

AC motor control circuits

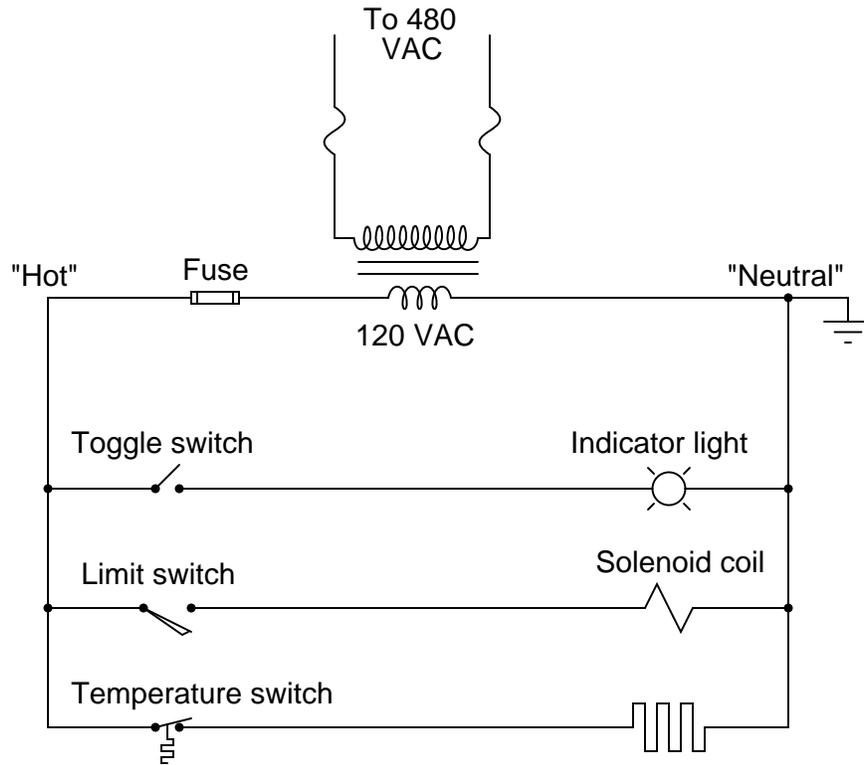
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Resources and methods for learning about these subjects (list a few here, in preparation for your research):

Questions

Question 1

An alternative to the conventional schematic diagram in AC power control systems is the *ladder diagram*. In this convention, the "hot" and "neutral" power conductors are drawn as vertical lines near the edges of the page, with all loads and switch contacts drawn between those lines like rungs on a ladder:



As you can see, the symbolism in ladder diagrams is not always the same as in electrical schematic diagrams. While some symbols are identical (the toggle switch, for instance), other symbols are not (the solenoid coil, for instance).

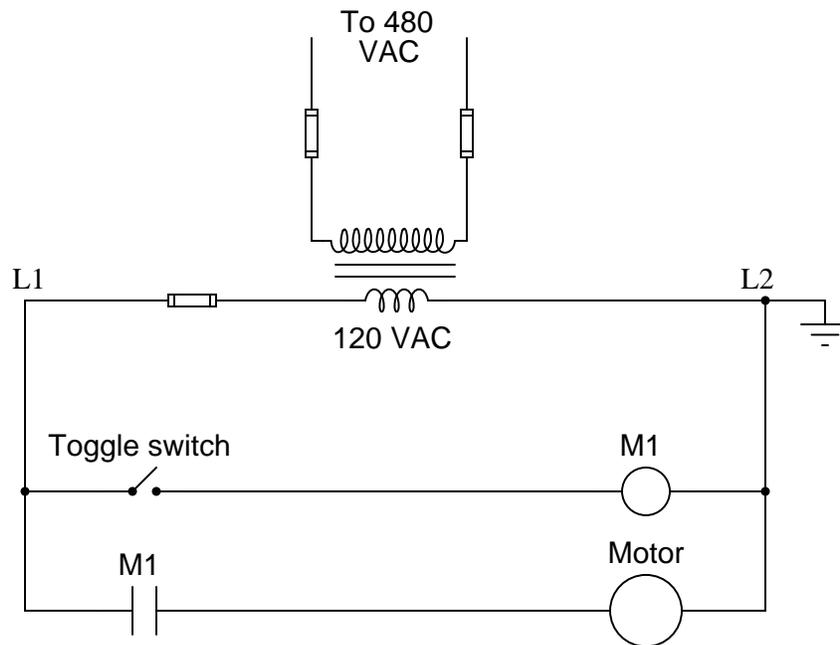
Re-draw this ladder diagram as a schematic diagram, translating all the symbols into those correct for schematic diagrams.

[file 00832](#)

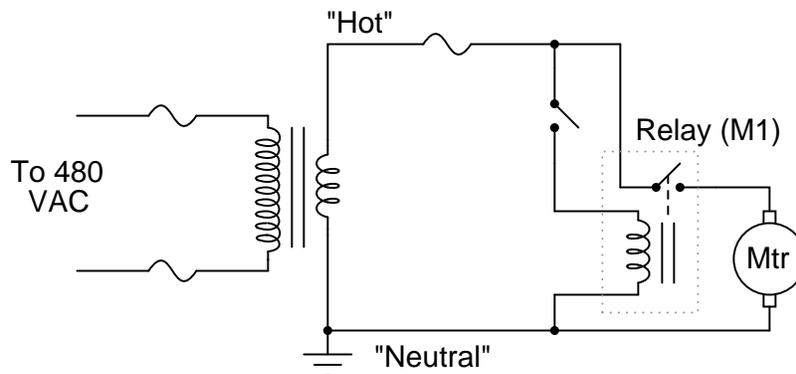
Question 2

Perhaps the most challenging aspect of interpreting ladder diagrams, for people more familiar with electronic schematic diagrams, is how electromechanical relays are represented. Compare these two equivalent diagrams:

First, the ladder diagram:



Next, the schematic diagram:



Based on your observations of these two diagrams, explain how electromechanical relays are represented differently between ladder and schematic diagrams.

file 00833

Question 3

Draw the necessary wire connections to build the circuit shown in this ladder diagram:

Ladder diagram:

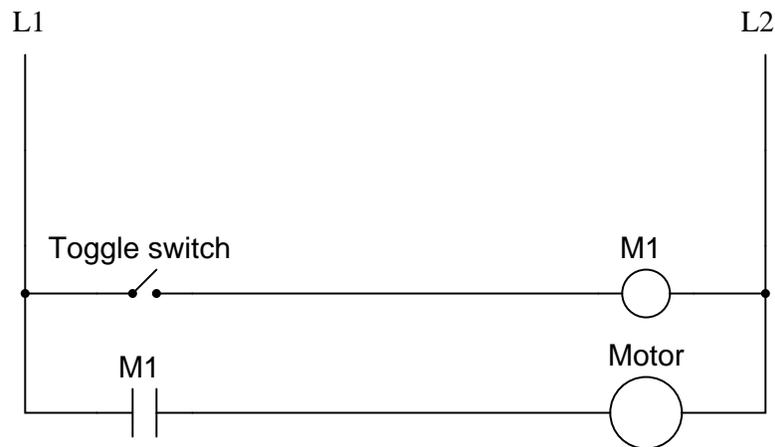
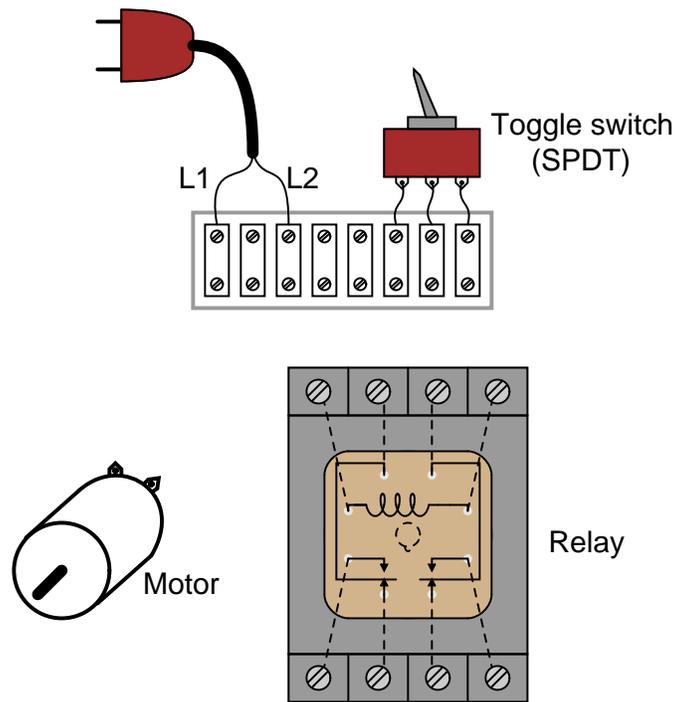


