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NAVAIR 00-110AHD50-2

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### Standard Aircraft Characteristics

# NAVY MODEL QH-50B AIRCRAFT

(TITLE UNCLASSIFIED)

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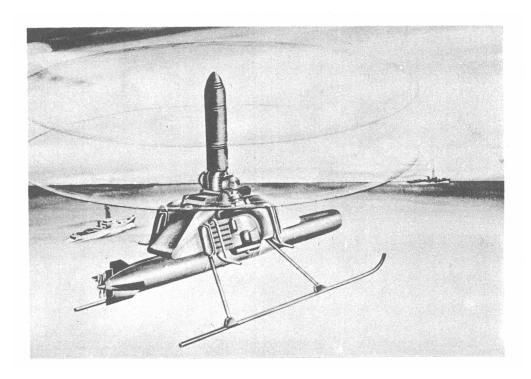
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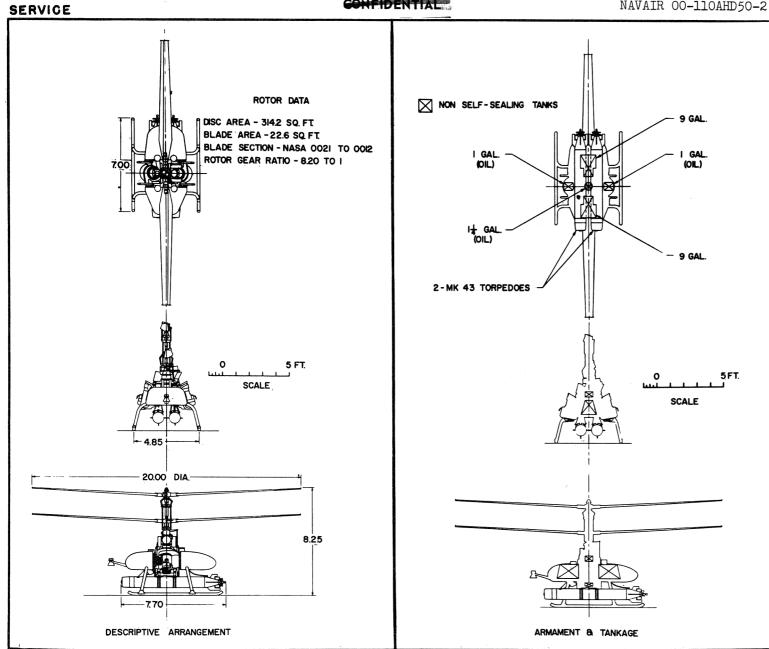




# STANDARD AIRCRAFT CHARACTERISTICS QH-50B

GYRODYNE











#### POWER PLANT

#### RATINGS

 BHP
 RPM
 ALT

 T.O.
 72
 4500
 SSL

 NORM.
 72
 4500
 SSL

Model Spec. No. 2 of 28 Jan 1959, revised 5 Aug 1959

#### **ORDNANCE**

Max. Load Capacity - 530 lbs.

#### MISSION AND DESCRIPTION

The Model DSN-2 Drone is a remotely controlled ASW Helicopter, designed to carry a 500 lb. weapon (torpedotype) and be capable of launching this weapon as directed by remote control. An alternate design loading (overload condition) is to carry two MK43 Torpedoes, each weighing 266 lbs.

The drone incorporates two two-bladed coaxial rotors of the semi-rigid (see-saw) type. The blades are of laminated wood construction incorporating taper in planform and thickness and 12° negative twist. Attitude is completely controllable through the rotors by conventional cyclicpitch control; yaw control is achieved by means of rotor blade tip air (drag) brakes.

Two Gyrodyne-Porsche Y0-95-4 four cylinder, four cycle reciprocating engines, rated at 72 hp (after cooling) at 4500 rpm at sea level, are incorporated in the DSN-2. Engine cooling is provided by a fan.

Service use of this drone weapons system is not presently contemplated, although it will be used for purposes of testing and checking out the avionics equipment and remote control system to be incorporated in the DSN-3.

#### DEVELOPMENT

First Flight ...... July 1960

#### **DIMENSIONS**

#### **WEIGHTS**

 LOADINGS
 LES.

