

LM TRANSFER PHASE INITIATION (TPI)
TARGETING PROGRAM (P74)

LOGIC REV 05 11/27/68

PURPOSE:

(1) TO CALCULATE THE REQUIRED DELTA V AND OTHER INITIAL CONDITIONS REQUIRED BY THE LGC FOR LM EXECUTION OF THE TRANSFER PHASE INITIATION MANEUVER, GIVEN:

(A) TIME OF IGNITION TIG (TPI) OR THE ELEVATION ANGLE (E) OF THE LM/CSM LOS AT TIG(TPI)

(B) CENTRAL ANGLE OF TRANSFER (CENTANG) FROM TIG(TPI) TO INTERCEPT TIME (TIG(TPF)).

(2) TO CALCULATE TIG (TPI) GIVEN E OR E GIVEN TIG (TPI).

(3) TO DISPLAY TO THE ASTRONAUT AND THE GROUND CERTAIN DEPENDENT VARIABLES ASSOCIATED WITH THE MANEUVER FOR APPROVAL BY THE ASTRONAUT/GROUND.

ASSUMPTIONS:

(1) THE PROGRAM MUST BE DONE OVER A TRACKING STATION FOR REAL TIME GROUND PARTICIPATION IN CMC DATA INPUT AND OUTPUT. CMC COMPUTED VARIABLES MAY BE STORED FOR LATER VERIFICATION BY THE GROUND. THESE STORAGE CAPABILITIES ARE LIMITED ONLY TO THE PARAMETERS FOR ONE THRUSTING MANEUVER AT A TIME.

(2) IF P20 IS IN OPERATION WHILE THIS PROGRAM IS OPERATING THE ASTRONAUT MAY HOLD AT ANY FLASHING DISPLAY AND TURN ON THE RENDEZVOUS SIGHTING MARK ROUTINE (EITHER R21 OR R23) AND TAKE OPTICS MARKS AND/OR HE MAY ALLOW VHF RANGING MARKS TO ACCUMULATE. SEE P20 FOR DETAILED DESCRIPTION.

(3) ONCE THE PARAMETERS REQUIRED FOR COMPUTATION OF THE MANEUVER HAVE BEEN COMPLETELY SPECIFIED, THE VALUE OF THE ACTIVE VEHICLE CENTRAL ANGLE OF TRANSFER IS COMPUTED AND STORED. THIS NUMBER WILL BE AVAILABLE FOR DISPLAY TO THE ASTRONAUT THROUGH THE USE OF V06N52.

THE ASTRONAUT WOULD CALL THIS DISPLAY TO VERIFY THAT THE CENTRAL ANGLE OF TRANSFER OF THE ACTIVE VEHICLE IS NOT WITHIN 170 TO 190 DEGREES. IF THE ANGLE IS WITHIN THIS ZONE THE ASTRONAUT SHOULD REASSESS THE INPUT TARGETTING PARAMETERS BASED UPON DELTA V AND EXPECTED MANEUVER TIME.

(4) THE OPERATION OF THE PROGRAM UTILIZES THE FOLLOWING FLAGS:

ACTIVE VEHICLE FLAG - DESIGNATES THE VEHICLE WHICH IS DOING RENDEZVOUS THRUSTING MANEUVERS TO THE PROGRAM WHICH CALCULATES THE MANEUVER PARAMETERS. SET AT THE START OF EACH RENDEZVOUS PRE-THRUSTING PROGRAM.

FINAL FLAG - SELECTS FINAL PROGRAM DISPLAYS AFTER CREW HAS SELECTED THE FINAL MANEUVER COMPUTATION CYCLE.

(5) THERE IS NO REQUIREMENT FOR ISS OPERATION DURING THIS PROGRAM UNLESS AUTOMATIC STATE VECTOR UPDATING IS DESIRED BY THE RENDEZVOUS NAVIGATION PROGRAM (P20).

(6) THIS PROGRAM IS SELECTED BY THE ASTRONAUT BY DSKY ENTRY.

SET UPDATE FLAG
(SEE P20)

"A"

HOLD . FLASH VERB-NOUN TO
..... REQUEST RESPONSE AND
SNAP . DISPLAY TIG(TPI):
V06N37
R1-TIG (TPI)-HRS
R2-TIG (TPI)-MIN
R3-TIG (TPI)-SEC

MONITOR DSKY:
OBSERVE VERB-NOUN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF TIG (TPI).

TIG(TPI)-TIME OF TPI
IGNITION (GET).
IN HRS, MIN, SEC
TO NEAREST .01 SEC.

AM I SATISFIED WITH
THIS VALUE?
(NOTE: THIS PROGRAM
ALWAYS REQUIRES AN
INITIAL VALUE OF
TIG(TPI) WHICH IS
WITHIN 30 MINUTES
OF THE ACTUAL VALUE
EVEN IF TIG (TPI) IS
TO BE CALCULATED
FROM A SPECIFIED E.)

.Y N.
.
.

RECORD THIS
VALUE FOR FUTURE
TRANSMISSION TO
THE LM.

#60

#70

#80

#90

#100

+05
++
PCR
206

RECORD THIS VALUE
FOR FUTURE TRANS-
MISSION TO THE LM.

#220

AM I SATISFIED WITH
THE PRESENT VALUE OF
CENTANG?

.Y .N

KEY IN V23E AND
LOAD THE DESIRED
CENTANG IN R3.

#230

RECORD THIS VALUE
FOR FUTURE TRANS-
MISSION TO THE LM.

#240

TERMINATE FLASH UPON
RECEIPT OF PROCEED
OR NEW DATA

KEY IN PROCEED

#250

.P . NEW
.R . DATA
.Q
.C
.E STORE DATA
.E
.D

#260

IS F SPECIFIED TO
BE +00000?

.N . Y.

. SET COMP E FLAG

..... "B"

..... "B"

++
+05
++
EDIT

. RESET UPDATE
. FLAG.

DID I SPECIFY E
TO BE +00000?

. IS COMP E FLAG
. SET?

.N . Y.

. COMPUTE E FOR
. SPECIFIED
. TIG(TPI)

.Y . N.

POSS
HOLD .
.....
SNAP .

. FLASH VERB-
. NOUN TO RE-
. QUEST RESPONSE
. AND DISPLAY
. CALCULATED E:
. V06 M55
. R1-BLANK
. R2-F
. R3-CENTANG

. MONITOR DSKY:
. OBSERVE
. VERB-NOUN
. FLASH TO RE-
. QUEST RESPON-
. SE AND DIS-
. PLAY OF CAL-
. CULATED E.

#270

#280

#290

#300

#310

(NOTE: FOR DE-
FINITION SEE
ABOVE).

RECORD THIS
VALUE FOR
FUTURE TRANS-
MISSION TO
THE LM.

#320

WAIT FOR KEY-
BOARD ENTRY

KEY IN PRO-
CEED.

#330

TERMINATE
FLASH UPON
RECEIPT OF
PROCEED

#340

.P
.R
.Q
.C
.E
.E
.D

RESET FINAL
FLAG

#350

++
+05
++
EDIT

COMPUTE TIG
(TPI) FOR THE
SPECIFIED F.
ESTABLISH
ALARM IF NO
SOLUTION CAN
BE REACHED

#360

.N .A
.D .L
. .A
.A .R
.L .M
.A .

#370

POSS
HOLD .
.....

M FLASH VERB-

MONITOR DSKY:

SNAP .	NCUN TO REQUEST RE- SPONSE AND DISPLAY ALARM CODE: V05N09 R1- R2- R3- EXPECTED ALARM CODE AT THIS TIME IS 00611	DOES ALARM CODE DISPLAY INDICATE THAT NO SOLUTION CAN BE REACHED? ----- .Y . N. -----	#380
	WAIT FOR KEYBOARD ENTRY	RETURN TO START OF PROGRAM AND ADJUST INPUT PARA- METERS. KEY IN PROCEED.	#390
	TERMINATE FLASH UPON RECEIPT OF PROCEED	----- ----- GO TO "A" ABOVE	#400
POSS HOLD .	FLASH VERR- NOUN TO RE- QUEST RESPONSE AND DISPLAY CALCULATED TIG(TPI): V06N37 R1-TIG(TPI) -HRS R2-TIG(TPI) -MINS R3-TIG(TPI) -SECS.	MONITOR DSKY: OBSERVE FLASH TO RE- QUEST RE- SPONSE AND DISPLAY OF CALCULATED TIG(TPI). ----- ----- RECCRD THIS VALUF FOR FUTURE TRANS-	#410
..... SNAP .	(NCTE: FOR DE- FINITION SEE ABOVE).			#420

MISSION TO
THE LM.

#430

WAIT FOR KEY-
BOARD ENTRY

KEY IN
PROCEED

TERMINATE
FLASH UPON
RECEIPT OF
PROCEED.

#440

.P
.R
.C
.C
.E
.E
.D

#450

BASED ON STORED
TARGET PARAMETERS
COMPUTE THE PARA-
METERS ASSOCIATED
WITH TPI AND
TPE AS DESCRIBED
IN SECTION
5.4.4.2 OF R577.

#460

++
+05
+
+
+05
++
PCN
582

#470

TERMINATE FLASH
UPON RECEIPT OF
PROCEED

#530

IS THE FINAL FLAG
SET?

IS THIS THE
FINAL PASS
THROUGH THIS
PROGRAM?

#540

.N .Y.

.Y .N.

PCN
582
++
+
+05
+
++

SFT UP-
DATE
FLAG
{SEE
P20}

#550

++
+05
+
+05
++
EDIT

RESET
NEW
TARGET
FLAG

#560

POSS
HOLD .
.....
SNAP .

FLASH VERB-
NOUN TO RE-
QUEST RESPONSE
AND DISPLAY
CALCULATED
COMPONENTS OF
DELTA V(LV)
FOR TPI:
V06N81
R1-DELTA
VX(LV)
R2-DELTA
VY(LV)
R3-DELTA
VZ(LV)

MONITOR DSKY:
OBSERVE
VERB-NOUN
FLASH TO RE-
QUEST RES-
PONSE AND
DISPLAY OF
DELTA V(LV)
FOR TPI

#570

DELTA VX(LV)-
COMPONENT OF
IMPULSIVE
DELTA V AT

AM I SATIS-
FIED WITH
THESE VALUES?
(NOTE: CREW
HAS THE OP-
TION AT THIS

#580

TIG(TPI) ALONG
(RXV)XP. IN
FPS TO NEAREST
.1 FPS.

DELTA VY(LV)-
COMPONENT OF
IMPULSIVE
DELTA V AT
TIG(TPI) ALONG
VXR. IN FPS TO
NEAREST .1 FPS

DELTA VZ(LV)-
COMPONENT OF
IMPULSIVE
DELTA V AT
TIG(TPI) ALONG
-R. IN FPS TO
NEAREST .1 FPS

WHERE R IS THE
LM GEOCENTRIC
(EARTH ORBIT)
OR SELENOCENT-
RIC (LUNAR
ORBIT) RADIUS
VECTOR AND V
IS THE LM IN-
ERTIAL VELO-
CITY VECTOR AT
TIG(TPI).

WAIT FOR KEY-
BOARD ENTRY

TIME TO RE-
DEFINE THE
DELTA V(LV)
COMPONENTS
FOR THE SUB-
SEQUENT THRU-
STING MANEU-
VER. THIS
CAPABILITY
WILL NORMALLY
BE EXERCISED
TO CORRECT
OUT OF PLANE-
NESS BY FIRST
SELECTING THE
RENDEZVOUS
OUT OF PLANE
DISPLAY ROU-
TINE (R36)
(V90E), AND
THEN MODIFY-
ING DELTA
VY(LV).
HOWEVER IT
MUST BE RE-
MEMBERED THAT
THE R36 CALC-
ULATION IS
BASED UPON AN
ACTIVE CSM.

.Y N.

KEY IN V25E.
AND LOAD
THE DESIRED
DELTA V
VALUES.

#590

#600

#610

#620

#630

RECORD THESE
VALUES FOR
FUTURE TRANS-
MISSION TO THE
LM.

#640

TERMINATE
FLASH UPON RE-
CEIPT OF PRO-
CEED OR NEW
DATA

KEY IN
PROCEED.

#650

.P .NEW
.R .DATA
.N .

.C
.E STORE DATA

.E
.D

SET NEW
TARGET
FLAG.

#660

IS THE NEW
TARGET FLAG
SET?

.N .Y
. .
. .

CALCULATE
NEW TARGET
VECTOR
BASED ON
NEWLY
LOADED
DELTA
V(LV) FOR
TPI.

#680

SET MGA DISPLAY
IN R3(BELOW)
= -00001.

SET MGA DIS-
PLAY IN R3
(BELOW) =
-00002.

#750

HOLD FLASH VERB-NOUN TO
MON REQUEST RESPONSE AND
 DISPLAY MARK CTRS
 TFI AND MGA;
 V16N45
 R1 - MARK CTRS
 R2 - TFI
 R3 - MGA

MONITOR DSKY:
OBSERVE VERB-NOUN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF MARK CTRS, TFI
AND MGA.