Illustration showing components:



(Dashed lines represent connections between relay terminals and socket screw lugs, hidden from sight)

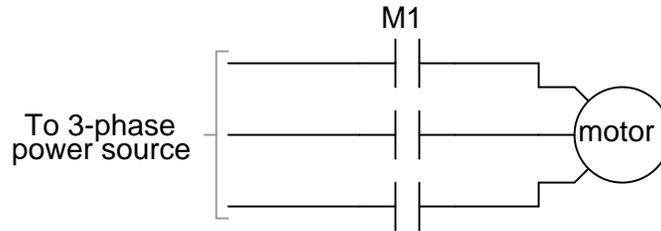
Yes, the "Run" switch shown in the diagram is a SPST, but the switch shown in the illustration is a SPDT. This is a realistic scenario, where the only type of switch you have available is a SPDT, but the

wiring diagram calls for something different. It is your job to improvise a solution!

[file 00836](#)

Question 4

Interpret this AC motor control circuit diagram, explaining the meaning of each symbol:

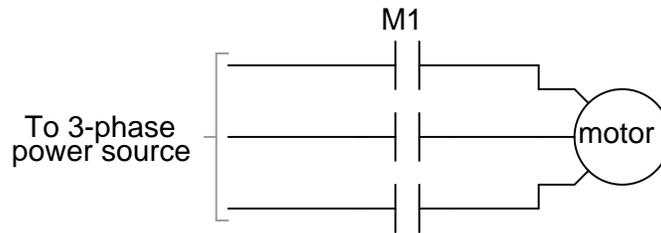
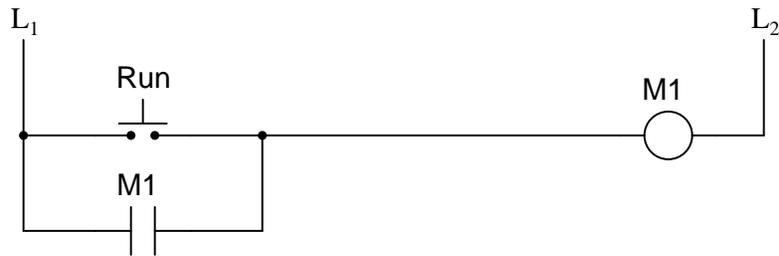


Also, explain the operation of this motor control circuit. What happens when someone actuates the "Run" switch? What happens when they let go of the "Run" switch?

[file 00834](#)

Question 5

Interpret this AC motor control circuit diagram, explaining the meaning of each symbol:

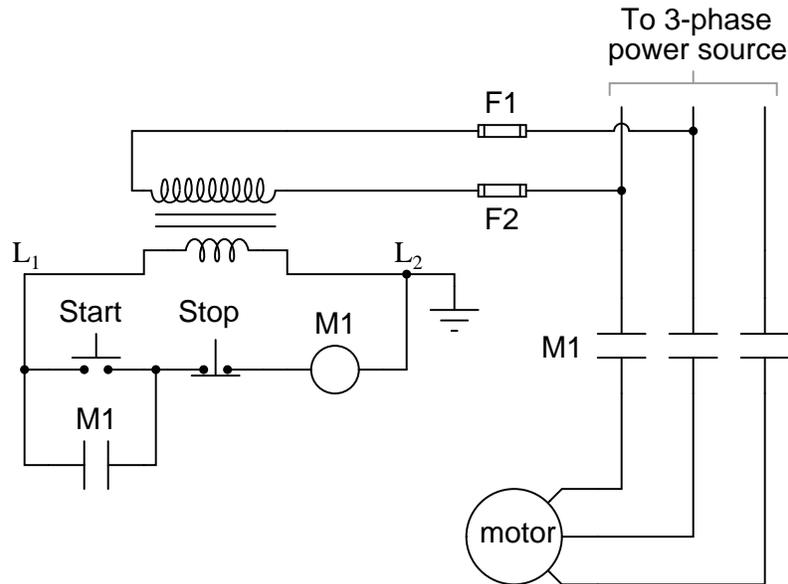


Also, explain the operation of this motor control circuit. What happens when someone actuates the "Run" switch? What happens when they let go of the "Run" switch?

[file 00835](#)

Question 6

A very common form of *latch* circuit is the simple "start-stop" relay circuit used for motor controls, whereby a pair of momentary-contact pushbutton switches control the operation of an electric motor. In this particular case, I show a low-voltage control circuit and a 3-phase, higher voltage motor:



Explain the operation of this circuit, from the time the "Start" switch is actuated to the time the "Stop" switch is actuated. The normally-open M1 contact shown in the low-voltage control circuit is commonly called a *seal-in contact*. Explain what this contact does, and why it might be called a "seal-in" contact.

file 01347

Question 7

Draw the necessary wire connections to build the circuit shown in this ladder diagram:

Ladder diagram:

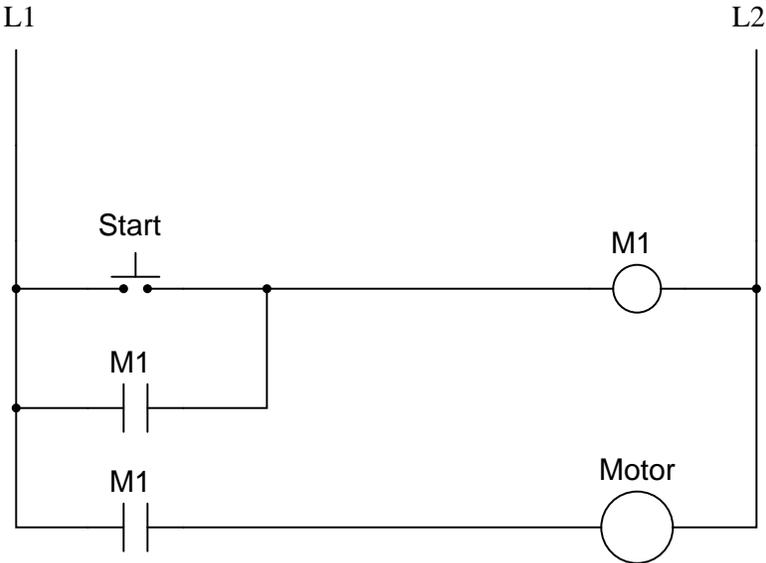
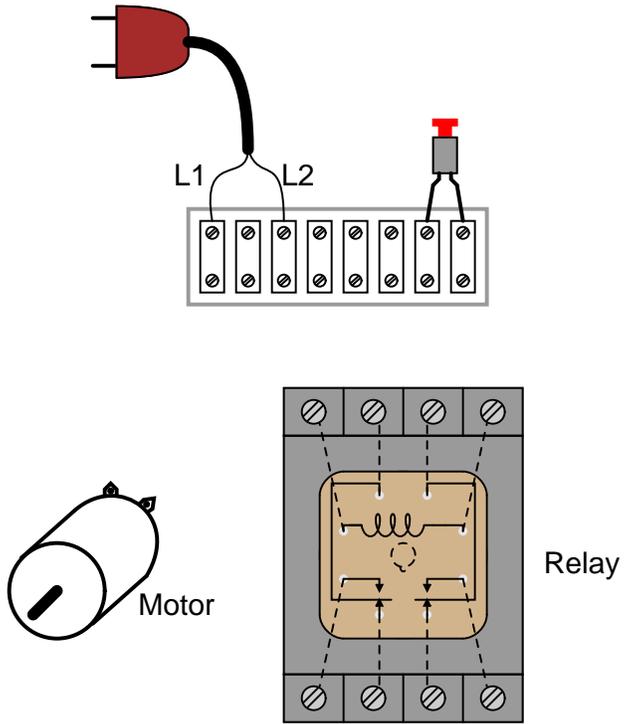


Illustration showing components:

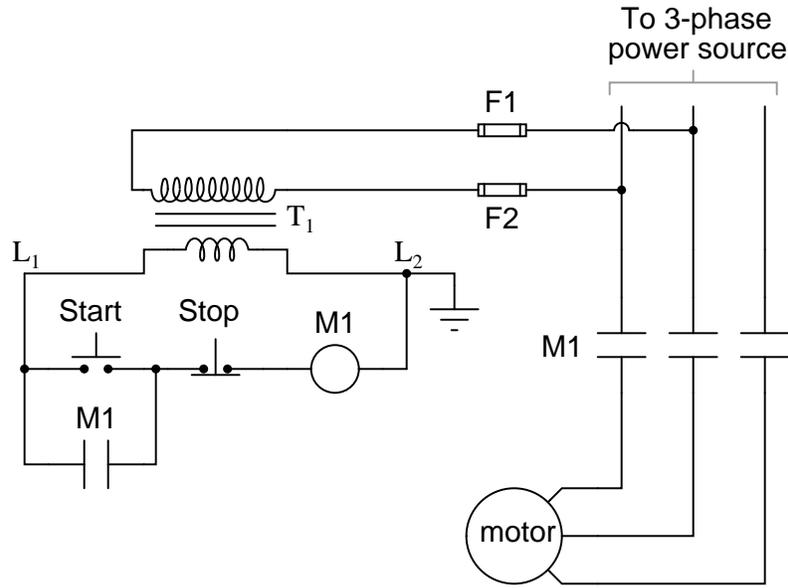


(Dashed lines represent connections between relay terminals and socket screw lugs, hidden from sight)

file 00838

Question 8

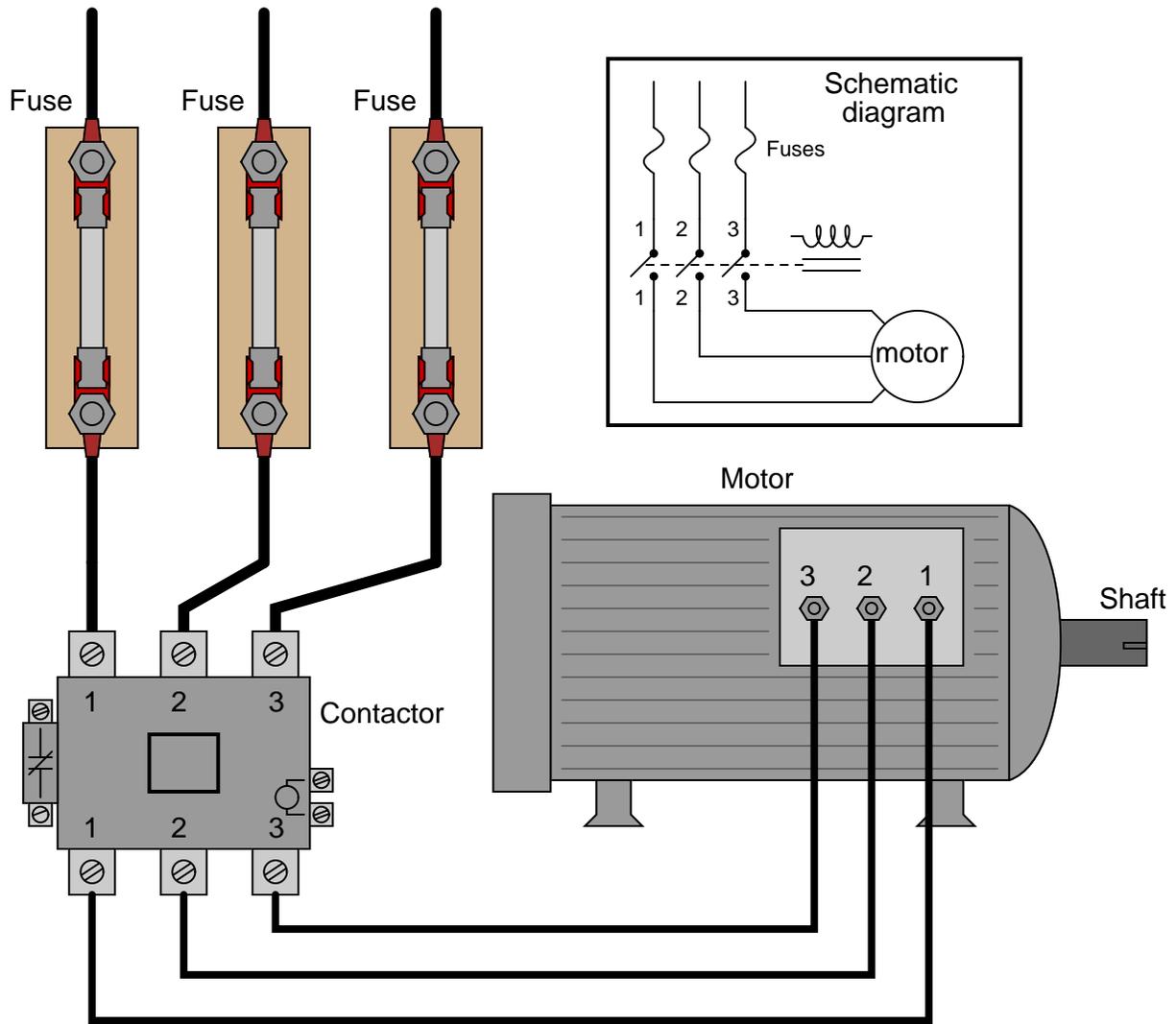
Identify at least one fault that would cause the motor to turn off immediately once the "Start" pushbutton switch was released, instead of "latch" in the run mode as it should:



For each of your proposed faults, explain *why* it will cause the described problem.
[file 03896](#)

Question 9

Examine this three-phase motor control circuit, where fuses protect against overcurrent and a three-pole relay (called a *contactor*) turns power on and off to the motor:



After years of faithful service, one day this motor refuses to start. It makes a "humming" sound when the contactor is energized (relay contacts close), but it does not turn. A mechanic checks it out and determines that the shaft is not seized, but is free to turn. The problem must be electrical in nature!

You are called to investigate. Using a clamp-on ammeter, you measure the current through each of the lines (immediately after each fuse) as another start is once again attempted. You then record the three current measurements:

Line	Current
1	52.7 amps
2	51.9 amps
3	0 amps

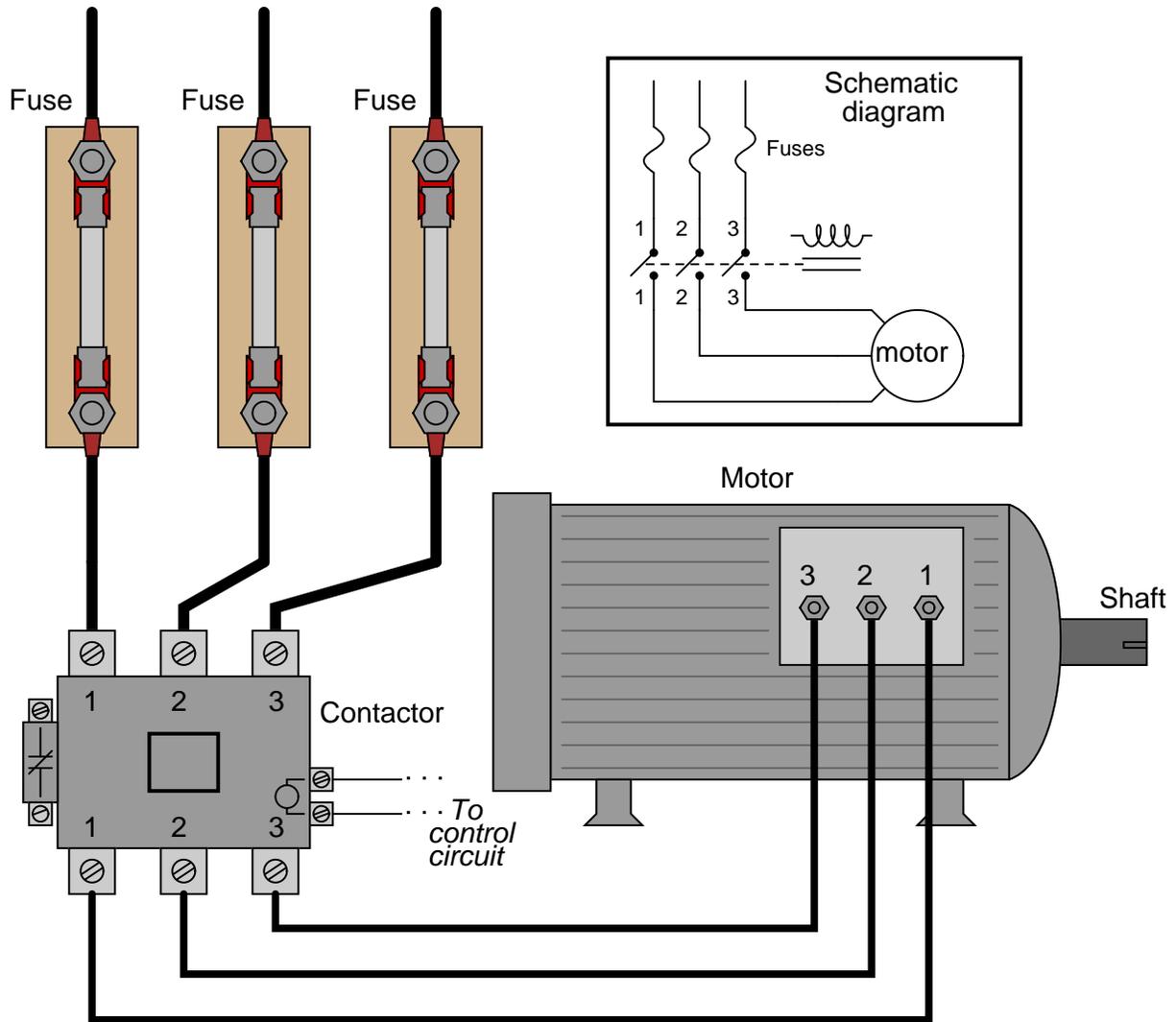
Determine at least two possible faults which could account for the motor's refusal to start and the

