hold/Rate Command

- 1. Flight Crew Reports/Logs
 - a. Initial body rates prior to auto attitude control. [12.8] (M)
 - b. Time auto attitude hold demonstration/periods begin. [12.8] (M)
 - c. Time interval of attitude error zero crossings in each axis for the min/max deadband attitude hold demonstrations. [12.8] (M)
 - d. Comments on the success of controlling the S/C in each of the mannual attitude control modes. [12.8] (M)
 - e. Comments on the success of manually controlling the S/C during the translation maneuver. [12.8] (M)
 - f. Comments regarding any unusual torques or venting detected. [12.8] (HD)
- 2. Ground Support
 - a. LM TM HBR [12.8] (M)
 - b. LM TM LBR [12.8] (M)
 - c. BET CSM/LM [20.78] (M)

```
AGS CONTROL AND MANEUVER CAPABILITY
S12.8 AGS/CES Attitude/Translation Control
Required:
  LM Staged
  TM - HBR
  AGS Control
  Demonstrate the Following:
    a) Automatic attitude hold - Min Dbnd
                                 Max Dbnd
    b) Manual attitude control - Prop Rate
                                 Pulse Mode
    c) Manual translation control
Procedure
. Guidance Control - AGS
  Mode Control - Attitude Hold
  Attitude Control R, P, Y - Mode Cont
  Deadband - Max
  ACA - Mnvr S/C to any New Attitude. Exceed 1.0 Deg/
         Sec. in All Axis During Maneuver
  Start Attitude Hold
  GET
  Allow 5 Min. Attitude Hold With Continuous TM
    Coverage
  Deadband - Min
  ACA - Maneuver S/C To Any New Attitude. Exceed
    1º/Sec. In All Axis During Maneuver
  Start Attitude Hold
  GET
  Allow 0.5 Min. Attitude Hold With Continuous TM
    Coverage
  Attitude Control R, P, Y - Pulse
  ACA - Maneuver S/C About 3 Axis (Free Drift)
  Attitude Control, R, P, Y - Mode Control
  TTCA Lever - Down
  TTCA - Translate S/C Along All 3 Axis In The
    + and - Directions
```

APS BURN TO DEPLETION

4

A. TEST OBJECTIVES

SI1.17-3 Overall PGNCS Errors During Thrusting Maneuvers

- S12.9-1 AGS Controlled APS Burn Over An Extended Range Of Inertias
- S12.9-2 Deleted
- S12.9-3 RCS Fuel Consumption
- S13.13-1 APS Performance Characteristics
- S13.13-2 APS Propellant Depletion Shutdown Hazard Determination

B. TEST REQUIREMENTS

- 1. LM IMU performance data to be obtained by TM. [11.17]
- Crew to preset LM switching prior to leaving LM for subsequent MCC control. [12.9]
 - a. Set mode control switch to AUTO.
 - b. Close the ABORT switch.
 - c. Set AGS DEDA address 616 to 0.
- 3. PGNCS to be programmed as if it were controlling the burn. External $\triangle V$ prethrust program P30 will be called and targeting parameter input VIA the uplink. P42 will be called prior to initiation of the burn. [12.9]
- 4. Continuous tracking and telemetry data are required for a delta velocity of at least 1000 feet per second. [12.9]
- 5. The APS burn will be AGS controlled to depletion with the ascent engine operating continuously for a minimum duration of 100 seconds. [13.13]
- C. TEST PROCEDURES/CHECKLISTS
 - 1. LM AOH paragraph 4.10.6, "APS Burn to Depletion"
- D. DATA REQUIREMENTS
 - 1. LM TM HBR [11.17, 13.13] (M)
 - 2. LM TM LBR [12.9, 13.13] (M)
 - 3. BET [12.9, 13.13] (M)
 - Preflight data on isolation value inlet pressures and tank temps from servicing to launch. [13.13] (M)

A. TEST OBJECTIVES

Β.