#760

MARK CTRS - THE NUM-
BER OF MARKS PROCES-
SED BY THE RENDEZ-
VOUS DATA PROCESSING
ROUTINE (R22) (REFER
TO ASSUMPTION (8) OF
P20). THE REGISTER
WILL DISPLAY XXBXX
WHERE THE TWO MOST
SIGNIFICANT DIGITS
IS THE VHF RANGING
MARK COUNTER AND THE
TWO LEAST SIGNIFI-
CANT DIGITS IS THE
OPTICS MARK COUNTER.

NOTE: THE OPTICS
MARK COUNTER DOES
NOT DISTINGUISH BE-
TWEEN BACK-UP AND
PRIMARY MARKS.

#770

#780

#790

397

CHANGE CONTROL NOTES

LOGIC REV 04 PCR MIT 66
LOGIC REV 05 PCR 206 EDITORIAL
PCN 582

01120000
01120001
01120002

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LM TRANSFER PHASE MIDCOURSE TARGETING PROGRAM (P75)

LOGIC REV 06 11/27/68

- PURPOSE: (1) TO CALCULATE THE REQUIRED DELTA V AND OTHER INITIAL CONDITIONS REQUIRED BY THE LGC FOR LM EXECUTION OF THE NEXT MIDCOURSE CORRECTION OF THE TRANSFER PHASE OF AN ACTIVE LM REND.
- ASSUMPTIONS: (1) IF P20 IS IN OPERATION WHILE THIS PROGRAM IS OPERATING THE ASTRONAUT MAY HOLD AT ANY FLASHING DISPLAY AND TURN ON THE RENDEZVOUS SIGHTING MARK ROUTINE (EITHER R21 OR R23) AND TAKE OPTICS MARKS AND/OR HE MAY ALLOW VHF RANGING MARKS TO ACCUMULATE, SEE P20 FOR DETAILED DESCRIPTION.
- (2) ONCE THE PARAMETERS REQUIRED FOR COMPUTATION OF THE MANEUVER HAVE BEEN COMPLETELY SPECIFIED, THE VALUE OF THE ACTIVE VEHICLE CENTRAL ANGLE OF TRANSFER IS COMPUTED AND STORED. THIS NUMBER WILL BE AVAILABLE FOR DISPLAY TO THE ASTRONAUT THROUGH THE USE OF V06N52.
 THE ASTRONAUT WOULD CALL THIS DISPLAY TO VERIFY THAT THE CENTRAL ANGLE OF TRANSFER OF THE ACTIVE VEHICLE IS NOT WITHIN 170 TO 190 DEGREES. IF THE ANGLE IS WITHIN THIS ZONE THE ASTRONAUT SHOULD REASSESS THE INPUT TARGETTING PARAMETERS BASED UPON DELTA V AND EXPECTED MANEUVER TIME.
- (3) THE OPERATION OF THIS PROGRAM UTILIZES THE FOLLOWING FLAGS:
 ACTIVE VEHICLE FLAG - DESIGNATES THE VEHICLE WHICH IS DOING RENDEZVOUS THRUSTING MANEUVERS TO THE PROGRAM WHICH CALCULATES THE MANEUVER PARAMETERS. SET AT THE START OF EACH RENDEZVOUS PRE-THRUSTING PROGRAM.
 FINAL FLAG-SELECTS FINAL PROGRAM DISPLAYS AFTER ASTRONAUT HAS SELECTED THE FINAL MANEUVER COMPUTATIONS.
- (4) THE TIME OF INTERCEPT (T(INT)) WAS DEFINED BY PREVIOUS COMPLETION OF THE LM TRANSFER PHASE INITIATION (TPI) PROGRAM (P74) AND IS PRESENTLY AVAILABLE IN CMC STORAGE.
- (5) THERE IS NO REQUIREMENT FOR ISS OPERATION DURING THIS PROGRAM UNLESS AUTOMATIC STATE VECTOR UPDATING IS DESIRED BY THE RENDEZVOUS NAVIGATION PROGRAM (P20).
- (6) THE PROGRAM IS SELECTED BY THE ASTRONAUT BY DSKY ENTRY.

PROG CONT	CMC	GROUND	CREW	CHECKLIST	TIME	TOTAL TIME
			.CREW .PROG .SELECTION			
----- START LM TRANSFER PHASE MIDCOURSE TARGETING (TPM) PROGRAM (P75). DISPLAY PROGRAM 75.	----- KEY IN LM TRANSFER PHASE MIDCOURSE TARGETING (TPM) PROGRAM (P75) V37E 75E -----			#10
			. . .			
						P75/COLOSSUS P75/LUMINARY

IS THE FINAL FLAG
SET?

.N .Y.

SET UPDATE
FLAG

IS THIS THE FINAL
PASS THROUGH THIS
PROGRAM?

.Y .N.

#130

POSS
HOLD .
.....
SNAP .

FLASH VERB-
NOUN TO REQ-
UEST RESPONSE
AND DISPLAY
CALCULATED
COMPONENTS OF
DELTA V(LV)
FOR TPM;
V06N81
R1-DELTA
VX(LV)
R2-DELTA
VY(LV)
R3-DELTA
VZ(LV)

MONITOR
DSKY:
OBSERVE
VFRB-NCUN
FLASH TO
REQUEST RE-
SPONSE AND
DISPLAY OF
DELTA V(LV)
FOR TPM

#140

DELTA VX(LV)-
COMPONENT OF
IMPULSIVE
DELTA V AT
TIG(TPM)
ALONG (RXV)
XR. IN FPS TO
NEAREST .1
FPS.

AM I SATIS-
FIED WITH
THESE
VALUES?
(NOTE: CREW
HAS THE OP-
TION AT
THIS TIME
TO REDEFINE
THE DELTA V
(LV) COM-
PONENTS FOR
THE SUBSE-
QUENT
THRUSTING
MANEUVER.
THIS CAPA-
BILITY WILL
NORMALLY BE
EXERCISED
TO CORRECT

#150

DELTA VY(LV)-
COMPONENT OF
IMPULSIVE
DELTA V AT
TIG(TPM)
ALONG VXR. IN
FPS TO NEAR-
EST .1 FPS

#160

DELTA VZ(LV)-

#170

++
+06
++
EDIT
PCR
206

COMPONENT OF
IMPULSIVE
DELTA V AT
TIG(TPM)
ALONG -R. IN
FPS TO NEAR-
EST .1 FPS

WHERE R IS
THE LM GEO-
CENTRIC
(EARTH ORBIT)
OR SELENO-
CENTRIC
(LUNAR ORBIT)
RADIUS VECTOR
AND V IS THE
LM INERTIAL
VELOCITY
VECTOR AT
TIG(TPM).

WAIT FOR KEY-
BOARD ENTRY

OUT OF
PLANENESS
BY FIRST SE-
LECTING THE
RENDEZVOUS
OUT OF
PLANE DIS-
PLAY ROU-
TINE (R36)
(V90E), AND
THEN MODIFY
VY(LV).
HOWEVER IT
MUST BE RE-
MEMBERED
THAT THE
R36 CALCU-
LATION IS
BASED UPON
AN ACTIVE
CSM.

.Y N.

KEY IN
V25E
AND
LOAD
THE DE-
SIRED
DELTA V
VALUES.

RECORD
THESE
VALUES FOR
FUTURE
TRANSMISSION
TO THE LM.

#180

#190

#200

#210

#220

#230

TERMINATE
FLASH UPON
RECEIPT OF
PROCEED OR
NEW DATA

KEY IN
PROCEED.

.P .NEW
.R .DATA
.D .
.C .
.E -----
.D STORE
DATA

#240

. SET NEW
TARGET
FLAG.

#250

IS THE NEW
TARGET FLAG
SET?

#260

.N .Y
. .
. .

. CALCULATE
NEW TAR-
GET VEC-
TOR BASED
ON NEWLY
LOADED
DELTA V
(LV) FOR
TPM.

#270

#280

405

POSS
HOLD .
.....
SNAP .

. . . .
. . . .
. . . .
. . . .
. . . .
. . . .

FLASH VERB-NOUN
TO REQUEST RE-
SPONSE AND DIS-
PLAY DELTA V (LOS)
FOR TPM:
V06N59
R1-DELTA
V1 (LOS)
R2-DELTA
V2 (LOS)
V3-DELTA
V3 (LOS)

DELTA V (LOS) -
LINE OF SIGHT
COMPONENTS IN FPS
TO NEAREST .1 FPS
(NOTE: FOR DEFIN-
ITION SEE SECTION
5.4.4.3 OF R577.)

. . . .
. . . .
. . . .
. . . .
. . . .
. . . .

WAIT FOR KEYBOARD
ENTRY
TERMINATE FLASH
UPON RECEIPT OF
PROCEED.

. P
. R
. C
. C
. F
. E
. D
. .
. .

IS THE FINAL FLAG
SET?

. N . Y .
. . . .
. . . .
. . . .
. . . .
. . . .

. . . .
. . . .
. . . .
. . . .
. . . .
. . . .

MONITOR DSKY:
OBSERVE VERB-
NOUN FLASH TO RE-
QUEST RESPONSE
AND DISPLAY OF
DELTA V (LOS).

. . . .
. . . .
. . . .
. . . .
. . . .
. . . .

RECORD THESE
VALUES FOR
FUTURE TRANSMIS-
SION TO THE LM.
(NOTE: UNLIKE
DELTA V (LV) FOR
TPM ABOVE, THESE
VALUES CANNOT BE
WRITTEN OVER.)

. . . .
. . . .
. . . .
. . . .

KEY IN PROCEED

. . . .
. . . .
. . . .
. . . .
. . . .
. . . .

P75/COLOSSUS
P75/LUMINARY

#290

#300

#310

#320

#330

P75/COLOSSUS
P75/LUMINARY

SET MGA DISPLAY
IN R3(BELCW)=
-00001.

SET MGA DIS-
PLAY IN R3
{BELCW)=
-00002.

#340

HOLD .
.....
MON .
FLASH VERB-NOUN TO
REQUEST RESPONSE AND
DISPLAY OF MARK CTRS
TFI AND MGA:
V16N45
R1-MARK CTRS
R2-TFI
R3-MGA

MONITOR DSKY:
OBSERVE VERB-NOUN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF MARK CTRS, TFI
AND MGA.

#350

MARK CTRS - THE
NUMBER OF MARKS PRO-
CESSED BY THE RENC-
EZVOUS DATA PROCESS-
ING ROUTINE (R22)
(REFER TO ASSUMPTION
(8) OF P20).
THE REGISTER WILL
DISPLAY XXXXX WHERE
THE TWO MOST SIGNIF-
ICANT DIGITS IS THE
VHF RANGING MARK
COUNTER AND THE TWO
LEAST SIGNIFICANT
DIGITS IS THE OPTICS
MARK COUNTER
NOTE : THE OPTICS
MARK COUNTER DOES
NOT DISTINGUISH BE-
TWEEN BACK-UP AND
PRIMARY MARKS.

#360

#370

#380

409

CHANGE CONTROL NOTES

REV 04 PCR MIT 66
REV 05 PCR 206
REV 06 PCR 206 EDITORIAL

00637000
00638000
00638001

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TERMINATE FLASH UPON
RECEIPT OF PROCEED
OR NEW DATA

.PROCEED .NEW
 .DATA

STORE DATA

KEY IN
PROCEED

KEY IN V25E
AND LOAD THE
CORRECT DELTA V.

#80

#90

HOLD . FLASH VERB-NOUN
..... TO REQUEST RESPONSE
SNAP . AND DISPLAY TIG
 V06N33
 R1-TIG-HRS
 R2-TIG-MINS
 R3-TIG-SECS

MONITOR DSKY
OBSERVE VERB-NOUN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF TIG.

#100

TIG-TIME OF IGNITION
(GET). IN HRS, MINS,
SEC TO NEAREST .01
SEC.

IS THE VALUE
DISPLAYED THE
CORRECT TIME AT
WHICH THE LM EXECUT-
ED OR WILL EXECUTE
THE MANEUVER?

#110

WAIT FOR KEYBOARD
ENTRY.

.Y .N
.
.
.

#120

TERMINATE FLASH UPON
RECEIPT OF PROCEED
OR NEW DATA

.P .NEW
.R .DATA

.O STORE DATA

.E
.E
.D
.
.
.
.

..... KEY IN PROCEED

KEY IN V25E
AND LOAD THE
CORRECT TIG

#130

UPDATE LM STATE
VECTOR TO REFLECT
THE DELTA V ADDED.

.
.
.

#140

ZERO THE RENDEZVOUS
OPTICS MARK COUNTER.

.
.
.

#160

ZERO THE RENDEZVOUS
VHF RANGING MARK
COUNTER.

.
.
.

#170

++
+05
++

DO ROUTINE R00

.
.
.
.
.
.
EXIT

..... DO ROUTINE R00

.
.
.
.
.
.
EXIT

#180

415

CHANGE CONTROL NOTES

LOGIC REV 5 PCR 440
 PCR 468

00269000
00270000

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PURPOSE:

- (1) TO ACCEPT A DESIRED TIME OF TRANSFER PHASE INITIATION (TIG(TPI)) AS A DSKY INPUT FROM THE ASTRONAUT, AND TO COMPUTE THEREFROM THE PARAMETERS ASSOCIATED WITH A MINIMUM ENERGY, SAFE PERIAPSIS TRANSFER MANEUVER AT TIG(TPI) AND THE RESULTANT RENDEZVUS INTERCEPT FOR AN ACTIVE LM.
- (2) TO PROVIDE THE ASTRONAUT WITH THE OPTION OF DEFINING TO THE CMC THE INITIAL TRANSFER TRAJECTORY SEARCH SECTOR FOR CENTRAL ANGLES EITHER GREATER THAN OR LESS THAN 180 DEGREES FROM THE POSITION OF THE ACTIVE VEHICLE (LM) AT TIG (TPI).
- (3) TO DISPLAY TO THE ASTRONAUT THE PARAMETERS ASSOCIATED WITH THE TRANSFER (TPI AND INTERCEPT).