three current measurements taken. Then, decide what your next measurement(s) will be to isolate the exact location and nature of the fault.

file 03623

Question 10

There is something wrong in this motor control circuit. When the start button is pressed, the contactor energizes but the motor itself does not run:



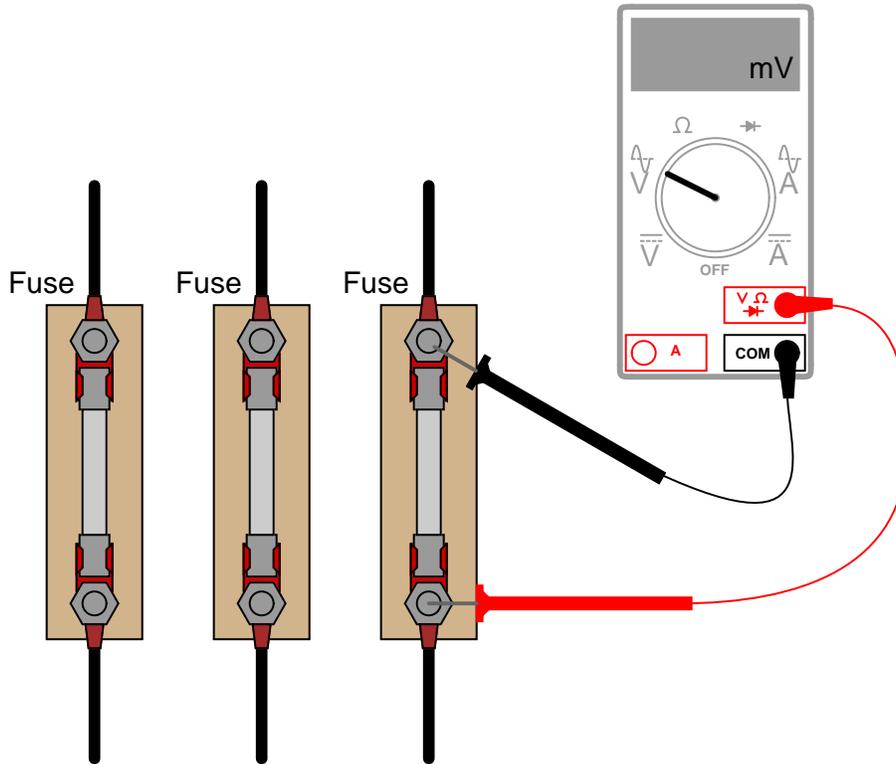
Identify a good place to check with your multimeter to diagnose the nature of the fault, and explain your reasoning.

file 03828

Question 11

Working on a job site with an experienced technician, you are tasked with trying to determine whether the line currents going to a three-phase electric motor are balanced. If everything is okay with the motor and the power circuitry, of course, the three line currents should be precisely equal to each other.

The problem is, neither of you brought a clamp-on ammeter for measuring the line currents. Your multimeters are much too small to measure the large currents in this circuit, and connecting an ammeter in series with such a large motor could be dangerous anyway. So, the experienced technician decides to try something different – he uses his multimeter as an AC milli-voltmeter to measure the small voltage drop across each fuse, using the fuses as crude shunt resistors:



He obtains the following measurements:

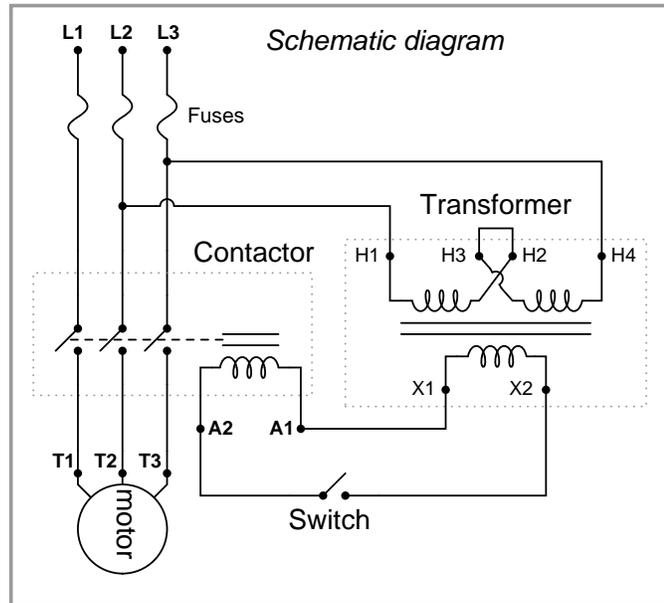
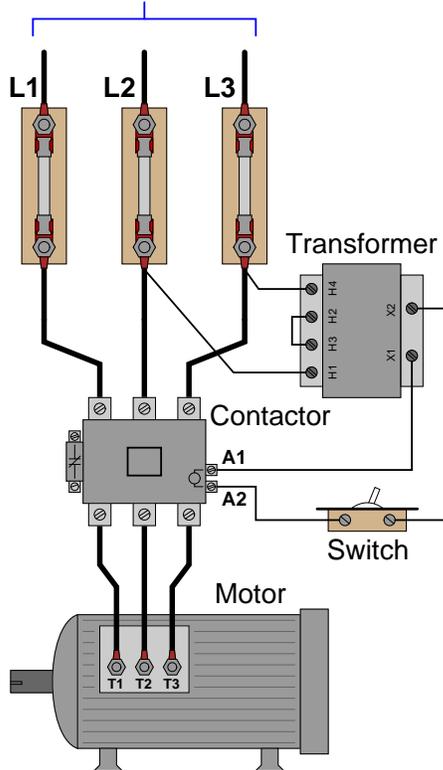
Line	Fuse voltage drop
1	24.3 mV
2	37.9 mV
3	15.4 mV

Do these voltage drop measurements suggest imbalanced motor line currents? Why or why not?
[file 03624](#)

Question 12

Identify at least three independent faults that could cause this motor not to start:

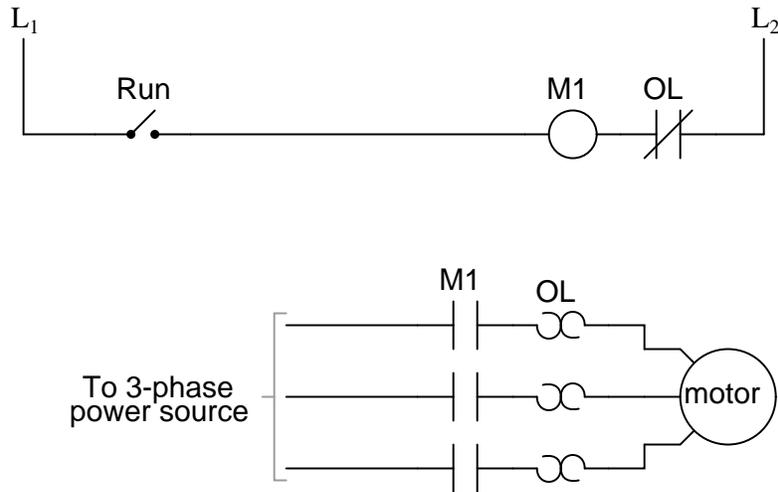
To 3- ϕ , 480 volt power source



For each of the proposed faults, explain *why* they would prevent the motor from starting.
[file 03829](#)

Question 13

A special type of overcurrent protection device used commonly in motor control circuits is the *overload heater*. These devices are connected in series with the motor conductors, and heat up slightly under normal current conditions:



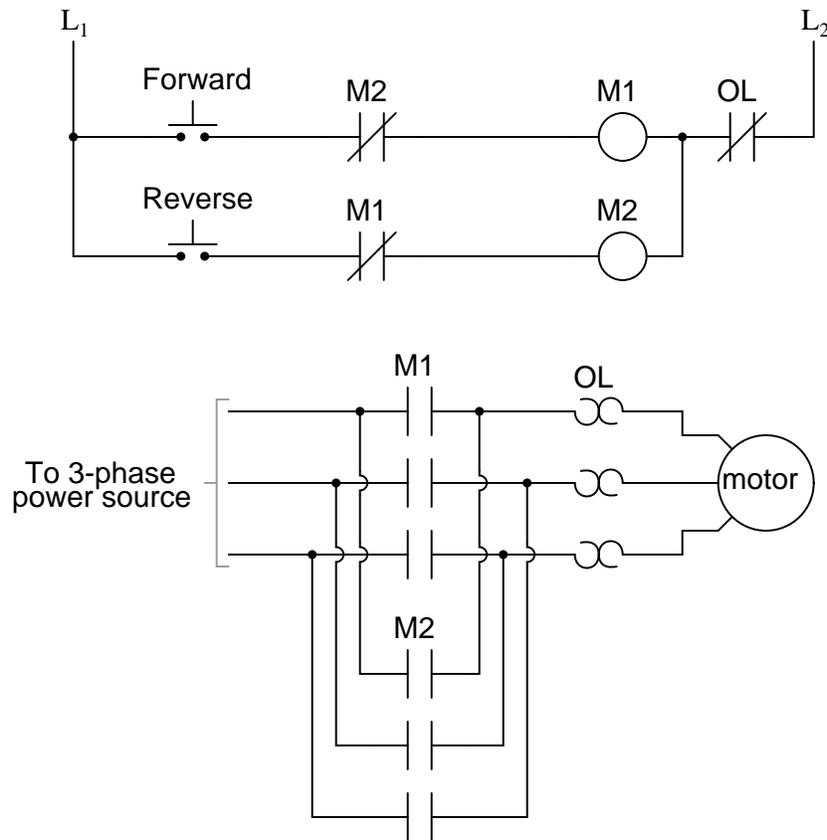
Although the "heater" elements are connected in series with the motor lines as fuses would be, they are *not* fuses! In other words, it is not the purpose of an overload heater to burn open under an overcurrent fault condition, although it is possible for them to do so.

The key to understanding the purpose of an overload heater is found by examining the single-phase (L₁ / L₂) control circuit, where a normally-closed switch contact by the same name ("OL") is connected in series with the motor relay coil.

How, exactly, do overload heaters protect an electric motor against "burnout" from overcurrent conditions? How does this purpose differ from that of fuses or circuit breakers? Does the presence of overload heaters in this circuit negate that need for a circuit breaker or regular fuses? Explain your answers.
[file 00837](#)

Question 14

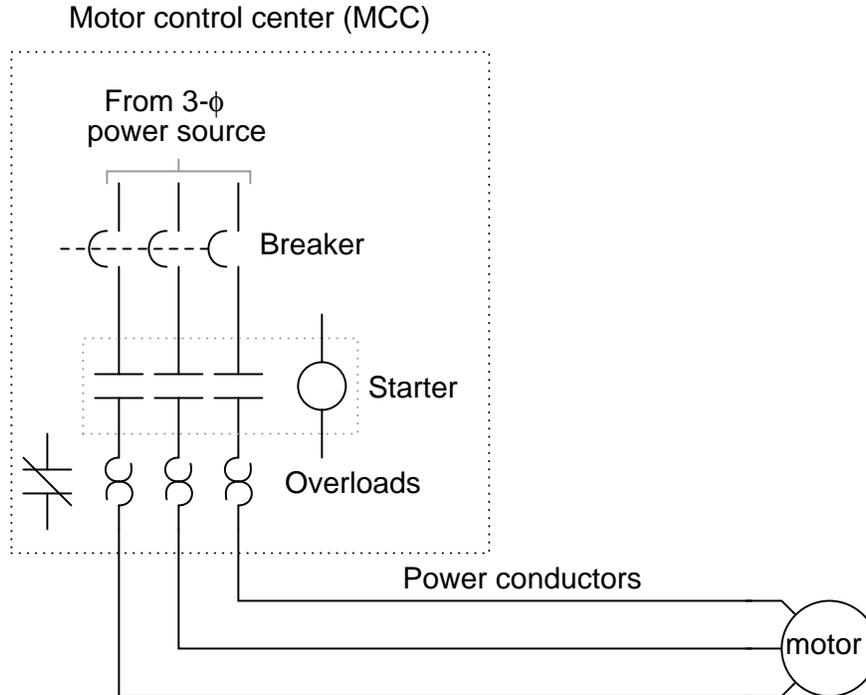
The circuit shown here provides two-direction control (forward and reverse) for a three-phase electric motor:



Explain how the reversal of motor direction is accomplished with two different motor starters, M1 and M2. Also, explain why there is only one set of overload heaters instead of two (one for forward and one for reverse). Finally, explain the purpose of the normally-closed contacts in series with each starter coil.

[file 03142](#)

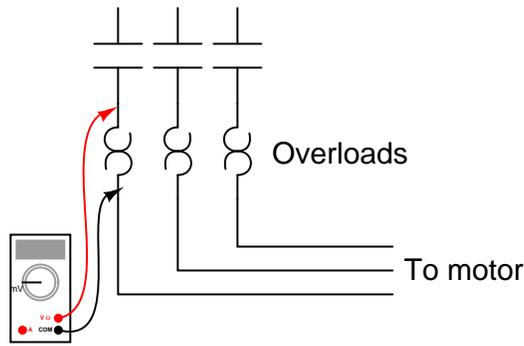
The starter and overload heater assembly for an industrial electric motor is often located quite a distance from the motor itself, inside a room referred to as a *motor control center*, or MCC:



Since it is impossible for a technician to be in two places at once, it is often necessary to perform diagnostic checks on a malfunctioning electric motor from the MCC where the technician has access to all the control circuitry.

One such diagnostic check is line current, to detect the presence of an open motor winding. If a three-phase motor winding fails open, the motor will not run as it should. This is called *single-phasing*. A good way to check for this condition is to use a clamp-on (inductive) ammeter to check line current on all three lines while the starter is energized. This may be done at any location where there is physical access to the motor power conductors.

Suppose, though, you are working on a job site where single-phasing is suspected and you do not have a clamp-on ammeter with you. All you have is a DMM (digital multimeter), which does not have the ability to safely measure the motor's current. You are about to head back to the shop to get a clamp-on ammeter when a more experienced technician suggests an alternate test. He takes your DMM, sets it to the AC *millivolt* range, then connects the test probes to either side of each overload heater element, one heater at a time like this:



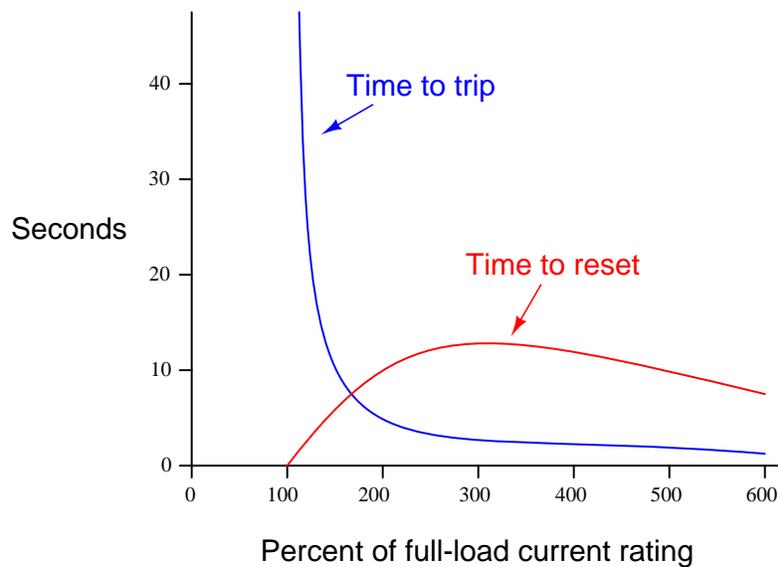
Across each overload heater element he measures about 20 mV AC with the starter engaged. From this he determines that the motor is *not* single-phasing, but is drawing approximately equal current on all three phases.