-

S6. P16 P16 P16 S16 S16 S16 S16 S16 S16 S16	 9-1 CSM High Gain Antenna Reflectivity 5.10-1 LM Steerable Antenna Comm Modes at 5.10-2 Verify LM Steerable Antenna on Tar 5.10-3 Evaluate Steerable Antenna Procedu Simulate Descent to Lunar Surface 5.12-1 LM Omni Antenna Comm Modes at Luna 5.12-1 LM Omni Antenna Comm Modes at Luna 5.17-1 CSM/LM/MSFN Simultaneous Voice Comference via S 5.17-2 LM/MSFN/CSM Voice Conference via S 5.17-3 LM/CSM/MSFN Voice Conference via S 5.17-4 Simultaneous LM Voice/LBR Transmis Dumping to MSFN 5.17-5 LM/CSM via VHF, LM/MSFN via S-Band 	with CSM/LM Docked Lunar Distance, Docked/Undocked get Gain mes During Maneuvers That r r Distance, Docked/Undocked munications Using S-Band & VHF -Band using MSFN as Voice Relay -Band and VHF using CSM as sion to CSM with CSM Recording/ I, LM Relay.			
TES	ST REQUIREMENTS				
۱.	Lunar distance or equivalent is defined	as: [6.9]			
	a. 200K NM with 85' ground antenna.				
	b. 110K NM with 30' ground antenna cooled.				
	c. 70K NM with 30' ground antenna uncoo	oled.			
2.	. Manual acquisition will be demonstrated using wide beam width. [6.9]				
3.	3. Automatic tracking will be demonstrated with the CSM high gain antenna using wide, medium and narrow beamwidths. [6.9]				
4.	<u>Tes tş</u>	Signal Combination (M)			
	a. Reflectivity Lunar Distance or Equivalent [6.9] (3 designated attitudes)	7.8			
	b. LM Steerable Antenna Lunar Distance [16.10]	6.2, 8.4 and 6.7			
	c. LM Omni Lunar Distance [16.12]	6.4, 6.1, 6.15 and 6.2			
5.	LM steerable antenna data will be obtain gain at lunar distance. [16.10]	ed to verify on target			
6.	LM steerable antenna operational procedures will be performed to simulate maneuvers during LM descent to the lunar surface. [16.10]				
7.	At least one signal combination while docked and at least one signal combination while undocked. [16.10]				

A. TEST OBJECTIVES

Β.

-

S6. P16 P16 P16 S16 S16 S16 S16 S16 S16 S16	 9-1 CSM High Gain Antenna Reflectivity 5.10-1 LM Steerable Antenna Comm Modes at 5.10-2 Verify LM Steerable Antenna on Tar 5.10-3 Evaluate Steerable Antenna Procedu Simulate Descent to Lunar Surface 5.12-1 LM Omni Antenna Comm Modes at Luna 5.12-1 LM Omni Antenna Comm Modes at Luna 5.17-1 CSM/LM/MSFN Simultaneous Voice Comference via S 5.17-2 LM/MSFN/CSM Voice Conference via S 5.17-3 LM/CSM/MSFN Voice Conference via S 5.17-4 Simultaneous LM Voice/LBR Transmis Dumping to MSFN 5.17-5 LM/CSM via VHF, LM/MSFN via S-Band 	with CSM/LM Docked Lunar Distance, Docked/Undocked get Gain mes During Maneuvers That r T Distance, Docked/Undocked munications Using S-Band & VHF -Band using MSFN as Voice Relay -Band using MSFN as Voice Relay -Band and VHF using CSM as sion to CSM with CSM Recording/ I, LM Relay.			
TES	ST REQUIREMENTS				
۱.	Lunar distance or equivalent is defined	as: [6.9]			
	a. 200K NM with 85' ground antenna.				
	b. 110K NM with 30' ground antenna cooled.				
	c. 70K NM with 30' ground antenna uncoo	oled.			
2.	. Manual acquisition will be demonstrated using wide beam width. [6.9]				
3.	3. Automatic tracking will be demonstrated with the CSM high gain antenna using wide, medium and narrow beamwidths. [6.9]				
4.	<u>Tes tş</u>	Signal Combination (M)			
	a. Reflectivity Lunar Distance or Equivalent [6.9] (3 designated attitudes)	7.8			
	b. LM Steerable Antenna Lunar Distance [16.10]	6.2, 8.4 and 6.7			
	c. LM Omni Lunar Distance [16.12]	6.4, 6.1, 6.15 and 6.2			
5.	LM steerable antenna data will be obtain gain at lunar distance. [16.10]	ed to verify on target			
6.	LM steerable antenna operational procedures will be performed to simulate maneuvers during LM descent to the lunar surface. [16.10]				
7.	At least one signal combination while docked and at least one signal combination while undocked. [16.10]				