ASSUMPTIONS:

- (1) IF P20 IS IN OPERATION WHILE THIS PROGRAM IS OPERATING THE ASTRONAUT MAY HOLD AT ANY FLASHING DISPLAY AND TURN ON THE RENDEZVUS SIGHTING MARK ROUTINE (EITHER R21 OR R23) AND TAKE OPTICS MARKS AND/OR HE MAY ALLOW VHF RANGING MARKS TO ACCUMULATE. SEE P20 FOR DETAILED DESCRIPTION.
- (2) THE OPERATION OF THIS PROGRAM UTILIZES THE ACTIVE VEHICLE FLAG WHICH DESIGNATES THE VEHICLE WHICH IS DOING THE RENDEZVUS THRUSTING MANEUVERS TO THE PROGRAM WHICH CALCULATES THE MANEUVER PARAMETERS. SET AT THE START OF EACH RENDEZVUS PRE-THRUSTING PROGRAM.
- (3) TO EXECUTE THE TPI MANEUVER SELECT THE LM TRANSFER PHASE INITIATION TARGETING (TPI) PROGRAM (74) AND TRANSMIT MANEUVER DATA TO THE LM.
- (4) THIS PROGRAM IS SELECTED BY THE ASTRONAUT BY DSKY ENTRY.

PROG CONT	CMC	GROUND	CREW	CHECKLIST	TIME	TOTAL TIME
			<ul style="list-style-type: none"> . CREW . PROGRAM ...SELECTION . 			
-----			-----			
START LM TPI SEARCH PROGRAM (P77).	KEY IN LM TPI SEARCH PROGRAM (P77) V37E77E			#10
	.		-----			
		MONITOR DSKY: OBSERVE DISPLAY OF PROGRAM 77.			
DISPLAY PROGRAM 77	.		-----			
	.					
	.					
	.					
	.					#20

SET TRACK FLAG
(SEE P20)

SET UPDATE FLAG
(SEE P20)

SET ACTIVE VEHICLE
FLAG TO LM

"A"

"A"

HOLD
SNAP

FLASH VERB-NOUN TO
REQUEST RESPONSE AND
DISPLAY TIG(TPI):
V06N37
R1-TIG(TPI)-HRS
R2-TIG(TPI)-MINS
R3-TIG(TPI)-SECS

MONITOR DSKY:
OBSERVE VERB-NOUN
FLASH TO REQUEST RE-
SPONSE AND DISPLAY
OF TIG(TPI).

TIG(TPI)-TIME OF TPI
IGNITION (GET). IN
HRS, MINS, SECS TO
NEAREST .01 SEC.

AM I SATISFIED WITH
THESE VALUES?

.Y .N

RECORD THIS
VALUE.

#30

#40

#50

#60

#70

HOLD	-----	MONITOR DSKY:	
.....	FLASH VERB-NOUN TO	OBSERVE VERB-NOUN	
SNAP	REQUEST RESPONSE AND	FLASH TO REQUEST	#130
	DISPLAY TPI PARA-	RESPONSE AND DISPLAY	
	METERS:	OF TPI PARAMETERS.	
	V06N72	-----	
	R1-DELT ANG(TPI)		
	R2-DELT ALT(TPI)		
	R3-SEARCH OPTION		
	DELT ANG(TPI)-CENT-		
	RAL ANGLE AROUND THE		
	EARTH OR MOON AT TIG		#140
	(TPI) BETWEEN THE		
	ACTIVE AND PASSIVE		
	VEHICLES. POLARITY		
	INDICATES ACTIVE VE-		
	HICLE IS BEHIND (-)		
	OR AHEAD OF (+)		
	PASSIVE VEHICLE. IN		
	DEGREES TO NEAREST		
	.01 DEGREE.		#150
	DELT ALT(TPI)-THE		
	MAGNITUDE OF THE		
	ALTITUDE DIFFERENC		
	BETWEEN THE POSITION		
	VECTORS OF THE ACT-		
	IVE AND PASSIVE		
	VEHICLES AT TIG(TPI)		
	IN NAUTICAL MILES TO		
	THE NEAREST .1 NM.		
	POLARITY INDICATES		#160
	THE PASSIVE VEHICLE		
	IS ABOVE (+) OR BE-		
	LOW (-) THE ACTIVE		
	SEARCH OPTION-AN OP-		
	TION CODE TO CONTROL		
	CMC SEARCH FOR TERM-		
	INAL PHASE		
	DEFINITION:		
	00001-CMC SEARCHES		
	TO DEFINE A TERMINAL		#170
	PHASE WHERE THE REN-		
	DEZVOUS INTERCEPT		
	OCCURS AT A CENTRAL		
	ANGLE LESS THAN 180		
	DEGREES FROM THE		
	ACTIVE VEHICLE POS-		
	ITION AT TIG(TPI).		
	CR		
	00002-SAME AS		
	00001 EXCEPT CENTRAL		#180
	ANGLE IS GREATER		
	THAN 180 DEGREES.		

:
:

WAIT FOR KEYBOARD
ENTRY.

DO I WISH TO
CHANGE TIG(TPI)?

.N .Y
:
:

KEY IN RECY-
CLE
V32E

GO TO
"A"
ABOVE

DO I WISH TO
CHANGE THE SEARCH
OPTION DISPLAYED?

.N .Y
:
:

RECORD THESE
VALUES

KEY IN PROCEED

#190

#200

#210

#220

#230

CENTANG-THE ORBITAL
CENTRAL ANGLE OF THE
PASSIVE VEHICLE
DURING TRANSFER FROM
TIG(TPI) TO TIME
OF INTERCEPT. IN
DEGREES TO THE NEAR-
EST .01 DEGREES.

DO I WISH TO ADJUST
TIG(TPI) AND/OR THE
SEARCH OPTION?

.N .Y
.
.

#450

RECORD THESE
VALUES

.
.
.

#460

WAIT FOR KEYBOARD
ENTRY.

KEY IN PROCEED

TERMINATE FLASH UPON
RECEIPT OF PROCEED,
OR RECYCLE.

KEY IN RECYCLE
V32E

.P .R
.R .E
.O .C
.C .Y
.E .C
.E .L
.D .E

GO TO
"A"
ABOVE

#470

GO TO
"A"
ABOVE

#480

DO ROUTINE R00

DO ROUTINE R00

#490

EXIT

EXIT

427

CHANGE CONTROL NOTES

P77/C01 ESSUS

LOGIC REV 63 PCR MIT 66
LOGIC REV 64 PCR 286 EDITORIAL

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LM STABLE ORBIT RENDEZVOUS TARGETING (SCPI)
PROGRAM (P78)

LOGIC REV 07 12/26/68

- PURPOSE:
- (1) TO CALCULATE THE REQUIRED DELTA V AND OTHER INITIAL CONDITIONS REQUIRED BY THE LGC FOR LM EXECUTION OF THE FIRST PHASE OF THE STABLE ORBIT RENDEZVOUS MANEUVER, GIVEN:
 - (A) TIME OF IGNITION (TIG).
 - (B) CENTRAL ANGLE OF TRANSFER (CENTANG) FROM TIG TO INTERCEPT TIME.
 - (C) THE OFFSET OF THE STABLE ORBIT POINT SPECIFIED AS A DISTANCE ALONG THE PASSIVE VEHICLE ORBIT.
 - (2) TO CALCULATE THE REQUIRED DELTA V AND OTHER INITIAL CONDITIONS REQUIRED BY THE LGC FOR LM EXECUTION OF THE SECOND PHASE OF THE STABLE ORBIT RENDEZVOUS MANEUVER, GIVEN:
 - (A) A RESPECIFICATION OF 1(A) ABOVE.
 - (B) AN OPTIONAL RESPECIFICATION OF 1(B) ABOVE.
 - (3) TO CALCULATE THESE PARAMETERS BASED UPON MANEUVER DATA APPROVED AND KEYED INTO THE CMC BY THE ASTRONAUT.
 - (4) TO DISPLAY TO THE ASTRONAUT AND THE GROUND CERTAIN DEPENDENT VARIABLES ASSOCIATED WITH THE MANEUVER FOR APPROVAL BY THE ASTRONAUT/GROUND.
- ASSUMPTIONS:
- (1) THE STABLE ORBIT POINT IS DEFINED AS THE FINAL POSITION (AT COMPLETION OF SECOND PHASE) OF THE ACTIVE VEHICLE RELATIVE TO THE PASSIVE VEHICLE.
 - (2) CMC COMPUTED VARIABLES MAY BE STORED FOR LATER VERIFICATION BY THE GROUND. THESE STORAGE CAPABILITIES ARE LIMITED ONLY TO THE PARAMETERS FOR ONE THRUSTING MANEUVER AT A TIME EXCEPT FOR STABLE ORBIT RENDEZVOUS MANEUVER SEQUENCES.
 - (3) IF P20 IS IN OPERATION WHILE THIS PROGRAM IS OPERATING THE ASTRONAUT MAY HOLD AT ANY FLASHING DISPLAY AND TURN ON THE RENDEZVOUS SIGHTING MARK ROUTINE (EITHER P21 OR P23) AND TAKE OPTICS MARKS AND/OR HE MAY ALLOW VHF RANGING MARKS TO ACCUMULATE. SEE P20 FOR DETAILED DESCRIPTION.
 - (4) ONCE THE PARAMETERS REQUIRED FOR COMPUTATION OF THE MANEUVER HAVE BEEN COMPLETELY SPECIFIED, THE VALUE OF THE ACTIVE VEHICLE CENTRAL ANGLE OF TRANSFER IS COMPUTED AND STORED. THIS NUMBER WILL BE AVAILABLE FOR DISPLAY TO THE ASTRONAUT THROUGH THE USE OF V06N52.
THE ASTRONAUT WOULD CALL THIS DISPLAY TO VERIFY THAT THE CENTRAL ANGLE OF TRANSFER OF THE ACTIVE VEHICLE IS NOT WITHIN 170 TO 190 DEGREES. IF THE ANGLE IS WITHIN THIS ZONE THE ASTRONAUT SHOULD REASSESS THE INPUT TARGETTING PARAMETERS BASED UPON DELTA V AND EXPECTED MANEUVER TIME.
 - (5) THE OPERATION OF THIS PROGRAM UTILIZES THE FOLLOWING FLAGS.
ACTIVE VEHICLE FLAG- DESIGNATES THE VEHICLE WHICH IS DOING RENDEZVOUS THRUSTING MANEUVERS TO THE PROGRAM WHICH CALCULATES THE MANEUVER PARAMETERS. SET AT THE START OF EACH RENDEZVOUS PRE-THRUSTING PROGRAM.
FINAL FLAG- SELECTS FINAL PROGRAM DISPLAYS AFTER THE CREW HAS SELECTED THE FINAL MANEUVER COMPUTATION CYCLE.
 - (6) THE SECOND PHASE OF THIS PROGRAM REQUIRES THE TIG INPUT BE BIASED AS A FUNCTION OF THE AND ANY MIDCOURSE CORRECTIONS PERFORMED IN THE LM STABLE ORBIT MIDCOURSE (TARGETING) PROGRAM (P79)

SET UPDATE FLAG.
(SEE D20)

HOLD .
.....
SNAP .

FLASH VER-NDJN
TO REQUEST RESPONSE
AND DISPLAY TIC.
V06 N37
R1-TIG HRS.
R2-TIG MIN.
R3-TIG SEC.

TIG - TIME OF IGNIT-
ION (GFT). IN HOURS
MIN AND SEC TO NEAR-
EST .01 SEC.

MONITOR DSKY:
OBSERVE VER-NDJN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF TIC.

AM I SATISFIED WITH
THIS VALUE?

RECORD THIS
VALUE FOR FUTURE
TRANSMISSION TO
THE IM.

WAIT FOR KEYBOARD
ENTRY.

KEY IN PROCEED

#50

#60

#70

#80

#90

1A

1A

TERMINATE FLASH UPON
RECEIPT OF PROCEED
OR NEW DATA.

KEY IN V250
AND LOAD THE
DESIRED TIG
(SDP)

.P .NEW
.R .DATA
.D .
.C .
.F .
.F .
.D .

STORE
DATA

#100

#110

HOLD .
.....
SNAP .

FLASH VERB-NOUN TO
REQUEST RESPONSE AND
DISPLAY CENTANG

MONITOR DSKY:
OBSERVE VERB-NOUN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF CENTANG:

#120

V06 N55
R1-BLANK
R2-BLANK
R3-CENTANG

CENTANG- THE ORBITAL
CENTRAL ANGLE OF THE
PASSIVE VEHICLE DURING
TRANSFER FROM
TIG TO TIME OF IN-
TERCEPT. IN DEGREES
TO NEAREST .01
DEGREES

#130

AM I SATISFIED WITH
THIS VALUE?

#140

.Y .N

RECORD THIS
VALUE FOR FUTURE
TRANSMISSION TO
THE LM.