Explain how this diagnostic check works, and why this determination can be made. Also describe what limitations this diagnostic procedure has, and how a clamp-on ammeter really is the best way to measure motor line current.

[file 03143](#)

Question 16

Shown here is a typical set of "curves" for an overload heater, such as is commonly used to provide overcurrent protection for AC electric motors:



Why is there any time required to re-set an overload heater contact after a "trip"? Circuit breakers can be re-closed mere moments after a trip with no problem, and fuses (of course) can be replaced moments after blowing. Is this an intentional design feature of overload heaters, or just an idiosyncrasy?

Also, explain why the reset curve starts to decrease for currents above 300% of the motor's full-load rating. Why doesn't the reset time curve continue to increase with increasing fault current magnitudes?

[file 00839](#)

Question 17

Protective relays are special power-sensing devices whose job it is to automatically open or close circuit breakers in large electric power systems. Some protective relays are designed to be used directly with large electric motors to provide sophisticated monitoring, shut-down, and start-up control.

One of the features of these motor-oriented protective relays is *start-up lockout*. What this means is the relay will prevent someone from attempting too many successive re-starts of a large electric motor. If the motor is started and stopped several times over a short period of time, the relay will prevent the person from starting it again until a sufficient "rest" time has passed.

Explain why a large electric motor would need to "rest" after several successive start-up events. If electric motors are perfectly capable of running continuously at full load for years on end, why would a few start-ups be worthy of automatic lock-out?

[file 03131](#)

Question 18

The simplest and least expensive style of electric motor control is the so-called *across-the-line* starter. Describe how this motor control circuit functions, and also define the word "starter" in this context.

[file 00840](#)

Question 19

Although "across-the-line" motor control circuits are simple and inexpensive, they are not preferred for starting large motors. An alternative to across-the-line motor starting is *reduced voltage* starting. Identify some of the reasons across-the-line starting is undesirable for large electric motors.

[file 00841](#)

Question 20

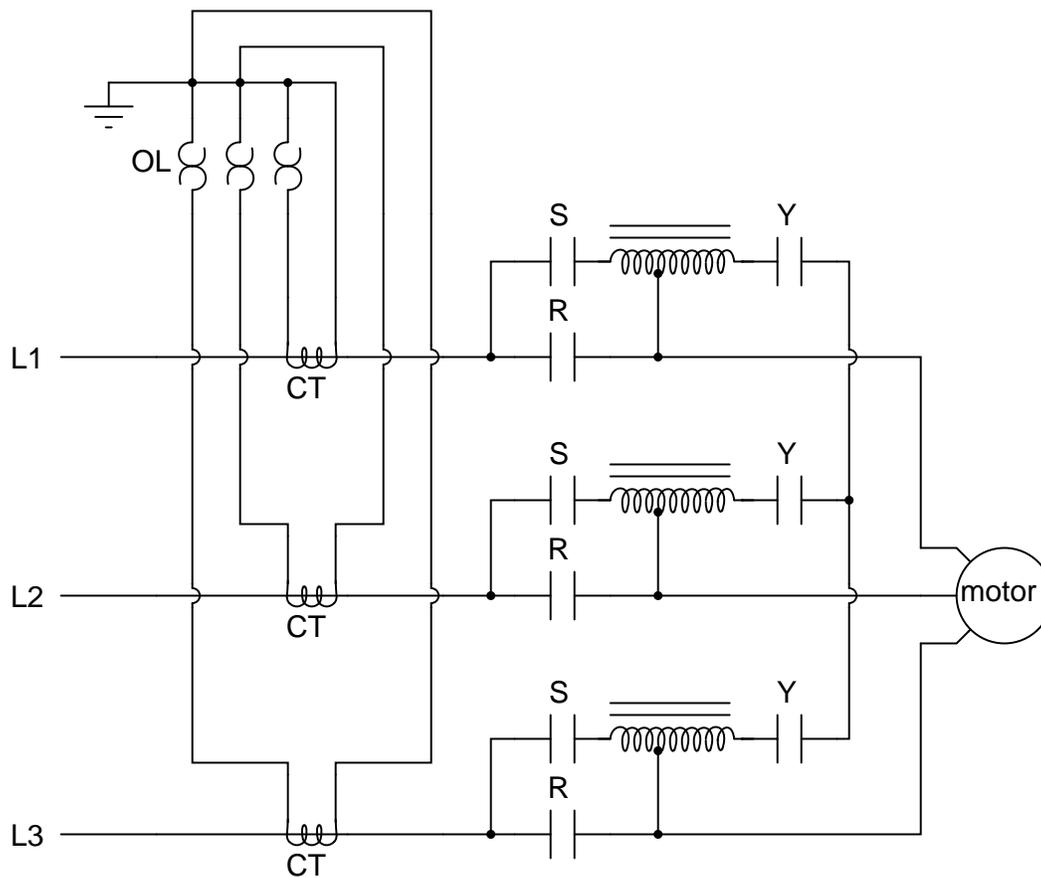
One method of achieving reduced-voltage starting for large electric motors is to insert series resistances into each of the motor's power conductors. When starting, all power must go through the resistors. After the motor has had time to speed up, another set of "starter" contacts bypass line power around the resistors, directly to the motor windings.

Draw a diagram showing how this could be done for a single-phase electric motor, using two starter contacts: "R" for "run" and "S" for "start". Hint: you only need two contacts and one resistor!

[file 00842](#)

Question 21

There are several different methods of providing *reduced-voltage starting* for electric motors. One of them is the *autotransformer* method. Here is a diagram showing how this works:



"L1," "L2," and "L3" represent the three phase power supply conductors. Three sets of contacts (R, S, and Y) serve to connect power to the motor at different times. The starting sequence for the motor is as follows:

1. Motor off (R open, S open, Y open)
2. Start button pressed (S and Y contacts all close)
3. Time delay (depending on the size of the motor)
4. Y contacts open
5. Time delay (depending on the size of the motor)
6. R contacts close, S contacts open

Explain the operation of this system. How do the autotransformers serve to reduce voltage to the electric motor during start-up?

file 00843

Question 22

A popular strategy for AC induction motor control is the use of *variable frequency drive* units, or VFDs. Explain what varying the frequency of power to an AC induction motor accomplishes, and why this might be advantageous.

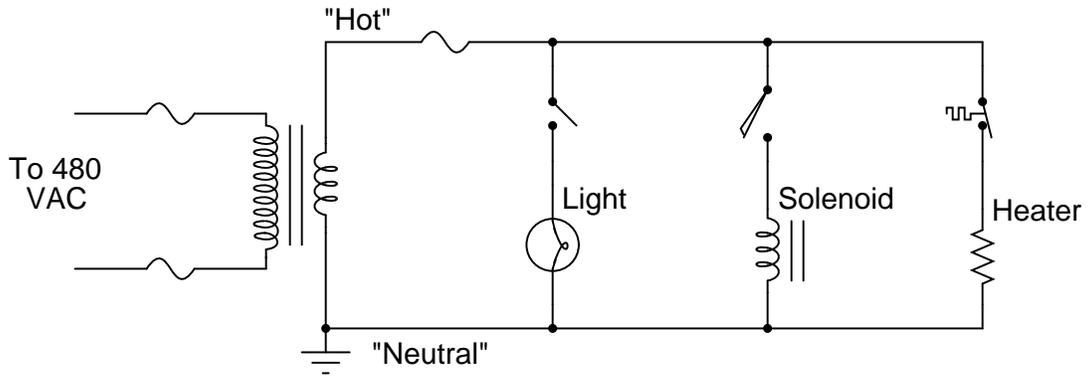
[file 03145](#)

Question 23

Electromechanical relays used to start and stop high-power electric motors (called "contactors" or "starters") must be considered a possible source of *arc flash*. Explain why this is. What is it about the construction or operation of such a relay that invites this dangerous phenomenon?