- 8. Simultaneous voice communications between the CSM and MSFN by S-band and between the LM and MSFN via S-band and between the LM and CSM via VHF will be demonstrated in the undocked configuration, using the S-band steerable antenna, CSM HI gain antenna and VHF inflight antennas. [16.17]
- 9. Voice conference capability among the LM, MSFN and the CSM will be demonstrated in the docked configuration using the LM S-band steerable and CSM High Gain antennas with MSFN acting as voice relay. [16.17]
- 10. Voice conference communications among the LM, CSM and MSFN will be demonstrated in the docked configuration using VHF voice communications between the LM and the CSM with CSM providing voice relay to MSFN via S-band. Use VHF inflight and CSM HI Gain antenna. [16.17]
- 11. LM voice will be transmitted via VHF-A simultaneous with LBR TM via VHF-B. The LM voice and LBR will be recorded by the CSM DSE. The LM TM data will be dumped by the CSM to MSFN via S-band FM mode 3. The LM voice data will be dumped by the CSM to MSFN via S-band FM mode 2. Use VHF inflight and CSM HI Gain antenna. [16.17]
- 12. Voice conference communications among the CSM, LM and MSFN will be demonstrated in the docked configuration using VHF voice between the CSM and LM and S-band voice between the LM and MSFN with LM relay. Use VHF inflight antennas and the LM steerable antenna. [16.17]
- C. TEST PROCEDURES/CHECKLISTS
 - 1. CSM AOH paragraph 4.7.6, "Telecommunications"
 - 2. FCAC, "Telecomm Procedures", S2-19
 - 3. LM AOH paragraph 4.13.2, "Communications"

- 1. Flight Crew Reports/Logs
 - a. Comments on adequacy of communications quality and procedures.
 [6.9, 16.10, 16.17] (M) [16.12] (HD)
 - b. Time/Pitch/Yaw/S-Band antenna information to be recorded during the S/C reflectivity tests. [6.9] (M)
 - c. Data TBD for the steerable antenna pattern coverage test. [16.10] (M)
 - d. Data acquired during simulated LM descent to lunar surface maneuvers concerning S-Band antenna procedures. [16.10] (M)
 - e. LM tape recording of MSFN voice. [16.10] (M)
 - f. LM recording of CSM, MSFN and MSFN relayed to CSM voice. [16.17] (M)

- 2. Ground Support
 - a. BET CSM [6.9] (M)
 - b. Post Launch Instrumentation Message containing information on adequacy of CSM/MSFN communication procedures and quality. [6.9, 16.10, 16.12] (HD)
 - c. Unified S-band telemetry bit stream. [16.10, 16.12] (M)
 - d. Unified S-band tracking data processor output. [6.9, 16.10] (M)
 [16.12] (HD)
 - e. BET LM [16.10] (M) [16.12] (HD)