#150

WAIT FOR KEYBOARD
ENTRY.

KEY IN
RECORDED.

#160

TERMINATE FLASH UPON
RECEIPT OF PROCEED
OR NEW DATA

KEY IN M23C
AND LOAD THE
DESIRED
CENTANG.

#170

P NEW DATA
P
D
C
F
F
D

STORE
DATA

#180

HOLD . FLASH VERB-NOIN TO
SNAP . REQUEST RESPONSE AND
DISPLAY OF ASSUMED
STABLE ORBIT RENEZ-
VOUS PHASE OPTION:
V04 N06
01-00005
02-0000X
03-011AX

MONITOR DISK:
OBSERVE VERB-NOIN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF ASSUMED STABLE
ORBIT RENEZVOUS
PHASE OPTION.

#190

113

PCN
577

COMPUTE
T(FINAL) GO TO

"A"
BELOW

GO TO
"A"
BELOW

#260

++
+07'
++
PCN
577

SFT UPDATE
FLAG

#270

HOLD
.....
SNAP

.....
FLASH VERR-NOUN
TO REQUEST RES-
PONSE AND DISPLAY
DELTA R:

.....
MONITOR DSKY:
OBSERVE VERR-
NOUN FLASH TO
REQUEST RES-
PONSE AND DIS-
PLAY OF DELTA
R.

#280

V06 N57
R1-DELTA P
R2-BLANK
R3-BLANK

DELTA R- THE OFFSET
OF THE STABLE
ORBIT POINT, SPE-
CIFIED AS THE DIS-
TANCE ALONG THE
PASSIVE VEHICLE
ORBIT. REFER TO
SECTION 5.4.4.5
OF 2577, FOR
DETAILED DESCIP-
TION. IN NM TO
THE NEAREST .1 NM
(+ INDICATES STABLE
ORBIT POINT BEHIND
PASSIVE VEHICLE;
- INDICATES AHEAD
OF THE PASSIVE
VEHICLE.)

AM I SATISFIED
WITH THIS
VALUE?

#290

#300

1A

1A

#310

RECORD
THIS
VALUE FOR
FUTURE
TRANSMIS-
SION TO
THE LM.

WAIT FOR KEYBOARD
ENTRY

KEY IN
PROCEED

#320

TERMINATE FLASH
UPON RECEIPT OF
PROCEED OR NEW
DATA

KEY IN
V21F
AND LOAD
DESIRED
DELTA P

#330

STORE
DATA

.P
.R
.D
.C
.F
.E
.D

HOLD .
.....
SNAP .

FLASH VERB-NOUN TO
REQUEST RESPONSE AND
DISPLAY T(FINAL):

MONITOR DSKY:
OBSERVE VERB-
NOUN FLASH TO
REQUEST RES-
PONSE AND DIS-
PLAY OF T
(FINAL)

#340

V06N34
R1-T(FINAL)HRS
R2-T(FINAL)MIN
R3-T(FINAL)SEC.

T(FINAL) - TIME OF
ARRIVAL AT STABLE
ORBIT (G.E.T.) IN
HOURS, MIN SEC TO
THE NEAREST .01 SEC-
ONDS.

#350

#470

DELTA V (SOR)-
REQUIRED IMPUL-
SIVE DELTA V TO
ACCOMPLISH SOR
MANEUVER AT TIC
IN EDS TO NEAREST
.1 EDS.

DELTA V(SOR-FIN-
AL) REQUIRED IM-
PULSIVE DELTA V
TO ACCOMPLISH SOR
MANEUVER AT TIME
OF INTERCEPT.
IN EDS TO NEAREST
.1 EDS.

#480

WAIT FOR KEYBOARD
ENTRY.

#490

TERMINATE FLASH
UPON RECEIPT OF
PROCEED

KEY IN PROCEED

PROCEED

#500

HOLD
.....
SNAP

FLASH VERR NOUN TO
REQUEST RESPONSE AND
DISPLAY DELTA V(I,V):
V06NR1
R1-DELTA VX (I,V)
R2-DELTA VY (I,V)
R3-DELTA VZ (I,V)

MONITOR DSKY:
OBSERVE VERR NOUN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF DELTA V(I,V)
COMPONENTS.

#510

DELTA VX - IMPULSIVE
COMPONENT OF DELTA V
AT TIC ALONG (RXY) X
IN EDS TO NEAREST
.1 EDS

1A

1A

DELTA VY IMPULSIVE
COMPONENT OF DELTA V
AT TIG ALONG VXP IN
FPS TO NEAREST
.1 FPS

#520

DELTA VZ IMPULSIVE
COMPONENT OF DELTA V
AT TIG ALONG -P IN
FPS TO NEAREST
.1 FPS

WHERE R IS THE LM
GEOCENTRIC (EARTH
ORBIT) OR SELENOCENT-
RIC (LUNAR ORBIT)
RADIUS VECTOR AND V
IS THE LM INERTIAL
VELOCITY VECTOR AT
TIG.

#530

RECORD THESE
VALUES FOR
FUTURE
TRANSMISSION
TO THE LM.

#540

WAIT FOR KEYBOARD
ENTRY

#550

#560

10A-MIDDLE CIRCUM-
ANGLE DISPLAY IS NOT
PERTINENT TO THIS
PROGRAM.

THEREFORE:

- (A) WHEN DISPLAYED
AT ANY TIME OTHER
THAN THE LAST
PASS THROUGH THE
PROGRAM THE
VALUE IS -00001.
- (B) ON THE LAST PASS
THE VALUE IS
-00002. IN
DEGREES TO THE
NEAREST .01
DEGREES.

WAS THIS THE
LAST PASS
THROUGH THE
PROGRAM?

.Y .N

DO I WISH
TO TERMIN-
ATE THE
MARK PRO-
CESS AND DO
THE FINAL
PASS THRO-
UGH THE
PROGRAM?

WAIT FOR KEYBOARD
ENTRY

KEY IN
DEGREE

#670

#680

#690

#700

#710

1A

1A

TERMINATE FLASH UPON
RECEIPT OF RECYCLE
OR PROCEED

.R .P
.E .R
.C .C
.Y .C
.C .E
.L .E
.F .D

GO TO
"A"
ABOVE

IS FINAL FLAG SET?

.N .Y

SET FINAL
FLAG

GO TO
"A"
ABOVE

DO ROUTINE P00

KEY IN
RECYCLE
V32E

GO TO
"B"
ABOVE

WAS THIS THE LAST
PASS THROUGH THE
PROGRAM?

.Y .N

GO TO
"B"
ABOVE

TRANSMIT ALL MANEU-
VER PARAMETERS TO
THE LM.

DO ROUTINE P00

#770

#730

#740

#750

#760

13

.
. .
. . .
. . . .
. . . .
EXIT

.
. .
. . .
. . . .
EXIT

978/001003HS
978/1111NAPV

#770

CHANGE CONTROL NOTES

- REV 03 PCR MIT 45
- REV 04 PCR MIT 66
- REV 05 PCR 206
- REV 06 PCR 206 EDITORIAL
PCN 578
- REV 07 PCN 577

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LM STABLE ORBIT MIDCOURSE TARGETING (SOM) PROGRAM (P79)

LOGIC REV 06 07/09/68

PURPOSE:

- (1) TO CALCULATE THE REQUIRED DELTA V AND OTHER INITIAL CONDITIONS REQUIRED BY THE LGC FOR LM EXECUTION OF THE NEXT POSSIBLE MIDCOURSE CORRECTION OF THE STABLE ORBIT TRANSFER PHASE OF AN ACTIVE LM RENDEZVOUS.
- (2) TO COMPUTE AND DISPLAY SUITABLE INFORMATION TO ENABLE THE CREW TO ENTER THE FINAL RENDEZVOUS PHASE AT THE CORRECT TIME TO COMPLETE THE REQUIRED THRUSTING MANEUVER.

ASSUMPTIONS:

- (1) THE ISS NEED NOT BE ON TO COMPLETE THIS PROGRAM.
- (2) IF P20 IS IN OPERATION WHILE THIS PROGRAM IS OPERATING THE ASTRONAUT MAY HOLD AT ANY FLASHING DISPLAY AND TURN ON THE RENDEZVOUS SIGHTING MARK ROUTINE (EITHER R21 OR R23) AND TAKE OPTICS MARKS AND/OR HE MAY ALLOW VHF RANGING MARKS TO ACCUMULATE. SEE P20 FOR DETAILED DESCRIPTION.
- (3) ONCE THE PARAMETERS REQUIRED FOR COMPUTATION OF THE MANEUVER HAVE BEEN COMPLETELY SPECIFIED, THE VALUE OF THE ACTIVE VEHICLE CENTRAL ANGLE OF TRANSFER IS COMPUTED AND STORED. THIS NUMBER WILL BE AVAILABLE FOR DISPLAY TO THE ASTRONAUT THROUGH THE USE OF V06N52.
THE ASTRONAUT WOULD CALL THIS DISPLAY TO VERIFY THAT THE CENTRAL ANGLE OF TRANSFER OF THE ACTIVE VEHICLE IS NOT WITHIN 170 TO 190 DEGREES. IF THE ANGLE IS WITHIN THIS ZONE THE ASTRONAUT SHOULD REASSESS THE INPUT TARGETTING PARAMETERS BASED UPON DELTA V AND EXPECTED MANEUVER TIME.
- (4) THE OPERATION OF THIS PROGRAM UTILIZES THE FOLLOWING FLAGS.

ACTIVE VEHICLE FLAG - DESIGNATES THE VEHICLE WHICH IS DOING RENDEZVOUS THRUSTING MANEUVERS TO THE PROGRAM WHICH CALCULATES THE MANEUVER PARAMETERS. SET AT THE START OF EACH RENDEZVOUS PRE-THRUSTING PROGRAM.

FINAL FLAG-SELECTS FINAL PROGRAM DISPLAYS AFTER CREW HAS SELECTED THE FINAL MANEUVER COMPUTATION AND DISPLAY CYCLE.
- (5) THE TIME OF INTERCEPT (T(INT)) WAS DEFINED BY PREVIOUS COMPLETION OF THE LM STABLE ORBIT RENDEZVOUS TARGETING (SOR) PROGRAM (P78) AND IS PRESENTLY AVAILABLE IN CMC STORAGE.
- (6) THIS PROGRAM IS SELECTED BY THE ASTRONAUT BY DSKY ENTRY.

.CREW
.PROG
.SELECTION
.
...
.

START LM STABLE
ORBIT MIDCOURSE
TARGETING (SOM)
PROGRAM (79).
DISPLAY PROGRAM 79.

.
.....
.

KEY IN LM STABLE
ORBIT MIDCOURSE
TARGETING (SOM)
PROGRAM (P79)
V37E79E

#10

.
.....
.

MONITOR DSKY:
OBSERVE DISPLAY OF
PROGRAM 79

#20

.
.
.

SET ACTIVE VEHICLE
FLAG TO LM

.
.
.

#30

RESET FINAL FLAG

.
.
.

SET TRACK FLAG (SEE
P20)

.
.
.

#40

SET UPDATE FLAG
(SEE P20)

.
.
.
.
.
.
.
.
.
.

"A"

.
.
.
.
.
.
.

#50

P79/COLOSSUS
P79/LUMINARY

449

.
. .
. .
. .
. .
. . . .
. . . .
. . . .

. RESET UPDATE FLAG
. (SEE P20).

#60

.
. .
. .
. .
. .
. . . .

. DEFINE TIG(MID) =
. T + "B" MINUTES
. WHERE:
. "B" WILL BE
. STORED IN ERASE-
. ABLE STORAGE AND
. MAY BE CHANGED BY
. PRELAUNCH ERASE-
. ABLE LOAD OR CMC
. UPDATE BY P27.
. NOTE: THIS PARA-
. METER (B) IS NOT
. THE SAME AS THAT
. REFERRED TO IN
. P39 AS A.

#70

.
. .
. .
. .
. .
. . . .

. EXTRAPOLATE LM
. STATE VECTOR TO
. TIG(MID).

#80

.
. .
. .
. .
. .
. . . .

. EXTRAPOLATE CSM
. STATE VECTOR TO T
. (INT) (NOTE:
. REFER TO ASSUMP-
. TION (5) ABOVE).

#90

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. .
. .
. .
. .
. .
. .
. .
. .
. .
. .
. .
. .
. .
. .
. .
. .
. .

#100

SET MGA DIS-
PLAY IN R3
(BELOW)
= -00001.

#220

SET MGA
DISPLAY IN
R3 (BELOW)
= -00002.

#230

HOLD .
.....
MON .
FLASH VERB-NOUN TO
REQUEST RESPONSE AND
DISPLAY MARK CTRS
TFI AND MGA:
V16 N45
R1-MARK CTRS
R2-TFI
R3-MGA

MONITOR DSKY:
OBSERVE VERB-NOUN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF MARK CTRS, TFI,
AND MGA

#240

MARK CTRS - THE NUM-
BER OF MARKS PROCES-
SED BY THE RENDEZ-
VOUS DATA PROCESSING
ROUTINE (P22) (REFER
TO ASSUMPTION (8) OF
P20). THE REGISTER
WILL DISPLAY XXRX
WHERE THE TWO MOST
SIGNIFICANT DIGITS
IS THE VHF RANGING
MARK COUNTER AND
THE TWO LEAST SIGNI-
FICANT DIGITS IS THE
OPTICS MARK COUNTER.