[file 03144](#)

Answer 1

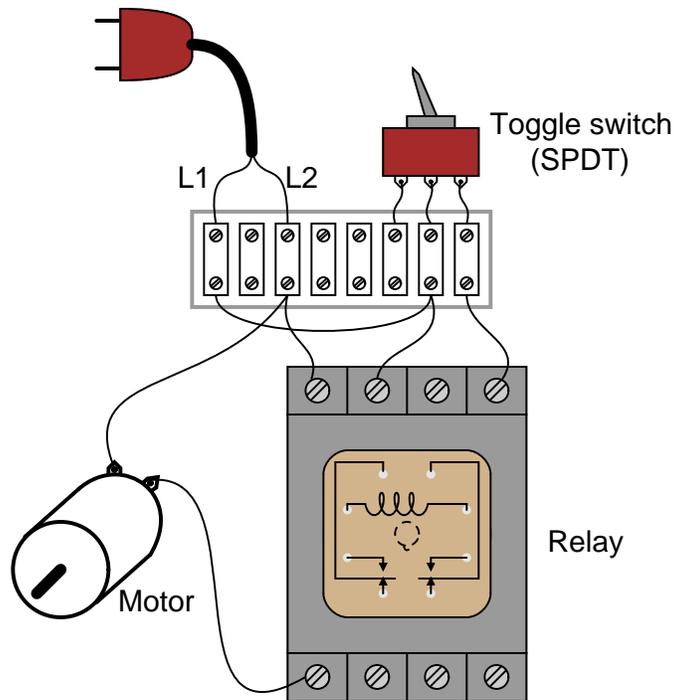


Answer 2

One of the most significant differences is that in ladder diagrams, relay coils and relay contacts (the normally-open contact in this diagram shown as a capacitor-like symbol) need not be drawn near each other.

Follow-up question: what do the two labels "L1" and "L2" represent?

Answer 3



Challenge question: which switch position (handle to the left or handle to the right) turns the motor on?

Answer 4

The "Run" switch is a normally-open pushbutton. Relay coil "M1" is energized by this switch, and actuates three normally-open contacts (also labeled "M1") to send three-phase power to the motor. Note that the details of the power supply are not shown in these diagrams. This is a common omission, done for the sake of simplicity.

Answer 5

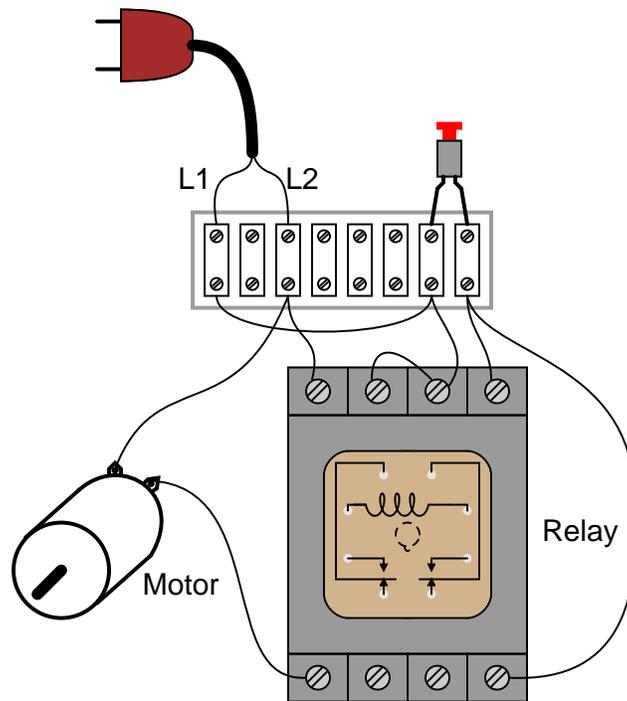
In this circuit, the motor will start once the "Run" switch is actuated. When the "Run" switch is released, the motor continues to run.

Follow-up question: this circuit has no "stop" switch! What would have to be modified in the ladder logic circuit to provide "stop" control?

Answer 6

Even though the "Start" and "Stop" switches are momentary, the "seal-in" contact makes the circuit *latch* in one of two states: either motor energized or motor de-energized.

Answer 7



Answer 8

- M1 control contact failed open.
- Wire(s) between M1 control contact and control circuit broken open.

Answer 9

Here are some possibilities:

- Fuse #3 blown open
- Third relay contact damaged (failed open) inside the contactor
- One winding failed open inside the motor (assuming a "Y" winding configuration)

There are several valid "next steps" you could take from this point. Discuss alternatives with your classmates.

Answer 10

Try checking for line voltages at the "line" (source) side of the contactor, between terminals 1 and 2, 2 and 3, and 1 and 3, with the contactor energized (motor is supposed to be running). I'll leave it to you to explain why this is a good place to check first.

Answer 11

The results are inconclusive, because resistance for the whole fuse and holder assembly is not a reliably stable quantity. Corrosion between one of the fuse ends and the fuse holder clip, for example, would increase resistance between the points where millivoltage is shown measured.

Follow-up question: just because the results of these millivoltage measurements are inconclusive in this scenario does not necessarily mean the principle of using fuses as current-indicating shunt resistors is useless. Describe one application where using a fuse as a current-indicating shunt would yield trustworthy information about the current.

Challenge question: determine where you could measure millivoltage, that might be more reliable in terms of quantitatively indicating line current.

Answer 12

Here are some possible faults (not an exhaustive list by any means!):

- Any fuse blown
- Contactor coil failed open
- Any transformer winding failed open
- Broken jumper between H3 and H2 on the transformer
- Corroded wire connection at terminal A1 or A2
- Motor winding failed shorted

Follow-up question: there will be a difference in operation between the L1 fuse blowing and either the L2 or L3 fuse blowing. Explain what this difference is, and why it might serve as a clue to what was wrong.

Answer 13

When the overload "heaters" become excessively warm from overcurrent, they trigger the opening of the "OL" contact, thus stopping the motor. The heaters do not take the place of regular overcurrent protection devices (circuit breakers, fuses), but serve a different purpose entirely. It is the task of the overload heaters to protect the *motor* against overcurrent by mimicking the thermal characteristics of the motor itself. Circuit breakers and fuses, on the other hand, protect an entirely different part of the circuit!

Answer 14

Motor reversal is accomplished by reversing the phase sequence of the three-phase power going to the motor (from ABC to ACB). The existence of only one set (three) heaters may be adequately explained if you consider a scenario where the motor overheats after being run in the "Forward" direction, then an immediate attempt is made to run it in "Reverse." Finally, the NC contacts (typically called *interlock* contacts) prevent lots of sparks from flying if both pushbuttons are simultaneously pressed!

Answer 15

Each overload heater element possesses a small amount of electrical resistance, which is the key to this diagnostic procedure. Of course, the measurement obtained is strictly qualitative, not quantitative as a clamp-on ammeter would give.

Follow-up question #1: what sort of result might occur with this diagnostic check if the motor were indeed single-phasing due to one of the overload heaters failing open?

Follow-up question #2: what other causes could there be for a three-phase motor "single-phasing" other than a motor winding failed open?

Answer 16

The reset time for an overcurrent heater is an intentional design feature. If the heater is too hot to re-set, then the motor is too hot to re-start.

Answer 17

I won't give you a direct answer here, but I will provide a big hint: *inrush current*.