 EMPTY
 813

 NORMAL
 1450

 OVERLOAD
 1500

All weights are estimated

#### FUEL AND OIL

#### **ELECTRONICS**

Gyrodyne-Lear automatic stabilization and remote control equipment

(Nomenclature not yet available)





		PERFORM	ANCE SUMMA	RY	
TAKE-OFF LOADING CONDITION		(1) NORMAL 1-500# Tor- pedo	(2) OVERLOAD 2-MK 43		
TAKE-OFF WEIGHT	1b.	1450	1500		
Fuel	1b.	95	95		
Payload	1b.	500	530	,	
Disc loading	lb./sq.ft.	4.62	4.78		
Vertical rate of climb at S.L. (A)	fpm.	640	420		
Absolute hovering ceiling (A)	ſt.	2950	1850		
Max. rate of climb at S.L. (A)	fpm.	1160	1040		
Service ceiling (100 fpm) (A)	ſt.	8600	7600		
Speed at S.L. (A)	kn.	76,8	76,0		
Max. speed/altitude (A)	kn./ft.	76.8/S.L.	76.0/S.L.		
Max. range	n.mi.	85.3			
Average cruising speed	kn.	65			
Cruising altitude	ſt.	S.L.			
Combat radius	n.mi.	32.0	31.2		
Average cruising speed	kn.	77.5	76.8		
Cruising altitude	ft.	S.L.	S.L.	·	
Max. Endurance	hrs.		1.60		
Average cruising speed kn.			42		
Cruising altitude	ft.		S.L.		

#### NOTES

#### (A) Normal Rated Power ( Take-off Power)

PERFORMANCE is based on calculations modified by contractor flight data of the Model XRON-1 Rotorcycle (17' rotor dia.) COMBAT RADIUS, RANGE, and ENDURANCE are based on engine specific fuel consumption increased 5%.

All performance is out of ground effect.

#### COMBAT RADIUS MISSION

Warm-up and Take-off: 1 min at NRP at Sea Level

Cruise out: at Vmax at Sea Level

Hover: 12 min at Sea Level

Drop Weapon: No fuel consumed, no distance

gained

Cruise back: at Vmax at Sea Level Reserve: 10% of initial fuel load

#### MAX. RANGE MISSION

at NRP at Sea Level Cruise: at speed for best

range at Sea Level

Reserve: 10% of initial

fuel load

#### MAX. ENDURANCE MISSION

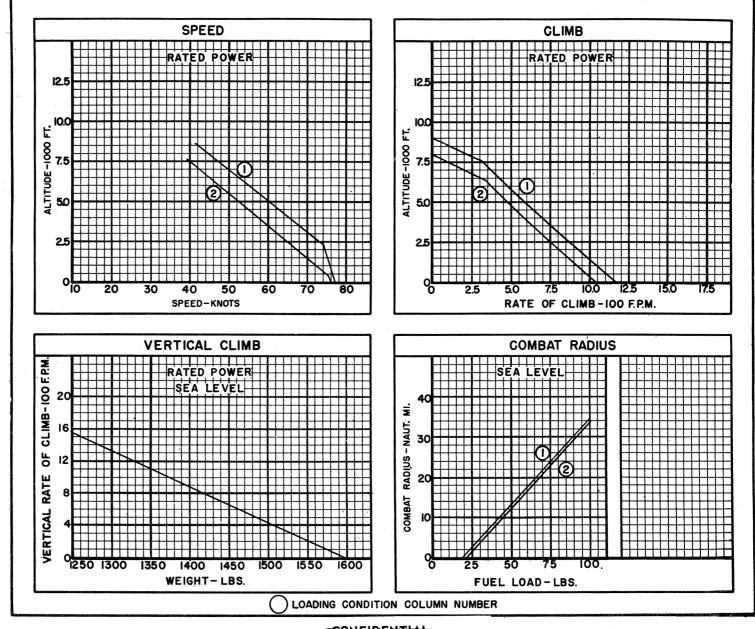
Warm-up and Take-off: 1 min Warm-up and Take-off: 1 min at NRP at Sea

Level

Cruise: at speed for best endurance at

Sea Level

Reserve: 10% of initial fuel load



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DEVENOVICE