#250

NOTE: THE OPTICS
MARK COUNTER DOES
NOT DISTINGUISH BE-
TWEEN BACK-UP AND
PRIMARY MARKS.

#260

TFI - TIME FROM TIG.
IN MIN AND SEC TO
NEAREST SEC.
MAXIMUM READING IS
59859. (-BEFORE
+ AFTER TIG.)

MGA-MIDDLE CIMBAL
ANGLE IS NOT PERTIN-
ENT IN THIS PROGRAM.

THEREFORE:
(A)WHEN DISPLAYED
AT ANY TIME OTHER
THAN THE LAST PASS
THROUGH THE PRO-
GRAM THE VALUE IS
-00001
(B)ON THE LAST
PASS THE VALUE IS
-00002 IN DEGREES
TO THE NEAREST .01
DEGREES

++
+
+06
++

WAIT FOR KEYBOARD
ENTRY

.....
.

.
. .
. . .
. . .
. . .
. . .

WAS THIS THE LAST
PASS THROUGH THE
PROGRAM?

.Y .N
. .
. .
. .

. DO I WISH TO TER-
. MINATE THE MARK
. PROCESS AND DO
. THE FINAL PASS
. THROUGH THE
. PROGRAM?

.Y .N
. .
. .
. .
. .
. .
. .
. .
. .
. .
. .

. KEY IN RECYCLE
. V32E

. .
. .
. .
. .
. .
. .
GO TO
"A"
ABOVE
. .
. .
. .
. .
. .
. .
. .
. .
. .
. .

#270

#280

#290

#300

#310

TERMINATE FLASH UPON
RECEIPT OF PROCEED
OR RECYCLE

KEY IN PROCEED

.R .P
.E .R
.C .O
.Y .C
.C .F
.L .E
.E .D

GO TO
"A"
ABOVE

WAS THIS THE LAST
PASS THROUGH THE
PROGRAM?

#320

.Y .N
.
.
.
GO TO
"A"
ABOVE

#330

IS THE FINAL
FLAG SET?

.Y .N
.
.
.

SET THE
FINAL FLAG.

GO TO
"A"
ABOVE

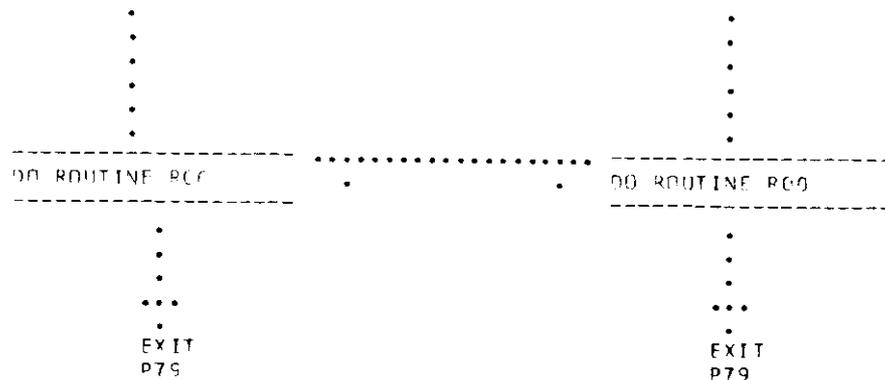
#340

#350

TRANSMIT ALL MANEUV-
ER PARAMETERS TO THE
LM.

#360

455



P79/COLOSSUS
P79/LUMINARY

#370

CHANGE CONTROL NOTES

REV 04 PCR MIT 45
 REV 05 PCR MIT 66
 REV 06 PCR 206

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FINAL AUTOMATIC REQUEST TERMINATE
ROUTINE (P20)

LOGIC REV 09 11/29/6A

- PURPOSE:
- (1) TO PROVIDE A STANDARD EXIT FOR PROGRAMS, AND AN OPTION TO SELECT ANY PROGRAM DESIRED.
 - (2) TO PROVIDE A GENERAL DESCRIPTION OF THE COMPUTER ACTIVITY FOLLOWING ANY V37EXXE.
- ASSUMPTIONS:
- (1) THE CALLING PROGRAM HAS SUCCESSFULLY COMPLETED ALL ITS FUNCTIONS OR THE OPERATOR HAS PREMATURELY TERMINATED THE PROGRAM.
 - (2) THE COMPUTER CHECKS ON THE RENDEZVOUS PROCESS FOLLOWING ANY V37EXXE IN THE FOLLOWING WAYS:
 - (A) IF P20 IS THE NEW PROGRAM KEYED IN AND IS NOT PRESENTLY RUNNING AND WAS NOT RUNNING IN THE BACKGROUND IT WILL BE STARTED AS A NEW PROGRAM.
 - (B) IF P20 IS THE NEW PROGRAM KEYED IN AND P20 IS PRESENTLY RUNNING (I.F. 20 DISPLAYED IN THE PROG LIGHTS) IT WILL BE STARTED AS A NEW PROGRAM (I.F. RE-INITIALIZED).
 - (C) IF P20 IS THE NEW PROGRAM KEYED IN AND IS NOT PRESENTLY THE ONLY PROGRAM RUNNING (I.F. A PROGRAM OTHER THAN P20 IS DISPLAYED IN THE PROG LIGHTS) AND P20 IS RUNNING IN THE BACKGROUND THE PROG LIGHTS WILL BE CHANGED TO 20 AND P20 WILL START AT REED P20 WITH THE FLAGS SET TO ALLOW TRACKING AND UPDATING.
 - (D) IF P00 IS SELECTED, THE RENDEZVOUS FLAG IS RESET (SHUTS OFF P20) AND P00 IS STARTED.
 - (E) IF A PROGRAM OTHER THAN P20 AND P00 IS KEYED IN, THE NEW PROGRAM WILL BE STARTED AND THE PROG LIGHTS WILL DISPLAY THE NEW PROGRAM. THE COMPUTER WILL THEN ATTEMPT TO RESTART P20 AND WILL BE SUCCESSFUL IF P20 WAS RUNNING IN THE BACKGROUND AND THE NEW PROGRAM WILL ALLOW TRACKING.

PROG CONT	CMC	GROUND	CREW	CHECKLIST	TIME	TOTAL TIME
--------------	-----	--------	------	-----------	------	---------------

```
    . CMC  
    . ROUTINE  
    . SELECTION  
    .  
    .  
-----  
    IS MAX OR FLAG SET?  
-----
```

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    . N    . Y
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    . .  
    . .  
    . .  
    . .  
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    . .  
    . .  
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    . .  
    . .
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```
    . CREW  
    . ROUTINE  
    . SELECTION  
    .  
    .  
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    .  
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    .  
    .
```

```
#10
```

#20

SET MAX
DEAD-
BAND IN
RCS PAR.

SET MIN DEAD-
BAND IN RCS PAR.

#30

HOI D .
.....
SNAP .

FLASH VERB 27 TO
REQUEST PLEASE PER-
FORM CHANGE OF
PROGRAM
V27 M BLANK
P1 BLANK
P2 BLANK
P3 BLANK

.....
.

MONITOR DSKY:
OBSERVE VERB 27
FLASH TO REQUEST
PLEASE PERFORM
CHANGE OF PROGRAM.

#40

WAIT FOR KEYBOARD
ENTRY TERMINATE
FLASH ON RECEIPT OF
OF XXF

.....
.

KEY IN DESIRED
PROGRAM:
XXF

#50

RECEIVE V27XXF
TO REQUEST NEW
PROGRAM.

.....
.

KEY IN DESIRED
PROGRAM:
V27XXF

#60

++
+00
++
RCP
507

PAR ENTRY
FROM V27
WITH PROGRAM
BOO SPECIFIED

459

R00/COL0SSUS
R00/SUNDANCE
R00/LUMINARY

#70

IS THE IMU BEING
INITIALIZED (IS IMU
CDU ZERO IN
PROCESS)?

.N .Y
.
.

TURN ON PROGRAM
ALARM LIGHT AND
STORE ALARM CODE
1520

EXIT

IS THE TVC DAP ON OR
IS THE ENGINE ON?

.Y .N
.
.

TERMINATE THE
ENGINE ON
COMMAND.

TURN OFF TVC
DAP

TURN OFF ALL
RCS TRANSLATION
AND ROTATION

MONITOR DSKY:
DOES PROGRAM
ALARM LIGHT COME
ON INDICATING THAT
THE IMU IS STILL
BEING INITIALIZED?

.N .Y
.
.

RESET ALARM
LIGHT.

#80

#90

#100

#110

#120

R00/COL0SSUS
R00/SUNDANCE

WAIT ABOUT 3
SECONDS

TURN ON PCS DAP

WRITE ZERO'S
INTO NEW PROG-
RAM SELECTION
SO THAT REGARD-
LESS OF THE
SELECTED PROG-
RAM, POO WILL
SELECT POO.

IS NEW PROGRAM POO?

.Y .N

. IS STATE VECTOR
. EXTRAPOLATION
. BEING PERFORMED
. IN THE CMC IDLING
. PROGRAM POO OR IS
. PDS ON?

.N .Y

#130

#140

#150

#160

#170

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.....
.....
.....
.....
.....

TURN ON PROGRAM ALARM LIGHT AND STORE ALARM CODE 1520

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.....
.....
.....

EXIT

DOES THE NEW PROGRAM EXIST?

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.....

TURN ON THE OPERATOR ERROR LIGHT

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EXIT

IS AVERAGE G ON?

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TURN AVERAGE G OFF

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MONITOR OSKY: DOES PROGRAM ALARM LIGHT COME ON, INDICATING THAT STATE VECTOR INTEGRATION IS BEING PERFORMED AND I MUST WAIT UNTIL IT IS FINISHED OR THAT P06 IS ON?

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.....

RESET ALARM LIGHT AND WAIT FOR COMPUTER ACTIVITY TO GO OUT INDICATING COMPLETION OF INTEGRATION OR, IF P06, SHUT DOWN THE CMC TO STANDBY BY KEYING IN PROCEED

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.....
.....

EXIT

#180

#190

#200

#210

#220

ZERO RENDEZ-
VOUS OPTICS
MARK COUNTER.

#230

ZERO RENDEZ-
VOUS VHF
RANGING MARK
COUNTER

#240

RESET THE Z-AXIS
FLAG

#250

COMMAND ZERO RATE
IN THE RCS DAP (TO
STOP RATE DRIVE
FROM P201)

#260

RESET THE TRACK FLAG

#270

RESET THE UPDATE
FLAG.

#280

.....

RESET STICK FLAG

.....

SHUT OFF UPLINK ACTY
LIGHT

.....

PESET VHF RANGE
FLAG

.....

IS MAX DB FLAG SET?

.N .Y
.....

SET MAX
DEAD-
BAND IN
RCS DAP.

.....

SET MIN DEAD-
BAND IN RCS DAP

.....

IS NEW PROGRAM P00?

.N .Y
.....

ROO/COLOSSUS
ROO/SUNDANCE
ROO/LUMINARY

#290

#300

#310

#320

#330

ROO/COLOSSUS
ROO/SUNDANCE

. . .

RESET
THE REN-
DEZVOUS
FLAG.

. . .

IS NEW PROGRAM P20?

.Y .N
. . .

IS THE CURRENT
PROGRAM P20?

.N .Y
. . .

RESET
THE REN-
DEZVOUS
FLAG.

. . .

IS THE RENDEZVOUS
FLAG SET?

.Y .N
. . .

SET THE TRACK
FLAG

. . .

#340

#350

#360

#370

#380

464

465

SET THE UPDATE
FLAG

DISPLAY NEW PROGRAM

DISPLAY NEW
PROGRAM AND
GO TO PROGRAM
SELECTED.

PLEASE DISPLAY
SYSTEM.

IS THE RENDEZVOUS
FLAG SET?

.N .Y

GO TO REND
P20 IN P20.

EXIT EXIT

.....
.

.....
.

MONITOR DSKY:
OBSERVE DISPLAY OF
NEW PROGRAM.

GO TO
PROGRAM
SELECTED

ROO/COLOSSUS
ROO/SUNDANCE
ROO/LUMINARY

#390

#400

#410

#420

#430

CHANGE CONTROL NOTES

REV 06	PCR 80.3	00510000
REV 07	PCR NASA 151	00511000
	PCR MIT 66	00512000
REV 08	PCR 465	00513000
	PCR 447	00514000
	PCR 492	00515000
	PCR 225	00516000
REV 09	PCR 507	00516001

IMU STATUS CHECK ROUTINE (R02)

LOGIC REV 03 04/12/68

PURPOSE: (1) TO CHECK WHETHER IMU IS ON AND IF ON WHETHER IT IS ALIGNED TO AN ORIENTATION KNOWN BY THE CMC.
 (2) TO ESTABLISH A PROGRAM ALARM AND STORE AN ALARM CODE IF THE IMU IS OFF OR NOT ALIGNED TO AN ORIENTATION KNOWN BY THE CMC.

ASSUMPTIONS: (1) THE ROUTINE IS ONLY AUTOMATICALLY SELECTED.

PROG CONT	CMC	GROUND	CREW	CHECKLIST	TIME	TOTAL TIME
	.CMC .ROUTINE .SELECTION . . .					
	----- START IMU STATUS CHECK ROUTINE (R02) -----					#10
	.					
	----- IS THE ISS ORIENTA- TION KNOWN FLAG SET? (CHECK REFSMMAT FLAG) -----					#20
	.Y	.N				
	.	.				
	.	.				
	----- IS THE ISS ON? -----					
	.Y	.N				
	.	.				
	.	.				#30
	.	.				
	.	.				
	.	.				
	.	.				
	.	.				
	.	.				
	.	.				
	.	.				
	.	.				
	.	.				
	.	.				
	.	.				