Answer 18

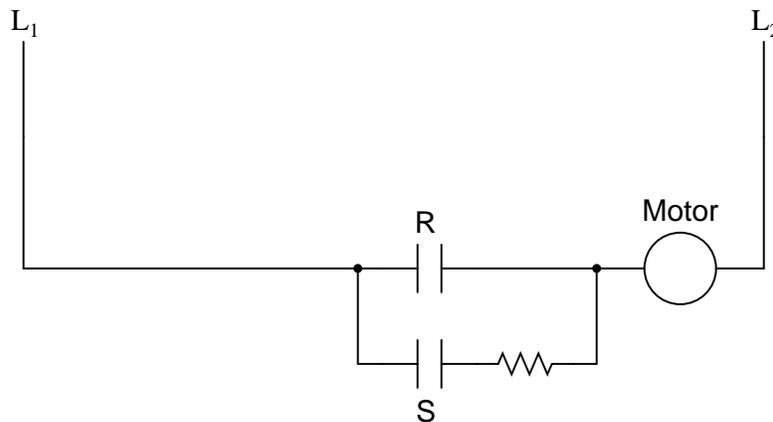
A "starter" is another name for the large power relay used to conduct current to the motor lines. Starters are also known as *contactors*, and are usually labeled with the letter "M" in ladder diagrams.

Answer 19

I'll let you research the answers to this question!

Answer 20

None of the control circuitry (start switch, overload contact, starter coil, etc.) is shown in this diagram:



Answer 21

When the "S" and "Y" contacts are all closed, the autotransformers form a three-phase "Y" connection, with line voltage (L1, L2, and L3) applied to the "tips" of the "Y," and a reduced motor voltage tapped off a portion of each autotransformer winding.

When the "Y" contacts open, the three autotransformers now function merely as series-connected inductors, limiting current with their inductive reactance.

When the "R" contacts close, the motor receives direct power from L1, L2, and L3.

Follow-up question: how do the overload heaters function in this circuit? They aren't connected in series with the motor conductors as is typical with smaller motors!

Answer 22

Variable frequency drives allow for the precise and efficient control of induction motor speed, which is not possible by other means.

Answer 23

Electromechanical relays interrupt circuit current by drawing pairs of metal contacts apart, separating them with an air gap. Because this contact motion is not instantaneous, it is possible to generate an arc across the air gaps of such magnitude that it becomes an arc flash.

Notes 1

While ladder diagrams have their own unique elegance, it may be frustrating for some students to have to learn a new diagram convention. Since ladder diagrams are so common in industry, your students really have no choice.

Notes 2

Discuss these diagrams with your students, noting any significant advantages and disadvantages of each convention.

In reference to the challenge question, the symbols "L1" and "L2" are very common designations for AC power conductors. Be sure your students have researched this and know what these labels mean!

Notes 3

This question helps students build their spatial-relations skills, as they relate a neat, clean diagram to a relatively "messy" real-world circuit. As usual, the circuit shown here is not the only way it could have been built, but it is one solution.

In reference to the challenge question, the particular style of SPDT switch shown is very common, and the terminal connections on the bottom might not be what you would expect from looking at its schematic symbol.

Notes 4

Discuss with your students the sources of electrical power for both circuits here: the relay control circuit and the motor itself. Challenge your students to explore this concept by asking them the following questions:

- Are the two sources necessarily the same?
 - How does the convention of linking relay coils with contacts by name (rather than by dashed lines and proximity) in ladder diagrams benefit multiple-source circuits such as this one?
 - Do these circuits even have to be drawn on the same page?
-

Notes 5

This circuit is known as a *latching* circuit, because it "latches" in the "on" state after a momentary action. The contact in parallel with the "Run" switch is often referred to as a *seal-in contact*, because it "seals" the momentary condition of the Run switch closure after that switch is de-actuated.

The follow-up question of how we may make the motor stop running is a very important one. Spend time with your students discussing this practical design problem, and implement a solution.

Notes 6

Motor "start-stop" circuits are very common in industry, and apply to applications beyond electric motors. Ask your students if they can think of any application for a circuit such as this.

Notes 7

This question helps students build their spatial-relations skills, as they relate a neat, clean diagram to a relatively "messy" real-world circuit. As usual, the circuit shown here is not the only way it could have been built, but it is one solution.

Notes 8

This form of motor control circuit is *very* popular in industry. It is well worth your students' time to study it and understand both how and why it works.

Notes 9

This is a practical scenario which you and your students should have some fun exploring. If they have never heard of a "contactor" before, this question is a good opportunity to introduce the component. Bring one with you to discussion if you have the opportunity!

Notes 10

Discuss with your students the various options they have in diagnostic steps, and what they think of the step proposed in the answer. Troubleshooting scenarios such as this are excellent for stimulating active class discussions, so take advantage of it!

Notes 11

While measuring millivoltage across a *fuse* may seem like a strange diagnostic technique, it is one I have gainfully applied for years. The "catch" is you have to know what it is good for and what it is not. It is *not* a precise, quantitative technique by any means!

Notes 12

Identifying multiple faults should be quite easy in this circuit. The real value of this question is the opportunity for explanation and discussion that it generates for your students as they share their answers with each other.

Notes 13

Ask your students to describe the information they found on overload heaters through their research. There are different styles and variations of overload heaters, but they all perform the same function. Also, be sure to review with your students the purpose of fuses and circuit breakers. These devices are not intended to protect the load (motor), but rather another important component of an electrical system!

An interesting way to explain the function of overload heaters is to refer to them as *analog models* of the motor windings. They are designed such that at any given current level, they will take as long to heat up and reach their trip point as the real motor itself will take to heat up to a point of impending damage. Likewise, they also cool off at the same rate as the real motor cools off when no power is applied. Overload heaters are like small motor-models with a thermostat mechanism attached, to trip the overload contact at the appropriate time. It is an elegant concept, and quite practical in real motor control applications.

Notes 14

Ask your students to explain exactly *why* "sparks [would fly]" if both pushbuttons were pressed at the same time. The name commonly given to the NC contacts is *interlock*, because each one "locks out" the other starter from being energized.

Notes 15

I have used this diagnostic check more than once to troubleshooting a single-phasing electric motor. It is amazing what sorts of diagnostic checks you can do with a high-quality DMM and a sound understanding of electrical theory!

Notes 16

Remind your students that the purpose of an overload heater is to provide a thermal analogue of the electric motor itself. Ideally, the heater heats up and cools down at the exact same rate as the motor. This explains why there is a necessary reset time after an overload heater causes the motor control circuit to "trip."

Ask your students to share the common design features of an overload heater, from their research. How do these devices actually function? If your students understand this, they should have no difficulty understanding why overload heater contacts require time to reset after a trip.

The reason for the reset time curve decreasing after about 300% full-load current is a bit more complex to answer. This, as well, is not an idiosyncrasy, but rather a design feature of the overload heater. Since greater levels of current will trip the heater in a shorter time, they actually heat up the motor less during that brief "on" time than a sustained overcurrent of lesser magnitude. Therefore the motor does not need to cool down as long prior to the next re-start.

Notes 17

Inrush current is a factor with *every* motor type, AC or DC. It is easy to forget just how substantially larger a typical motor's inrush current is compared to its normal full-load current. When students consider the magnitude of the currents involved, and also the fact that most electric motors are fan-cooled and therefore lacking in cooling during the initial moments of a start-up, the reason for automatic lock-out after several successive start-up events becomes obvious.

Notes 18

Ask your students to identify any motor control circuit diagrams they've already seen as being "across-the-line." If there are no convenient motor control circuit diagrams available for illustration, you may want to ask a student to draw an "across-the-line" starter circuit on the whiteboard for everyone to see.

Notes 19

The reasons for using reduced-voltage starting instead of across-the-line starting go beyond electrical! Discuss this with your students.

Notes 20

If students have studied the autotransformer method of reduced-voltage starting, ask them to compare this method against that. Certainly, the resistive method is simpler, but does the autotransformer method have its own advantage(s)?

Notes 21

For each step of the start-up sequence, it is possible to re-draw the circuit feeding power to the motor, in order to make its function more apparent. Do not create these re-drawings yourself, but have your students draw an equivalent circuit for each step in the start-up sequence.

The follow-up question is a good review of current transformers (CT), as well as an introduction to the use of overload heaters in high-current electrical systems.

Notes 22

Central to the answer of this question is the principle of a *rotating magnetic field* and how rotor speed is primarily a function of line frequency. While the internal details of a VFD are quite complex, the basic operating principle (and rationale) is not.

Arc flash is just as hazardous to electrical technicians as electric shock, yet I have seen (and worked with) people who pay no attention to the dangers! It must be understood that motor starters are by their very nature arc-generating devices, and that under certain unusual conditions may generate lethal arc flashes. You might want to ask your students what sorts of unusual conditions could lead to a contactor producing an actual arc flash (rather than merely a few small sparks).