4

- f. Flight Director's Post-Mission Report [6.9] (M) [16.10, 16.12] (M)
- g. MSFN tape recording of LM voice. [16.10, 16.12, 16.17] (M)
- h. MSFN records of received S-band signal strength. [16.10, 16.12] (M)
- i. LM TM HBR [16.10, 16.12] (M)
- j. LM TM LBR [16.10, 16.12] (M)
- k. MSFN tape recording of LM emergency key mode. [16.12] (HD)
- 1. MSFN recording of CSM voice. [16.17] (M)
- m. MSFN recording of CSM playback of LM LBR TM. [16.17] (M)
- n. MSFN recording of CSM playback of LM voice. [16.17] (M)
- o. MSFN recording of the LM voice relayed from the CSM. [16.17] (M)
- p. LM recording of MSFN voice. [16.17] (M)
- q. LM recording of CSM voice. [16.17] (M)
- r. LM recording of MSFN voice for CSM. [16.17] (M)

CSM COMMUNICATIONS TEST S6.9 CSM High Gain Antenna Reflectivity **PROCEDURE** MNVR R 71.5 P 323.8 Y 318.5 (PTC REFSMMAT) R P Y COMMUNICATIONS MODE 7.8 SWITCH CONFIGURATION - BASIC, EXCEPT S-BAND RANGING - OFF SET UP HGA OPERATION (HGA pitch -10° , yaw 340°) ATTITUDE HOLD - MAX D/B, LOW RATE STEPS 1 THROUGH 7, COLUMN 1 1. VERIFY HGA TWO WAY LOCK 2. MNVR S/C TO - PITCH (HGA METER) $\frac{1}{-10^{\circ}}$ $\frac{2}{-20^{\circ}}$ $\frac{3}{-30^{\circ}}$ YAW (HGA METER) 340° 350° 360° 3. SET HGA CNTL POSITION - PITCH -10° -20° -30° 320° 330° 340° YAW 4. BEAM WIDTH - WIDE, TRACK SW - MANUAL (when HGA indicators compare to cntl settings) 5. TRACK SW - AUTO, BEAM WIDTH - NARROW COLUMN 1 2 3 6. RECORD: <u>X</u>__, <u>X</u>__, <u>X</u>__ M16 DEGREES PITCH M18 DEGREES YAW ___^ _ __ __ __ __ M17 PERCENT SIGNAL X __, X __, X __, 7. EVALUATE VOICE COMMUNICATIONS REPEAT STEPS 1. THROUGH 7. COLUMN 2 REPEAT STEPS 1. THROUGH 7. COLUMN 3 RETURN TO COAST AWAKE COMMUNICATIONS MODE

LM S-BAND COMMUNICATIONS TESTS P16.10 LM STEERABLE ANTENNA LUNAR DISTANCE **REQUIRED:** LM - S Band/Steerable Antenna MSFN - Line of Sight SW Configuration - LM Basic Per Crew Checklist PROCEDURE SIGNAL COMB PANEL SWITCH POSITION 6.2 BASIC 8.4 BASIC, Except 12 Updata Link - VOICE BU Voice - DN VOICE BU 12 12 S-Bd Range - OFF Audio Cont - BU 12 TLM PCM - LOW S-Bd Pwr Amp1 - OFF 12 12 TLM BIOMED - OFF 12 12 ICS Volume - AS REQD S-Bd - OFF 8 VHF A - OFF 8 BASIC, Except 6.7 12 S-Bd Range - OFF TLM PCM - LOW 12 S-Bd Pwr Ampl - OFF 12

L

.

<u>REQUIRED</u> LM - OM MSFN - I SW Conf	NI Fwd or Aft Line of Sight iguration - LM Cł	1 Basic Per Crew necklist
PROCEDURE SIGNAL		
COMB	PANEL	SWITCH POSITION
6.4	12	BASIC, Except *S-Bd Antenna - FWD OR
	12	AFT TLM PCM - LOW
-	12 12	Voice - DN VOICE BU TLM BIOMED - OFF
	12	S-Bd Range - OFF
6.1	12	BASIC, Except
	12	AFT

	PROCEDURE	CONTD.	
	SIGNAL COMB	PANEL	SWITCH POSITION
	6.15	12	BÁSIC, Except *S-Bd Antenna - FWD OR
		12 12	AFT Voice - OFF BIOMED - OFF
	6.2	10	BASIC, Except
		12	*S-BO Antenna - FWD OK AFT
	* Maneuver Either t	LM to Permit (he Forward or	Optimum Communications With Rear Omniantenna.