```

-----
. TURN ON PROGRAM .
. ALARM LIGHT BUT .....
. DO NOT CHANGE .
. PRESENT DIS- .
. PLAY. (PROGRAM .
. ALARM DISPLAY .
. IF CALLED IS: .
.   V05N09 .
.   R1- .
.   R2- .
.   R3- .

```

```

-----
. MONITOR DSKY: .
.   DOFS PROGRAM .
. ALARM LIGHT INDICATE .
. THAT EITHER IMU IS .
. NOT ON OR NOT .
. ALIGNED? .

```

```

. EXPECTED ALARM .
. CODE IS 00210 .
-----

```

#40

```

-----
. TURN ON PROGRAM .
. ALARM LIGHT BUT .
. DO NOT CHANGE .
. PRESENT DISPLAY. .
. PROGRAM ALARM .....
. DISPLAY IF .
. CALLED IS: .
.   V05 N09 .
.   R1- .
.   R2- .
.   R3- .

```

```

. EXPECTED ALARM .
. CODE AT THIS .
. TIME IS 00220 .
-----

```

#50

#60

++
+03
++

```

-----
. Y . N .
. . . .
. . . .

```

#70

```

-----
. CALL PROGRAM ALARM .
. DISPLAY (V05N09) .
. TO IDENTIFY ABNOR- .
. MALITY. WHEN FIN- .
. IShed PUSH KEY .
. RELEASE. .
-----

```

#80

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DIGITAL AUTOPILOT DATA LOAD
ROUTINE (R03)

LOGIC REV 06 07/09/68

- PURPOSE: (1) TO LOAD AND VERIFY CMC DIGITAL AUTOPILOT (DAP) DATA.
 (2) TO PROVIDE THE CREW A MEANS FOR SELECTING APPROPRIATE CCAST AUTOPILOTS. AFTER COMPLETION OF THIS ROUTINE, WHICH IDENTIFIES THE VEHICLE CONFIGURATION, THE USE OF VERB 46 ENTER ("ESTABLISH GNC CONTROL") WILL CAUSE THE APPROPRIATE DAP TO BECOME ACTIVE.
- ASSUMPTIONS: (1) THE MOMENTS OF INERTIA AND OTHER PERTINENT PARAMETERS ARE STORED IN THE CMC AS A FUNCTION OF THE KEYED IN WEIGHTS.
 (2) THE TVC DAP REDUCES THE VALUE FOR WEIGHT LINEARLY AS A FUNCTION OF SPS MANEUVER TIME DURING SPS THRUSTING PROGRAM (P40) MANEUVERS ONLY. ALL THRUSTING MANEUVERS THAT ARE PERFORMED WITHOUT USING P40 COULD CAUSE THE CMC'S KNOWLEDGE OF WEIGHT TO BE COMPROMISED.
- ++
 +05 (3) THIS ROUTINE IS SELECTED BY THE ASTRONAUT BY DSKY ENTRY.
 ++
 (4) THIS ROUTINE IS NOT AVAILABLE IF UNDER THRUST VECTOR CONTROL.

PROG CONT	CMC	GROUND	CREW	CHECKLIST	TIME	TOTAL TIME
			.CREW .ROUTINE .SELECTION			
	START DAP DATA LOAD ROUTINE (R03)	KEY IN V48E			#10
	.					
	.					
	.					
++ +06 +	IS ANOTHER EXTENDED VERB ACTIVE?					
+	.N .Y					
+	.					
+	.					
+	.					#20
+	. TURN ON OPERATER . ERROR LIGHT.					
+	.					
+	.					
+	.					
+	.					
+	.					
+	.					
+	.					

```

+
+
+
+
+
+
+
+
+06
++

```

EXIT

#30

```

HOLD .
.....
SNAP .

```

```

-----
FLASH VERB-NOUN TO
REQUEST RESPONSE AND
DISPLAY DAP CONFIG-
URATION DATA:
V04 N46
R1-ABCDE
R2-ABCDE
R3-BLANK

```

```

R1 DATA CODE:
A-VEHICLE CONFIG.
CODE:
0-NO DAP
1-CSM
2-CSM + LM
  (ASCENT PLUS
  DESCENT)
3-SIVB
6-CSM + LM
  (ASCENT ONLY)
B-QUAD AC FOR
+X TRANS CODE:
0-DON'T USE
QUAD
1-USE QUAD
C-QUAD BC FOR
+X TRANS CODE:
0-DON'T USE
QUAD
1-USE QUAD
D-DEADBAND CODE:
0-0.5 DEG
1-5.0 DEG
E (LSB)-MANEUVER
RATE CODE:
0-0.05 DEG/SEC
1-0.2 DEG/SEC
2-0.5 DEG/SEC
3-4.0 DEG/SEC
NOTE: IF BOTH B+C
DISPLAY ZERO
THIS MEANS 1-1

```

```

-----
MONITOR DSKY:
OBSERVE VERB-NOUN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF DAP CONFIGURATION
DATA
-----

```

#40

```

-----
AM I SATISFIED WITH
THE STORED DAP CON-
FIGURATION DATA?
-----

```

#50

```

.Y .N

```

#60

#70

R2 DATA CODE:
 A-QUAD AC OR RD
 ROLL CODE
 0-USE RD
 1-USE AC
 R-QUAD A CODE
 0-DON'T USE
 QUAD
 1-USE QUAD
 C-QUAD B CODE
 0-DON'T USE
 QUAD
 1-USE QUAD
 D-QUAD C CODE
 0-DON'T USE
 QUAD
 1-USE QUAD
 E-QUAD D CODE
 0-DON'T USE
 QUAD
 1-USE QUAD

#80

#90

#100

 .
 .
 .

 WAIT FOR KEYBOARD
 ENTRY

 KEY IN PRO-
 CEED

 .
 .
 .

 TERMINATE FLASH UPON
 RECEIPT OF PROCEED
 OR NEW DATA

 KEY IN V21E, V22E,
 OR V24E AND LCAD DE-
 SIRED DATA CODES IN
 R1, R2

#110

 .PROCEED .NEW DATA
 .
 .
 .
 .

 .
 .
 .

 TRANSFER STORE DATA
 DATA TO
 DAP

#120

 .
 .
 .

 DID THE ASTRONAUT
 SELECT MAXIMUM DEAC-
 BAND (D IN R1 = 1)?

#130

 .N .Y
 .
 .
 .

RESET
MAX DB
FLAG

#140

SET MAX DB
FLAG

#150

HOLD .
.....
SNAP .

FLASH VERB-NOUN TO
REQUEST RESPONSE AND
DISPLAY CSM AND LM
WEIGHTS:
V06 N47
R1-CSM WEIGHT
R2-LM WEIGHT
R3-BLANK

CSM WEIGHT-WEIGHT OF
THE CSM IN POUNDS TO
THE NEAREST POUND.

LM WEIGHT-WEIGHT OF
THE LM IN POUNDS TO
THE NEAREST POUND.

MONITOR DSKY:
OBSERVE VERB-NOUN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF CSM AND LM WEIGHT

#160

IS THE LM ATTACHED?

.Y .N
. .
. .

#170

ARE THE VALUES
FOR CSM AND
LM CORRECT?

.N .Y
. .
. .

IS THE CSM
WEIGHT
CORRECT?

#180

.Y .N

475

WAIT FOR KEYBOARD
ENTRY

KEY IN
PROCEED

#190

KEY IN V21E,
V22E, OR V24E
AND LOAD
CORRECT DATA

#200

KEY IN V21E
AND LOAD
CORRECT DATA

#210

TERMINATE FLASH UPON
RECEIPT OF PROCEED
OR NEW DATA

.P .NEW
.R .DATA
.O .
.C .
.E
.E STORE DATA
.D

#220

IS THE VEHICLE CON-
FIGURATION CODE
EQUAL TO 0 OR 3?

#230

.Y .N

#240

05
++

IS VEHICLE CONFIGUR-
ATION CODE EQUAL TO
2 OR 6?

.N .Y

TRANSFER TRANSFER
CSM WEI- LM + CSM
GHT TO WEIGHT TO
DAP DAP

#250

FLASH VERB-NOUN TO
REQUEST RESPONSE AND
DISPLAY GIMBAL ACTU-
ATOR TRIM VALUES:
V06 N48
R1-PITCH TRIM
R2-YAW TRIM
R3-BLANK

HOLD .
.....
SNAP .

MONITOR DSKY:
OBSERVE VERB-NOUN
FLASH TO REQUEST
RESPONSE AND DISPLAY
OF GIMBAL ACTUATOR
TRIM VALUES

#260

PITCH TRIM AND YAW
TRIM-SPS ENGINE BELL
TRIM ANGLES AT
IGNITION DATA
TAKEN IN DEGREES
TO NEAREST .01
DEGREE.

DO THESE VALUES
AGREE WITH MY CARRY
ON DATA?

#270

Y. .N

WAIT FOR KEYBOARD
ENTRY

KEY IN PROCEED

#280

417

R03/COLUSSUS

TERMINATE FLASH UPON
RECEIPT OF PROCEED
OR NEW DATA

KEY IN V21F, V22F,
OR V24F AND LOAD THE
CORRECT DATA

P. . NEW
P. . DATA
Q. .
C. .
E. .
E. .
D. .
.
.

STORE DATA

TRANSFER
DATA TO DAP

.
.
...
.
EXIT R03

#290

#300

#310

CHANGE CONTROL NOTES

- REV 04 PCR 123
- PCR 151
- REV 05 PCR 423
- PCR 474
- REV 06 PCR 206

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TURN ON
OPERATOR
ERROR
LIGHT.

MONITOR DSKY:
DOES OPERATOR ERROR
LIGHT COME ON INDIC-
ATING THAT THIS
ROUTINE CAN NOT BE
SELECTED AT THIS
TIME?

#30

.N .Y

IN ORDER
TO TURN
THIS ROU-
TINE ON
SELECT CMC
IDLING
PROGRAM
(POO) BY
KEYING IN
V37E00F
AND RESE-
LECT THIS
ROUTINE.

#40

EXIT

EXIT

#50

#60

DO IMU STATUS CHECK
ROUTINE (R02)

DO IMU STATUS CHECK
ROUTINE (R02)

#70

EXTRAPOLATE CSM
STATE VECTOR TO
PRESENT TIME USING
CONIC EQUATIONS

#80

481

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·
·
·
·
·

· CALCULATE VECTOR
· FROM CSM TO EARTH
· CENTER IN CSM BODY
· AXIS

·
·
·
·

· CALCULATE REQUIRED
· S-BAND ANTENNA PITCH
· AND YAW GIMBAL
· ANGLES.

·
·
·
·

HOLD · · · · · FLASH VERB-NOUN TO
· · · · · REQUEST RESPONSE AND
MON · · · · · DISPLAY REQUIRED S-
· · · · · BAND ANTENNA GIMBAL
· · · · · ANGLES.
· · · · · V06N51
· · · · · R1 RHO
· · · · · R2 GAMMA
· · · · · R3 BLANK

· RHO-S-BAND ANTENNA
· PITCH GIMBAL
· ANGLE-CORRE-
· SPONDING TO
· THE S-BAND
· PITCH GIMBAL
· DIAL IN DEGREES
· TO THE NEAREST
· .01 DEGREE.

· GAMMA-S-BAND ANTENNA
· YAW GIMBAL ANGLE
· CORRESPONDING TO
· THE S-BAND YAW
· GIMBAL DIAL IN
· DEGREES TO THE
· NEAREST .01
· DEGREE.

· NOTE: FOR
· DEFINITION OF
· S-BAND DISPLAY
· ANGLES REFER TO

·
·
·
·
·
·

· MONITOR DSKY:
· OBSERVE VERB-NOUN
· FLASH TO REQUEST RE-
· SPONSE AND DISPLAY
· OF THE REQUIRED S-
· BAND ANTENNA PITCH
· AND YAW GIMBAL ANG-
· LES REQUIRED TO
· POINT THE ANTENNA AT
· EARTH CENTER WITH
· THE CSM AT ITS PRE-
· SENT POSITION AND
· ATTITUDE.

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·
·
·
·
·

#90

#100

#110

#120

#130

.....
N Y

SET AN-
TENNA TO
THESE
ANGLES

#200

.....
USING
THE RHC
MANEU-
VER THE
VEHICLE
UNTIL
SATIS-
FACTORY
ANGLES
ARE AC-
HIEVED.

#210

#220

.....

KEY IN PROCEED

#230

.....
EXIT
R05

TERMINATE FLASH UPON
RECEIPT OF PROCEED

#240

.P
.R
.D
.C
.E
.F
.D
.
.

.
. .
. . .
. . .
. . .
. . .
. . .
. . .
. . .
. . .
EXIT
R05

CHANGE CONTROL NOTES

LOGIC REV C9 PCR MIT 66
REV 10 EDITORIAL

48

RENDEZVOUS TRACKING SIGHTING MARK ROUTINE (R21)

LOGIC REV OR 11/27/68

PURPOSE: (1) TO PERFORM SIGHTING MARKS IN CONJUNCTION WITH THE RENDEZVOUS NAVIGATION PROGRAM (P20).

ASSUMPTIONS: (1) SIGHTINGS ARE MADE ON THE LM USING THE SXT.

PCR (2) WHEN THE CMC ACCEPTS A MARK IT RECORDS AND STORES 5 ANGLES (3 GCDUS AND 2 OGDUS) AND THE TIME OF MARK POSITION #1 AND MOVES PREVIOUS MARK DATA (IF ANY) TO POSITION #2. IF A MARK IS REJECTED (BY PRESSING MARK REJECT BUTTON) THE MARK DATA IN POSITION #1 IS ERASED. THE RENDEZVOUS TRACKING DATA PROCESSING ROUTINE (R22) ATTEMPTS TO PROCESS THE MARK DATA (IF ANY) IN POSITION #2 ONCE EVERY 4 SECONDS. IF DATA IS IN POSITION #2, IT IS MOVED TO POSITION #3 FOR PROCESSING BY (R22). IF NO DATA IS IN POSITION #2, R 22 INTERROGATES POSITION #2 AFTER 4 SECONDS. IF MARKS ARE MADE AT A GREATER FREQUENCY THAN R22 PROCESSES THEM THE OVERFLOW FROM POSITION #2 IS LOST.

(3) THE TRACKING ATTITUDE ROUTINE (R61) WILL AUTOMATICALLY HOLD RENDEZVOUS REFERENCE VECTOR AIMED AT THE LM, IF THE SC CONTROL SWITCH IS PLACED AT CMC, IF THE AUTOMODE IS SELECTED AND IF THE PREFERRED ATTITUDE FLAG IS SET. IF THE FREE MODE IS SELECTED THE ASTRONAUT MAY HOLD THE LM IN THE FIELD OF VIEW USING THE MINIMUM IMPULSE CONTROLLER. IF THE ATTITUDE HOLD MODE IS SELECTED THE ASTRONAUT MAY HOLD THE LM IN THE FIELD OF VIEW USING THE ROTATIONAL HAND CONTROLLER.

(4) THIS ROUTINE IS MANUALLY SELECTED BY THE ASTRONAUT BY KEYING IN V57E.

PROG CONT	CMC	GROUND	CREW	CHECKLIST	TIME	TOTAL TIME
--------------	-----	--------	------	-----------	------	---------------

.CREW
.ROUTINE
.SELECTION
.
.
.
.

START RENDEZVOUS
TRACKING SIGHTING
MARK ROUTINE (R21)

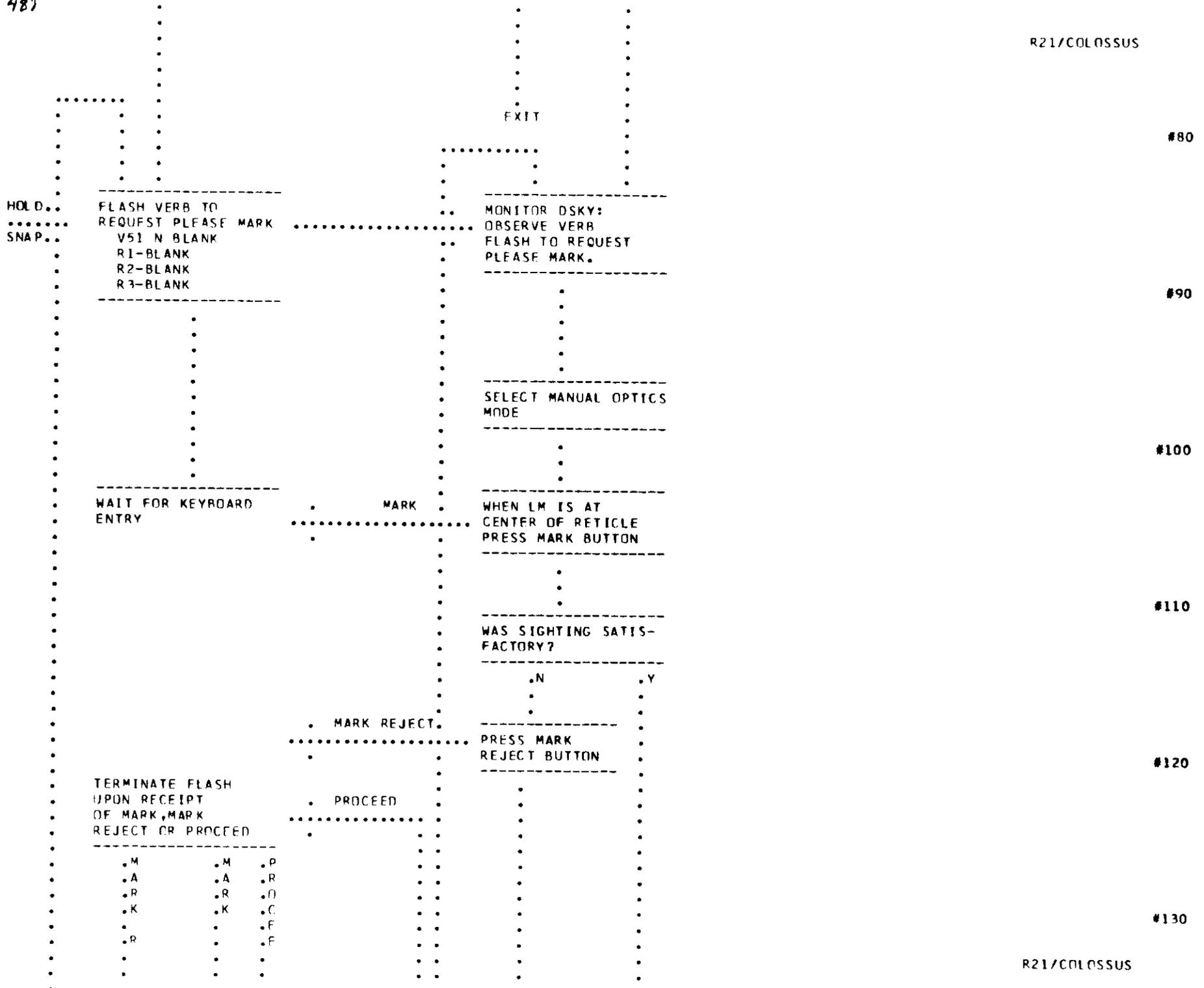
..... KEY IN V57E

#10

IS ANOTHER EXTENDED
VEH ACTIVE?

N.	Y
.	.
.	.
.	.
.	.
.	.
.	.
.	.
.	.
.	.
.	.

#20



.E .D
.J
.F
.C
.T

ERASE
MARK DATA
IN POSI-
TION #1
(IF ANY)

DO I WISH TO
MAKE MORE MARKS

.Y .N

#140

KEY IN PROCEED

#150

TURN OPTICS MODE
SWITCH TO CMC

#160

IS THERE
MARK DATA
IN POSI-
TION #1?

.Y .N

EXIT R21

#170

TRANSFER
MARK DATA
FROM POSI-
TION #1 TO
POSITION
#2

#180

489

R21/C/CLOSSUS

```

.      .      .      .
.      .      .      .
.      .      .      .
.      .      .      .
.      .      .      .
.      .      .      .
.-----
. STORE NEW
. MARK DATA
. IN POSI-
. TION #1 AND
. TAG AS PRIMARY
. MARK DATA FOR
. USE BY R22.
.-----
.      .
.      .
.      .
.....
.
.
.
.

```

#190

```

.-----
. IS THERE MARK DATA
. IN POSITION #1?
.-----

```

#200

```

.      .Y      .N
.      .      .
.      .      .
.-----

```

```

.-----
. TRANSFER
. MARK DATA
. FROM POSITION
. #1 TO POSITION
. #2.
.-----

```

#210

```

.      .
.      .
.      .
.      .
.      .
.      .
EXIT  EXIT
R21   R21

```

CHANGE CONTROL NOTES

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PURPOSE: (1) TO PROCESS RENDEZVOUS SIGHTING MARK DATA TO UPDATE THE STATE VECTOR OF EITHER THE CSM OR LM AS DEFINED BY THE STATE VECTOR FLAG (SEE P20).
 (2) TO PROCESS RENDEZVOUS VHF RANGING DATA TO UPDATE THE STATE VECTOR OF EITHER THE CSM OR LM AS DEFINED BY THE STATE VECTOR FLAG (SEE P2G).

ASSUMPTIONS: (1) THIS ROUTINE IS AUTOMATICALLY SELECTED BY THE RENDEZVOUS NAVIGATION PROGRAM (P20).
 (2) V06N49 DISPLAYED IN THIS ROUTINE IS A PRIORITY DISPLAY AND WILL REMAIN UP A MINIMUM OF 2 SECONDS. RESPONSE AFTER 2 SECONDS WILL CAUSE THE PROGRAM TO CONTINUE AS DESCRIBED.

PROG CONT	CMC	GROUND	CREW	CHECKLIST	TIME	TOTAL TIME
	.CMC .ROUTINE .SELECTION					
	----- START RENDEZVOUS TRACKING DATA PROC- ESSING ROUTINE (R22) -----					#10
					
	----- SET VHF TIMER TO ZERO -----					#20
 "R"					#30
.....					

++
+16
++
EDIT

WAIT 4 SECONDS

#40

++
+16
++
EDIT

IS THE REFSMMAT
FLAG SET?

#50

.Y .N
. .
. .
. .
. .
. .
. .
. .
. .
. .
EXIT

#60

IS R60 OPERATING?

.Y .N
. .
. .
. .
. .
. .
. .
. .
. .
. .
.....

#70

IS THE UPDATE FLAG
SET?

.Y .N
. .
. .

#80

IS THE TRACK
FLAG SET?

.N .Y
. .
. .
. .
. .
. .
. .
. .

493

.
.
.
.
.
.
.
.
.

R22/COLOSSUS

#90

++
+16
+
++
EDIT

.
.
.
.
.
.
.
.
.
.

IS THERE DATA IN
MARK DATA POSITION
#2?

#100

.Y .N
.
.
.
.
.
.
.
.

#110

TRANSFER DATA OUT
OF MARK DATA POSI-
TION #2 AND INTO
POSITION #3

#120

.
.
.

CLEAR POSITION #2

.
.
.

CALCULATE THE LCS TO
THE LM

#130

.
.
.

SET SOURCE
CODE TO 1

#140

.
.
.
.
.
.
.
.
.
.

R22/COLOSSUS

GO TO
"C"

#150

"C"
.
.
.
...
.

#160

BASED ON THE DATA
AND ITS SOURCE
(OPTICS OR VHF ANC,
IF OPTICS-PRIMARY OR
BACK UP)
CALCULATE THE RE-
QUIRED CORRECTION
TO UPDATE THE STATE
VECTOR DESIGNATED BY
THE STATE VECTOR
FLAG (SEE P20).
FOR DESCRIPTION
OF UPDATE PROCESS
REFER TO SECTION
5.2.5.2.2 OF R577

#170

.
.
.

#180

IS THIS THE 2ND
OPTICS CORRECTION
FOR THIS MARK?

.Y	.N
.	.
.	.
.....	.
.	...
.	.
.	.
.	.
.	.
.	.
.	.
.	.
.	.
.	.
.	.
.	.

#190

494

495

. IS THE MAGNITUDE
 . OF THE STATE VECTOR
 . CHANGE GREATER THAN
 . THE TEST TOLERANCE
 . STORED IN ERASABLE
 . MEMORY?
 . FOR DEFINITION
 . OF TEST TOLFRANCE
 . REFER TO ERASABLE
 . LOAD FOR THE SPECI-
 . FIC MISSION.

#200

. .N .Y
 . . .
 . . .
 . . .
 . . .
 . . .
 . . .
 . . .

#210

POSS
PRIO
HOLD
SNAP

. FLASH VERB-NOUN TO
 . REQUEST RESPONSE AND
 . DISPLAY EXCESSIVE
 . UPDATE PARAMETERS.
 . V06 N49
 . R1-DELTA R
 . R2-DELTA V
 . R3-SOURCE CODE

. MONITOR DSKY: DOES
 . VERB NOUN FLASH TO
 . REQUEST RESPONSE AND
 . DISPLAY EXCESSIVE
 . UPDATE PARAMETERS?

#220

. DELTA R-MAGNITUDE
 . OF THE DIFFERENCE
 . BETWEEN THE POSITION
 . VECTOR BEFORE AND
 . AFTER INCORPORATION
 . OF THIS MARK DATA.
 . IN N.M. TO THE NEAR-
 . EST .1 NM.

. IS THE SOURCE CODE
 . IN R3 = 1?

#230

. DELTA V-MAGNITUDE
 . OF THE DIFFERENCE
 . BETWEEN THE VELOCITY
 . VECTOR BEFORE AND
 . AFTER INCORPORATION
 . OF THIS MARK DATA.
 . IN FPS TO THE NEAR-
 . EST .1 FPS.

. VERIFY THAT
 . MARKING WAS DONE
 . ON THE LM AND
 . DISCUSS OUT OF
 . TOLERANCE CON-
 . DITION WITH THE
 . GROUND, IF
 . POSSIBLE.

#240

. SOURCE CODE-DEFINES
 . SOURCE OF DATA:
 . 1 = OPTICS MARKS
 . 2 = VHF RANGING

501

·
·
·
·
·
·
·
·
·
·

GO TO
"B"

SHUT OFF TRACKER
FAIL LIGHT.

·
·
·

SET SOURCE CODE TO 2

·
·
·
·
·

GO TO
"C"

R22/COLOSSUS

#520

#530

CHANGE CONTROL NOTES

LOGIC REV 13	PCR# MIT 54
LOGIC REV 14	PCR MIT 66
LOGIC REV 15	PCR MIT 465
	PCR 440
	PCR 468
	PCR 491
	PCR 226
LOGIC REV 16	PCN 570

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BACKUP RENDEZVOUS TRACKING SIGHTING MARK ROUTINE (R23) LOGIC REV 08 11/27/68

PURPOSE: (1) TO PERFORM SIGHTING MARKS IN CONJUNCTION WITH THE RENDEZVOUS NAVIGATION PROGRAM (P20) BY USE OF A BACKUP OPTICAL DEVICE.

ASSUMPTIONS: (1) THE ASTRONAUT KNOWS THE COORDINATES (OPTICS) OF THE ALTERNATE LOS HE MUST USE FOR THIS ROUTINE
 EDIT
 ++ (2) WHEN THE CMC ACCEPTS A MARK IT RECORDS AND STORES THE 3 ICDU'S, THE CONTENTS OF NOUN 94 AND THE TIME OF MARK IN
 +08 POSITION #1 AND MOVES PREVIOUS MARK DATA (IF ANY) TO POSITION #2. IF A MARK IS REJECTED BY KEYING IN V86E THE MARK
 ++ DATA IN POSITION #1 IS ERASED.
 PCR THE RENDEZVOUS TRACKING DATA PROCESSING ROUTINE (R22) ATTEMPTS TO PROCESS THE MARK DATA (IF ANY) IN
 491 POSITION #2 ONCE EVERY 4 SECONDS. IF DATA IS IN POSITION #2, IT IS MOVED TO POSITION #3 FOR PROCESSING BY (R22). IF
 ++ NO DATA IS IN POSITION #2, R22 INTERROGATES POSITION #2 AFTER 4 SECONDS.
 +08
 ++ (3) THIS ROUTINE IS MANUALLY SELECTED BY THE ASTRONAUT BY KEYING IN V54E.

PROG CONT	CMC	GROUND	CREW	CHECKLIST	TIME	TOTAL TIME
			.CREW .ROUTINE .SELECTION ...			
	----- START BACK UP REN- DEZVOUS TRACKING SIGHTING MARK ROU- TINE (R23) -----	----- KEY IN V54E -----			#10
 : : -----					
++ +08 + + + + + +08 ++	IS ANOTHER EXTENDED VERB ACTIVE? ----- N. Y. . . ----- . TURN ON OPERATOR ERROR LIGHT -----					#20
PCN 586 : : : : :					