.





LM CONSUMABLES

4

A. TEST OBJECTIVES

S20.83-1 Electrical Loads and Crew Procedures Affecting Demands on Batteries, Battery Capacity and Load Distribution
S20.83-2 Water/Oxygen Requirements Data
S20.83-3 LiOH Cartridge Requirements Data
S20.83-4 APS/DPS/RCS Propellant Requirements Data
S20.83-5 Crew Food Requirements Data

B. TEST REQUIREMENTS

- 1. Perform management and use of the EPS per the flight plan. [20.83]
- 2. Obtain data on water/oxygen consumption. [20.83]
- 3. Manage the replacement of LiOH cartridges per the flight plan. [20.83]
- 4. Manage the consumption of APS/DPS/RCS propellant as required. [20.83]
- 5. Utilize the food supply per the flight plan. [20.83]

C. TEST PROCEDURES/CHECKLISTS

- 1. LM AOH paragraph 4.13, "Subsystems Management"
- 2. FCAC: LM Subsystems Management

- 1. Flight Crew Reports/Logs
 - a. Deviations from the EP configuration (HD)
 - b. LiOH log (M)
 - c. Comments regarding crew comfort level (HD)
 - d. Water Log (M)
 - e. Food Log (HD)
- 2. Ground Support
 - a. BET before and after APS/DPS burns (M)
 - b. LM TM HBR (M)

PASSIVE TESTS

A. TEST OBJECTIVES

S7.26-1 TC System - Translunar and Transearth
S7.26-2 TC System - Lunar Orbit
S13.14-1 LM Supercritical Helium Pressure Profile
P20.66-1 Pre-LOI Through DOI Timeline
P20.66-2 Lunar Orbit Mission Timeline
S20.80-1 Ground Support for Lunar Mission

B. TEST REQUIREMENTS

- 1. All CM and LM crew procedures will be accomplished in the same manner, where feasible, as for the lunar landing mission. [20.66]
- 2. All CM and LM procedures will be accomplished within the same timeline as for the lunar landing mission from the pre-LOI preparation through DOI. [20.66]
- MSFN will provide state vector update and targeting information for maneuvers. [20.80]
- Translunar and transearth flight will be accomplished using the PTC modes identified under Passive Thermal Control. [7.26]
- Lunar orbit flight will be accomplished in the CSM/LM docked and undocked configurations. [7.26]
- 6. LM supercritical helium pressure data will be acquired from LM activiation to LM staging. [13.14]

- Flight Crew Reports/Logs
 - a. Recommended changes in procedures and/or equipment. [20.66] (M)
 - b. Procedures requiring repeating or not accomplished. [20.66] (M)
- 2. Ground Support
 - a. The Flight Director will assess the ground operational support and determine its adequacy for the entire mission. [20.80] (M)
 - CSM TM HBR periodically to generate time history of temperatures during TL and TE phases. [7.26] (M)
 - c. MSFN voice recordings of CSM/MSFN and LM/MSFN communications.
 [20.66] (HD)

d. LM TM HBR when LM is manned and activated while in lunar orbit of the front side of the moon. [7.26] (M)

e. LM TM LBR [13.14] (M)

TRANSEARTH INJECTION

•

A. TEST OBJECTIVES S3.22-1 Deleted

.

:

SECTION 5 - CONSUMABLES ANALYSIS

۰.

CONSUMABLES DATA TO BE SUPPLIED

۰.

i