```

.
.
.
.
.
.
.
.
.
.
.
EXIT
.
.

```

#30

```

-----
IS THE RENDEZVOUS
FLAG SET?
-----

```

```

.Y           .N
.
.
.
.

```

#40

```

-----
IS TRACK FLAG
SET (SEE P20)?
-----

```

```

.Y           .N
.
.
.
.

```

```

++
+08
+
+
+
+
+08
++
EDIT
PCR
206

```

```

. TURN ON PRO-
. GRAM ALARM
. LIGHT. (NOTE:
. ALARM CODE
. IF CALLED BY
. ASTRONAUT
. IS:
. V05N09
. R1-
. R2-
. R3-
. EXPECTED
. ALARM CODE
. AT THIS TIME
. IS 406
-----

```

```

-----
MONITOR DSKY:
DOES PROGRAM
ALARM INDICATE
THAT THE RENDEZVOUS
NAVIGATION PROGRAM
(P20) IS NOT IN
PROCESS?
-----

```

#50

```

.Y           .N
.
.
.
.
.
.
.

```

#60

```

-----
THIS ROUTINE
MAY NOT BE SE-
LECTED AT THIS
TIME. PRESS
ALARM RESET TO
RESET PROGRAM
ALARM
-----

```

#70

```

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.
.
.
.
.
.
EXIT
.
.
.
.

```

#80

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.....
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.
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.....
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.
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.
.

```

HOLD .. FLASH VERB-NOUN TO
 REQUEST RESPONSE AND
 SNAP .. DISPLAY ALTERNATE
 LOS COORDINATES
 VJ6 N94
 R1 SHAFT
 R2 TRUNNION
 R3 BLANK

SHAFT-OPTICS SHAFT
 ANGLE IN DEGREES TO
 NEAREST .01 DEGREES
 TRUNNION-OPTICS
 TRUNNION ANGLE IN
 DEGREES TO NEAREST
 .001 DEGREES

WAIT FOR KEYBOARD
 ENTRY:

TERMINATE FLASH
 UPON RECEIPT OF NEW
 DATA OR PROCEED

.NEW .PROCEED
 .DATA .

MONITOR DSKY:
 OBSERVE VERB-NOUN
 FLASH TO REQUEST
 RESPONSE AND DISPLAY
 NEW OCDU ANGLES.

NOTE: THE VALUE OF
 THESE REGISTERS
 SHOULD CORRESPOND TO
 THE CHOSEN ALTERNATE
 LOS.

(THE NOMINAL ANGLES
 TO BE USED FOR COAS
 SIGHTINGS ARE:
 R1-00000
 R2-57470)

ARE THE DISPLAYED
 ANGLES CORRECT FOR
 THE CHOSEN LOS?

.Y .N

KEY IN V24F
 AND LOAD
 ANGLES.

KEY IN
 PROCEED

#90

#100

#110

#120

#130

STORE
NEW DATA

#140

HOLD
SNAP

FLASH VERB-TO
REQUEST PLEASE PER-
FORM ALTERNATE LOS
SIGHTING MARK
V53 N BLANK
R1-BLANK
R2-BLANK
R3-BLANK

MONITOR DSKY:
OBSERVE VERB
FLASH TO REQUEST
PLEASE PERFORM AL-
TERNATE LOS SIGHTING
MARK.

#150

WAIT FOR KEYBOARD
ENTRY

USING THE ROTATIONAL
HAND CONTROLLER PO-
SITION THE SPACE-
CRAFT SO THAT THE
LM IS PRECISELY
ALONG THE LOS
CHOSEN.

#160

KEY IN ENTER

#170

WAS SIGHTING SATIS-
FACTORY?

#180

.N .Y

#190

TERMINATE FLASH
UPON RECEIPT
OF ENTER, V86E
OR PROCEED

.....
PROCEED
.....

.....
KEY IN V86E
.....

.V .E .P
.8 .N .R
.6 .T .D
.E .E .C
. .R .E
. . .E
. . .D

ERASE
MARK DATA
IN POSI-
TION #1
(IF ANY)

DO I WISH TO
MAKE MORE MARKS?

.Y .N

IS THERE
MARK DATA
IN POSI-
TION #1?

KEY IN PROCEED

.Y .N

.....
EXIT
R23

TRANSFER
MARK DATA
FROM POSI-
TION #1 TO
POSITION
#2

#200

#210

#220

#230

#240

TFF-TIME OF FREE
FALL TO 300,000 FT
FOR EARTH ORBIT
OR 35,000 FT FOR
LUNAR ORBIT.
ALTITUDE DEFINED
ABOVE THE LAUNCH
PAD RADIUS (EARTH
ORBIT) AND ABOVE
THE LUNAR RADIUS
AT THE MOST RECENT-
LY DEFINED LAND-
ING SITE (LUNAR
ORBIT).
IN MIN, SEC TO
NEAREST SEC. MAX
READING IS -59859
(IF PER ALT
IS GREATER
THAN 300,000/
35,000 FT THE TFF
DISPLAY WILL READ
-59859.)

#230

++
+10
++
PCR
524

NOTE: IF PER ALT OR
APO ALT EXCEEDS
SCALE THE DISPLAY
WILL BE 9999.9 NM.

#250

WAIT FOR KEYBOARD
ENTRY

KEY IN
RECYCLE
V32F

#260

TERMINATE FLASH UPON
RECEIPT OF PROCEED
OR RECYCLE

NOTE:
REFER TO ASSUMP-
TIONS FOR DEFINI-
TION OF ADDITIONAL
DISPLAYS AVAILABLE
IN THIS ROUTINE.
WHEN FINISHED WITH
THIS ROUTINE
KEY IN PROCEED

#270

RECYCLE PROCEED
OR AVE G
AUTOMATIC
RECYCLE
.....

#280

515

.
.
.
.
.
.
.
.
.
.
.
EXIT

.
.
.
.
.
.
.
.
.
.
.
EXIT

R30/COLOSSUS
R30/SUNDANCE
R30/LUMINARY

CHANGE CONTROL NOTES

REV 08 PCR MIT 66
REV 09 PCR 206
REV 09 PCR 490
REV 10 PCR 524
PCR 509
REV 11 PCN 586

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RENDEZVOUS PARAMETER DISPLAY ROUTINE NO 1 (R31)

LOGIC REV 08 11/27/68

PURPOSE: (1) TO DISPLAY AT ASTRONAUT REQUEST CMC CALCULATED RENDEZVOUS PARAMETERS (RANGE, RANGE RATE, THETA)

ASSUMPTIONS: (1) RANGE AND RANGE RATE ARE CALCULATED BY THE CMC ON THE BASIS OF THE STORED LM AND CSM STATE VECTORS AND DO NOT REQUIRE THAT THE ISS BE ON. THE ISS MUST BE ON AND ALIGNED TO A "KNOWN" ORIENTATION IF A CORRECT DISPLAY OF THETA IS DESIRED. THE RANGE/RANGE RATE/ THETA DISPLAY IS NOT INHIBITED HOWEVER IF THE IMU IS NOT ON AND ALIGNED.

(2) THE ROUTINE IS SELECTED BY THE ASTRONAUT BY DSKY ENTRY.

PRG CONT	CMC	GROUND	CREW	CHECKLIST	TIME	TOTAL TIME
-------------	-----	--------	------	-----------	------	---------------

.CRFW
.ROUTINE
.SELECTION
.
...
.

START
RENDEZVOUS PARAMETER
DISPLAY ROUTINE (R31)

KEY IN V83E

#10

++
+08
+
+
+
+
+
+
+08
++

IS ANOTHER EXTENDED
VERB ACTIVE?

N. Y.

TURN ON OPERATOR
ERROR LIGHT

#20

PCN
586

EXIT

#30

R31/COLOSSUS
R31/SUNDANCE
R31/LUMINARY

SET T = PRESENT
TIME

EXTRAPOLATE CSM AND
LM STATE VECTORS TO
T USING COASTING
INTEGRATION ROUTINE.

.....
.....
.....
.....
.....
.....
.....
.....

IS AVERAGE G RUN-
NING?

.....
.....
.....
.....
.....
.....

SET TF = PRESENT
TIME

.....
.....
.....
.....
.....
.....

EXTRAPOLATE LM
AND CSM STATE
VECTORS TO TF
FROM T USING
KEPLER SUBROUTINE

.....
.....
.....
.....
.....
.....

SET TF = AVERAGE
G TIME.

#40

#50

#60

#70

#80

519

R31/COLOSSUS
R31/SUNDANCE
R31/LUMINARY

. . .
. . .
. . .
. . .
. . .
. . .

. . .
. . . EXTRAPOLATE LM
. . . STATE VECTOR TO
. . . TF FROM T USING
. . . COASTING INTE-
. . . GRATION ROUTINE.

#90

++
+08
++
EDIT

. . .
. . .
. . .
. . .
. . .
. . .

#100

. . .
. . . CALCULATE RANGE,
. . . RANGE RATE AND
. . . THETA

HOLD
MON

. . .
. . .
. . .

. . .
. . . FLASH VERB-NOUN TO
. . . REQUEST RESPONSE AND
. . . DISPLAY RENDEZVOUS
. . . PARAMETERS:
. . . V16 N54
. . . R1-RANGE
. . . R2-RANGE RATE
. . . R3-THETA

. . .
. . . MONITOR DSKY:
. . . OBSERVE VERB-NOUN
. . . FLASH TO REQUEST
. . . RESPONSE AND DISPLAY
. . . OF RENDEZVOUS
. . . PARAMETERS.
. . . (NOTE: THESE PARA-
. . . METERS WILL BE
. . . UPDATED EVERY TWO
. . . SECONDS.

#110

. . .
. . . RANGE-CALCULATED
. . . RANGE TO LM. IN
. . . NAUTICAL MILES TO
. . . NEAREST .01 NM.

#120

. . .
. . . RANGE RATE-
. . . CALCULATED RANGE
. . . RATE BETWEEN CSM AND
. . . LM. NEGATIVE SIGN
. . . INDICATES CLOSING
. . . IN FPS TO NEAREST
. . . .1 FPS

#130

R31/COLOSSUS
R31/SUNDANCE
R31/LUMINARY

521

CHANGE CONTROL NOTES

LOGIC	REV 5	PCR MIT 66
	REV 6	PCR 495
	REV 7	PCR 511
	REV 8	PCN 586

00203000
00204000
00204001
00204002

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